Module 3.0 - Real Neural Networks

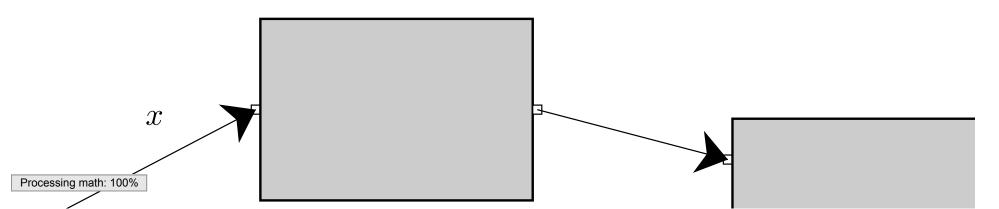
Review: Chain Rule

f(G(x))

•
$$z_1 = g^1(x), z_2 = g^2(x)$$

•
$$d_1 = f'_{z_1}(z_1, z_2), d_2 = f'_{z_2}(z_1, z_2)$$

•
$$f_x'(G(x)) = d_1g_x^{'1}(x) + d_2g_x^{'2}(x)$$



Review: Chain Rule

f(G(x))

•
$$z_1 = g^1(x), z_2 = g^2(x), \dots$$

•
$$d_1 = f'_{z_1}(z), d_2 = f'_{z_2}(z), \dots$$

•
$$f_{x}'(G(x)) = \sum_{i} d_{i}g_{x}^{i}(x)$$

Tensor Functions

Think of it as many functions with many arguments

$$G(x) = [G^{1}(x_{1}, ...), G^{2}(x_{1}, ...), ..., G^{N}(x_{1}, ...)]$$

Derivative

Derivative of i'th output wrt j'th input

$$G_{x_j}^{'i}(x)$$

Full Chain Rule For Gradients

f(G(x))

•
$$z_1 = G^1(x), z_2 = G^2(x), \dots$$

•
$$d_1 = f'_{z_1}(z), d_2 = f'_{z_2}(z), \dots$$

$$\bullet \ f_{x_j}'(G(x)) = \sum_i d_i G_{x_j}^{'i}(x)$$

Backward Function

Backward function needs to compute:

- d_i tensor
- $G_{x_j}^{i}$ change in i

$$\sum_{i} d_{i} G_{x_{j}}^{i}(x)$$

Special Function: Map

•
$$G_{x_j}^{i}(x) = 0$$
 if $i \neq j$

$$\bullet \ f_{x_j}^{'}(G(x)) = d_i g_{x_j}^{'j}(x)$$

Implies:

$$\bullet \ f_{x_i}^{'}(G(x)) = d_i G_{x_i}^{'i}(x)$$

Map Gradient

Example: Tensor Negation

$$\bullet \ G^i(x) = -x_i$$

$$\bullet \ G_{x_i}^{'i}(x) = -1$$

$$\bullet \ f_{x_i}^{'}(G(x)) = -d_i$$

Example: Tensor Negation

```
class Neg(minitorch.Function):
    @staticmethod
    def forward(ctx, t1: Tensor) -> Tensor:
        return t1.f.neg_map(t1)

    @staticmethod
    def backward(ctx, d: Tensor) -> Tensor:
        return d.f.neg_map(d)
```

Example: Tensor Inversion

$$\bullet \ G^i(x) = 1/x_i$$

•
$$G_{x_i}^{'i}(x) = -(x_i)^{-2}$$

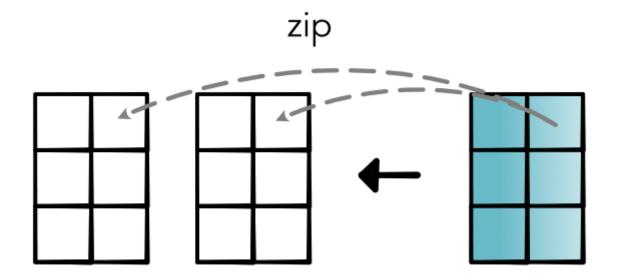
•
$$f'_{x_i}(G(x)) = -(x_i)^{-2} * d_i$$

Example: Inv

```
class Inv(minitorch.Function):
    @staticmethod
    def forward(ctx, t1: Tensor) -> Tensor:
        ctx.save_for_backward(t1)
        return t1.f.inv_map(t1)

    @staticmethod
    def backward(ctx, d: Tensor) -> Tensor:
        (t1,) = ctx.saved_values
        return d.f.inv_back_zip(t1, d)
```

