



E6318 - Microwave Circuit Design

Columbia University

Spring 2006

Yves Baeyens

Outline of Lecture 1

- ◆ Course information & overview
 - Contact info, syllabus, calendar, website
- ◆ Introduction to Microwaves
 - Applications, microwave bands, ...
 - Microwave circuits
- ◆ Transmission line theory
 - Telegrapher equations
 - Terminated transmission lines

Personal Info

- ◆ Yves Baeyens
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 - Office hours: after class, by appointment (e-mail!)
- ◆ Course: Th 4:10-6:40 PM, 1127 Mudd
- ◆ Webpage: <http://www.cisl.columbia.edu/~ee6318/>
- ◆ CA/TA: **Austin Chen (yc2134@columbia.edu)**

Website

- ◆ Webpage: <http://www.cisl.columbia.edu/~ee6318/>
- ◆ These notes, assignments and some useful files and links will be posted in a password-protected area, please do not share this password or any files downloaded from this area.
- ◆ username: ee6318
password: 4MWcour53only
- ◆ Please check website regularly for updates on assignments, possible rescheduling of classes, etc...

Calendar

◆ Course: Th 4:10-6:40 PM, 1127 Mudd

- 01/19
- 01/26
- 02/02
- 02/09
- 02/16
- 02/23
- 03/02
- 03/09 **Midterm**
- 03/16 **Spring Holidays**
- 03/23
- 03/30
- 04/06
- 04/13
- 04/20
- 04/27
- **Final (05/11)**

Objectives of Microwave Circuit Design Course

- ◆ Learn Basic Microwave Design Principles:
 - Transmission lines & Smith-chart
 - S-parameters, Microwave networks
 - Impedance matching and tuning
 - Coupled line theory
- ◆ Study Practical Microwave Components:
 - Transmission lines, power dividers & couplers
 - Active and passive microwave devices
- ◆ Study design of some active microwave circuits
 - Amplifiers: smallband, low-noise, broadband, power
 - Non-linear circuits: oscillators, multipliers, mixers

Objectives of Microwave Circuit Design Course

- ◆ Take a look at simulation and measurement tools for microwave circuits
- ◆ Apply Microwave Design in small design-projects
 - after midterm
 - Agilent ADS
- ◆ Study transmission line effects in digital systems

Detailed syllabus

1. Transmission line theory 2 wks
 - Transmission lines, standing waves and VSWR
 - Smith chart
 - Quarterwave transformer, lossy lines
 - Transients in transmission lines
2. Microwave transmission lines in practice 1 wk
 - Effective dielectric constant, dispersion, attenuation, skin effect
 - Coaxial lines (Waveguides)
 - Microstrip and strip-lines, coplanar waveguide
3. Microwave Network Analysis 1 wk
 - S-parameter matrix and properties of S-parameters
 - Mason's signal flow rules,
 - Discontinuities in transmission lines

Detailed syllabus (2)

4. Impedance matching and tuning

1½ wks

- Matching using lumped elements
- Lumped microwave components (inductors, capacitors, etc...)
- Matching using transmission lines (single and double stub, quarterwave transformer)
- Multi-section transformers and Bode-Fano Criterion

5. Microwave Resonators

½ wk

Detailed syllabus (3)

6. Power dividers and directional couplers 1 wk

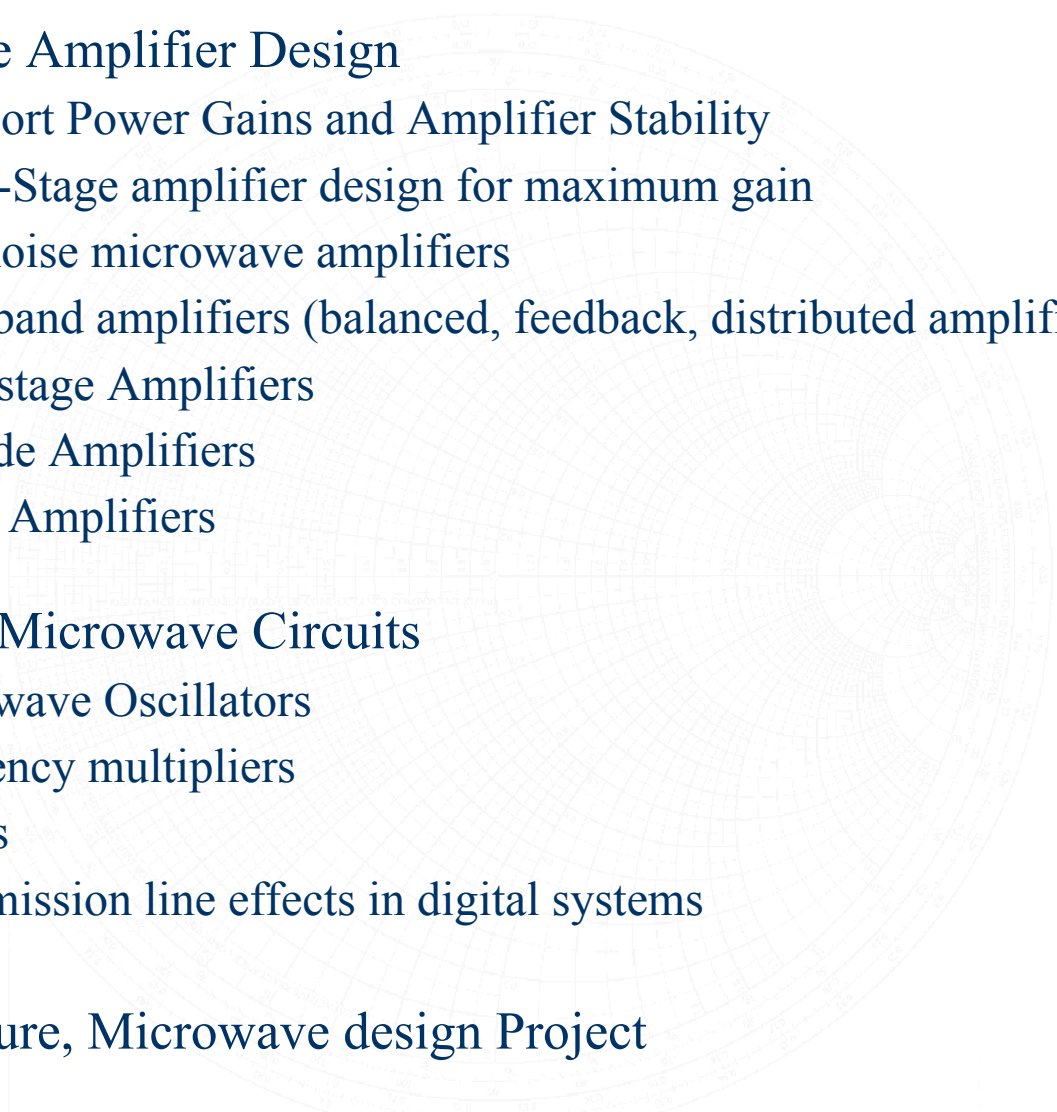
- Basic properties 3 and 4-ports
- T-junction and Wilkinson Power divider
- Quadrature hybrid (branch-line coupler)
- Coupled line directional couplers and Lange coupler
- The 180° hybrid (rat-race)

----- MIDTERM -----

7. Noise and active microwave devices 1 wk

- Noise in Microwave Circuits (noise temperature and noise figure)
- Dynamic Range and Intermodulation
- Modern Microwave Transistors: Figures of Merit, modelling, Current state-of-the-art in active devices

Detailed syllabus (4)

- 
8. Microwave Amplifier Design 2 ½ wks
 - Two-port Power Gains and Amplifier Stability
 - Single-Stage amplifier design for maximum gain
 - Low-noise microwave amplifiers
 - Broadband amplifiers (balanced, feedback, distributed amplifiers)
 - Multi-stage Amplifiers
 - Cascode Amplifiers
 - Power Amplifiers
 9. Nonlinear Microwave Circuits 1 ½ wks
 - Microwave Oscillators
 - Frequency multipliers
 - Mixers
 - Transmission line effects in digital systems
 10. Recap lecture, Microwave design Project 1 wk

Grading

- ◆ Homework (~weekly), including couple small design projects towards end 30%
- ◆ Midterm (written) 20%
- ◆ Final (written) 50%

Reference book

D. Pozar: “**Microwave Engineering**”, 3rd Ed., J. Wiley & Sons

While Pozar’s book (typically 2 semester course) describes the mathematical derivation of EM properties in detail, this course will concentrate on the outcome of these derivations.

