

```

1 html"""<style>
2 main {
3     margin: 0 auto;
4     max-width: 90%;
5     padding-left: max(50px, 1%);
6     padding-right: max(253px, 10%);
7     # 253px to accomodate TableOfContents(aside=true)
8 }
9 """

```

```

1 begin
2     using Markdown
3     using InteractiveUtils
4     using Pkg, DrWatson, PlutoUI
5 end

```

TaskLocalRNG()

```

1 begin
2     using Distributions
3     using FillArrays
4     using StatsPlots
5
6     using LinearAlgebra
7     using Random
8     using Turing
9
10    # Import all libraries.
11    using DataFrames
12    #DirichletProcess, ChineseRestaurantProcess,
13    StickBreakingProcess
14    using Turing.RandomMeasures
15    # DocStringExtensions provides $(SIGNATURES)
16    using DocStringExtensions
17    # Set a random seed.
18    Random.seed!(3)
end

```

```

1 using DynamicPPL, Printf

```

```

1 using Plots
2 # Plot the cluster assignments over time

```

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```

1 begin
2     PlutoUI.TableOfContents()
3 end

```

1 `versioninfo()`

```
Julia Version 1.10.2
Commit bd47eca2c8a (2024-03-01 10:14 UTC)
Build Info:
  Official https://julialang.org/ release
Platform Info:
  OS: Linux (x86_64-linux-gnu)
  CPU: 32 × Intel(R) Xeon(R) CPU E5-2630 v3 @ 2.40GHz
  WORD_SIZE: 64
  LIBM: libopenlibm
  LLVM: libLLVM-15.0.7 (ORCJIT, haswell)
Threads: 16 default, 0 interactive, 8 GC (on 32 virtual cores)
Environment:
  JULIA_PKG_SERVER = https://mirrors.tuna.tsinghua.edu.cn/julia
  JULIA_REVISE_WORKER_ONLY = 1
```

# Mixture models

---

- <https://turinglang.org/dev/tutorials/o6-infinite-mixture-model/>

# 1 Two-component mixture model.

---

- Check Gaussian mixture.jl or .ipynb for more.

two\_comp\_mixture (generic function with 2 methods)

```
1 @model function two_comp_mixture(x)
2   # Hyper-parameters
3    $\mu_0 = 0.0$ 
4    $\sigma_0 = 1.0$ 
5
6   # Draw weights.
7    $\pi_1 \sim \text{Beta}(1, 1)$ 
8    $\pi_2 = 1 - \pi_1$ 
9
10  # Draw locations of the components.
11   $\mu_1 \sim \text{Normal}(\mu_0, \sigma_0)$ 
12   $\mu_2 \sim \text{Normal}(\mu_0, \sigma_0)$ 
13
14  # Draw latent assignment.
15   $z \sim \text{Categorical}([\pi_1, \pi_2])$ 
16
17  # Draw observation from selected component.
18  if  $z == 1$ 
19     $x \sim \text{Normal}(\mu_1, \sigma_0)$ 
20  else
21     $x \sim \text{Normal}(\mu_2, \sigma_0)$ 
22  end
23 end
```

## 2 Finite Mixture Model

If we have more than two components, this model can elegantly be extended using a Dirichlet distribution as prior for the mixing weights,  $\pi_1, \dots, \pi_K$ . Note that the Dirichlet distribution is the multivariate generalization of the beta distribution. The resulting model can be written as:

$$(\pi_1, \dots, \pi_K) \sim \text{Dirichlet}(K, \alpha)$$

$$\mu_k \sim \text{Normal}(\mu_0, \Sigma_0), \forall k$$

$$z \sim \text{Categorical}(\pi_1, \dots, \pi_K)$$

$$x \sim \text{Normal}(\mu_z, \Sigma)$$

which resembles the model in the [Gaussian mixture model tutorial](#) with a slightly different notation.

```
1 md"# 2 Finite Mixture Model
2
3 If we have more than two components, this model can
  elegantly be extended using a Dirichlet distribution as
  prior for the mixing weights,  $\pi_1, \dots, \pi_K$ . Note
  that the Dirichlet distribution is the multivariate
4 generalization of the beta distribution. The resulting
5 model can be written as:
6
7  $(\pi_1, \dots, \pi_K) \sim \text{Dirichlet}(K, \alpha)$ 
8
9  $\mu_k \sim \text{Normal}(\mu_0, \Sigma_0), \forall k$ 
10
11  $z \sim \text{Categorical}(\pi_1, \dots, \pi_K)$ 
12
13  $x \sim \text{Normal}(\mu_z, \Sigma)$ 
```

which resembles the model in the [Gaussian mixture model tutorial](https://turinglang.org/stable/tutorials/01-gaussian-mixture-model/) with a slightly different notation."

# 3 Infinite Mixture Model

The question now arises, is there a generalization of a Dirichlet distribution for which the dimensionality is infinite, i.e.  $K = \infty$ ?

But first, to implement an infinite Gaussian mixture model in Turing, we first need to load the `Turing.RandomMeasures` module.

`RandomMeasures` contains a variety of tools useful in nonparametrics.

