



# Module 2.0 - Neural Networks



# Complex Graphs

```
def expression():  
    x = Scalar(1.0, name="x")  
    y = Scalar(1.0, name="y")  
    z = -y * sum([x, x, x]) * y + 10.0 * x  
    return z + z
```

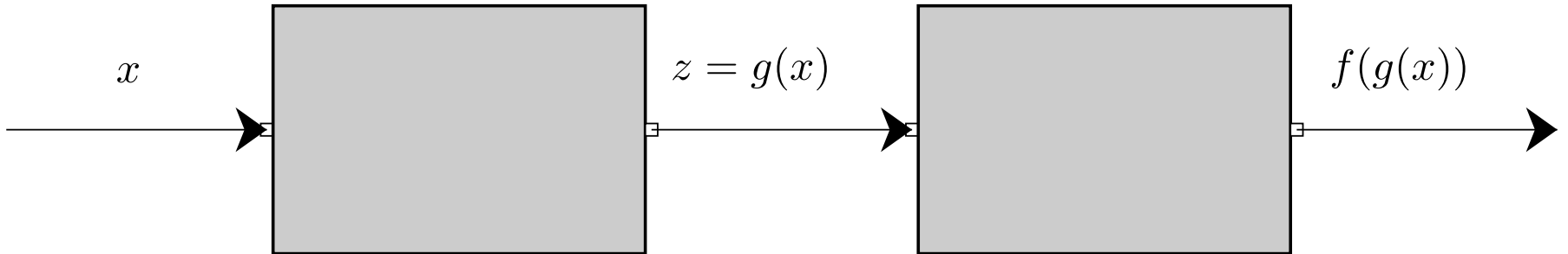


# Chain Rule

$$z = g(x)$$

$$d = f'(z)$$

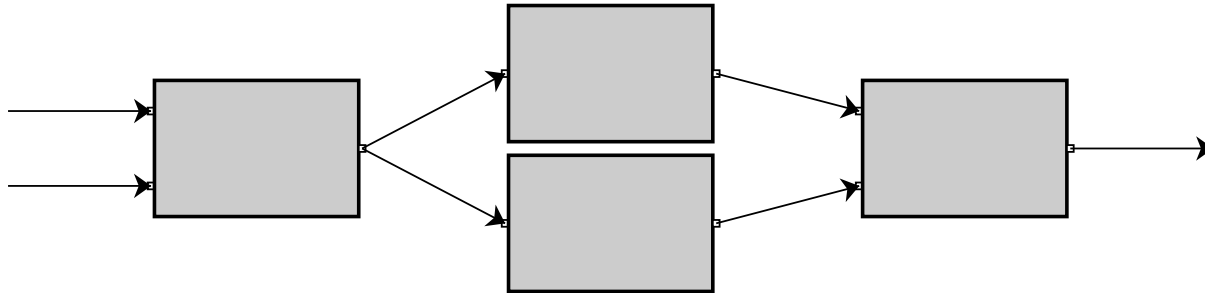
$$f'_x(g(x)) = g'(x) \times d$$





# Two Arguments: Chain

$$f(g(x, y))$$







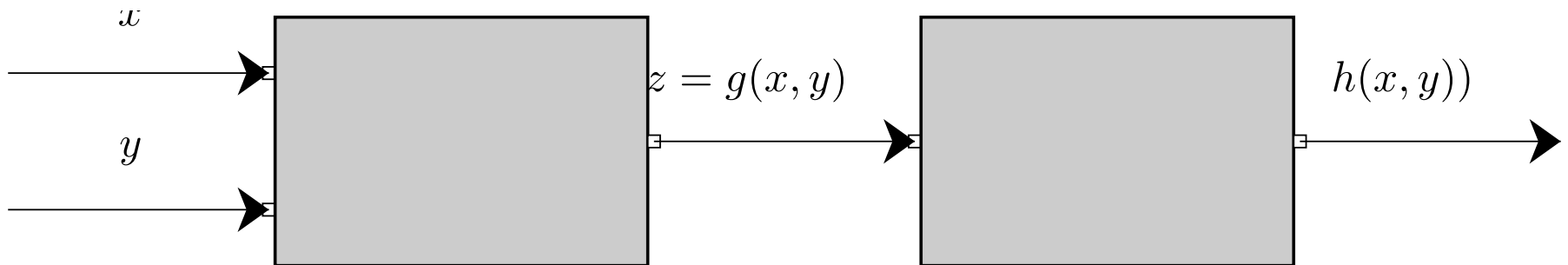
# Two Arguments: Chain

$$z = g(x, y)$$

$$d = f'(z)$$

$$f'_x(g(x, y)) = g'_x(x, y) \times d_{out}$$

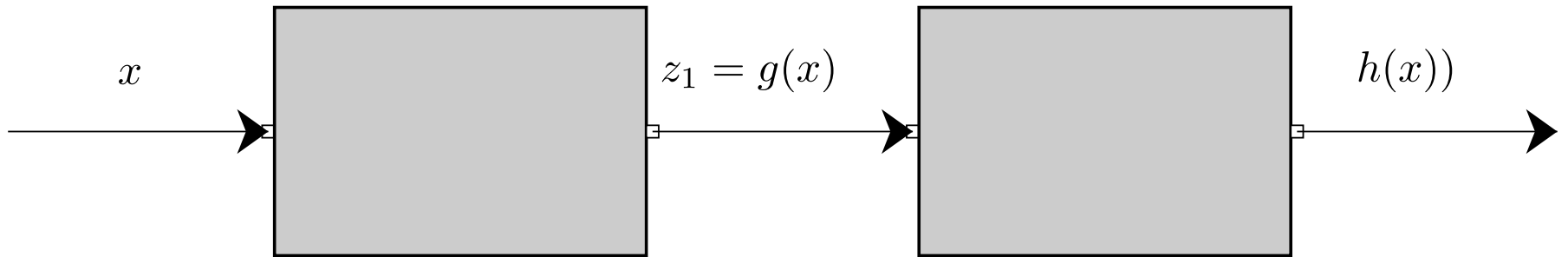
$$f'_y(g(x, y)) = g'_y(x, y) \times d_{out}$$





# Multivariable Chain

$$f(g(x), h(x))$$

