MAURICE RAHME

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Chicago, IL

PROJECT HIGHLIGHTS

Baxter Plays Checkers

- Programmed a Baxter robot to play a full game of checkers.
- Project completed using ROS, Movelt, OpenCV, and a custom Al move generator based on the minimax algorithm with alpha-beta pruning.
- Won 1^{st} Place out of 6 teams \P .

BEng Thesis: PATBLC

- Designed and built two laser transceivers to command an underwater rover. Inverse Kinematics based motor actuation maintains system uplink.
- Programmed pointing and tracking algorithm using elliptical template matching via occlusion-resistant camera input using Kalman-filtering in LABVIEW.
- Awarded prize: IMechE Best BEng Project for 2019 \mathbb{T}.

EXPERIENCE

Building Automation Intern

- Co-designed the GRMS layout for the Zabeel One project worth 500,000\$.
- Extension to August: developed a building automation design tool using VBA. It generates a bill of quotation in PDF format. Saved 5 hours per client order.

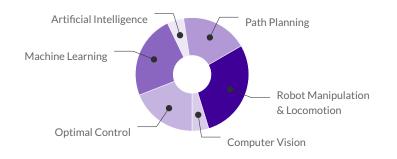
Electrical Engineering Intern - Body Control Module (BCM)

- Received 'Outstanding' grade on performance review.
- Produced BCM code for the 2017 Frankfurt Autoshow in STATEFLOW.
- Coded and manufactured a digital strain gauge and line and wall following RC-car module to supplement JLR's '4x4 in Schools' competition.

Aerodynamics '17 & Suspension '18 Team Manager

- Managed teams of 8-10 people in each post and led training workshops.
- Taught and assisted team members with CAD design in SOLIDWORKS.
- Used SIMULINK to calculate wheel braking and cornering forces.
- Built a MATLAB design tool for Parallel/Ackermann steering design.
- Reviewed design reports and raised £9,000 in sponsorship.

INTERESTS



EDUCATION

MSc in Robotics **Northwestern University**

• GPA: 3.85/4.0

B.Eng (Honors) in Electrical & Mechanical Engineering

The University of Edinburgh

• First Class (GPA: 4.0)

</> </>LANGUAGES

Pvthon C++

LabVIEW

MATLAB/SimuLink

VBA



SKILLS

ROS Robot Manipulation Machine Learning Artificial Intelligence Path Planning Bayesian Filters Linux **Version Control (Git)**

OpenCV **Analogue Electronics**

SolidWORKS



AWARDS



IMechE - Best BEng Project

The University of Edinburgh The Institution of Mechanical Engineers



The Edinburgh Award

The University of Edinburgh



The Spirit of Formula Student Formula Student UK

Y LANGUAGES

English French Arabic **Spanish**