Reading (see website for updates!):

- ♦ **Chapter 1:** optional reading
- ♦ **Chapter 2:** completely (L1&L2)
- ♦ **Chapter 3:** only some results discussed in class (L3)
- ♦ **Chapter 4:** 1&2 optional, in class: 3, 4 & 5 (L4&5)
- ♦ **Chapter 5:** sections 1,2,3,4 & 9
- ♦ **Chapter 6:** 1&2
- ♦ **Chapter 7:** 1,2,3,5,6,7,8,9
- ♦ **Chapter 10:** 1, 2, 3 4&5 optional
- ♦ **Chapter 11:** 1,2,3,4,5 in part, complemented with notes
- ♦ **Chapter 12:** 1,2,3,4 and 6 in part, complemented with notes



Other good reference works

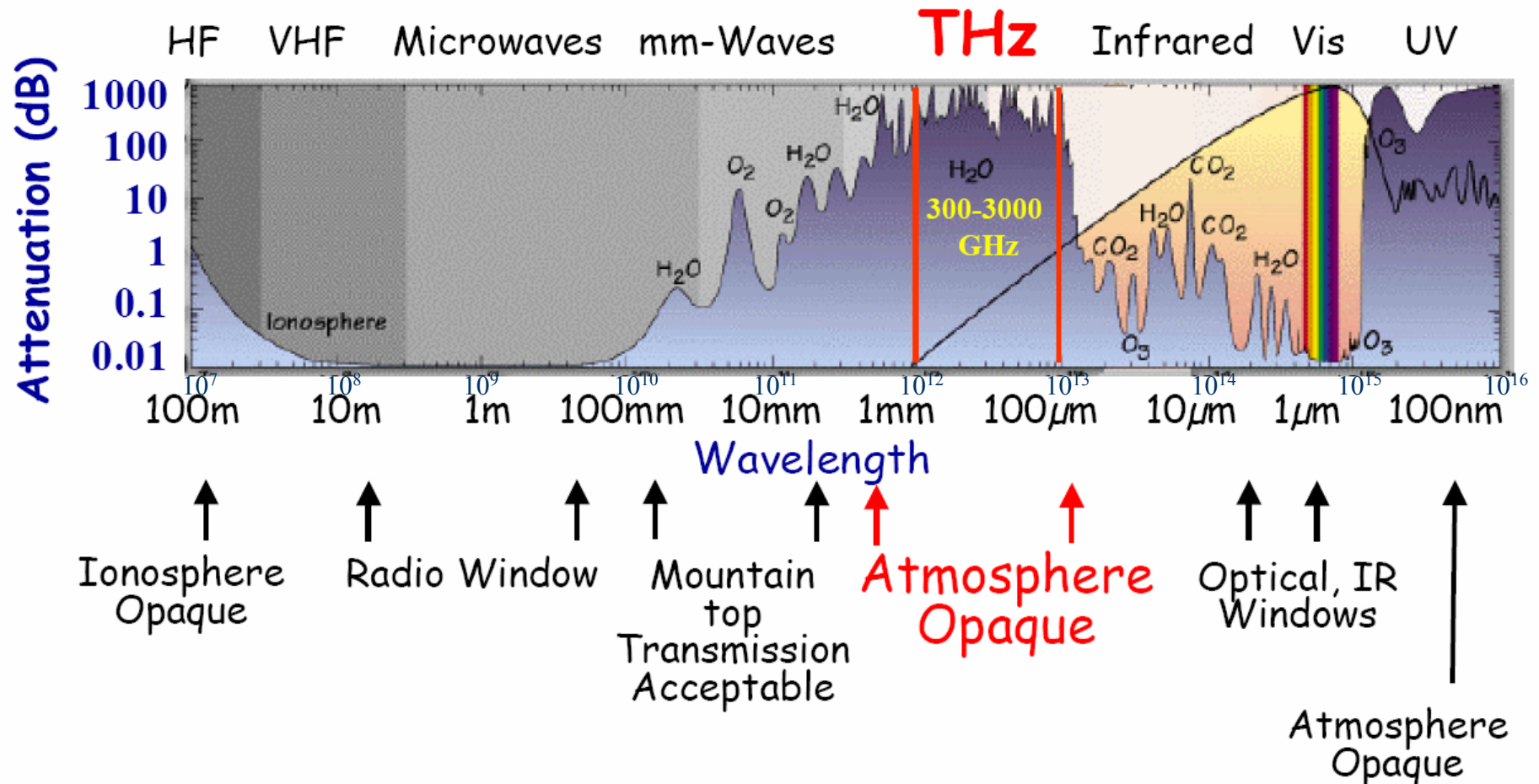
- ♦ G. Gonzalez: “**Microwave Transistor Amplifiers: analysis and design**”, 2nd Ed., Prentice Hall, Inc.
- ♦ S. Y. Liao: “**Microwave Circuit Analysis and Amplifier Design**”, Prentice Hall, Inc.
- ♦ J. C. Freeman: “**Fundamentals of Microwave Transmission Lines**”, John Wiley & Sons, Inc.
- ♦ S. H. Hall: “**High-Speed Digital System Design: A Handbook of Interconnect Theory and Design Practices**”, John Wiley & Sons, Inc.
- ♦ R.J. Weber: “**Introduction to Microwave Circuits**”, IEEE Press.
- ♦ J. White: “**High Frequency Techniques**”, John Wiley & Sons, Inc.

Microwaves

- ◆ Microwave range:
 - $300 \text{ MHz} \leq \text{frequency} \leq 300 \text{ GHz}$
 - $100 \text{ cm} \leq \lambda \leq 0.1 \text{ cm}$
- ◆ IEEE Microwave bands:

■ L: 1-2 GHz	λ : 30-15 cm
■ S: 2-4 GHz	λ : 15-7.5 cm
■ C: 4-8 GHz	λ : 7.5-3.75 cm
■ X: 8-12.5 GHz	λ : 3.75-2.4 cm
■ Ku: 12-18 GHz	λ : 2.4-1.67 cm
■ K: 18-26.5 GHz	λ : 1.67-1.13 cm
■ Ka: 26-40 GHz	λ : 1.13-0.75 cm
■ mm-waves: 40-300 GHz	λ : 7.5-1 mm
■ mm-waves further divided in U (Q), V, W, D, F, G waveguide bands	
■ sub-mm-wave (THz): >300 GHz	λ : 1-0.1 mm

The electromagnetic spectrum



Typical telecom applications in .1-100 GHz range (μwave, mm-wave) and in optical range (~200 THz)

The need for higher frequencies!!!

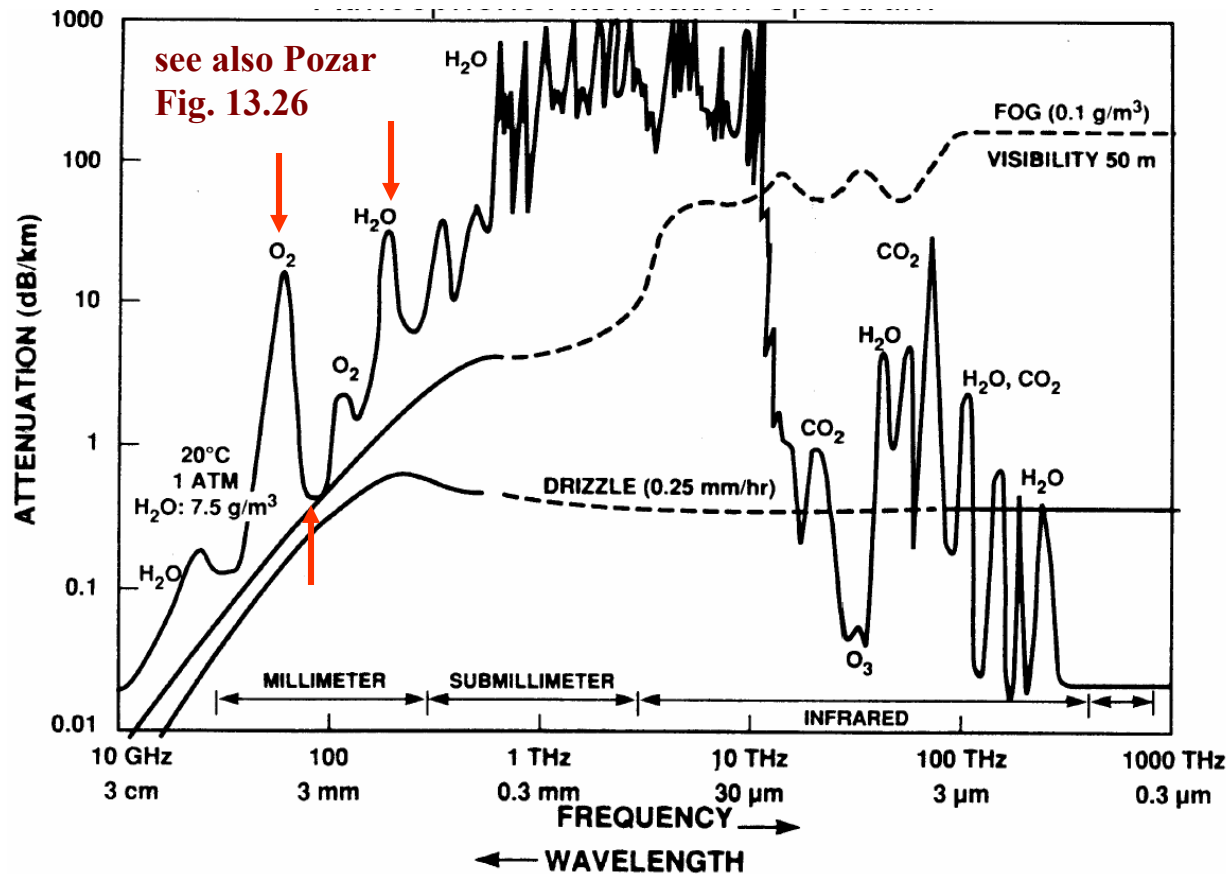
- ◆ The higher the frequency, the **more information** can be sent over same fractional bandwidth (600 MHz: 1% BW=1 TV channel, at 60 GHz: 1% =100 TV channels, at 200 THz,)
- ◆ The higher the frequency, the **smaller** wavelength and wavelength depending structures (antennas, radar resolution, waveguides, etc...)
- ◆ At higher frequency, specific molecular spectra can be used to our advantage (radio-astronomy, secure LAN, T-ray imaging)



But some drawbacks for telecom...

- ◆ The higher the frequency, the **smaller** (read more accurate and therefore expensive) things get...
- ◆ This definitely applies to the **electronics** and **test** equipment!
- ◆ The higher the frequency, the **more loss** (ohmic, dielectric, molecular absorption etc...) atmospheric transmission will incur
- ◆ Data transmission at microwave frequencies is prone to **signal degradation** due to multiple reflections, Doppler, etc...

Atmospheric attenuation vs. frequency



- ♦ Molecular resonance peaks at 22 & 183 G (H₂O), at 60 & 120G (O₂)
- ♦ Windows at 35, 94 and 140 GHz (high-resolution radar)
- ♦ MM-wave lossy, but still better than optical in fog!!