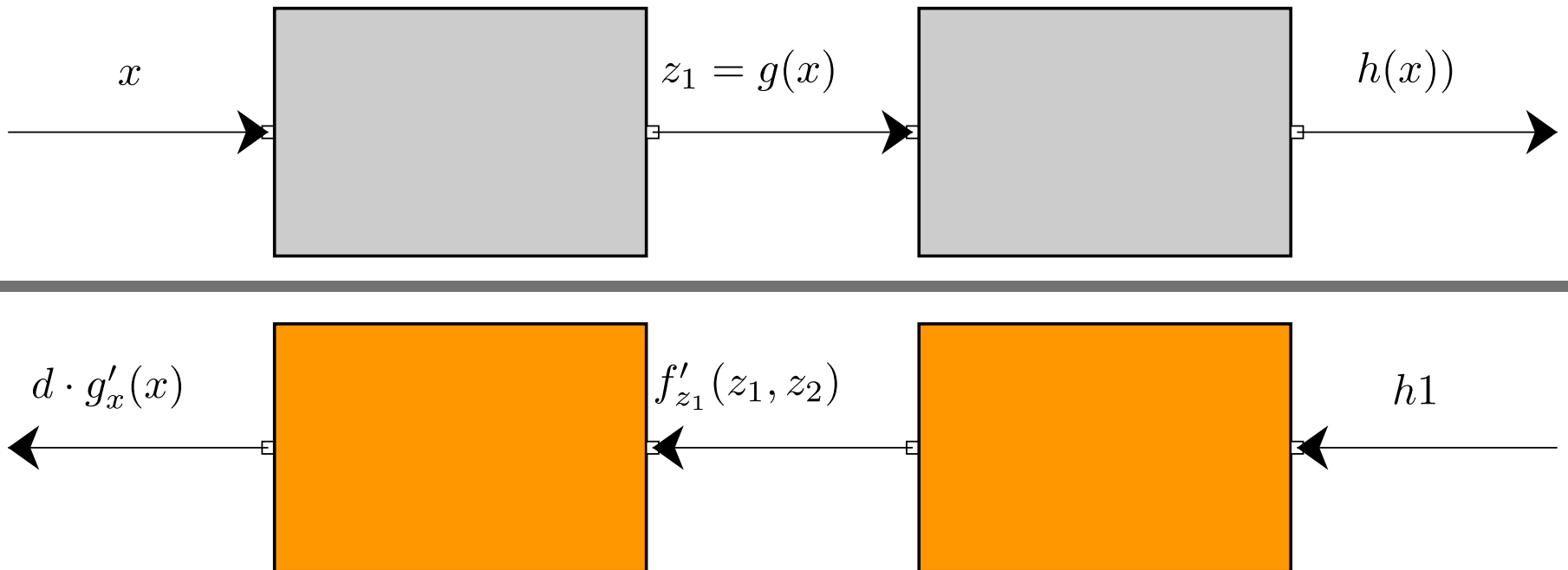




# Multivariable Chain

$$d = 1 \cdot f'_{z_1}(z_1, z_2) + 1 \cdot f'_{z_2}(z_1, z_2)$$

$$h'_x(x) = d \cdot g'_x(x)$$





# Topological Sorting

- Topological Sorting
- High-level -> Run depth first search and mark nodes.





# Algorithm: Outer Loop

1. Call topological sort
2. Create dict of Variables and derivatives
3. For each node in backward order:

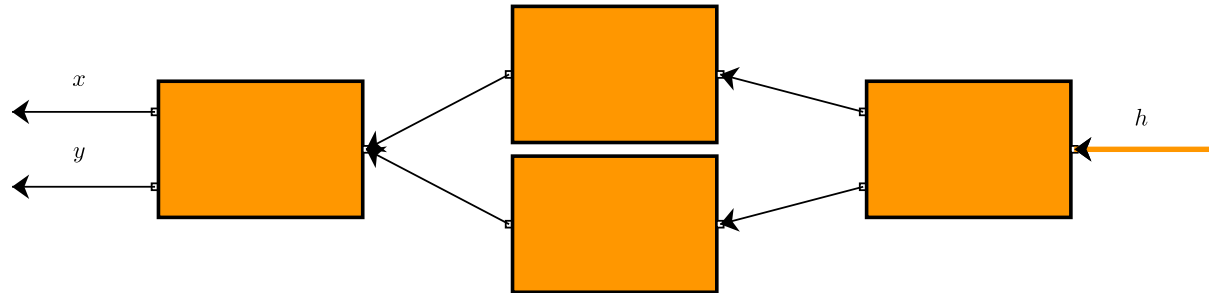


# Algorithm: Inner Loop

1. if Variable is leaf, add its final derivative
2. if the Variable is not a leaf, 1) call backward with  $d$  2) loop through all the Variables+derivative 3) accumulate derivatives for the Variable

