P-values from Wilcoxon Signed-Rank Test

	Scenario 1	Scenario 2	Scenario 3
The robot's behavior was natural.	0.0584	0.4617	**0.0024**
I clearly understood what the robot was trying to communicate.	**0.0339**	0.3037	0.0848
The robot appeared competent in performing the behavior.	0.0772	0.4901	**0.0306**
The behavior matched what I would expect for this situation.	0.3692	0.2270	**0.0006**
The robot's movement looked realistic.	0.0559	0.7240	0.0536
I would trust the robot to perform this action in a real interaction.	**0.0320**	0.2519	**0.0019**