Applications of Microwave Circuit Design

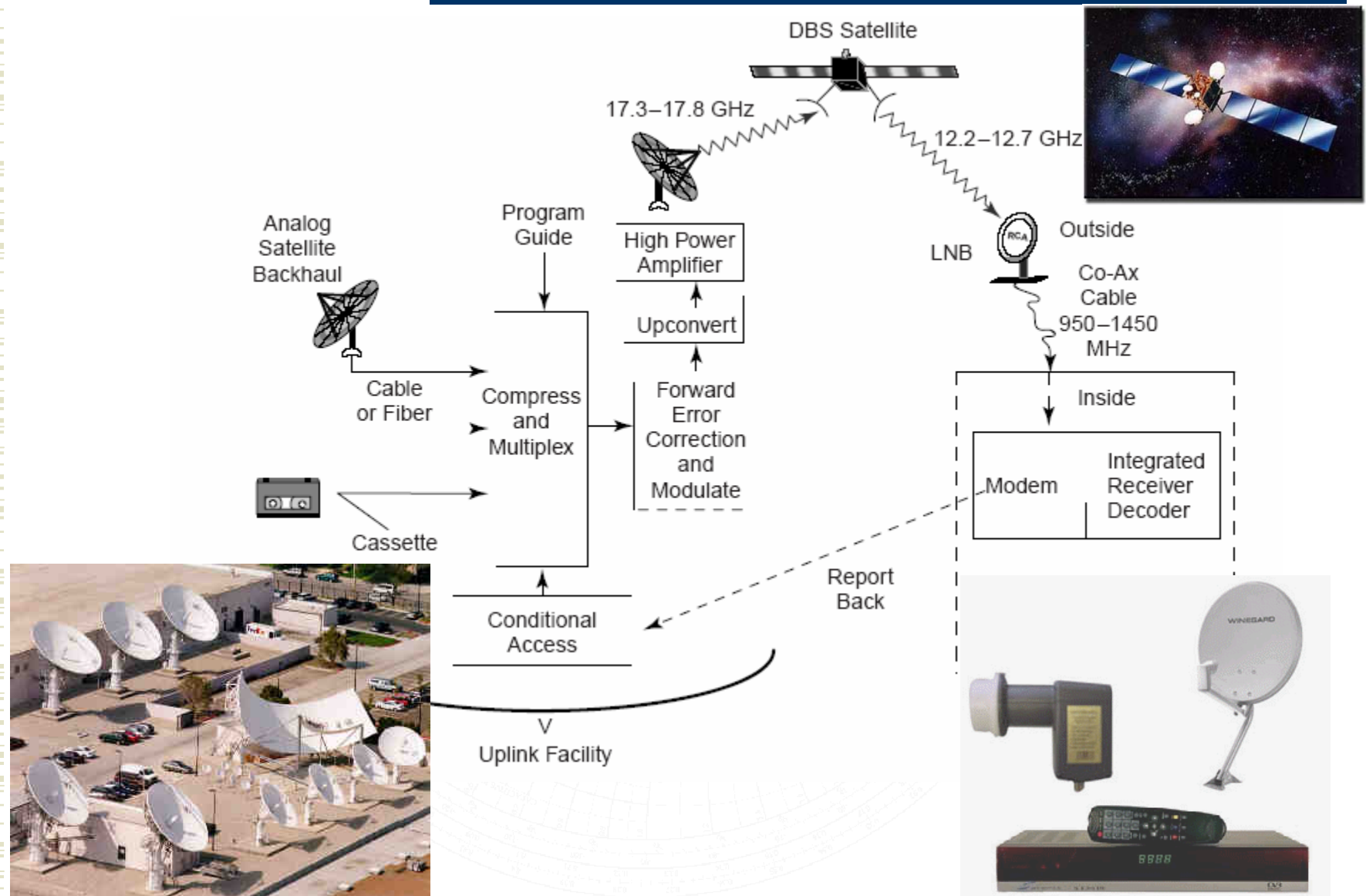
- ◆ Telecommunications
 - Wireless: cellular, WLAN, pt-to-pt link, satellite
 - Wireline: optical (OC-768), Gigabit-ethernet, ...
- ◆ High-speed VLSI design
 - On-chip interconnects
 - Packaging, high-speed bus
- ◆ Radar / Remote Sensing
- ◆ Radio-astronomy
- ◆ Global Positioning Satellite (GPS)



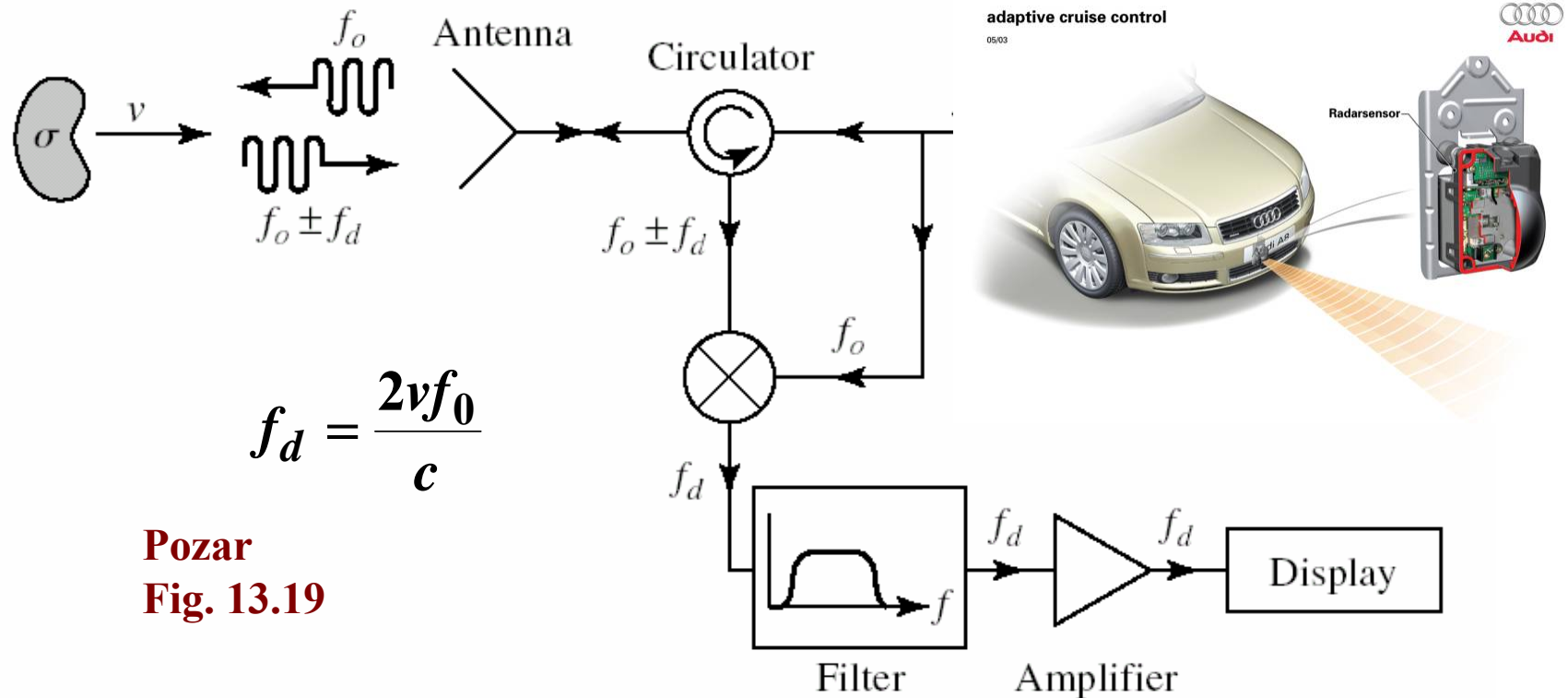
High-frequencies put in perspective....

- ◆ AM Radio: 2 MHz
- ◆ Intel 8086 clock speed: 4.7 & 8 MHz
- ◆ FM Radio: 85-105 MHz
- ◆ Cellular Phone: ~1 & 2 GHz
- ◆ Fastest Pentium clock speed: 3.8 GHz
- ◆ WLAN (802.11): 2.4 GHz & 5.8 GHz
- ◆ DBS (Direct Broadcast Satellite): 12 GHz
- ◆ AICC: 24 & 77 GHz
- ◆ Gigabit LAN: 60 GHz
- ◆ High-resolution Radar: 94 & 140 GHz
- ◆ Fastest Bell-Labs electronic circuit: 270 GHz
- ◆ Optical carrier frequency: ~200 THz, modulation: 100 Gb/s

Example Microwave System: Direct Broadcast Satellite



Example 2: Doppler Radar System (77 GHz)



- Returned signal shifted in frequency according to speed
- Combination with pulsed (pulse-doppler radar) gives both range and velocity

Microwave versus analog/digital design

Microwave:

- ◆ Design optimizes power-flow
- ◆ Performance close to limits active devices in frequency, noise, power added efficiency
- ◆ Typically smallband (AC)
- ◆ Very few active devices
- ◆ Which dissipate lots of power
- ◆ Combined with large reactive passives (TL's, inductors,...)
- ◆ Resulting in relatively large circuit size
- ◆ Mostly single-ended design

Analog/Digital:

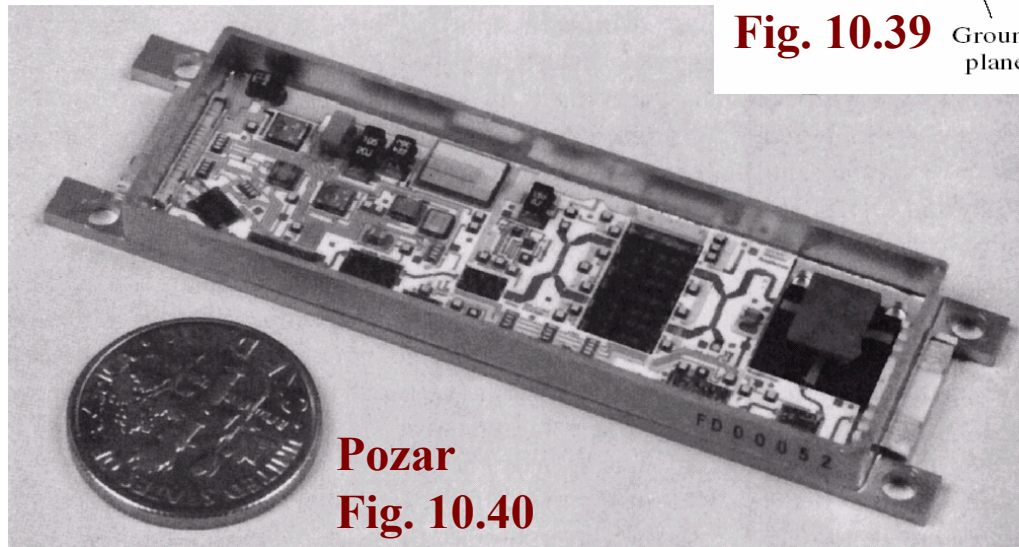
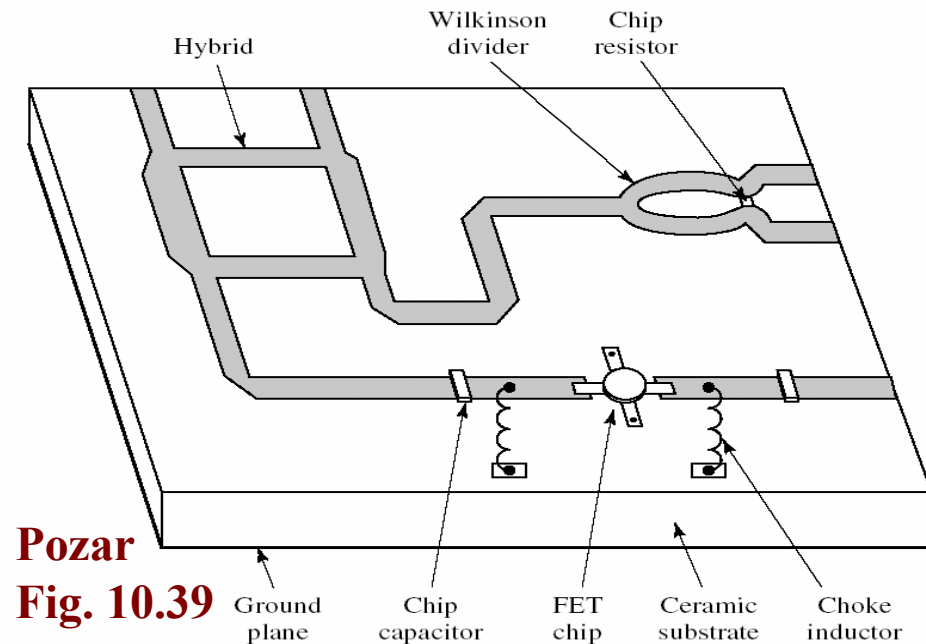
- ◆ Voltage/current
- ◆ Performance at single frequency typically far from fundamental limit
- ◆ Broadband operation (DC)
- ◆ K's (analog)/M's (digital)
- ◆ Each device low power
- ◆ With small resistors (or only FETs)
- ◆ Relatively small even with M's of FETs
- ◆ Very often differential

Why using transmission lines at high-speed?

- ◆ Make longer connections which:
 - Are low-loss: low **ohmic** or **dielectric** losses + minimal **radiation**
 - Have well-known characteristics allowing to avoid degradation in analog or digital systems due to reflections, ringing, limited bandwidth, ...
- ◆ Use the transmission lines as circuit element:
 - Reactive matching element to optimize power transfer, maximize gain of active elements, etc...
 - Frequency dependent properties: resonators, filters
 - Multiports with interesting power combining properties: couplers, hybrid-T's. etc...

Microwave integrated circuits: hybrid

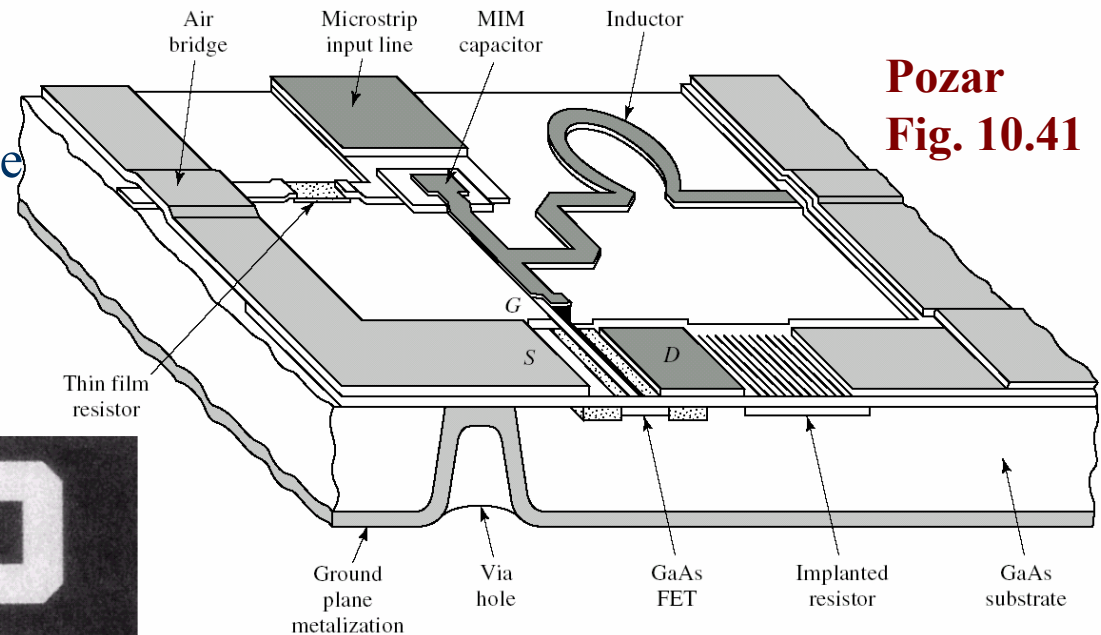
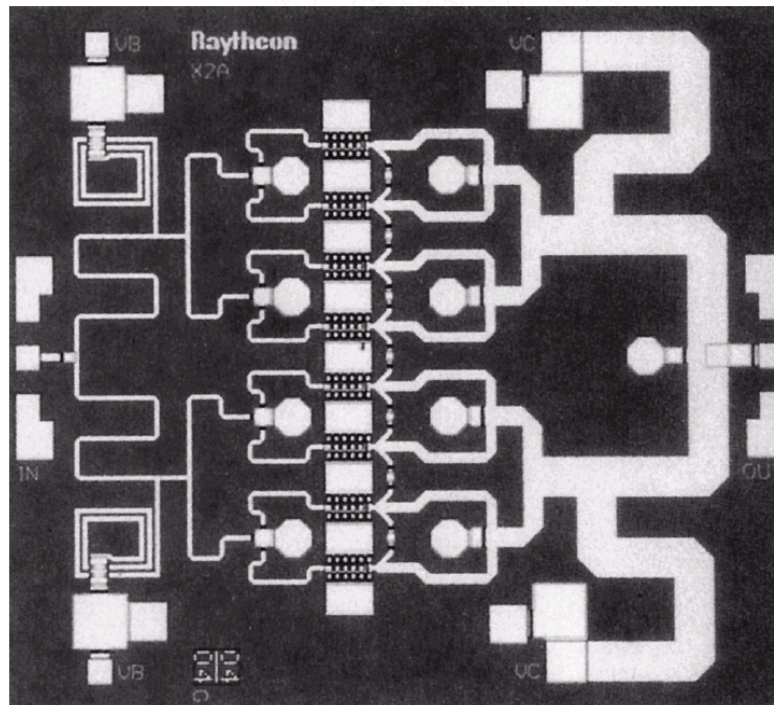
Layout hybrid microwave integrated circuit (MIC) in this case microstrip topology



Radar T/R module, contains phase shifters, amplifiers, switches, couplers, circulator..