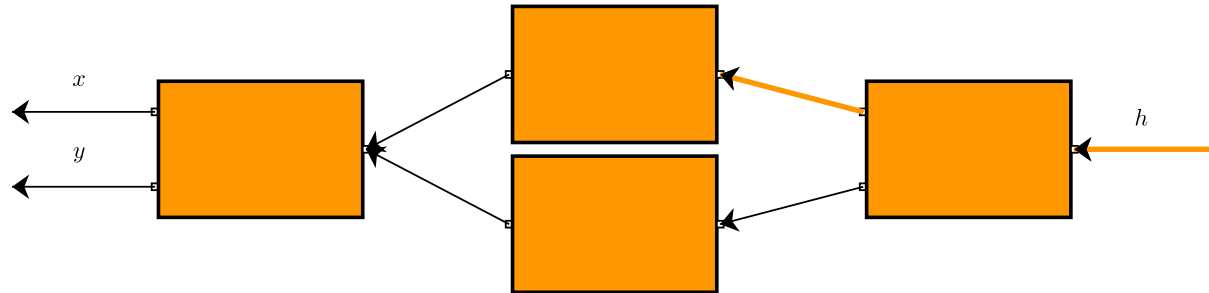


# Example





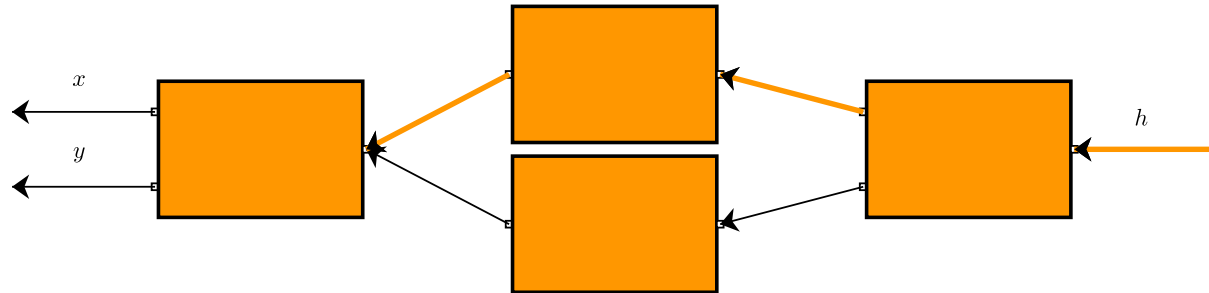
# Example





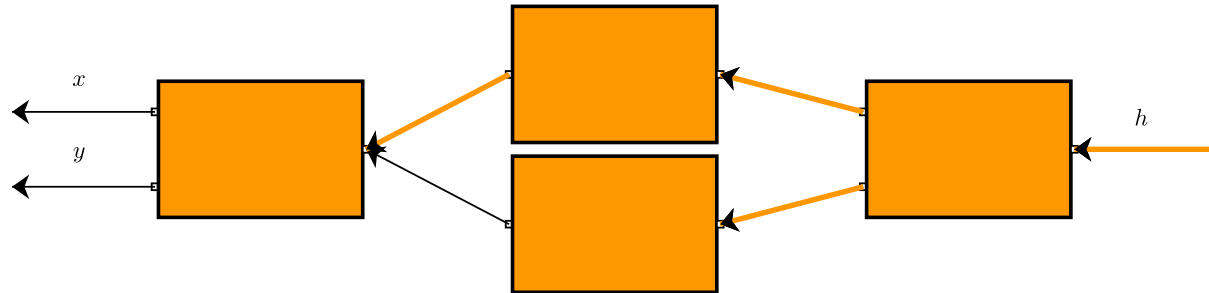


# Example



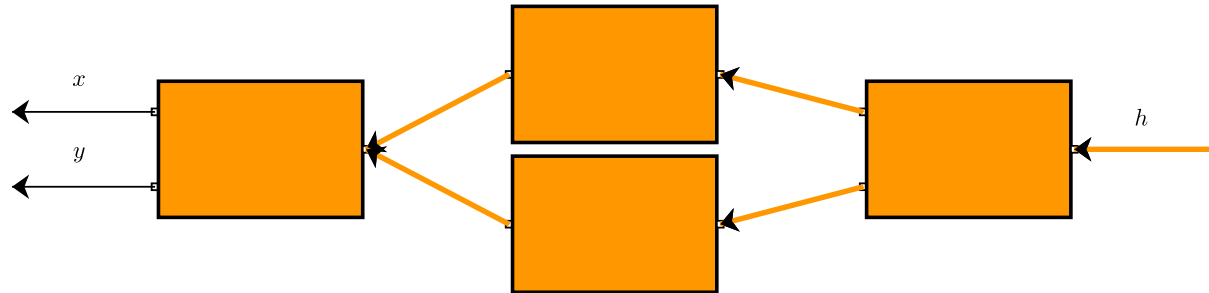


# Example



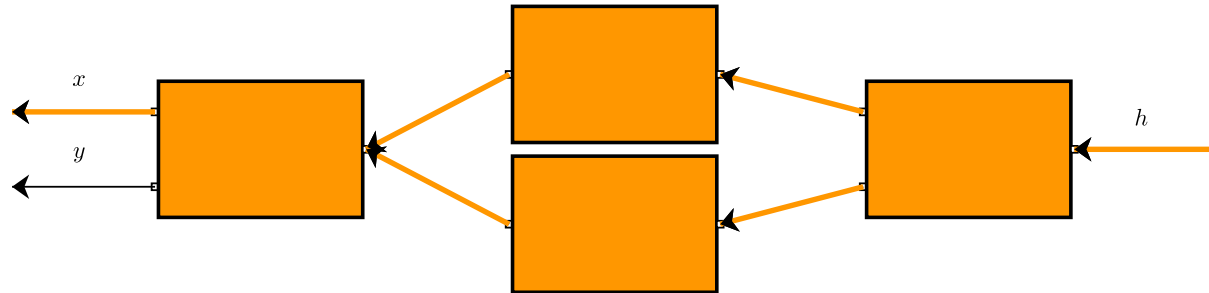


# Example





# Example







# Example



# Lecture Quiz



# Outline

- Model Training
- Neural Networks
- Modern Models



# Model Training





# Reminder

- Dataset - Data to fit
- Model - Shape of fit
- Loss - Goodness of fit



# Model 1

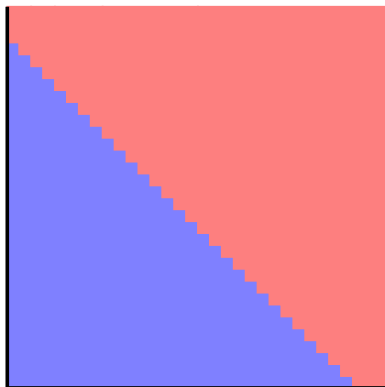
