

# Computer Games Exercises: 2024s s06 (all)

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## Answer header

Please put the author information in the header of all code files.

- `name` (Name)
- `coauthor list`

## C03b: Collision time

### Preparation

Please read the source code of the "Collision time" game and understand the game logic.

There is a path along which an object is moving from left to right, and a wall. The object movement is identified by the offset along the path with the speed  $V$ . After every interval  $T$ , the collision detection is performed. When a collision is detected at  $T_2$ , the collision time is calculated with the information at  $T_1 (= T_2 - T)$  and  $T_2$ .

## Task

Please extend the game.

- Use the parameter value of speed  $V$  and interval  $T$  from the interface to move the object, and show the results in the corresponding labels when the object stops moving.
- Implement the function `distance()` to calculate the physical distance from the object to the wall.

$$d(x_{\text{object}}) = \begin{cases} x_{\text{wall\_left}} - x_{\text{object}} & \text{if } x_{\text{object}} \leq x_{\text{wall\_middle}} \\ x_{\text{object}} - x_{\text{wall\_right}} & \text{if } x_{\text{object}} > x_{\text{wall\_middle}} \end{cases}$$

- Update the function `_process()` to perform collision detection after every interval  $T$ .
  - When the distance from the object to the wall is negative, there is an intersection.
  - When there is no collision (NC), draw a red circle at the current position of the object (using `draw_circle()`), and keep the object moving.
  - When there is an intersection (IS), stop the object, estimate the collision time using the "fast correction method" and the "bisection method", and show the results in the corresponding labels.
  - The collision time is represented in seconds with 3 digits right to the decimal, referring to the start time of the object movement `timeStart`.
- Implement the function `fast_correction()` to estimate the collision time using the "fast correction method" at time  $T_2$ .

$$\tau = T_1 + d(x(T_1))/V$$

- Implement the function `bisection()` to estimate the collision time using the "bisection method" at time  $T_2$ .

$$\begin{aligned} t_1 &= T_1, t_2 = T_2 \\ \text{while } |t_1 - t_2| > T/1000 : \\ &\quad \tilde{t} = (t_1 + t_2)/2 \\ &\quad \text{if NC at } \tilde{t} : t_1 = \tilde{t} \\ &\quad \text{else : } t_2 = \tilde{t} \\ \tau &= t_1 \end{aligned}$$

Note:  $d(x(\tilde{t}))$  should be explicitly calculated by moving the object along the path to perform collision detection at time  $\tilde{t}$ .

- Update the function `_process()` to call the function `record_actual()`.
  - Implement the function `record_actual()` to perform collision detection at each frame, and record the actual collision time by the frame time.
  - The actual collision time is represented in seconds with 3 digits right to the decimal, referring to the start time of the object movement `timeStart`.

## Questions

Write the corresponding answers in the script file.

- With which interval  $T$  the collision may not be detected when speed  $V = 2000$  pixel/s?
- When the object may be overseen, which strategy has to be used instead?
- In the lecture you learned that we have a broad and narrow phase: Could you improve the collision time estimate via bisection using these two phases? What is the expected gain in performance on average?