Microwave integrated circuits: monolithic

Layout monolithic microwave integrated circuit (MMIC) again microstrip topology



**Pozar
Fig. 10.41**

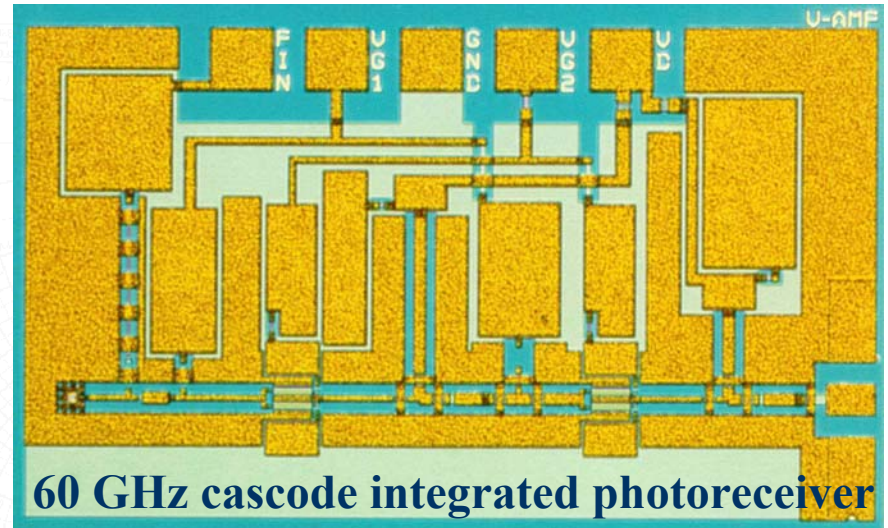
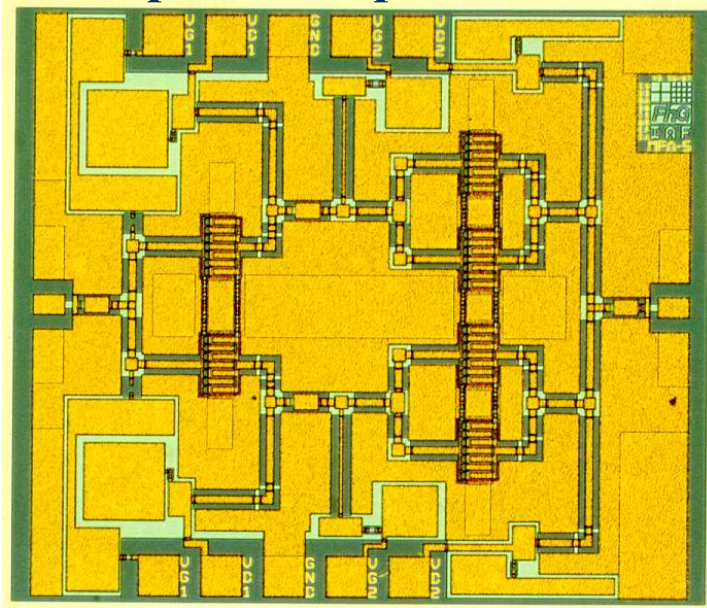
Example of MMIC:
Integrated X-band power amplifier

Multiple HBT's combined to deliver 5W

**Pozar
Fig. 10.42**

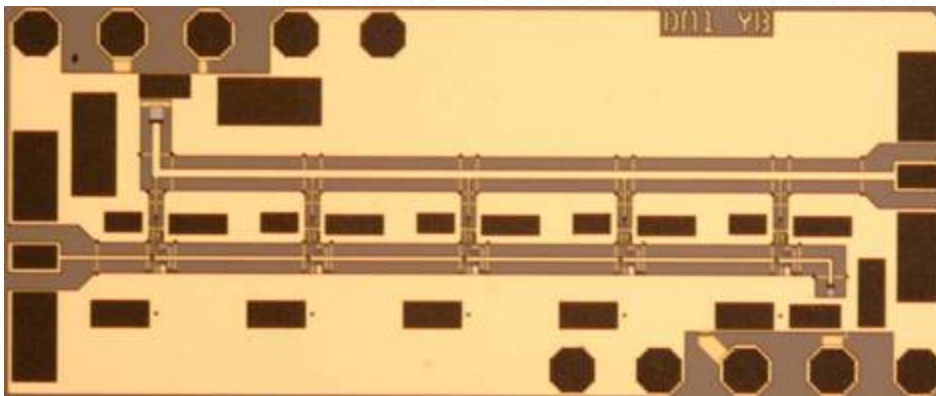
Some more recent MMIC examples....

1W power amp at 42 GHz

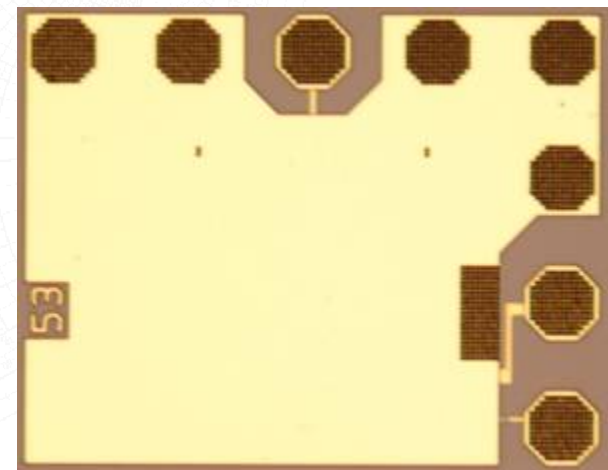


60 GHz cascode integrated photoreceiver

>110 GHz BW InP HBT amplifier



270 GHz InP HBT push-push VCO



Hierarchy of Microwave Engineering

◆ Electromagnetics Theory

- Gauss', Ampere's and Faraday's law
- Maxwell Equations



uniform, TEM

◆ Distributed Circuits

- Transmission lines, Telegraph Equations
- Smith Chart, S-parameters, etc...



dimensions $\ll \lambda$

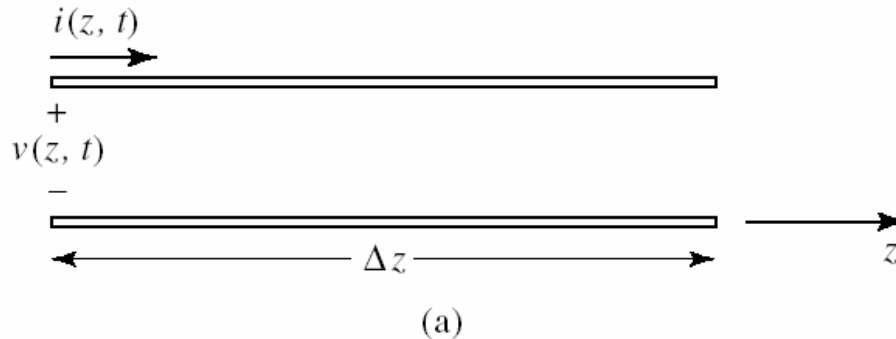
◆ Lumped Circuits

- Ohm's and Kirchoff's Law
- R, L, C

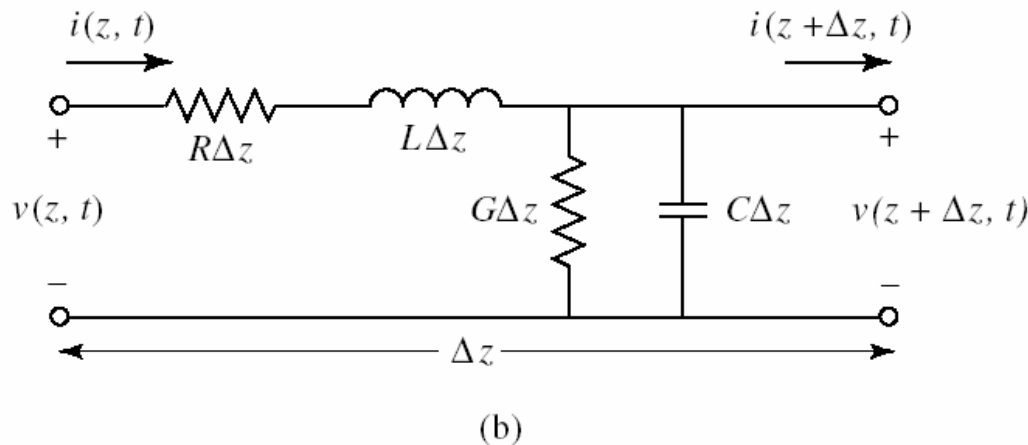
Transmission line theory: lumped-element circuit

- ◆ Circuit theory: physical dimensions \ll electrical wavelength
- ◆ Transmission lines: size fraction wavelength or larger
- ◆ As a result voltages and current vary in both magnitude and phase along distributed transmission line
- ◆ TL schematically represented as 2-wire line (TEM propagation: at least 2 conductors). Short piece of TL modelled with per unit length quantities:
 - R: series resistance in Ω/m
 - L: series inductance in H/m
 - G: shunt conductance in S/m
 - C: shunt capacitance in F/m
- ◆ Finite length of TL: cascade of multiple sections

Transmission line theory: lumped-element circuit



Voltage and current definitions for incremental length of transmission line



Pozar
Fig. 2.1

Lumped-element equivalent circuit

- ◆ **KVL:**
$$v(z, t) - R\Delta z \cdot i(z, t) - L\Delta z \cdot \frac{\partial i(z, t)}{\partial t} - v(z + \Delta z, t) = 0$$
- ◆ **KCL:**
$$i(z, t) - G\Delta z \cdot v(z + \Delta z, t) - C\Delta z \cdot \frac{\partial v(z + \Delta z, t)}{\partial t} - i(z + \Delta z, t) = 0$$

Transmission line theory: wave equations

- ◆ Dividing by Δz and taking limit for $\Delta z \rightarrow 0$

$$\frac{\partial v(z,t)}{\partial z} = -R \cdot i(z,t) - L \cdot \frac{\partial i(z,t)}{\partial t}$$

time-domain form TL
or telegrapher equations

$$\frac{\partial i(z,t)}{\partial z} = -G \cdot v(z,t) - C \cdot \frac{\partial v(z,t)}{\partial t}$$

- ◆ For sinusoidal steady-state (cosine-phasors):

$$\frac{dV(z)}{dz} = -(R + j\omega L) \cdot I(z)$$

$$\frac{dI(z)}{dz} = -(G + j\omega C) \cdot V(z)$$

- ◆ Solved simultaneously gives wave eq. $V(z)$ & $I(z)$

$$\frac{d^2 V(z)}{dz^2} - \gamma^2 \cdot V(z) = 0 \quad \frac{d^2 I(z)}{dz^2} - \gamma^2 \cdot I(z) = 0$$

γ is complex propagation constant

$$\gamma = \alpha + j\beta = \sqrt{(R + j\omega L)(G + j\omega C)}$$

Traveling wave solutions

- Traveling wave solutions to last equation can be found:

$$\begin{aligned} V(z) &= V_o^+ e^{-\gamma z} + V_o^- e^{+\gamma z} \\ I(z) &= I_o^+ e^{-\gamma z} + I_o^- e^{+\gamma z} \end{aligned} \quad \begin{array}{l} V, I = \text{sum of 2 waves, one in pos. } z \\ \text{direction one in negative} \end{array}$$

