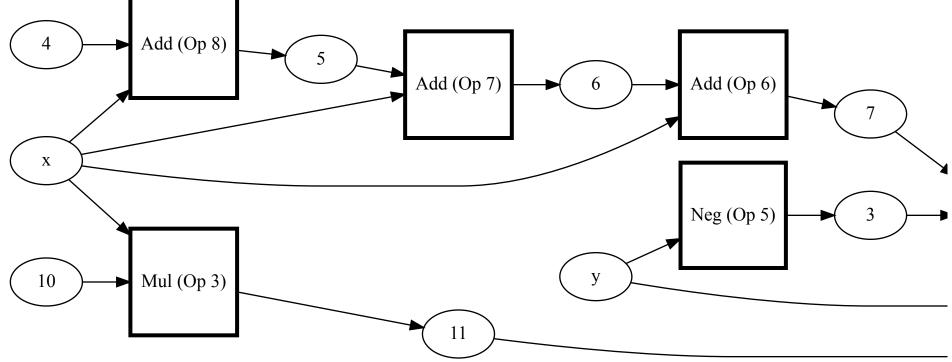
Module 2.0 - Neural Networks

Our Goal

Compute derivative of Python function with respect to inputs.

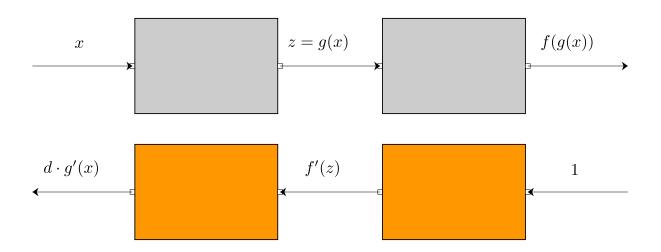
Example: Function

```
def expression():
    x = Scalar(1.0, name="x")
    y = Scalar(1.0, name="y")
    z = -y * sum([x, x, x]) * y + 10.0 * x
    h_x_y = z + z
    return h_x_y
```



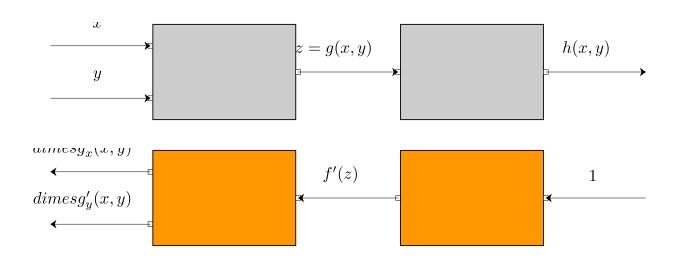
Chain Rule: Simple Case

$$egin{aligned} z &= g(x) \ d &= f'(z) \ f_x'(g(x)) &= g'(x) imes d \end{aligned}$$



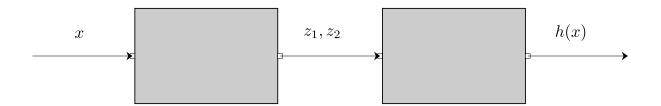
Chain Rule: Two Arguments

$$egin{aligned} z &= g(x,y) \ d &= f'(z) \ f_x'(g(x,y)) &= g_x'(x,y) imes d \ f_y'(g(x,y)) &= g_y'(x,y) imes d \end{aligned}$$



