MAURICE RAHME

🔗 moribots.github.io

🐙 github.com/moribots 📞 +1 224 244 1684 @ mauricerahme2020@u.northwestern.edu in linkedin.com/in/mauricerahme

EXPERIENCE

Staff Robotics Engineer - Stretch
Boston Dynamics 📍 Waltham, MA 📅 Jan 2021 – Present

- Developed Task-Space Controller for Stretch Base Driving.
- Performed first-time system-integration of full Stretch Robot.
- Wrote joint-space Hermite Spline trajectory generating behaviour.

Senior Robotics Engineer - Stretch
Boston Dynamics 📍 Waltham, MA 📅 Nov 2020 – Jan 2021

- Implemented generic Directed Graph search library.
- Co-authored CAN-interfacing high-rate motor controller code.
- Built bringup software to increase actuator checkout rate by >12x.
- Created actuator characterisation suite for BLDC motors.

Aerodynamics '17 & Suspension '18 Team Manager
Edinburgh Univ. Formula Student 📍 Edinburgh, UK 📅 Jul 2016 – Jul 2018

- Designed and manufactured Aerodynamic and Suspension components.
- Managed teams of 8-10 people and led training workshops.
- Calculated wheel braking and cornering forces using SIMULINK.
- Built a MATLAB design tool for Parallel/Ackermann steering design.
- Taught CAD in SolidWorks and raised £9,000 in sponsorship.

PROJECTS

Quadruped Locomotion from Scratch
Northwestern University 📅 Apr 2020 - Aug 2020

- Crafted 12-point Bezier Curve Gait and Leg/Body Inverse Kinematics.
- Simulated custom quadruped in Pybullet with sim2real ROS framework.
- Architected novel Rinforcement Learning method for Terrain Adaptation.
- Designed custom quadruped that can be built for under $600.

Motion Planning Library in C++ and ROS
Northwestern University 📅 Apr 2020 - Jun 2020

- Implemented scalable Probabilisitc Roadmap and Grid Map.
- Developed Library containing A*, Theta*, D*Lite, Potential Fields, MPPI.
- Co-created and taught course for 1 credit at Northwestern.

EKF SLAM on Turtlebot3
Northwestern University 📅 Jan 2020 – Mar 2020

- Developed 2D Kinematics library in C++ for Differential Drive robots.
- Wrote feature detection algorithm for LiDAR scanner.
- Performed EKF SLAM with Unknown Data Association.

Baxter Plays Checkers
Northwestern University 📅 Nov 2019 – Dec 2019

- Led 3 teammates to program a Baxter robot to play checkers.
- Utilized ROS, MoveIt, OpenCV, and a custom AI move generator based on the minimax algorithm with alpha-beta pruning.
- Won 1st Place out of 6 teams 🏆.

EDUCATION

Northwestern University
Master of Science in Robotics 📅 Aug 2020

- GPA: 3.95/4.0

The University of Edinburgh
B.Eng (Honors) in Electrical & Mechanical Engineering 📅 Jun 2019

- GPA: 4.0/4.0; equivalent of First Class

</> LANGUAGES

C++	●●●●●
Python	●●●●●
C	●●●●○
Bash	●●●○○
MATLAB	●●●○○

SKILLS

Robot Dynamics	●●●●●
Robot Manipulation	●●●●●
Motion Planning	●●●●●
Optimal Control	●●●●○
Bayesian Filters	●●●●○
ROS	●●●●○
Gazebo, Pybullet	●●●●○
URDF/Xacro	●●●●●
Linux (Ubuntu)	●●●●○
Git	●●●●○
Unit Testing	●●●●○
Altium	●●●●○
Analogue Electronics	●●●○○
3D Printing	●●●●○
SolidWORKS/OnShape	●●●○○

AWARDS

🏆 **IMechE - Best BEng Project**
The University of Edinburgh
The Institution of Mechanical Engineers

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🎓 **The Edinburgh Award**
The University of Edinburgh

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🚩 **The Spirit of Formula Student**
Formula Student UK

👤 LANGUAGES

English	●●●●●
French	●●●●●
Arabic	●●●●○