```
1 md"# 3 Infinite Mixture Model
2
3 The question now arises, is there a generalization of a
  Dirichlet distribution for which the dimensionality is
4 infinite, i.e.  $K=\infty$ ?
5
  But first, to implement an infinite Gaussian mixture model
  in Turing, we first need to load the
  `Turing.RandomMeasures` module. RandomMeasures contains a
  variety of tools useful in nonparametrics."
```

We utilize the fact that one can integrate out the mixing weights in a Gaussian mixture model allowing us to arrive at the Chinese restaurant process construction. See Carl E. Rasmussen: The Infinite Gaussian Mixture Model, NIPS (2000) for details.

In fact, if the mixing weights are integrated out, the conditional prior for the latent variable is given by:

$$p(z_i = k | z_{-i}, \alpha) = \frac{n_k + \alpha K}{N - 1 + \alpha}$$

where  $z_{-i}$  are the latent assignments of all observations except observation  $i$ . Note that we use  $n_k$  to denote the number of observations at component  $k$  excluding observation  $i$ . The parameter  $\alpha$  is the concentration parameter of the Dirichlet distribution used as prior over the mixing weights.

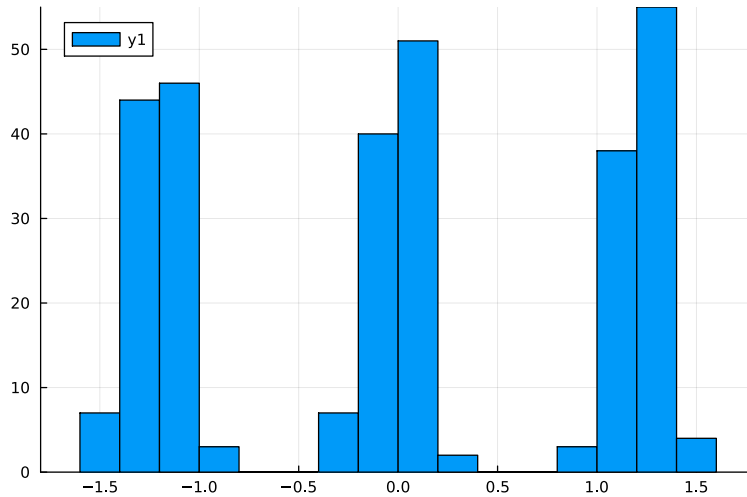
```
1 md"We utilize the fact that one can integrate out the
  mixing weights in a Gaussian mixture model allowing us to
  arrive at the Chinese restaurant process construction. See
2 Carl E. Rasmussen: The Infinite Gaussian Mixture Model,
3 NIPS (2000) for details.

4 In fact, if the mixing weights are integrated out, the
5 conditional prior for the latent variable is given by:
6
7  $p(z_i=k | z_{-\neg i}, \alpha) = \frac{n_k + \alpha K}{N - 1$ 
8  $+ \alpha$ 
```

where  $z_{-i}$  are the latent assignments of all observations except observation  $i$ . Note that we use  $n_k$  to denote the number of observations at component  $k$  excluding observation  $i$ . The parameter  $\alpha$  is the concentration parameter of the Dirichlet distribution used as prior over the mixing weights."

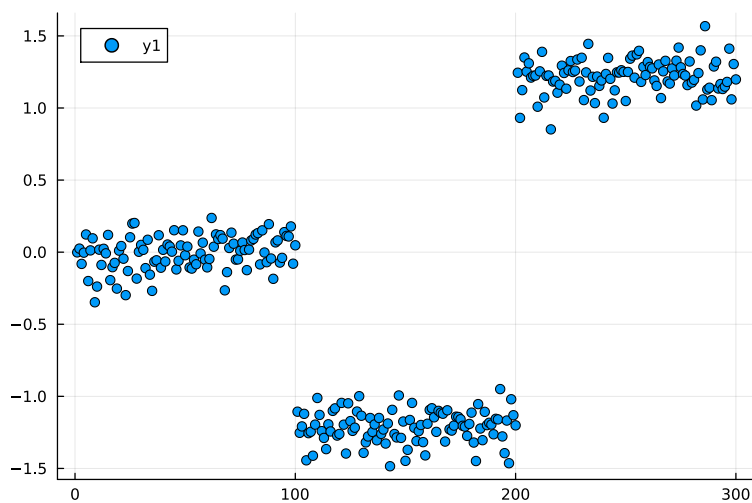
## 3.0 Simulate a 3-cluster Gaussian mixture data

We simulate/create some random data that comes from three clusters, with means of 0, -10, and 10, which is a bit easier than to infer 0, -5, 10.