- Linear Model

```
@dataclass
class Linear:
    # Parameters (Now scalars)
    w1: Scalar
    w2: Scalar
    b: Scalar

    def forward(self, x1, x2):
        return self.w1 * x1 + self.w2 * x2 + self.b
```



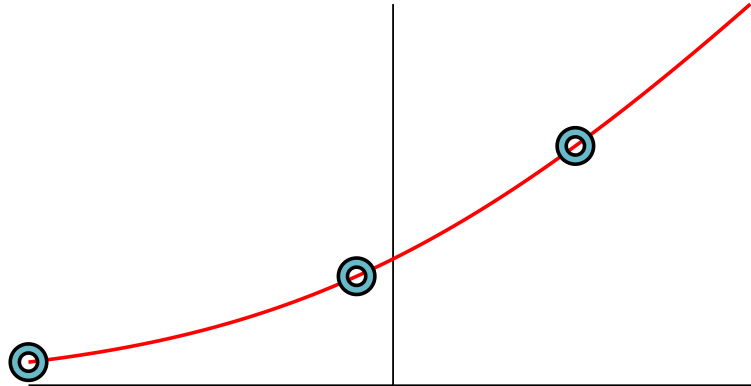
# Decision Boundary: Model 1





# Point Loss

```
def point_loss(x):  
    return -math.log(minitorch.operators.sigmoid(-x))  
  
def full_loss(m):  
    l = 0  
    for x, y in zip(s.X, s.y):  
        l += point_loss(-y * m.forward(*x))  
    return -l
```