- Applying $\frac{dV(z)}{dz} = -(R + j\omega L) \cdot I(z)$

$$I(z) = \frac{\gamma}{R + j\omega L} \left[V_o^+ e^{-\gamma z} - V_o^- e^{+\gamma z} \right]$$

With Z_0 : characteristic impedance, relates V and I on line

$$Z_0 = \frac{R + j\omega L}{\gamma} = \sqrt{\frac{R + j\omega L}{G + j\omega C}} = \frac{V_o^+}{I_o^+} = -\frac{V_o^-}{I_o^-} \quad V_o^+ \& I_o^+ \text{ are in phase if } Z_0 \text{ real}$$

This becomes:
$$I(z) = \frac{V_o^+}{Z_0} e^{-\gamma z} - \frac{V_o^-}{Z_0} e^{+\gamma z}$$

Traveling wave solutions in time domain

- ♦ Converting back in time domain:

$$V(z) = |V_o^+| \cos(\omega t - \beta z + \phi^+) e^{-\alpha z} + |V_o^-| \cos(\omega t + \beta z + \phi^-) e^{\alpha z}$$

for fixed point on wave ($\omega t - \beta z = \text{cte}$) z has to increase if t increases, so wave traveling in pos. z direction

- ♦ From this we can find wavelength on line:

$[\omega t - \beta z] - [\omega t - \beta(z + \lambda)] = 2\pi$
for distance between 2
reference points

$$\lambda = \frac{2\pi}{\beta}$$

Phase velocity on line (velocity fixed phase point on wave):

$$v_p = \frac{dz}{dt} = \frac{d}{dt} \left(\frac{\omega t - \text{constant}}{\beta} \right) = \frac{\omega}{\beta} = \lambda \cdot f$$

$$v_p = 1 / \sqrt{\mu_0 \epsilon_0 \epsilon_r} = c / \sqrt{\epsilon_r}$$



$$\lambda = \frac{c \cdot f}{\sqrt{\epsilon_r}}$$

TEM (will see in Lecture 3)

c : velocity of light free-space: $2.998 \times 10^8 \text{ m/s}$

ϵ_r : dielectric constant (effective for quasi-TEM)

In case of lossless line:

- Many practical cases loss very small and can be neglected

$$\gamma = j\beta = j\omega\sqrt{LC}$$

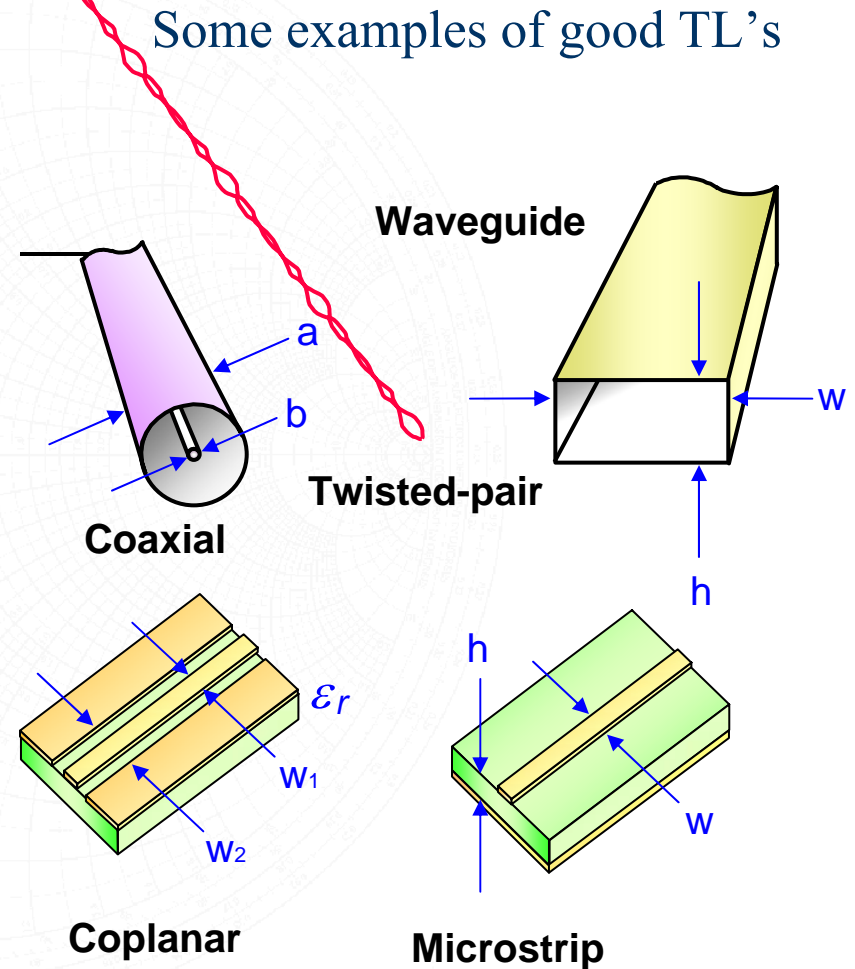
$$Z_0 = \sqrt{\frac{L}{C}}$$

$$\lambda = \frac{2\pi}{\beta} = \frac{2\pi}{\omega\sqrt{LC}}$$

$$v_p = \frac{\omega}{\beta} = \frac{1}{\sqrt{LC}}$$

$$V(z) = V_o^+ e^{-j\beta z} + V_o^- e^{+j\beta z}$$

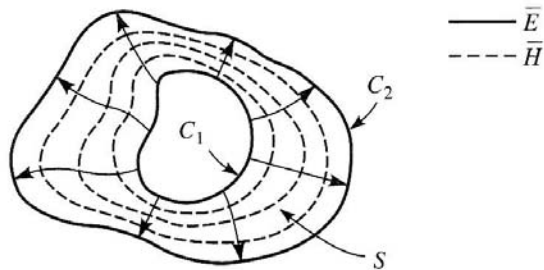
$$I(z) = \frac{V_o^+}{Z_0} e^{-j\beta z} - \frac{V_o^-}{Z_0} e^{+j\beta z}$$



When do we care about transmission lines?

- ◆ Analog/microwave applications:
 - Lumped if dimensions $(l) \ll \lambda/10$
 - Back-of-the-envelope: $\lambda = \frac{c \cdot f}{\sqrt{\epsilon_r}}$, so for $\epsilon_r=9$ (Alumina board)
 - 1 GHz ($\epsilon_r=9$): $\lambda=3 \cdot 10^8/3 \cdot 10^9=0.1$ m, $l < 10$ mm
 - 10 GHz ($\epsilon_r=9$): $\lambda=3 \cdot 10^8/3 \cdot 10^{10}=10$ mm, $l < 1$ mm
 - 30 GHz (free-space): $\lambda=3 \cdot 10^8/3 \cdot 10^{10}=10$ mm, $l < 1$ mm
 - 300 GHz (free-space): $\lambda=3 \cdot 10^8/3 \cdot 10^{11}=1$ mm, $l < .1$ mm
- ◆ Digital Applications (see Agilent TL Fundamentals):
 - Lumped only if $T_d < T_r$ ($T_r/2.5$) ("flight-time= L/v_p " along TL < rise (or fall) time digital signal (/2.5))
 - TL important if total series $R < 5 \cdot Z_0$, lossless if $R < Z_0/5$
 - Back-of-the-envelope:
 - 1.25 Gb/s backplane: $T_r \sim 250$ ps on board with $\epsilon_r=4$ ($v_p=3 \cdot 10^8/\sqrt{4}$ m/s or 150 mm/ns), so max. length 37.5 (15) mm
 - 4 GHz Pentium: $T_r \sim 100$ ps on low-K Si ($\epsilon_r=2.25$, $v_p=200$ mm/ns), so max. length 20 (8) mm
 - For clock, lumped approximation for analog case!

Field analysis of Transmission Lines



- ◆ Transmission line equations can also be derived from Maxwell equations – see 2.2
- ◆ Transmission line parameters from E and H fields

$$L = \frac{\mu}{|I_o|^2} \int_S \overline{H} \cdot \overline{H}^* ds \quad \text{H/m}$$

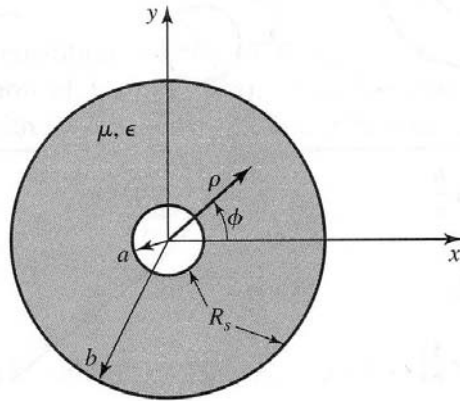
$$R = \frac{R_s}{|I_o|^2} \int_{C_1+C_2} \overline{H} \cdot \overline{H}^* dl \quad \Omega/\text{m}$$

$$C = \frac{\epsilon}{|V_o|^2} \int_S \overline{E} \cdot \overline{E}^* ds \quad \text{F/m}$$

$$G = \frac{\omega \epsilon''}{|V_o|^2} \int_S \overline{E} \cdot \overline{E}^* ds \quad \text{S/m}$$

More on physical transmission lines in Lecture 3

Field analysis of Transmission Lines (coax)



$$\bar{E} = \frac{V_o \hat{\rho}}{\rho \ln b/a} e^{-\gamma z},$$

$$\bar{H} = \frac{I_o \hat{\phi}}{2\pi \rho} e^{-\gamma z},$$

$$L = \frac{\mu}{(2\pi)^2} \int_{\phi=0}^{2\pi} \int_{\rho=a}^b \frac{1}{\rho^2} \rho d\rho d\phi = \frac{\mu}{2\pi} \ln b/a \quad \text{H/m},$$

$$C = \frac{\epsilon'}{(\ln b/a)^2} \int_{\phi=0}^{2\pi} \int_{\rho=a}^b \frac{1}{\rho^2} \rho d\rho d\phi = \frac{2\pi\epsilon'}{\ln b/a} \quad \text{F/m},$$

