


MAURICE RAHME

 moribots.github.io

 github.com/moribots  +1 224 244 1684  mauricerahme2020@u.northwestern.edu  linkedin.com/in/mauricerahme  Chicago, IL

PROJECTS

TD3 Reinforcement Learning for Bipedal Robot
Northwestern University  Jan 2020 – Mar 2020


- Implemented TD3 algorithm with biologically-inspired reward function.
- Simulated PLEN robot in Gazebo and Pybullet using OpenAI Gym interface.
- Designed manual foot trajectory and deployed to real robot.

EKF SLAM on Turtlebot3
Northwestern University  Jan 2020 – Mar 2020

- Developed 2D Kinematics library in C++ for Differential Drive robots.
- Wrote feature detection algorithm for LiDAR scanner.
- Performed EKF SLAM with Unknown Data Association.



Baxter Plays Checkers
Northwestern University  Nov 2019 – Dec 2019

- Led 3 teammates to program a Baxter robot to play checkers.
- Utilized ROS, MoveIt, OpenCV, and a custom AI move generator based on the minimax algorithm with alpha-beta pruning.
- Won 1st Place out of 6 teams 🏆.



BEng Thesis: PATBLC
The University of Edinburgh  Jan 2019 – May 2019

- Developed 2-DOF laser transceivers to command an underwater rover.
- Implemented Kalman Filter and template matching for tracking in LABVIEW.
- Awarded prize: IMechE Best BEng Project for 2019 🏆.

EXPERIENCE

Building Automation Intern
ASEA BROWN BOVERI (ABB)  Dubai, UAE  May 2018 – Aug 2018

- Co-designed Electrical layout for the Zabeel One project worth \$500,000.
- Composed automation design tool in VBA that saved 5 hours per client order.

Electrical Engineering Intern - Body Control Module (BCM)
Jaguar Land Rover  Gaydon, UK  Jun 2017 – Sep 2017

- Received 'Outstanding' grade on performance review (highest possible).
- Created task allocation and follow-up system to boost work output, while leading 10-person open issue list meetings.
- Produced BCM code for the 2017 Frankfurt Autoshow in StateFlow.
- Built a line and wall following RC-car module coupled with a digital strain gauge to supplement JLR's "4x4 in Schools" competition.


Aerodynamics '17 & Suspension '18 Team Manager
Edinburgh Univ. Formula Student  Edinburgh, UK  Jul 2016 – Jul 2018

- Designed and manufactured Aerodynamic and Suspension components.
- Managed teams of 8-10 people and led training workshops.
- Taught and mentored team members with CAD in SolidWorks.
- Calculated wheel braking and cornering forces using SIMULINK.
- Built a MATLAB design tool for Parallel/Ackermann steering design.
- Reviewed design reports and raised £9,000 in sponsorship.

EDUCATION

Northwestern University
Master of Science in Robotics  Aug. 2020

- GPA: 3.92/4.0















The University of Edinburgh
B.Eng (Honors) in Electrical & Mechanical Engineering  Jun. 2019

- GPA: 4.0/4.0; equivalent of First Class


</> LANGUAGES

C++	
Python	
C	
MATLAB/SimuLink	
LabVIEW	
VBA	

SKILLS

ROS/Gazebo/MoveIt!	
Robot Manipulation	
SLAM	
PyBullet	
Machine Learning	
Pytorch	
Motion Planning	
Bayesian Filters	
Search Algorithms	
Linux	
Version Control (Git)	
Unit Testing	
Analogue Electronics	
SolidWORKS	

AWARDS

 **IMechE - Best BEng Project**
The University of Edinburgh
The Institution of Mechanical Engineers

 **The Edinburgh Award**
The University of Edinburgh

 **The Spirit of Formula Student**
Formula Student UK

👤 LANGUAGES

English	
French	
Arabic	