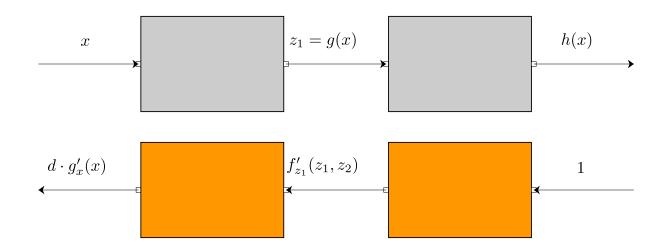
Chain Rule: Repeated Use

$$z=g(x)$$
 $f(z,z)$



Chain Rule: Repeated Use

$$d = f_{z_1}'(z_1,z_2) + f_{z_2}'(z_1,z_2) \ h_x'(x) = d imes g_x'(x)$$

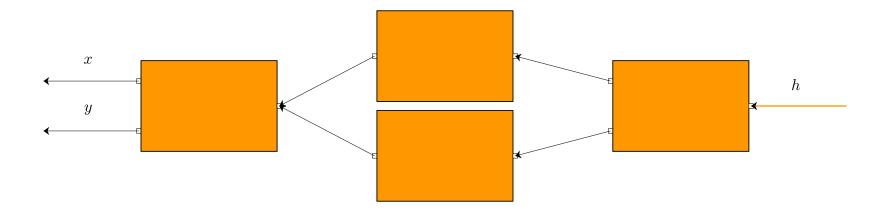


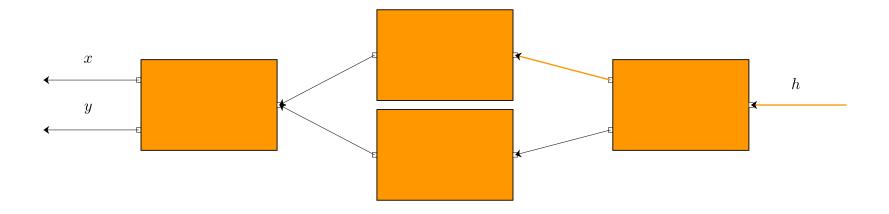
Algorithm: Outer Loop

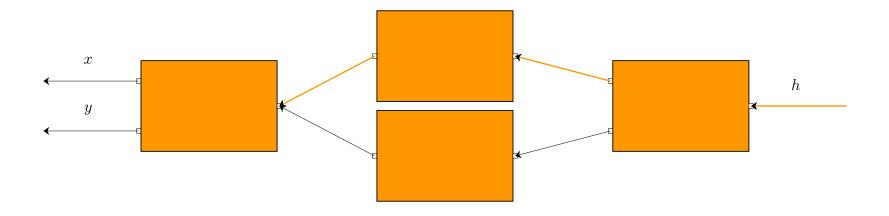
- 1. Call topological sort
- 2. Create dict of edges and empty d values.
- 3. For each edge and d in topological order:

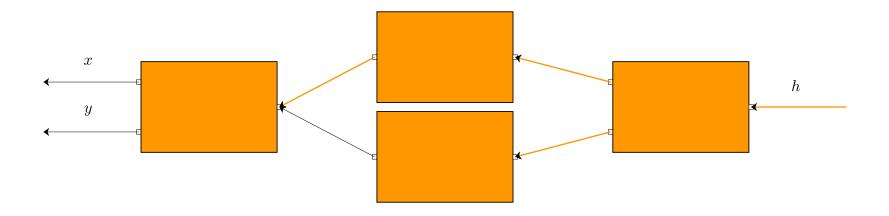
Algorithm: Inner Loop

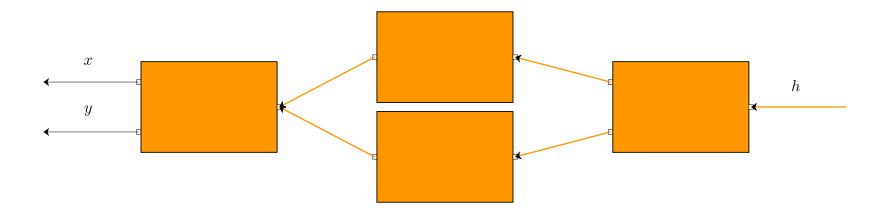
- 1. If edge goes to Leaf, done
- 2. Call `backward`` with d on previous box
- 3. Loop through all its input edges and add derivative