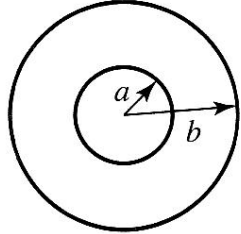
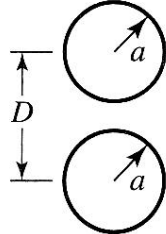
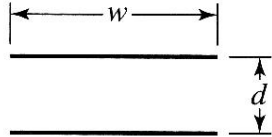
$$R = \frac{R_s}{(2\pi)^2} \left\{ \int_{\phi=0}^{2\pi} \frac{1}{a^2} a d\phi + \int_{\phi=0}^{2\pi} \frac{1}{b^2} b d\phi \right\} = \frac{R_s}{2\pi} \left(\frac{1}{a} + \frac{1}{b} \right) \quad \Omega/\text{m},$$

$$G = \frac{\omega\epsilon''}{(\ln b/a)^2} \int_{\phi=0}^{2\pi} \int_{\rho=a}^b \frac{1}{\rho^2} \rho d\rho d\phi = \frac{2\pi\omega\epsilon''}{\ln b/a} \quad \text{S/m}.$$



Parameters for some common lines

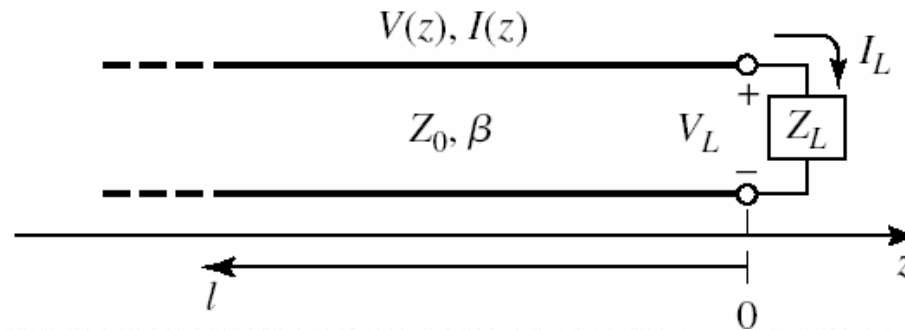
TABLE 2.1 Transmission Line Parameters for Some Common Lines

	COAX	TWO-WIRE	PARALLEL PLATE
			
L	$\frac{\mu}{2\pi} \ln \frac{b}{a}$	$\frac{\mu}{\pi} \cosh^{-1} \left(\frac{D}{2a} \right)$	$\frac{\mu d}{w}$
C	$\frac{2\pi\epsilon'}{\ln b/a}$	$\frac{\pi\epsilon'}{\cosh^{-1}(D/2a)}$	$\frac{\epsilon' w}{d}$
R	$\frac{R_s}{2\pi} \left(\frac{1}{a} + \frac{1}{b} \right)$	$\frac{R_s}{\pi a}$	$\frac{2R_s}{w}$
G	$\frac{2\pi\omega\epsilon''}{\ln b/a}$	$\frac{\pi\omega\epsilon''}{\cosh^{-1}(D/2a)}$	$\frac{\omega\epsilon'' w}{d}$

- R_s is the surface resistivity related with skin-depth δ_s
- permittivity $\epsilon = \epsilon' - j \epsilon'' = \epsilon' (1 - j \tan \delta)$ lossy dielectric fill
- permeability $\mu = \mu_0 \mu_r$

$$R_s = \frac{1}{\sigma \delta_s} = \sqrt{\frac{\omega \mu}{2 \sigma}}$$

Terminated **lossless** line



$$V(z) = V_o^+ e^{-j\beta z} + V_o^- e^{+j\beta z}$$

$$I(z) = \frac{V_o^+}{Z_0} e^{-j\beta z} - \frac{V_o^-}{Z_0} e^{+j\beta z}$$

At load: $Z_L = \frac{V(0)}{I(0)} = Z_0 \frac{V_o^+ + V_o^-}{V_o^+ - V_o^-}$

Solving for V_o^- :

$$V_o^- = \frac{Z_L - Z_0}{Z_L + Z_0} V_o^+$$

Voltage reflection coefficient Γ :

$$V(z) = V_o^+ \left[e^{-j\beta z} + \Gamma e^{+j\beta z} \right]$$

$$I(z) = \frac{V_o^+}{Z_0} \left[e^{-j\beta z} - \Gamma e^{+j\beta z} \right]$$

I and V superposition of Incident and reflected waves

$$\Gamma = \frac{V_o^-}{V_o^+} = \frac{Z_L - Z_0}{Z_L + Z_0}$$

$\Gamma=0$ if $Z_L = Z_0$ or load matched to line

Time-averaged power flow along TL

$$P_{av} = \frac{1}{2} \operatorname{Re} [V(z) I(z)^*] = \frac{1}{2} \frac{|V_o^+|^2}{Z_0} (1 - |\Gamma|^2)$$

\downarrow **Power delivered in load by TL** \downarrow **Incident power** \nwarrow **Reflected power**

For matched generator (no double reflections):

- Average power flow constant each point of line
- Total power in load = incident - reflected power
- $\Gamma=0$: maximum power delivered to load, $\Gamma=1$: no power

Fraction of incident power absorbed by load missing from signal returned to generator: **return loss (RL)**

$$RL = -20 \log |\Gamma| \text{ dB}$$

- Matched load ($|\Gamma|=0$): $RL = \infty$ dB
- Total reflection ($|\Gamma|=1$): $RL = 0$ dB

Voltage Standing Waves and VSWR

- ◆ Matched load ($|\Gamma|=0$) $\Rightarrow |V(z)| = |V_o^+|$ so constant
- ◆ For $|\Gamma| \neq 0 \Rightarrow$ standing waves ($|V(z)|$ not constant)

$$|V(z)| = \left| V_o^+ (e^{-j\beta z} + \Gamma e^{+j\beta z}) \right| = |V_o^+| (1 + |\Gamma| e^{j(\theta - 2\beta l)})$$

where $l = -z$ the positive distance away from load and θ is the phase of Γ ; $\Gamma = |\Gamma|e^{j\theta}$

- ◆ Voltage magnitude oscillates with z along line, maximum and minimum values when phase term $e^{j(\theta - 2\beta l)} = \pm 1$:

$$V_{\max, \min} = |V_o^+| (1 \pm |\Gamma|)$$

- ◆ Measure of mismatch of load is **standing wave ratio or voltage standing wave ratio**

$$SWR = VSWR = \frac{V_{\max}}{V_{\min}} = \frac{1 + |\Gamma|}{1 - |\Gamma|}$$

Standing Waves and Impedance

- ◆ $|V(z)| = |V_o^+| (1 + |\Gamma| e^{j(\theta - 2\beta l)})$ so distance between successive max. (or min.) is $\lambda/2$, distance between a max. and a min is $\lambda/4$
- ◆ In general Γ and Z_{in} varying with position along line:

$$\Gamma(l) = \frac{V_o^-}{V_o^+} e^{-2j\beta l} = \Gamma(0) e^{-2j\beta l} \quad \begin{aligned} V(z) &= V_o^+ [e^{-j\beta z} + \Gamma e^{+j\beta z}] \\ I(z) &= \frac{V_o^+}{Z_0} [e^{-j\beta z} - \Gamma e^{+j\beta z}] \end{aligned} \quad \Gamma = \frac{Z_L - Z_0}{Z_L + Z_0}$$

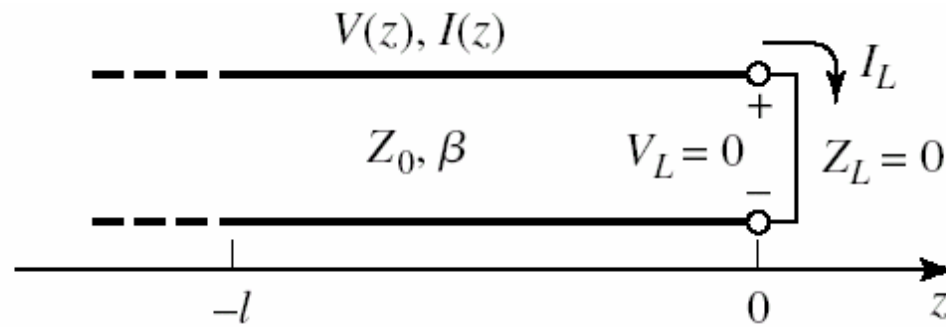
$$Z_{in} = \frac{V(-l)}{I(-l)} = Z_0 \frac{e^{j\beta l} + \Gamma e^{-j\beta l}}{e^{j\beta l} - \Gamma e^{-j\beta l}} = Z_0 \frac{1 + \Gamma e^{-2j\beta l}}{1 - \Gamma e^{-2j\beta l}} = Z_0 \frac{1 + \Gamma(l)}{1 - \Gamma(l)}$$

$$Z_{in} = Z_0 \frac{(Z_L + Z_0)e^{j\beta l} + (Z_L - Z_0)e^{-j\beta l}}{(Z_L + Z_0)e^{j\beta l} - (Z_L - Z_0)e^{-j\beta l}} = Z_0 \frac{Z_L \cos \beta l + jZ_0 \sin \beta l}{Z_0 \cos \beta l + jZ_L \sin \beta l}$$