```
1 begin
2     # Generate some test data.
3     Random.seed!(1)
4     # cluster size
5     csize=100
6     data_gmm = vcat(randn(csize), randn(csize) .- 10,
7                     randn(csize) .+ 10)
8     @show size(data_gmm)
9     @show mean(data_gmm)
10    # normalize data
11    data_gmm ./= mean(data_gmm)
12    data_gmm /= std(data_gmm);
13    # draw histogram
14    histogram(data_gmm, bins=20)
end
```

```
size(data_gmm) = (300,)
mean(data_gmm) = 0.07469478561903005
```



```
1 # plot 3 clusters of simulated data
2 scatter(1:csize*3, data_gmm)
```

```
view(::Vector{Int64}, 201:300): [3, 3, 3, 3, 3, 3, 3, 3, 3, 3, 3,
```

```
1 begin
2     z_truth_vec = ones{Int, csize*3};
3     z_truth_vec[101:200] .= 2
4     z_truth_vec[201:300] .= 3
5 end
```

## 3.1 Chinese Restaurant Process

To obtain the Chinese restaurant process construction, we can now derive the conditional prior if  $K \rightarrow \infty$ .

For  $n_k > 0$ , we obtain:

$$p(z_i = k | z_{-i}, \alpha) = \frac{n_k}{N - 1 + \alpha}$$

and for all infinitely many clusters that are empty (combined) we get:

$$p(z_i = k | z_{-i}, \alpha) = \frac{\alpha}{N - 1 + \alpha}$$

Those equations show that the conditional prior for component assignments is proportional to the number of such observations, meaning that the Chinese restaurant process has a rich get richer property.

To get a better understanding of this property, we can plot the cluster chosen by for each new observation drawn from the conditional prior.

Turing.RandomMeasures

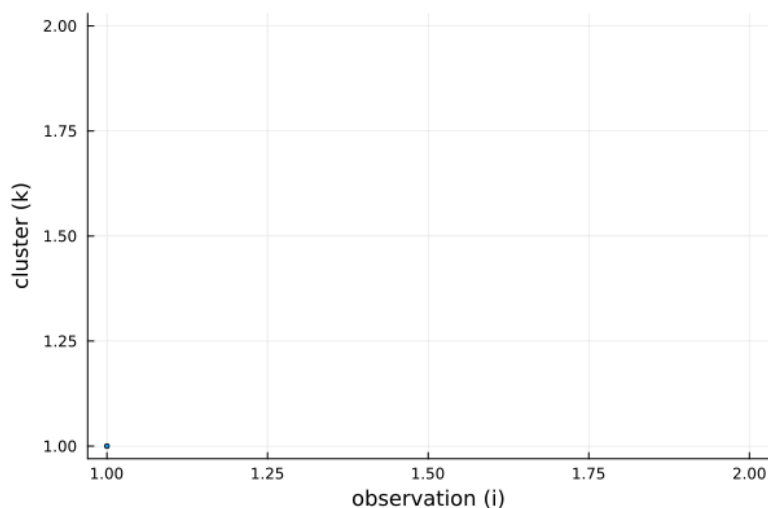
```
1 begin
2     @show parentmodule(DirichletProcess)
3     @show parentmodule(ChineseRestaurantProcess)
4     @show parentmodule(StickBreakingProcess)
5 end
```

```
parentmodule(DirichletProcess) = Turing.RandomMeasures
parentmodule(ChineseRestaurantProcess) = Turing.RandomMeasures
parentmodule(StickBreakingProcess) = Turing.RandomMeasures
```



### 3.1.1 Visualize the cluster growth given the growing data points

