





MAURICE RAHME

 moribots.github.io

 github.com/moribots  +1 224 244 1684  mauricerahme2020@u.northwestern.edu  linkedin.com/in/mauricerahme


EXPERIENCE

Staff Robotics Engineer - Stretch

Boston Dynamics  Waltham, MA  Jan 2021 – Present

- Developed Task-Space Force Controller for Stretch Base Driving.
- Performed first-time system-integration of full Stretch Robot.
- Wrote joint-space Hermite Spline trajectory generating behaviour.

Senior Robotics Engineer - Stretch

Boston Dynamics  Waltham, MA  Nov 2020 – Jan 2021

- Implemented generic Directed Graph search library.
- Co-authored CAN-interfacing high-rate motor controller code.
- Built bringup software to increase actuator checkout rate by >12x.
- Created actuator characterisation suite for BLDC motors.

Aerodynamics '17 & Suspension '18 Team Manager

Edinburgh Univ. Formula Student  Edinburgh, UK  Jul 2016 – Jul 2018

- Designed and manufactured Aerodynamic and Suspension components.
- Managed teams of 8-10 people and led training workshops.
- Calculated wheel braking and cornering forces using SIMULINK.
- Built a MATLAB design tool for Parallel/Ackermann steering design.
- Taught CAD in SolidWorks and raised £9,000 in sponsorship.

PROJECTS

Quadruped Locomotion from Scratch

Northwestern University  Apr 2020 - Aug 2020

- Crafted 12-point Bezier Curve Gait and Leg/Body Inverse Kinematics.
- Simulated custom quadruped in Pybullet with sim2real ROS framework.
- Architected novel Reinforcement Learning method for Terrain Adaptation.
- Designed custom quadruped that can be built for under \$600.

Motion Planning Library in C++ and ROS

Northwestern University  Apr 2020 - Jun 2020

- Implemented scalable Probabilistic Roadmap and Grid Map.
- Developed Library containing A*, Theta*, D*Lite, Potential Fields, MPPI.
- Co-created and taught course for 1 credit at Northwestern.

EKF SLAM on Turtlebot3

Northwestern University  Jan 2020 – Mar 2020

- Developed 2D Kinematics library in C++ for Differential Drive robots.
- Wrote feature detection algorithm for LiDAR scanner.
- Performed EKF SLAM with Unknown Data Association.

Baxter Plays Checkers

Northwestern University  Nov 2019 – Dec 2019

- Led 3 teammates to program a Baxter robot to play checkers.
- Utilized ROS, MoveIt, OpenCV, and a custom move generator based on the minimax algorithm with alpha-beta pruning.
- Won 1st Place out of 6 teams 🏆.

EDUCATION

Northwestern University

Master of Science in Robotics  Aug 2020

- GPA: 3.95/4.0

The University of Edinburgh
















B.Eng (Honors) in Electrical & Mechanical Engineering  Jun 2019

- GPA: 4.0/4.0; equivalent of First Class


</> LANGUAGES


C++	
Python	
C	
Bash	
MATLAB	


SKILLS

Robot Dynamics	
Robot Manipulation	
Motion Planning	
Optimal Control	
Bayesian Filters	
ROS	
Gazebo, Pybullet	
URDF/Xacro	
Linux (Ubuntu)	
Git	
Unit Testing	
Altium	
Analogue Electronics	
3D Printing	
SolidWORKS/OnShape	

AWARDS

 **IMechE - Best BEng Project**
The University of Edinburgh
The Institution of Mechanical Engineers

 **The Edinburgh Award**
The University of Edinburgh

 **The Spirit of Formula Student**
Formula Student UK

👤 LANGUAGES

English	
French	
Arabic	