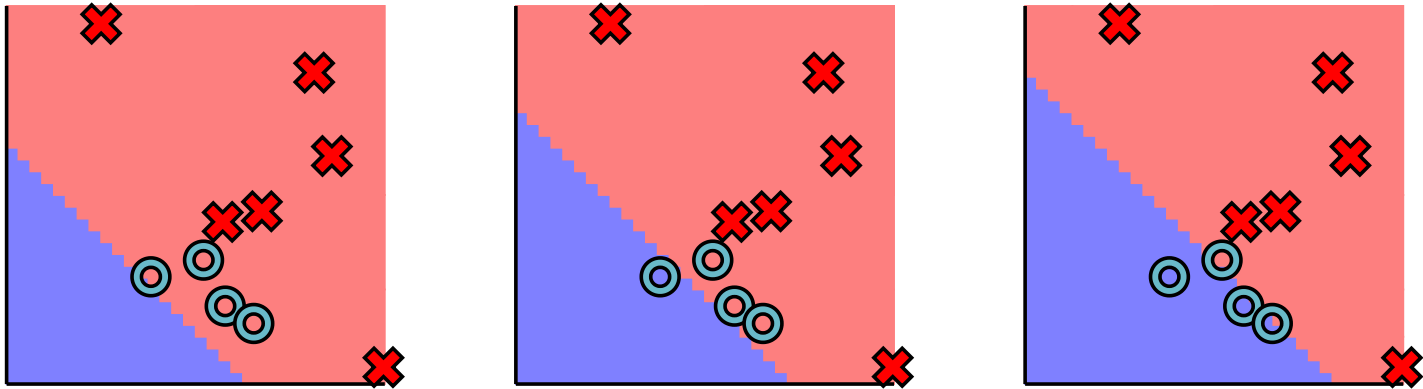






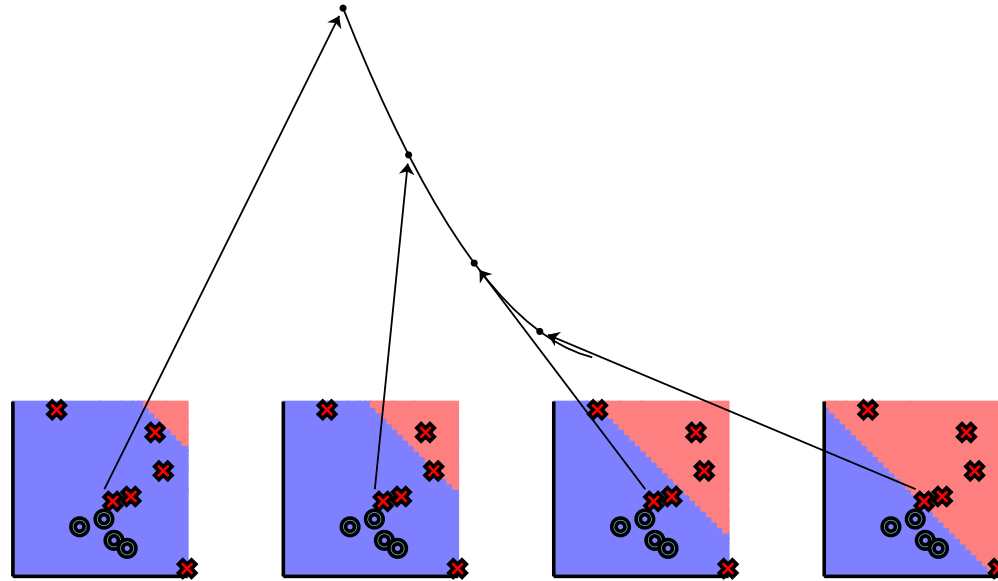
# Class Goal

- Find parameters that minimize loss





# Update Procedure





# Full: Module

```
class LinearModule(minitorch.Module):
    def __init__(self):
        super().__init__()
        self.w1 = Parameter(Scalar(0.0))
        self.w2 = Parameter(Scalar(0.0))
        self.bias = Parameter(Scalar(0.0))

    def forward(self, x1: Scalar, x2: Scalar) -> Scalar:
        return x1 * self.w1.value + x2 * self.w2.value + self.bias.value
```



# Full: Loop

```
def train_sketch():  
    x_1, x_2 = Scalar(x[i][0]), Scalar(x[i][1])  
    # Forward (loss function)  
    loss = -self.model.forward((x_1, x_2)).log()  
    # Backward  
    loss.backward()  
    # Update Params  
    . . .
```





# Linear Model

$$m(x; w, b) = x_1 \times w_1 + x_2 \times w_2 + b$$



# More Features

$$\text{lin}(x; w, b) = x_1 \times w_1 + \dots + x_n \times w_n + b$$



# Neural Networks



# Reminder

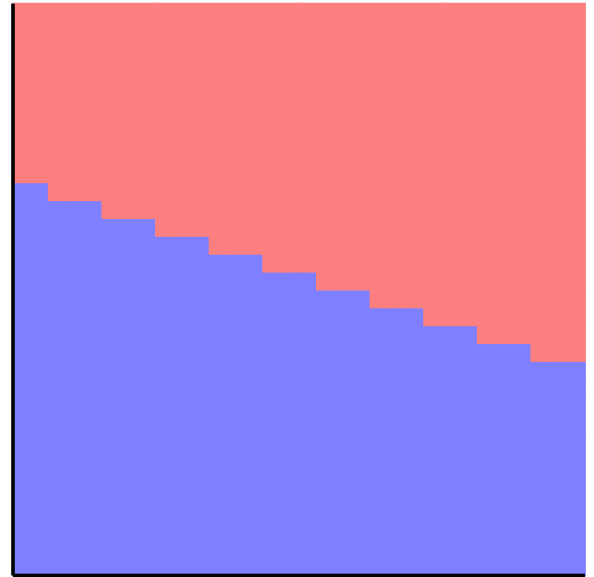
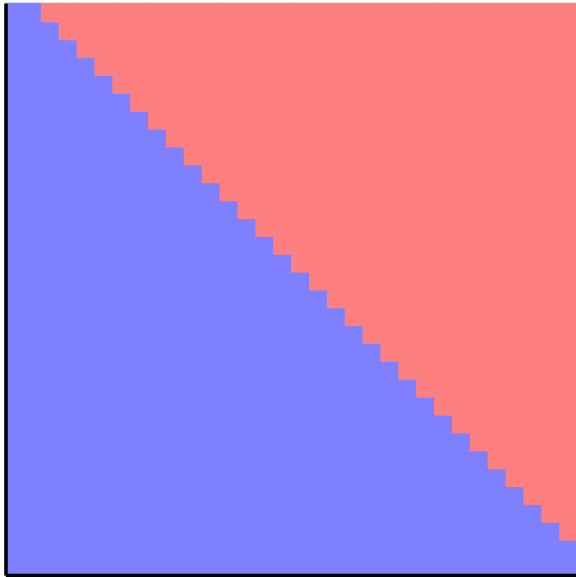
- Dataset - Data to fit
- Model - Shape of fit
- Loss - Goodness of fit