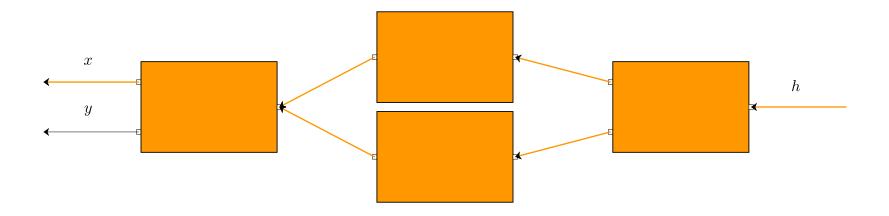












Quiz

Outline

- Model Training
- Neural Networks
- Modern Models

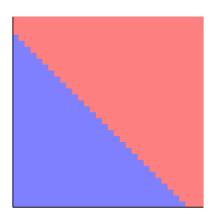
Model Training

Reminder: MiniML

- Dataset Data to fit
- Model Shape of fit
- Loss Goodness of fit

Model 1

Linear Model

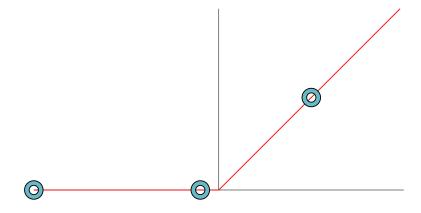


Point Loss

```
def point_loss(x):
    return minitorch.operators.relu(x)

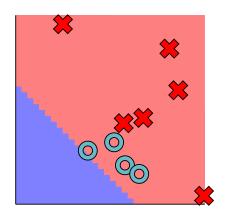
def full_loss(m):
    l = 0
    for x, y in zip(s.X, s.y):
        l += point_loss(-y * m.forward(*x))
    return -l

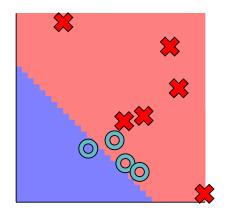
graph(point_loss, [], [-2, -0.2, 1])
```

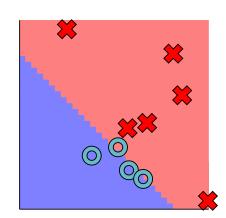


Class Goal

• Find parameters that minimize loss







Parameter Fitting

- 1. (Forward!) Compute the loss function, $L(w_1, w_2, b)$
- 2. (Backward!) See how small changes would change the loss
- 3. Update to parameters to locally reduce the loss

Update Procedure

Module for Linear

```
class LinearModule(minitorch.Module):
    def __init__(self):
        super().__init__()
        # 0.0 is start value for param
        self.w1 = Parameter(Scalar(0.0))
        self.w2 = Parameter(Scalar(0.0))
        self.bias = Parameter(Scalar(0.0))

def forward(self, x1: Scalar, x2: Scalar) -> Scalar:
        return x1 * self.w1.value + x2 * self.w2.value + self.bias.value
```

Training Loop

```
def train_step(optim, model, data):
    # Step 1 - Forward (Loss function)
    x_1, x_2 = Scalar(data[0]), Scalar(data[1])
    loss = model.forward(x_1, x_2).relu()
    # Step 2 - Backward (Compute derivative)
    loss.backward()
    # Step 3 - Update Params
    optim.step()
```

More Features: Linear Model

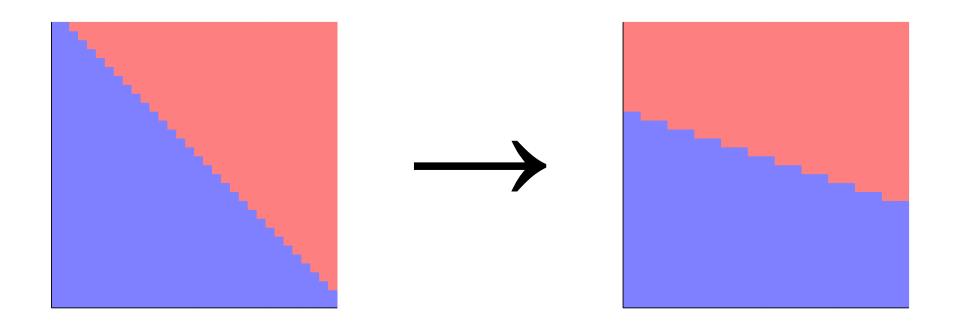
$$\lim(x;w,b)=x_1\times w_1+\ldots+x_n\times w_n+b$$

