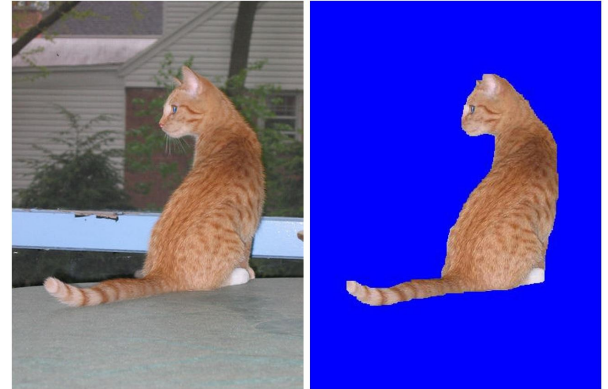


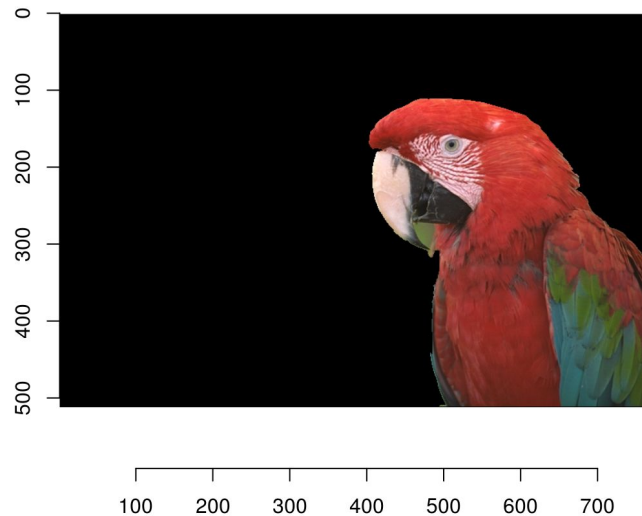
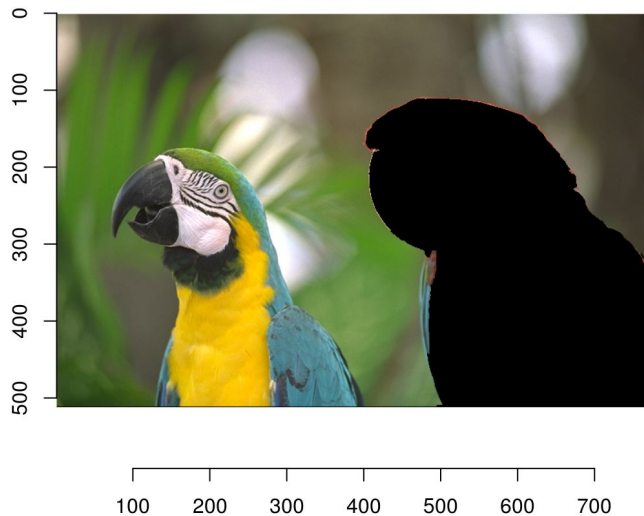
# Foreground/Background Image Segmentation

By Natalia Frumkin



# Problem Statement

Segment an image into **background** and **foreground**



# *Techniques*

## 1. Image Filtering



## 2. Max Flow Algorithms



# Otsu's Method for Filtering

Big idea: automatic thresholding by minimizing intra-class variance

objective:

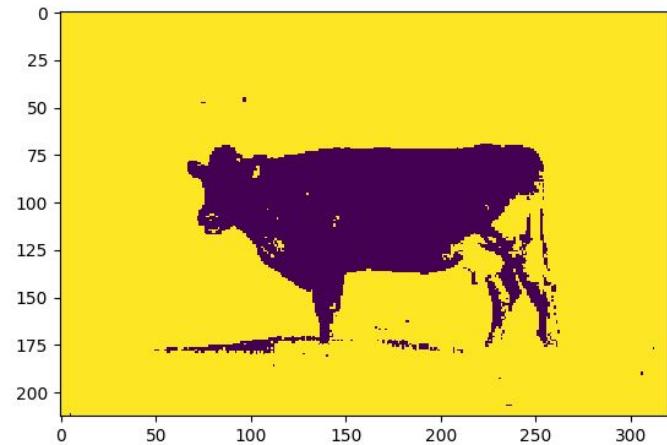
$$\sigma_w^2(t) = \omega_0(t)\sigma_0^2(t) + \omega_1(t)\sigma_1^2(t)$$

Class 0 variance



Class 1 variance

# Results



# Max-Flow Techniques

# Energy Minimization

$$E(L) = \sum_{p \in \mathcal{P}} D_p(L_p) + \sum_{(p,q) \in \mathcal{N}} V_{p,q}(L_p, L_q)$$