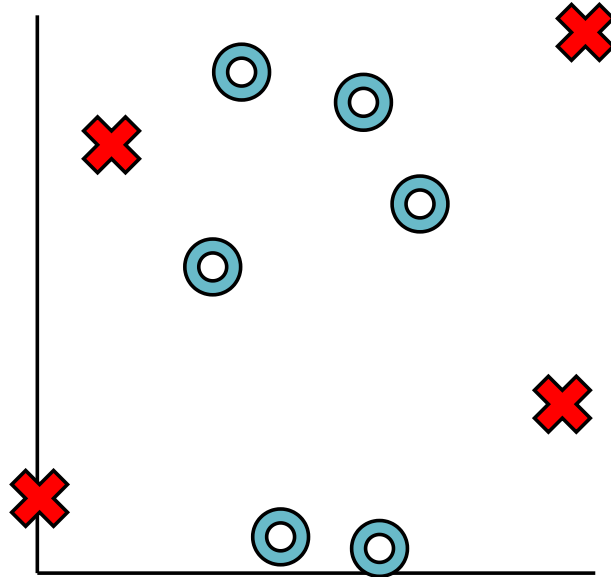
# Linear Model Example

- Parameters





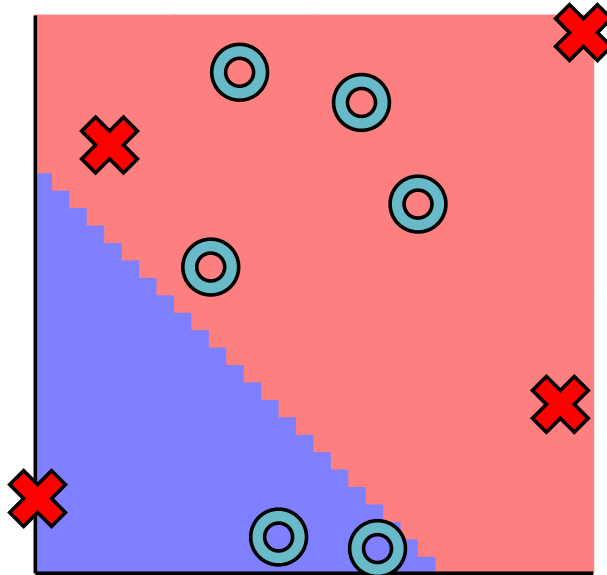
# Harder Datasets





# Harder Datasets

- Model may be too "weak"





# Neural Networks

- New *model*
- Uses repeated splits of data
- Loss will not change





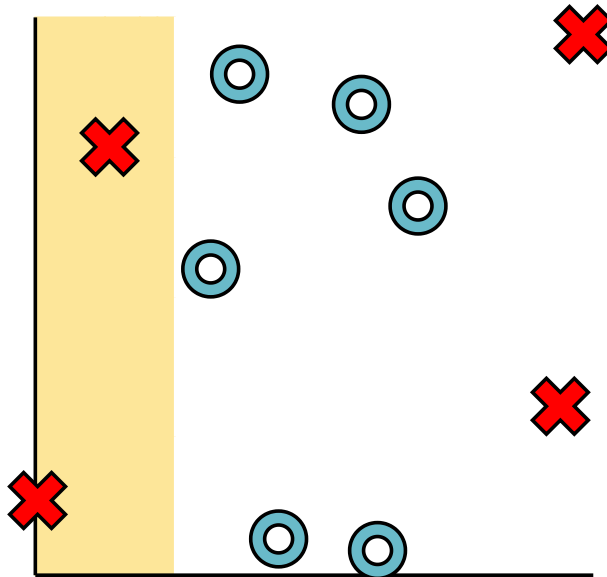
# Intuition: Neural Networks

1) Apply many linear separators 2) Reshape the data space based on results 3) Apply a linear model on new space