More Features: Linear (Code)

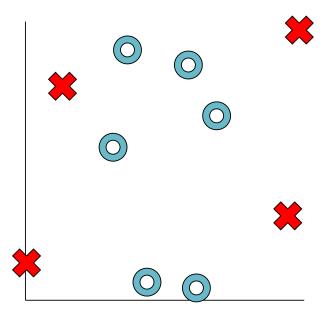
Neural Networks

Linear Model Example

Parameters

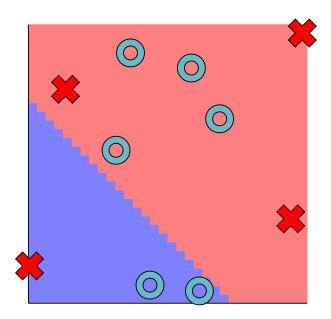


Harder Datasets



Harder Datasets

Model may not be good with any parameters.



Neural Networks

- New model
- Uses repeated splits of data
- Loss will not change

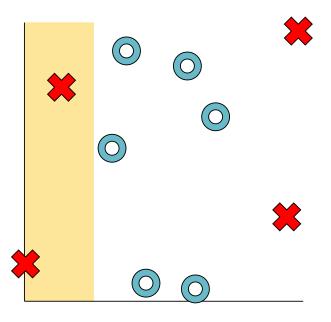
Intuition: Neural Networks

- 1. Apply many linear seperators
- 2. Reshape the data space based on results
- 3. Apply a linear model on new space

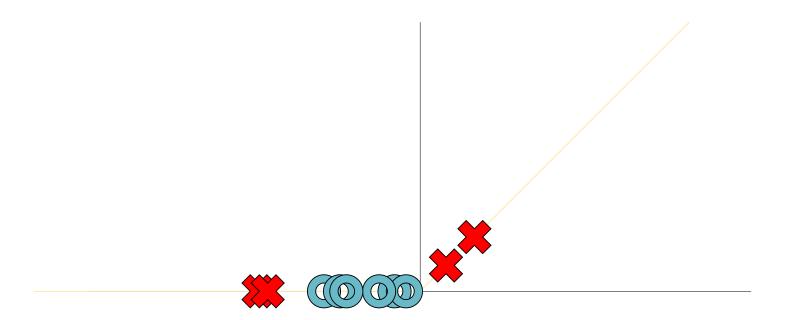
Notation: Multiple Parameters

- Use superscript w^0 and w^1 to indicate different parameters.
- Our final model will have many linears.
- These will become Torch sub-modules.