## Data Penalty Term

Individual pixel intensity

## Interaction Potential Term

Promotes spatial coherence between neighboring pixels



### **Interaction Potential Term**

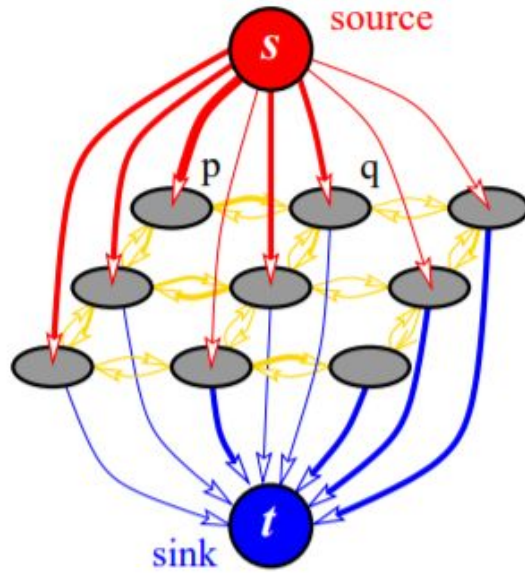
Promotes spatial coherence between neighboring pixels

### **Data Penalty Term**

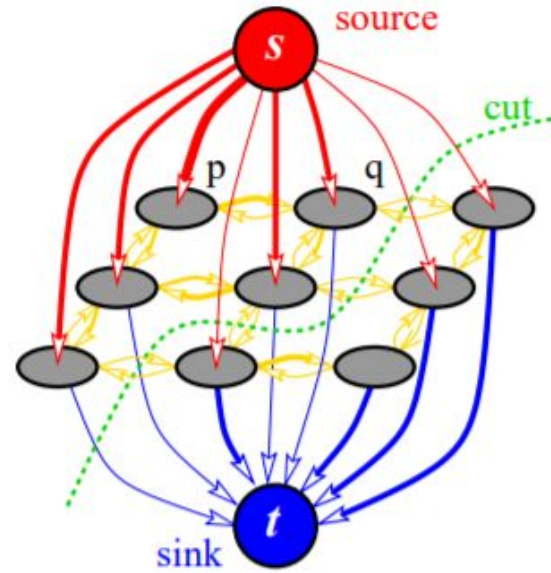
Individual pixel intensity



# Graph Setup



(a) A graph  $\mathcal{G}$



(b) A cut on  $\mathcal{G}$

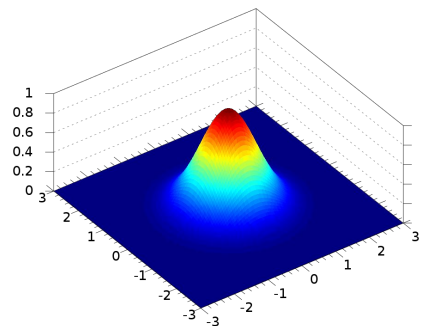
# Graph Weights

## Intensity weights (Data Penalty)

distribution of individual pixels match src/sink labels

*computed by:*

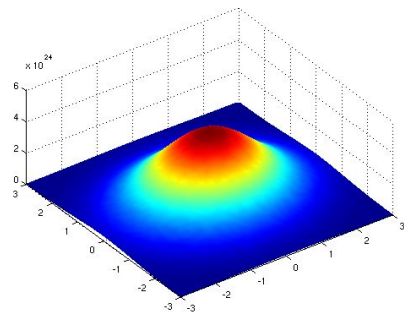
$$\exp\left(-\frac{(I_p - I_q)^2}{2\sigma^2}\right)$$



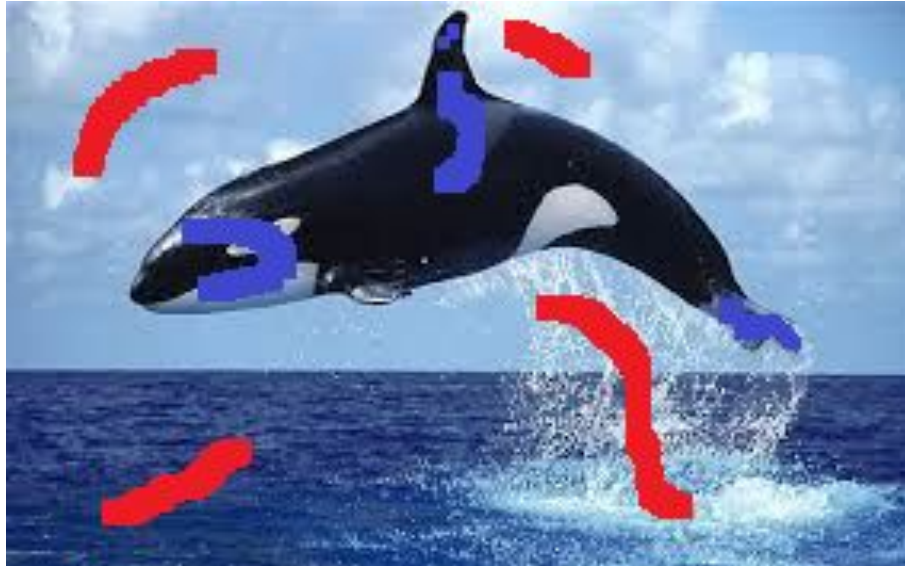
## Interpixel weights (Interaction Potential)