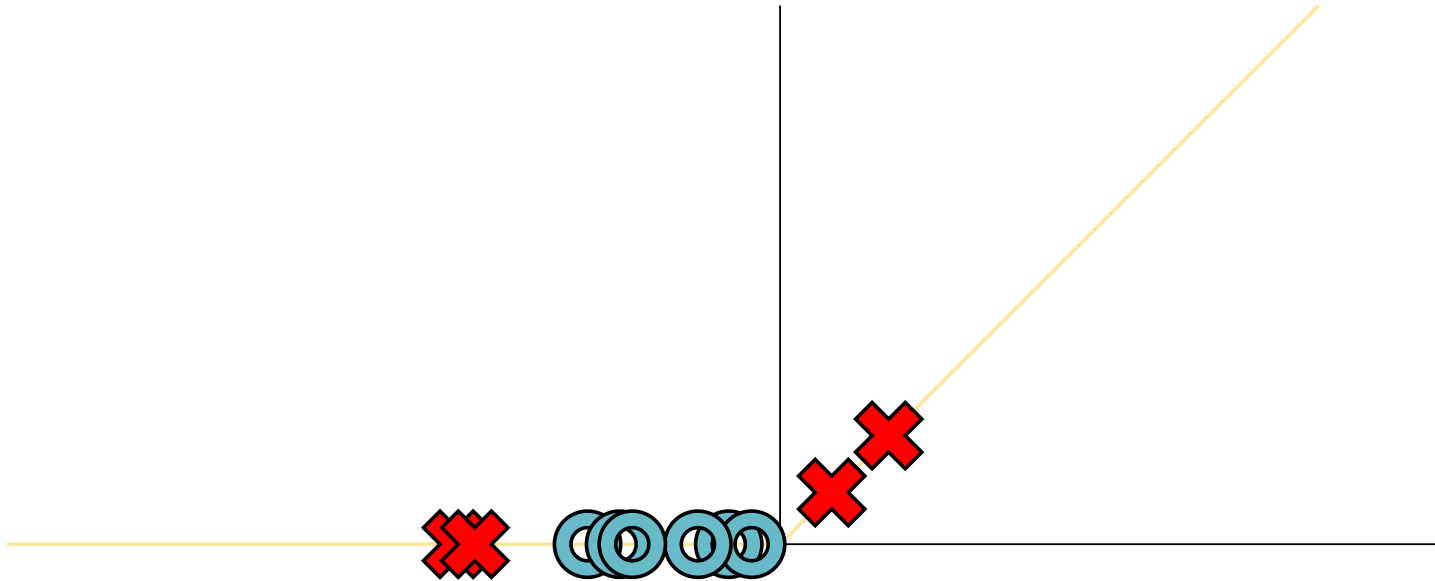
# Intuition: Split 1

```
yellow = Linear(-1, 0, 0.25)
```





# Reshape: ReLU





# Math View

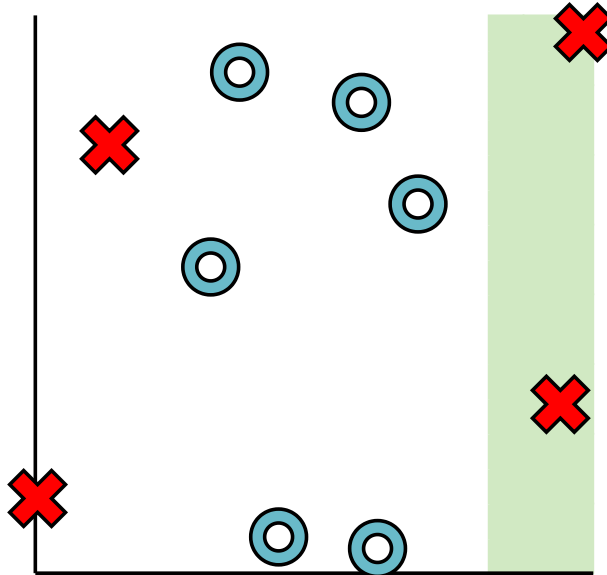
$$h_1 = \text{ReLU}(\text{lin}(x; w^0, b^0))$$