Intuition: Split 1



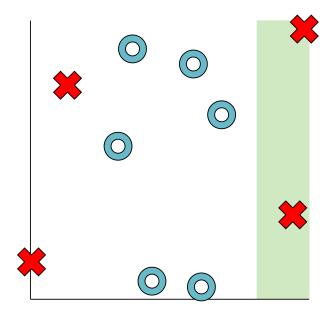
Reshape: ReLU



Math View

$$h_1 = \mathrm{ReLU}(\mathrm{lin}(x; w^0, b^0))$$

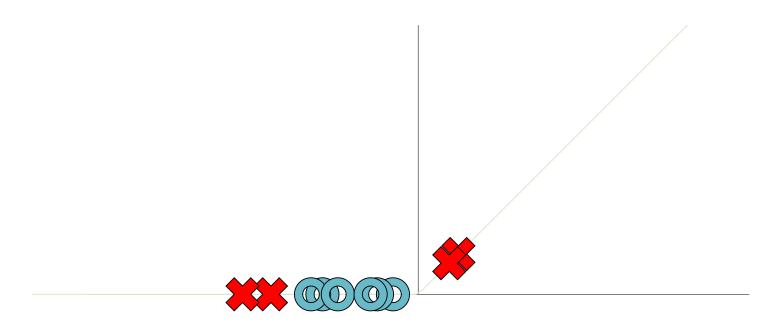
Intuition: Split 2



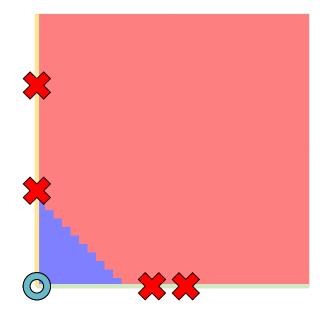
Math View

$$h_2 = \mathrm{ReLU}(\mathrm{lin}(x; w^1, b^1))$$

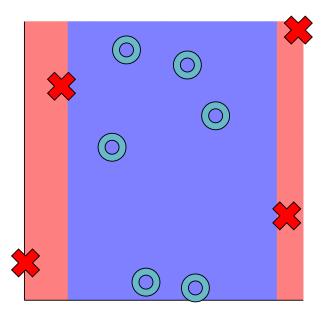
Reshape: ReLU



Reshape: ReLU



Final Layer



Math View

$$h_1 = ext{ReLU}(x_1 imes w_1^0 + x_2 imes w_2^0 + b^0) \ h_2 = ext{ReLU}(x_1 imes w_1^1 + x_2 imes w_2^1 + b^1) \ m(x_1, x_2) = h_1 imes w_1 + h_2 imes w_2 + b$$

Parameters: $w_1, w_2, w_1^0, w_2^0, w_1^1, w_2^1, b, b^0, b^1$

Math View (Alt)

$$h_1 = \mathrm{ReLU}(\mathrm{lin}(x; w^0, b^0)) \ h_2 = \mathrm{ReLU}(\mathrm{lin}(x; w^1, b^1)) \ m(x_1, x_2) = \mathrm{lin}(h; w, b)$$

Code View

Linear

```
class LinearModule(Module):
    def __init__(self):
        super().__init__()
        self.w_1 = Parameter(Scalar(0.0))
        self.w_2 = Parameter(Scalar(0.0))
        self.b = Parameter(Scalar(0.0))

def forward(self, inputs):
    return inputs[0] * self.w_1.value + inputs[1] * self.w_2.value + self.b.value
```

Code View

Model

```
class Network(minitorch.Module):
    def __init__(self):
        super().__init__()
        self.unit1 = LinearModule()
        self.unit2 = LinearModule()
        self.classify = LinearModule()

    def forward(self, x):
        h1 = self.unit1.forward(x).relu()
        h2 = self.unit2.forward(x).relu()
        return self.classify.forward((h1, h2))
```

Training

- All the parameters in model are leaves
- Computing backward on loss fills their derivative

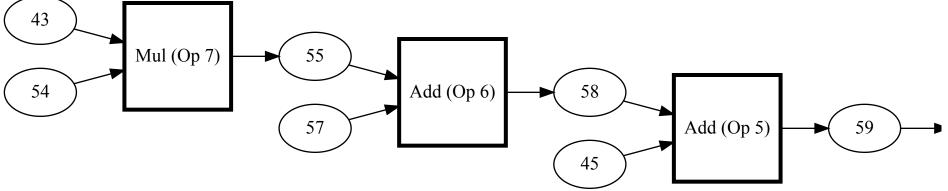
```
model = Network()
parameters = dict(model.named_parameters())
parameters

{'unit1.w_1': Scalar(0.000000),
   'unit1.w_2': Scalar(0.000000),
   'unit1.b': Scalar(0.000000),
   'unit2.w_1': Scalar(0.000000),
   'unit2.w_2': Scalar(0.000000),
   'unit2.b': Scalar(0.000000),
   'classify.w_1': Scalar(0.000000),
   'classify.w_2': Scalar(0.000000),
   'classify.b': Scalar(0.000000)}
```

Derivatives

All the parameters in model are leaf Variables

```
model = Network()
x1, x2 = Scalar(0.5), Scalar(0.5)
# Step 1
out = model.forward((0.5, 0.5))
loss = out.relu()
# Step 2
SVG(make_graph(loss, lr=True))
```



Derivatives

All the parameters in model are leaf scalars

```
parameters["unit1.w_1"].value.derivative
```

Playground

NN Playground