distribution using intensity difference between neighboring pixels

*computed through closed-form gaussian estimation*



# Annotation: Supervised Method



# Ford Fulkerson Algorithm

## 1. Growth Phase

**Find** path from source to sink using BFS

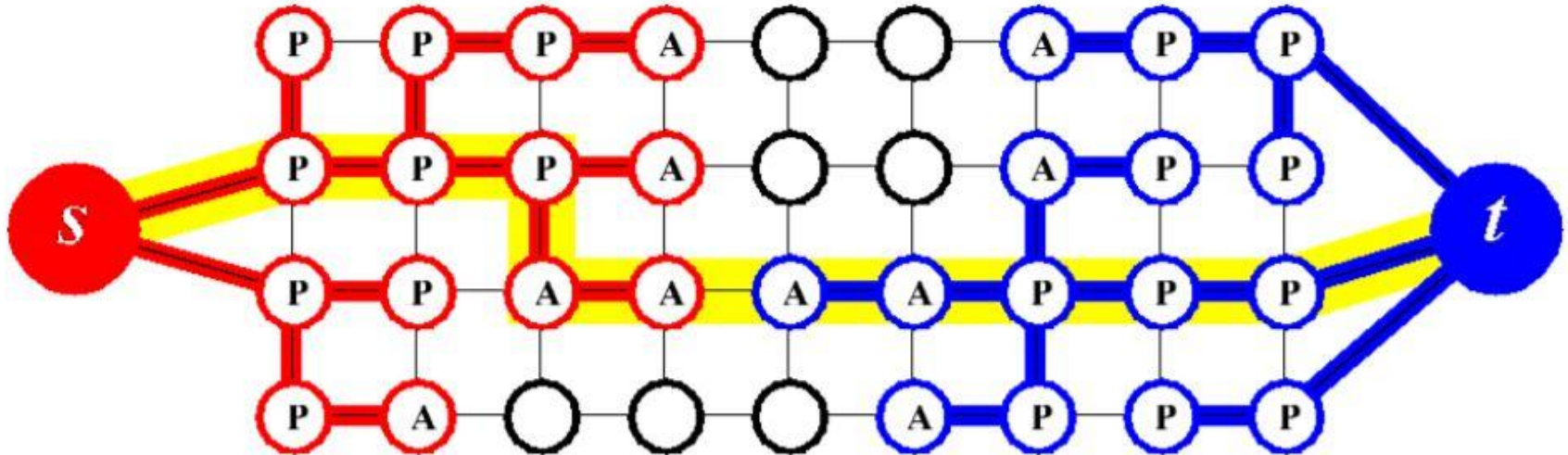
## 2. Augment Phase

**Push** flow from  $s \rightarrow t$

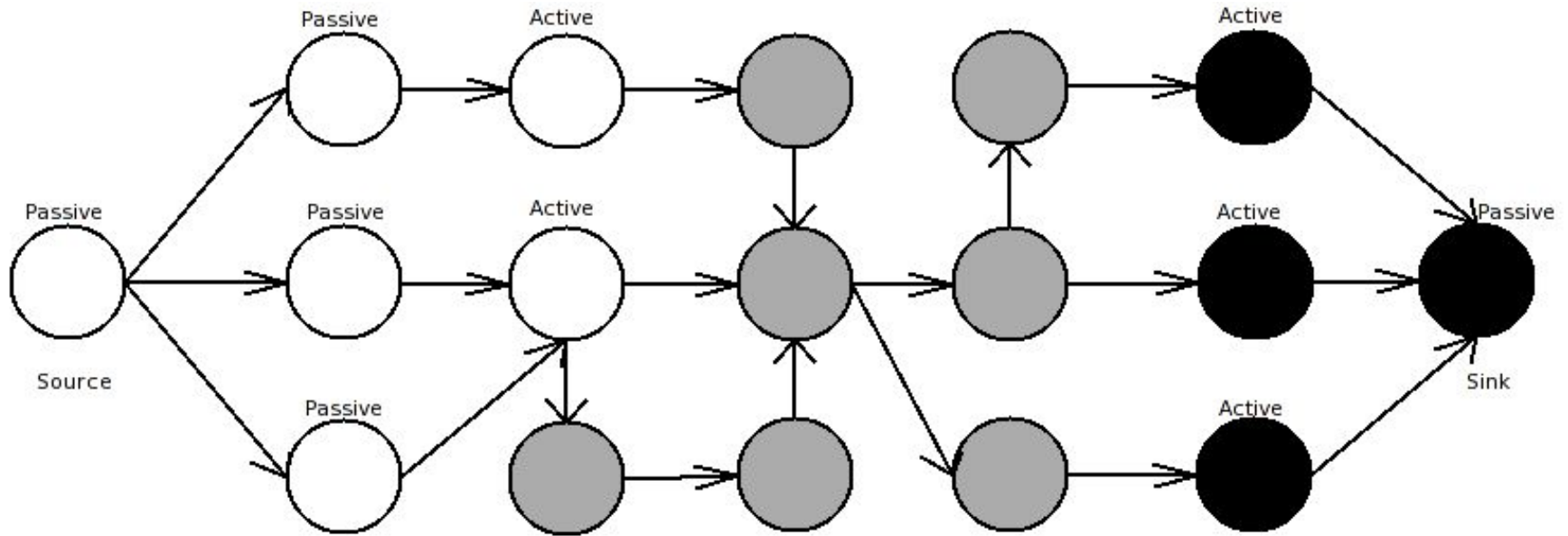
**Update** residual graph and max-flow

Repeat until no paths can be found between source & sink

# The Boykov-Kolmogorov Max-Flow Algorithm



# The Boykov-Kolmogorov Max-Flow Algorithm



Example with labeled vertices and active/passive status

# The Boykov-Kolmogorov Max-Flow Algorithm

## 1. Growth Phase

**Search** trees  $S$  and  $T$  grow until they touch giving an  $s \rightarrow t$  path

## 2. Augment Phase