# Intuition: Split 2

```
green = Linear(1, 0, -0.8)
```



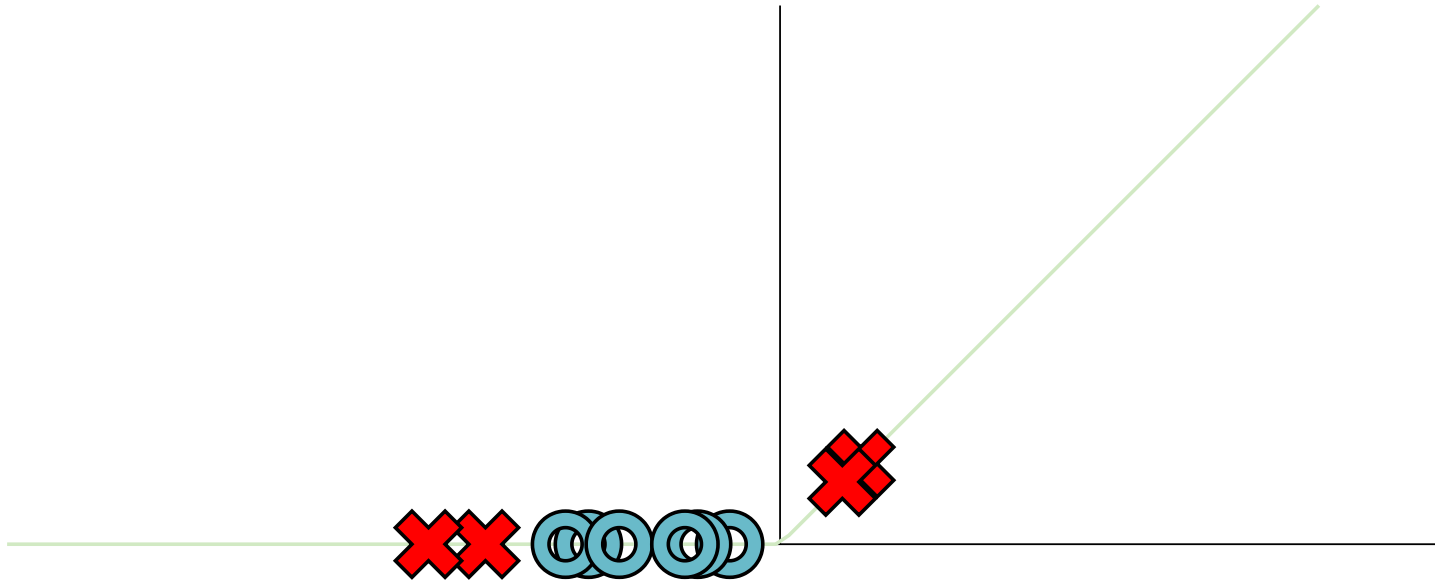


# Math View

$$h_2 = \text{ReLU}(\text{lin}(x; w^1, b^1))$$

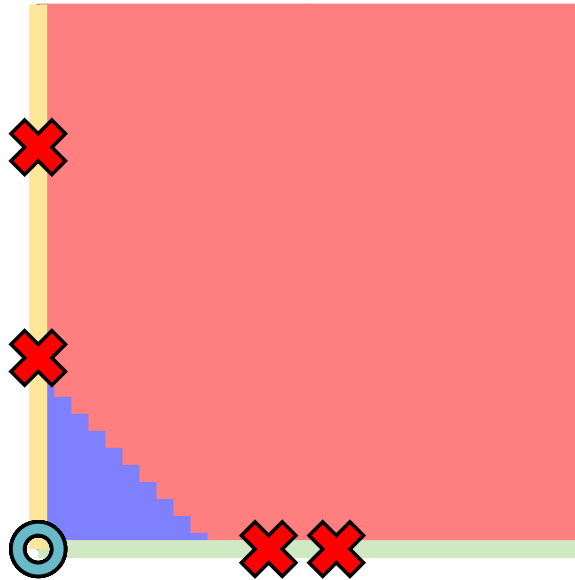


# Reshape: ReLU





# Reshape: ReLU





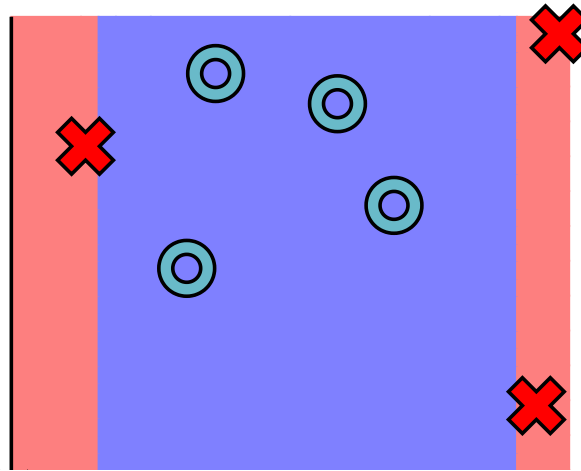


# Final Layer

```
@dataclass
class MLP:
    lin1: Linear
    lin2: Linear
    final: Linear

    def forward(self, x1, x2):
        x1_1 = minitorch.operators.relu(self.lin1.forward(x1, x2))
        x2_1 = minitorch.operators.relu(self.lin2.forward(x1, x2))
        return self.final.forward(x1_1, x2_1)
```

```
mlp = MLP(green, yellow, Linear(3, 3, -0.3))
draw_with_hard_points(mlp)
```





# Math View

$$h_1 = \text{ReLU}(x_1 \times w_1^0 + x_2 \times w_2^0 + b^0)$$

$$h_2 = \text{ReLU}(x_1 \times w_1^1 + x_2 \times w_2^1 + b^1)$$

$$m(x_1, x_2) = h_1 \times w_1 + h_2 \times w_2 + b$$

Parameters:  $w_1, w_2, w_1^0, w_2^0, w_1^1, w_2^1, b, b^0, b^1$



# Math View (Alt)

$$\text{lin}(x; w, b) = x_1 \times w_1 + x_2 \times w_2 + b$$

$$h_1 = \text{ReLU}(\text{lin}(x; w^0, b^0))$$

$$h_2 = \text{ReLU}(\text{lin}(x; w^1, b^1))$$

$$m(x_1, x_2) = \text{lin}(h; w, b)$$

Parameters:  $w_1, w_2, w_1^0, w_2^0, w_1^1, w_2^1, b, b^0, b^1$



# Code View

## Linear

```
class Linear(Module):
    def __init__(self):
        super().__init__()
        self.w_1 = Parameter(Scalar(0.0))
        self.w_2 = Parameter(Scalar(0.0))
        self.b = Parameter(Scalar(0.0))

    def forward(self, inputs):
        return inputs[0] * self.w_1.value + inputs[1] * self.w_2.value + self.b.value
```





# Code View

## Model

```
class Network(minitorch.Module):
    def __init__(self):
        super().__init__()
        self.unit1 = Linear()
        self.unit2 = Linear()
        self.classify = Linear()

    def forward(self, x):
        h1 = self.unit1.forward(x).relu()
        h2 = self.unit2.forward(x).relu()
        return self.classify.forward((h1, h2))
```



# Training

- All the parameters in model are leaves
- Computing backward on loss fills their derivative

```
model = Network()  
...  
parameters = dict(model.named_parameters())
```



# Derivatives

- All the parameters in model are leaf Variables

```
model = Network()  
x1, x2 = Scalar(0.5), Scalar(0.5)  
out = model.forward((0.5, 0.5))  
loss = -(-out).sigmoid().log()  
loss.backward()
```



# Derivatives

- All the parameters in model are leaf Variables

```
parameters["unit1.w_1"].value.derivative
```





# Playground

## NN Playground