$$Z_{in} = Z_0 \frac{Z_L + jZ_0 \tan \beta l}{Z_0 + jZ_L \tan \beta l}$$

Transmission line equation

Special terminations (1): short circuit



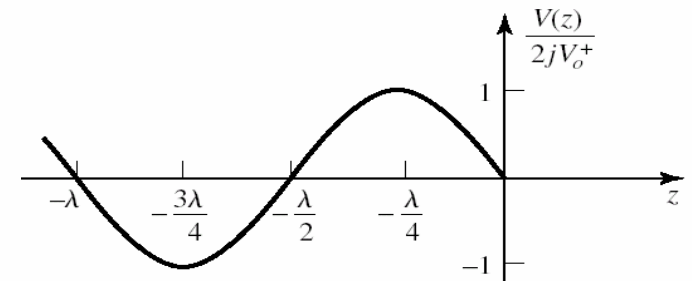
- if $Z_L=0$, then $\Gamma = -1$, so

$$V(z) = V_o^+ [e^{-j\beta z} - e^{+j\beta z}] = -2jV_o^+ \sin \beta z$$

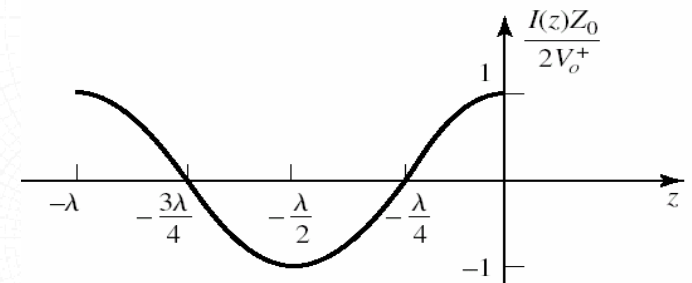
$$I(z) = \frac{V_o^+}{Z_0} [e^{-j\beta z} + e^{+j\beta z}] = \frac{2V_o^+}{Z_0} \cos \beta z$$

$$Z_{in} = \frac{V(-l)}{I(-l)} = jZ_0 \tan \beta l$$

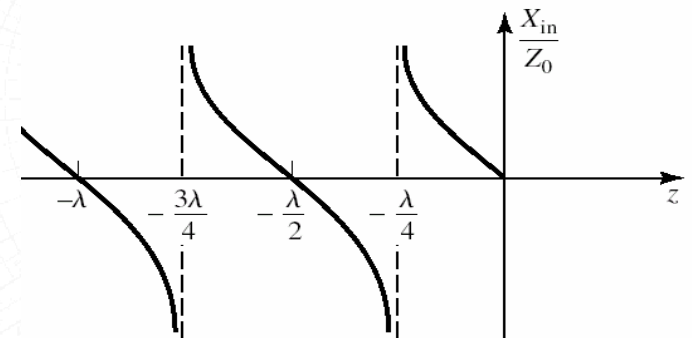
- So impedance purely imaginary
- For $l=0$: $Z_{in}=0$ but for $l=\lambda/4$: $Z_{in} = \infty$
- Impedance is periodic with $\lambda/2$



(a)

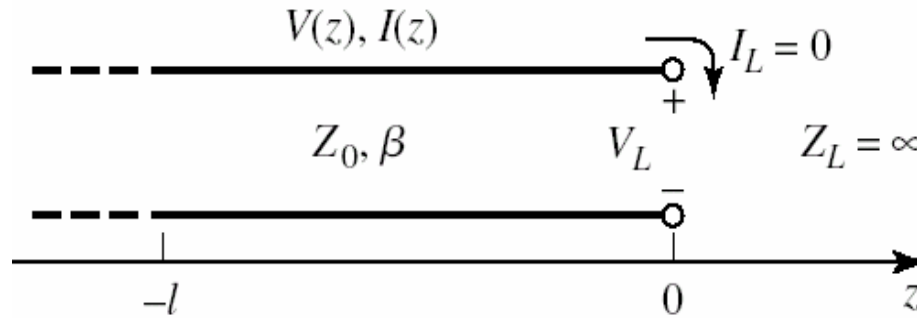


(b)



(c)

Special terminations (2): open circuit



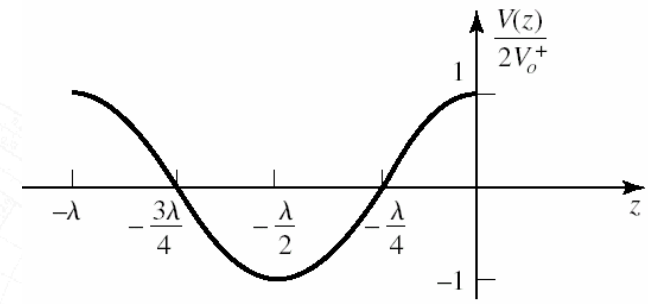
- if $Z_L = \infty$, then $\Gamma = +1$, so

$$V(z) = V_o^+ [e^{-j\beta z} + e^{+j\beta z}] = 2V_o^+ \cos \beta z$$

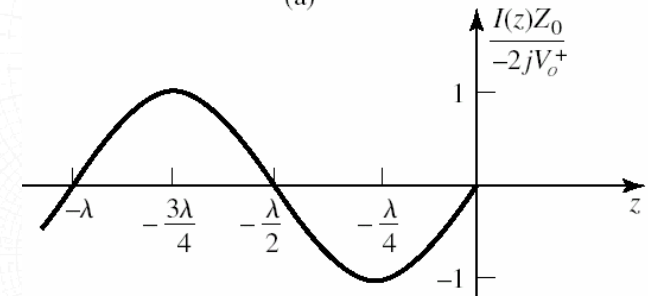
$$I(z) = \frac{V_o^+}{Z_0} [e^{-j\beta z} - e^{+j\beta z}] = -\frac{2jV_o^+}{Z_0} \sin \beta z$$

$$Z_{in} = \frac{V(-l)}{I(-l)} = -jZ_0 \cot \beta l$$

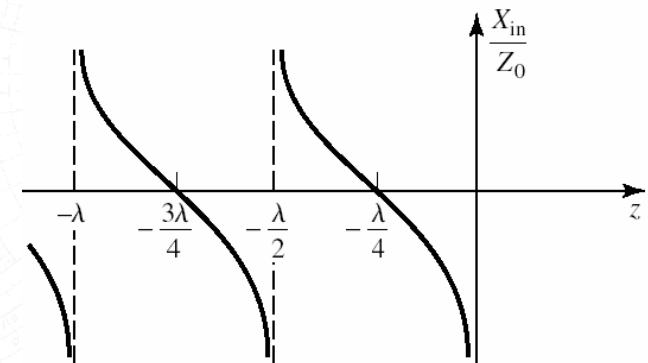
- So impedance purely imaginary
- For $l=0$: $Z_{in} = \infty$ but for $l=\lambda/4$: $Z_{in}=0$
- Impedance is periodic with $\lambda/2$



(a)



(b)



(c)

Special lengths of transmission line

- ♦ A half-wavelength line ($l=n\lambda/2$) does not alter or transform the load impedance, regardless of Z_0

$$Z_{in} = Z_0 \frac{Z_L + jZ_0 \tan \beta l}{Z_0 + jZ_L \tan \beta l} \Rightarrow Z_{in}(\lambda/2) = Z_L$$

- ♦ A quarter-wavelength line ($l=\lambda/4+n\lambda/2$) transforms the impedance, according to characteristic impedance of line

$$Z_{in} = Z_0 \frac{Z_L + jZ_0 \tan \beta l}{Z_0 + jZ_L \tan \beta l} = \frac{Z_0^2}{Z_L}$$

- ♦ This is called quarter-wave transformer, to be studied more in detail next lecture (2.5)

Termination with matched transmission line

- Line with characteristic impedance Z_0 feeds line with characteristic impedance Z_1 , if this TL is infinitely long or terminated with Z_1 , then $Z_L = Z_1$, so

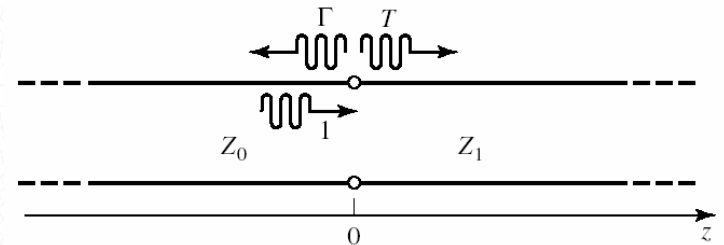
$$\Gamma = \frac{Z_1 - Z_0}{Z_1 + Z_0}$$

- Not all incident wave reflected, part transmitted onto line 2 with voltage amplitude T

$$V(z) = V_o^+ \left[e^{-j\beta z} + \Gamma e^{+j\beta z} \right], \quad z < 0$$

$$V(z) = V_o^+ T e^{-j\beta z}, \quad z > 0$$

Equating both at $z=0$ gives $T = 1 + \Gamma = 1 + \frac{Z_1 - Z_0}{Z_1 + Z_0} = \frac{2Z_1}{Z_1 + Z_0}$



- Transmission coefficient expressed as **insertion loss**

$$IL = -20 \log |T| \text{ dB}$$

Recap & next lecture

- ◆ In this lecture, we reviewed fundamental properties of transmission lines:
 - TL's support two waves (traveling in positive and negative direction)
 - Relation voltage & current for each of these waves: characteristic line impedance Z_0
 - Relation voltage incoming & reflected wave: voltage reflection coefficient Γ
 - Total voltage (current) on line is sum (difference) of both waves
 - Due to changing phase difference between waves both current and voltage and impedance will change along direction of line when moving away from load, will result in voltage standing waves
- ◆ Is explained intuitively in the Agilent TL Fundamentals Course (see link website), will take brief look next lecture, please review this program!
- ◆ Next lecture we will study the Smith Chart, quarterwave-length transformers (also from multiple reflection point), transient on TL's, etc...