```
1 begin
2   # Concentration parameter.
3    $\alpha$  = 1.0
4
5   # Random measure, e.g. Dirichlet process.
6   rpm = DirichletProcess( $\alpha$ )
7
8   # Cluster assignments for each observation.
9   z = Vector{Int}{}
10
11  # Maximum number of observations we observe.
12  Nmax = 500
13
14  for i in 1:Nmax
15    # Number of observations per cluster.
16    K = isempty(z) ? 0 : maximum(z)
17    nk = Vector{Int}(map(k -> sum(z .== k), 1:K))
18
19    # Draw new assignment.
20    push!(z, rand(ChineseRestaurantProcess(rpm, nk)))
21  end
22 end
```



```
1 @gif for i in 1:Nmax
2   scatter(
3     collect(1:i),
4     z[1:i];
5     markersize=2,
6     xlabel="observation (i)",
7     ylabel="cluster (k)",
8     legend=false,
9   )
10 end
```

Saved animation to /tmp/jl\_rK7SnUxGny.gif

[121, 220, 144, 8, 4, 3]

```
1 begin
2   # number of samples in each cluster
3   no_of_clusters = maximum(z)
4   nk=Vector{Int}(map(k -> sum(z .==k), 1:no_of_clusters ))
5 end
```

1

```
1 rand(ChineseRestaurantProcess(rpm, nk))
```

Further, we can see that the number of clusters is logarithmic in the number of observations and data points. This is a side-effect of the rich-get-richer phenomenon, i.e. we expect large clusters and thus the number of clusters has to be smaller than the number of observations.

$$E[K|N] \approx \alpha * \log(1 + \frac{N}{\alpha})$$

We can see from the equation that the concentration parameter  $\alpha$  allows us to control the number of clusters formed *a priori*.

In Turing we can implement an infinite Gaussian mixture model using the Chinese restaurant process construction of a Dirichlet process as follows:

### 3.1.2 CRP on a 3-cluster-Gaussian-Mixture-generated data

```
1 md"### 3.1.2 CRP on a 3-cluster-Gaussian-Mixture-generated data"
```

infiniteGMM (generic function with 4 methods)

```
1 @model function infiniteGMM(x, warn=true)
2   # Hyper-parameters, i.e. concentration parameter and
3   parameters of H.
4    $\alpha$  = 0.5 # the smaller  $\alpha$  is, the less clusters a priori.
5    $\mu_0$  = 0.0 #  $\mu$  of Prior to draw Gaussian cluster mean
6    $\sigma_0$  = 1.0 #  $\sigma$  of Prior to draw Gaussian cluster mean
7    $\sigma_1$  = 1.0 #  $\sigma$  for each Gaussian cluster
8
9   # Define random measure, e.g. Dirichlet process.
10  rpm = DirichletProcess( $\alpha$ )
11
12  # The base distribution, to draw the mean value of all
13  Gaussian distributions in the Dirichlet process.
14  H = Normal( $\mu_0$ ,  $\sigma_0$ )
15
16  # Latent assignment.
17  z = zeros(Int, length(x)) # tzeros() = zeros()
18
19  # Locations of the infinitely many Gaussian clusters.
20   $\mu$  = zeros(Float64, 0)
21  # Number of clusters.
22  K = 0
23
24  for i in 1:length(x)
25    # Number of clusters.
26    #K = maximum(z)
27    nk = Vector{Int}(map(k -> sum(z .== k), 1:K))
28
29    # Draw the latent assignment.
30    z[i] ~ ChineseRestaurantProcess(rpm, nk)
31
32    # Create a new cluster?
33    if z[i] > K
34      K += 1
35      push!( $\mu$ , 0.0)
36
37      # Draw location of new cluster.
38       $\mu$ [z[i]] ~ H
39    end
40
41    # An observation that follows this distribution
42    x[i] ~ Normal( $\mu$ [z[i]],  $\sigma_1$ )
43  end
44 end
```

[0, 0, 0]

```
1 # test: tzeros() seems to be identical to zeros(). not sure
2 why the original example uses tzeros()
   tzeros(Int, 3)
```

We can now use Turing to infer the assignments of some data points.

	iteration	chain	z[1]	z[2]	z[3]	z[4]	
1	1	1	1.0	1.0	1.0	1.0	1
2	2	1	1.0	1.0	1.0	1.0	1
3	3	1	1.0	1.0	1.0	1.0	1
4	4	1	1.0	1.0	1.0	1.0	1
5	5	1	1.0	1.0	1.0	1.0	1
6	6	1	1.0	1.0	1.0	1.0	1
7	7	1	1.0	1.0	1.0	1.0	1
8	8	1	1.0	1.0	1.0	1.0	1
9	9	1	1.0	1.0	1.0	1.0	1
10	10	1	1.0	1.0	1.0	1.0	1
more							