Zip Gradient



Example: Tensor Inversion

$$\bullet \ G^i(x,y) = x_i + y_i$$

$$\bullet \ G_{x_i}^{'i}(x,y) = 1$$

$$\bullet \ f_{x_i}^{'}(G(x)) = d_i$$

Example: Add

```
class Add(minitorch.Function):
    @staticmethod
    def forward(ctx, t1: Tensor, t2: Tensor) -> Tensor:
        return t1.f.add_zip(t1, t2)

    @staticmethod
    def backward(ctx, grad_output: Tensor) -> Tuple[Tensor, Tensor]:
        return grad_output, grad_output
```

Example: Tensor Inversion

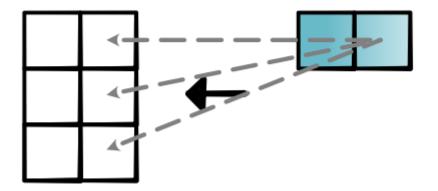
•
$$G(x) = \sum_{i} x_{i}$$

$$\bullet \ G_{x_i}^{'}(x) = 1$$

$$\bullet \ f_{x_i}^{'}(G(x)) = d$$

Reduce Gradient

reduce



Quiz

Outline

- Training
- Simple NLP

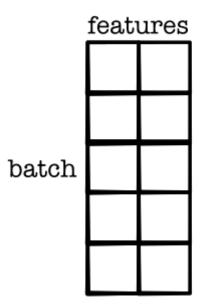
Training

Parameter Fitting

- 1. Compute the loss function, :math: L(w 1, w 2, b)
- 2. See how small changes would change the loss
- 3. Update to parameters to locally reduce the loss

Batching

input



Loss

1) Compute Loss ::

```
out = model.forward(X).view(data.N)
  loss = -((out * y) + (out - 1.0) * (y - 1.0)).log()
```

Model: Math

$$lin(x; w, b) = x_1 \times w_1 + x_2 \times w_2 + b$$

$$h_1 = ReLU(lin(x; w^0, b^0))$$

$$h_2 = ReLU(lin(x; w^1, b^1))$$

$$m(x_1, x_2) = lin(h; w, b)$$

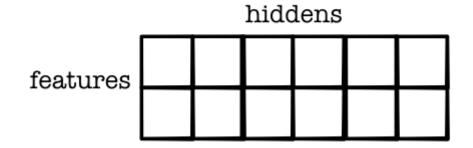
Model: Code

1) Model

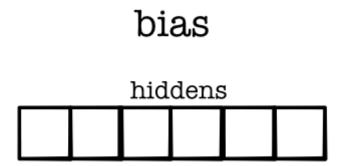
```
class Network(minitorch.Module):
    def __init__(self):
        self.layer1 = Linear(2, HIDDEN)
        self.layer2 = Linear(HIDDEN, HIDDEN)
        self.layer3 = Linear(HIDDEN, 1)
```

Layer 1: Weight

weights



Layer 1: Bias



Key Task

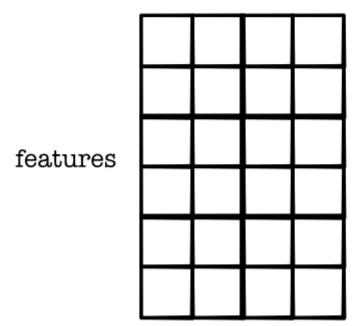
- Use broadcasting to implement the linear function
- Hint: Align batch x features x hidden to make it work

Processing math: 100%

Layer 2: Weights

weights

hiddens

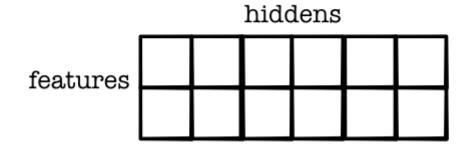


Compute Derivatives

Step 2

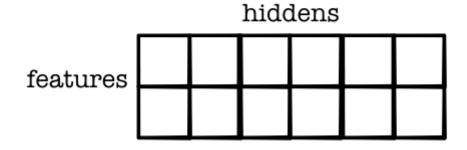
```
(loss.sum().view(1)).backward()
print(model.layer1.w_1.value.grad)
```

weights

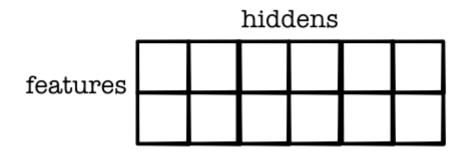


Layer 1: Weight Grad

weights



weights



Update Parameters

Step 3

```
for p in model.parameters():
    if p.value.grad is not None:
        p.update(p.value - RATE * (p.value.grad / float(data.N)))
```

Broadcasting

- Batches
- Loss Computation
- Linear computation
- Autodifferentiation
- Gradient updates

Observations

- Exactly the same function as Module-1
- No loops within tensors