

Maurice Rahme

Curriculum Vitae

Chicago, Illinois, USA

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Education

- **Northwestern University**

Master of Science in Robotics

- No GPA yet.

Evanston, IL
Sep. 2019 - Exp. Dec 2020

- **The University of Edinburgh**

Bachelor of Engineering (Honors) in Electrical & Mechanical Engineering

- First Class (4.0 GPA)

Edinburgh, UK
Sep. 2015 - Jul. 2019

Work Experience

- **ASEA Brown Boveri (ABB)**

Engineering Intern - Medium/Low Voltage and Building Automation

- Co-designed the GRMS layout for the Zabeel One project worth 500,000\$.
- Coded an automated project proposal sheet using VBA. Est. 1-2 hours saved per proposal.
- Installed switch-gear and building automation products.
- **Extension to August:** developed a building automation design tool using VBA for ABB's future® linear product line. It generates a bill of quotation along with local contact and legal details and a per-configuration appendix in PDF format. Reported time savings: 5 hours per client order. 2 hours per revision.

Dubai, UAE
May. 2018 - Aug. 2018

- **Jaguar Land Rover (JLR)**

Engineering Intern - Body Control Module (BCM)

- Received 'Outstanding' grade on performance review.
- Coded a STATEFLOW model for blinker light control on a new car line.
- Produced and tested BCM code for the 2017 Frankfurt Autoshow in STATEFLOW.
- Led and took minutes for 10-person open issue list meetings and implemented a task allocation and follow-up system to boost work output.
- Programmed and manufactured a digital strain gauge and line and wall following RC-car module to supplement challenges in JLR's '4x4 in Schools' competition.

Gaydon, UK
Jun. 2017 - Sep. 2017

Student Engineering Experience

- **Project InnSpace, The University of Edinburgh**

Executive Secretary

- Conducted administration, communications, website maintenance, and event organization (teaching workshops, laboratory inductions, project exhibitions) for a 30-person society.
- Created and maintained an online booking system in Javascript with file drop-off and process notifications for InnSpace's 3D printers.

Edinburgh, UK
May. 2018 - May. 2019

• **Edinburgh University Formula Student (EUFs)**

Edinburgh, UK

Aerodynamics (2016-2017) and Suspension (2017-2018) Team Manager

Jul. 2016 - Jul. 2018

- Managed the design and manufacturing of suspension and aerodynamics components for teams of 8 people in each post.
- Taught and assisted team members with CAD design in SOLIDWORKS.
- Computed a SIMULINK model to calculate braking and cornering forces on wheels.
- Constructed a MATLAB design tool for Parallel and Ackermann steering configurations.
- Reviewed design reports and raised £9,000 in unmatched sponsorship (50% of budget in both years).

• **Edinburgh University Hyperloop Team (HypED)**

Edinburgh, UK

Dynamics Engineer

Sep. 2016 - Jun. 2017

- Researched halbach wheels for pod stability, thrust and braking.
- Drafted a solenoid-actuated suspension design for pod stability.
- Taught fibreglass manufacturing and wrote design reports.

Research Experience

• **BEng Project (Thesis) - Supervised by Dr. Aristides Kiprakis**

The University of Edinburgh

Pointing & Tracking Device for Bidirectional Laser Communication

Sep. 2018 - May. 2019

- Designed and built two laser transceivers to command a submerged rover. Inverse Kinematics based motor actuation maintains system uplink in a half-spherical FOV.
- Programmed pointing and tracking algorithm based on elliptical template matching via camera input processed in LabVIEW with occlusion-resistance using Kalman-filtering.
- Awarded prize: IMechE Best BEng Project for 2019.

• **Final Year Group Project**

The University of Edinburgh

Electromagnetic Levitation in Multiple Dimensions

Sep. 2018 - Nov. 2018

- Created a stepwise control strategy to decouple a nonlinear two-solenoid MIMO system, then implemented cascaded compensators on decoupled paths for 2D levitation control.

• **Sustainable Energy Group Project**

The University of Edinburgh

Portable 15W Wind Turbine to Charge two Mobile Phones

Jan. 2018 - Apr. 2018

- Designed and manufactured an axial-flux-permanent-magnet generator and control system.
- An Arduino reads generator revolution frequency as measured by a PCB-mounted schmitt trigger on one phase to monitor and control speed. Performance data is shown on an I2C OLED screen.

Awards

IMechE Best BEng Project (UofE) 2019
 The Edinburgh Award (extracurricular achievement - UofE) 2018
 The Spirit of Formula Student Award (FSUK) 2016

Skills

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|----------------------|-----------------------------------|-----------------------|
| • C/Python | • LabVIEW/OpenCV | • Altium |
| • MATLAB | • L ^A T _E X | • Arduino/RaspberryPI |
| • SimuLink/StateFlow | • SolidWorks/SolidEdge | • VBA/Javascript |

Languages

- | | | |
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| • English – Fluent | • French – Native | • Arabic – Native |
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