```
1 begin
2   # Fit InfiniteGMM (CRP-based) model to the simulated
3   data above
4   Random.seed!(2)
5   # compile the model
6   @time model_infini_GMM_CRP = infiniteGMM(data_gmm);
7   # sample 1500 iterations via the Sequential Monte Carlo
8   sampler.
9   @time chain_infini_GMM_CRP =
10    sample(model_infini_GMM_CRP, SMC(), 1500);
11 end
```

100%

0.000000 seconds  
55.146279 seconds (86.20 M allocations: 11.144 GiB,  
5.93% gc time)

	iteration	chain	z[1]	z[2]	z[3]	z[4]	
1	1496	1	1.0	1.0	1.0	1.0	1.0
2	1497	1	1.0	1.0	1.0	1.0	1.0
3	1498	1	1.0	1.0	1.0	1.0	1.0
4	1499	1	1.0	1.0	1.0	1.0	1.0
5	1500	1	1.0	1.0	1.0	1.0	1.0

```
1 begin
2   # turn the MCMC chains/estimates into a dataframe
3   @time chain_infini_GMM_CRP_DF =
4   DataFrame(chain_infini_GMM_CRP)
5   #@show first(chain_infini_GMM_CRP_DF,5)
6   last(chain_infini_GMM_CRP_DF, 5)
7 end
```

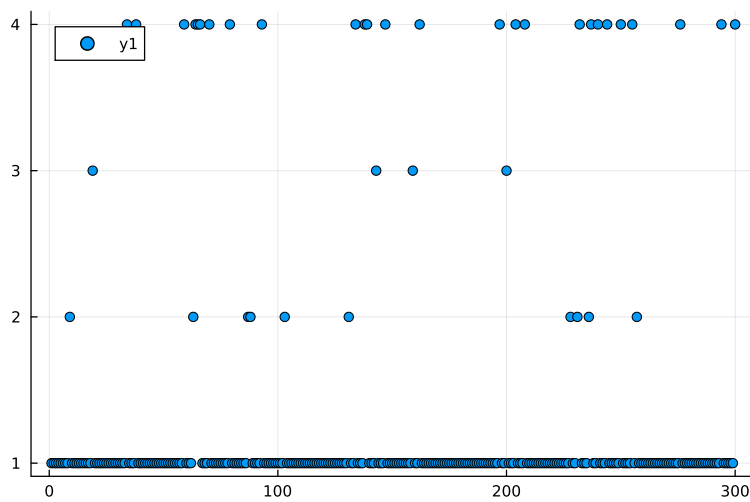
0.007099 seconds (4.65 k allocations: 8.340 MiB)

```
["iteration", "chain", "z[1]", "z[2]", "z[3]", "z[4]", "z[5]", "z[6]", "z[7]", "z[8]", "z[9]", "z[10]"]
```

```
1 names(chain_infini_GMM_CRP_DF)
```

```
(1500, 310)
```

```
1 size(chain_infini_GMM_CRP_DF)
```



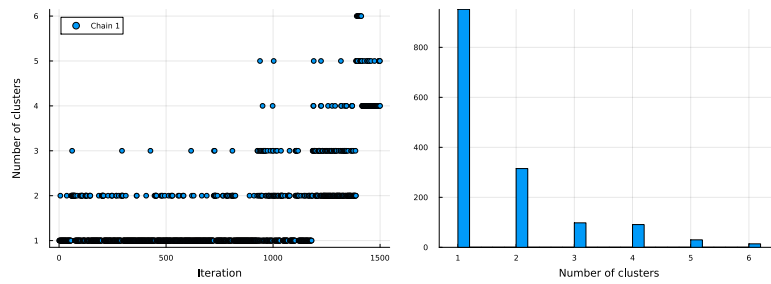
```
1 begin
2   #plot the estimated z (cluster membership) vs data
3   index (do not look good)
4   z_estimated = vec(chain_infini_GMM_CRP[1500,
5   MCMCChains.namesingroup(chain_infini_GMM_CRP,
6   :z),:].value)
7   scatter(1:size*3, z_estimated)
8 end
```