**Augment**  $s \rightarrow t$  path by pushing flow

## 3. Adoption Phase

**Restore** single-tree structure of sets  $S$  and  $T$

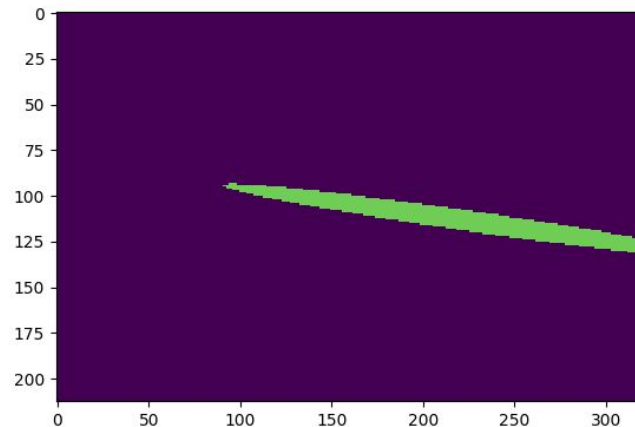
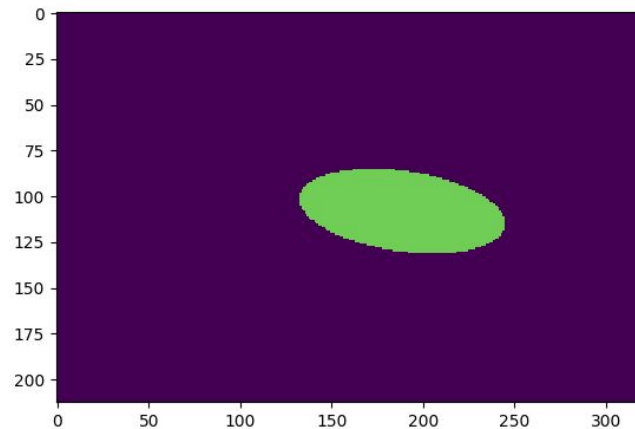
# The Boykov-Kolmogorov Max-Flow Algorithm

Repeat three phases until **end conditions** are satisfied:

- 1) S & T Trees can not grow (no active nodes)
- 2) Trees are separated by saturated edges



# Issues: Parameter Fitting



Next Steps:

- Grid search for optimal lambda and sigma
- Use Gaussian Mixture Models for weights

# Runtime

## Otsu's Method

$O(\max(N_{\text{pixels}}, N_{\text{bins}} * N_{\text{bins}}))$

*real runtime: 0.0017 sec*

## Ford-Fulkerson Method

$O(V * E^2)$

*real runtime: Too long :(*

## Boykov-Kolmogorov Method

$O(V^2 * E * |C|)$

*real runtime: 10.6+0.00088 sec*

Demo!