```
[1.0, 2.0, 3.0, 4.0]
```

```
1 # return the unique clusters discovered by infini_GMM_CRP
2 unique(z_estimated)
```

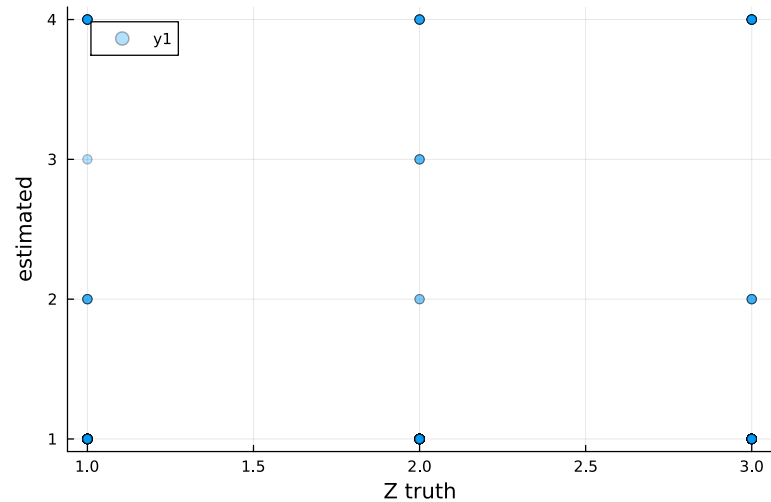
```
draw_cluster_no_in_chain (generic function with 1 method)
```

```
1 function draw_cluster_no_in_chain(chain; burnin_iter=1,
2 iterations=1000)
3   # Extract the number of clusters for each sample of the
4   Markov chain.
5   K = map(
6     t -> length(unique(vec(chain[t,
7   MCMCChains.namesingroup(chain, :z), :].value))),
8     burnin_iter:iterations,
9   );
10
11   # Visualize the number of clusters.
12   s_of_K = scatter(burnin_iter:iterations, K;
13   xlabel="Iteration",
14   ylabel="Number of clusters", label="Chain 1")
15   h_of_K = histogram(K; xlabel="Number of clusters",
16   legend=false)
17
18   plot(s_of_K, h_of_K, layout=(1,2),
19   left_margin=5*Plots.mm,
20   bottom_margin=5*Plots.mm, size=(1200,430) )
21 end
```



```
1 @time draw_cluster_no_in_chain(chain_infini_GMM_CRP;
  burnin_iter=1, iterations=1500)
```

```
0.322596 seconds (2.85 M allocations: 190.556 MiB, 14.13% gc time) ?
```



```
1 scatter(z_truth_vec , z_estimated, alpha=0.3, xlab="Z
  truth", ylab="estimated")
```

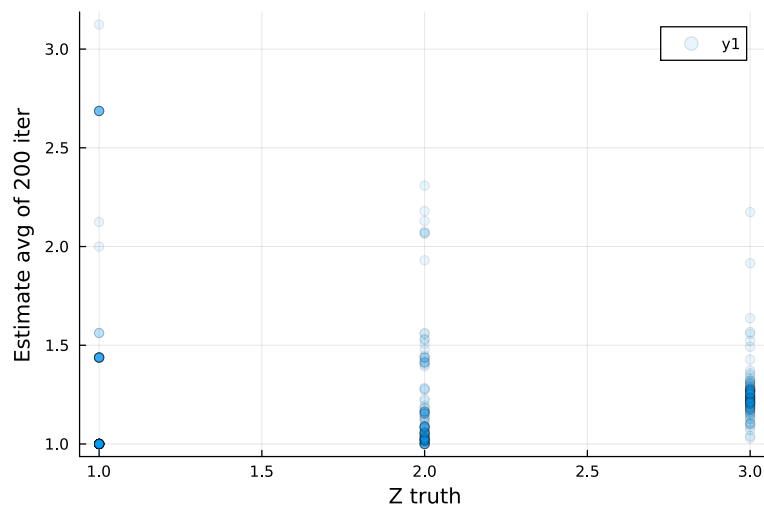
```
201×300 Matrix{Float64}:
 1.0  1.0  1.0  1.0  1.0  1.0  1.0  1.0  ...  1.0  1.0  1.0  1.0  1
 1.0  1.0  1.0  1.0  1.0  1.0  1.0  1.0  ...  1.0  1.0  1.0  1.0  1
 1.0  1.0  1.0  1.0  1.0  1.0  1.0  1.0  ...  1.0  1.0  2.0  1.0  1
 1.0  1.0  1.0  1.0  1.0  1.0  1.0  1.0  ...  2.0  2.0  1.0  1.0  1
 1.0  1.0  1.0  1.0  1.0  1.0  1.0  1.0  ...  1.0  1.0  2.0  1.0  1
 1.0  1.0  1.0  1.0  1.0  1.0  1.0  1.0  ...  1.0  1.0  1.0  1.0  1
 1.0  1.0  1.0  1.0  1.0  1.0  1.0  1.0  ...  1.0  1.0  1.0  2.0  1
 ⋮
 1.0  1.0  1.0  1.0  1.0  1.0  1.0  1.0  ...  1.0  2.0  3.0  1.0  1
 1.0  1.0  1.0  1.0  1.0  1.0  1.0  1.0  ...  1.0  1.0  1.0  1.0  1
 1.0  1.0  1.0  1.0  1.0  1.0  1.0  1.0  ...  1.0  1.0  1.0  1.0  4
 1.0  1.0  1.0  1.0  1.0  1.0  1.0  1.0  ...  1.0  1.0  4.0  4.0  1
 1.0  1.0  1.0  1.0  1.0  1.0  1.0  1.0  ...  1.0  1.0  1.0  4.0  1
 1.0  1.0  1.0  1.0  1.0  1.0  1.0  1.0  ...  1.0  4.0  1.0  1.0  1
```

```
1 begin
2
3     z_estimate_chain_value =
4     Array(chain_infini_GMM_CRP[1300:1500,
5     MCMCChains.namesingroup(chain_infini_GMM_CRP, :z),:])
6     z_estimate_ar = reshape(z_estimate_chain_value, (201,
7     300))
8 end
```

```
@time z_estimate_avg =
  [1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.0, 1.56219, 1.0, 1.0, 1.0,
```

```
1 @time z_estimate_avg = mean.(eachcol(z_estimate_ar))
```

```
0.000102 seconds (3 allocations: 2.562 KiB) ?
```



```
1 scatter(z_truth_vec , z_estimate_avg, alpha=0.1, xlab="Z
truth", ylab="Estimate avg of 200 iter")
```

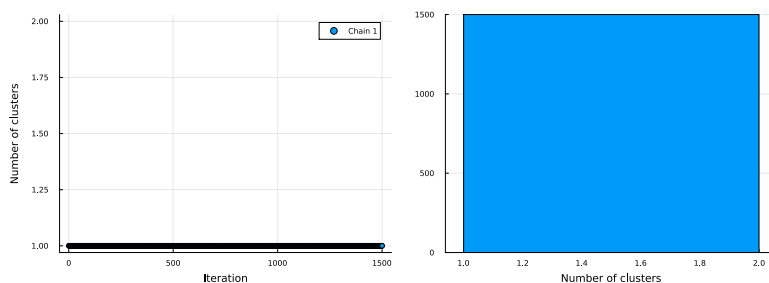
### 3.1.3 Use a PG+HMC Gibbs sampler

```
1 md"### 3.1.3 Use a PG+HMC Gibbs sampler"
```

```
1 # k, μ, w are all mapped into the sampler?
2 @time chain_infini_GMM_CRP_via_Gibbs =
  sample(model_infini_GMM_CRP, Gibbs(PG(100, :z), HMC(0.05,
10, :μ)), 1500);
```

100%

4348.623424 seconds (6.72 G allocations: 722.361 Gi B, 3.47% gc time, 0.19% compilation time) ?



```
1 @time
draw_cluster_no_in_chain(chain_infini_GMM_CRP_via_Gibbs;
burnin_iter=1, iterations=1500)
```

0.549389 seconds (2.87 M allocations: 191.821 Mi B, 34.84% gc time, 16.57% compilation time) ?

## 3.2 Stick-breaking process

$$\beta_k \sim \text{Beta}(1, \alpha)$$

$$\pi_k = \beta_k \prod_{l=1}^{k-1} (1 - \beta_l)$$

$$\theta_k^* \sim H$$

$$G = \sum_{k=1}^{\infty} \pi_k \delta_{\theta_k^*}$$

- no further testing.

## 3.3 Size biased sampling

### infiniteGMM\_size\_biased

Arguments:

- x: 1D data.
- rpm: is a Random process measure. e.g. Dirichlet process.

```
rpm = DirichletProcess(0.5)
```

- Hyper-parameters, i.e. concentration parameter and parameters of H.

```
1
2 """
3 $(SIGNATURES)
4 Arguments:
5 - x: 1D data.
6 - rpm: is a Random process measure. e.g. Dirichlet process.
7
8 ```julia
9 rpm = DirichletProcess(0.5)
10 ```
11
12 - Hyper-parameters, i.e. concentration parameter and
13 parameters of H.
14
15 """
16 @model function infiniteGMM_size_biased(x, rpm)
17     # The base distribution, to draw the mean value of all
18     # Gaussian distributions in the Dirichlet process.
19     H = Normal(0.0, 2)
20
21     N = length(x)
22     # Latent assignment.
23     z = zeros{Int, N} #was tzeros()
24
25     # Locations of the infinitely many clusters.
26     μ = zeros{Float64, 0}
27
28     # probability weights for each class
29     J = zeros{Float64, N}
30
31     K = 0
32     surplus=1.0
33     for i in 1:N
34         ps = vcat(J[1:K], surplus)
35         z[i] ~ Categorical(ps)
36
37         # Create a new cluster?
38         if z[i] > K
39             K += 1
40             push!(μ, 0.0)
41             # Assign a weight
42             J[K] ~ SizeBiasedSamplingProcess(rpm, surplus)
43             μ[K] ~ H
44             surplus -= J[K]
45         end
46
47         # An observation that follows this distribution
48         x[i] ~ Normal(μ[z[i]], 1)
49     end
50 end
```

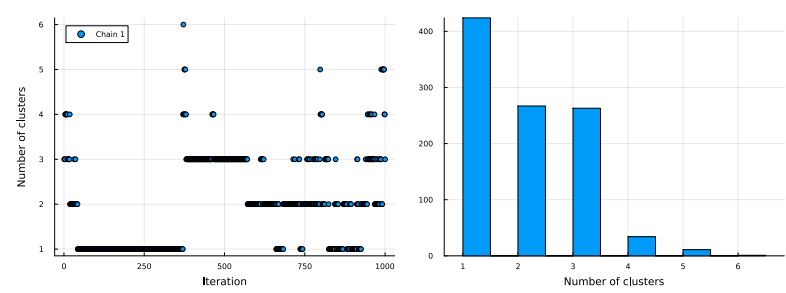


	iteration	chain	z[1]	z[2]	z[3]	z[4]	
1	1	1	1.0	1.0	1.0	1.0	1
2	2	1	1.0	1.0	1.0	1.0	1
3	3	1	1.0	1.0	1.0	1.0	1
4	4	1	1.0	1.0	1.0	1.0	1
5	5	1	1.0	1.0	1.0	1.0	1
6	6	1	1.0	1.0	1.0	1.0	1
7	7	1	1.0	1.0	1.0	1.0	1
8	8	1	1.0	1.0	1.0	1.0	1
9	9	1	1.0	1.0	1.0	1.0	1
10	10	1	1.0	1.0	1.0	1.0	1
more							

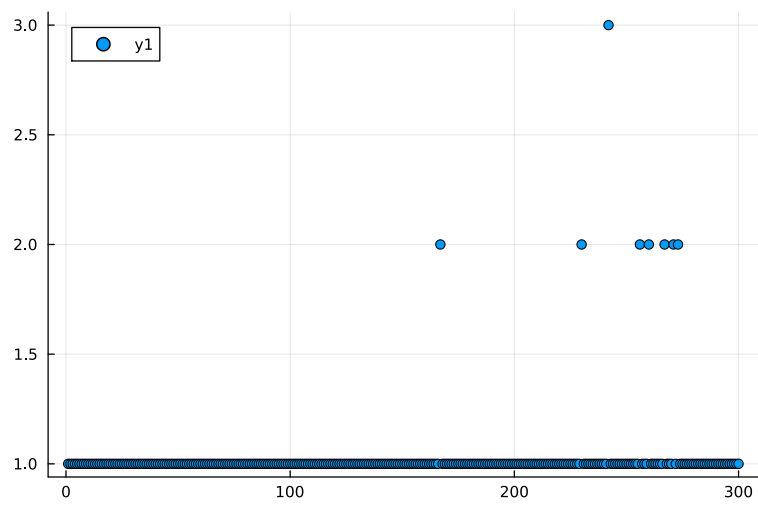
```
1 begin
2   # Fit the simulated GMM data with an size_biased
3   infinite GMM
4   Random.seed!(2)
5   @time model_size_biased =
6   infiniteGMM_size_biased(data_gmm,
7   DirichletProcess(0.5));
8   # MCMC via Sequential Monte Carlo
9   @time chain_infini_GMM_size_biased =
10  sample(model_size_biased, SMC(), 1000);
11 end
```

100%

0.000000 seconds  
31.720661 seconds (52.98 M allocations: 5.094 GiB, 5.28% gc time)



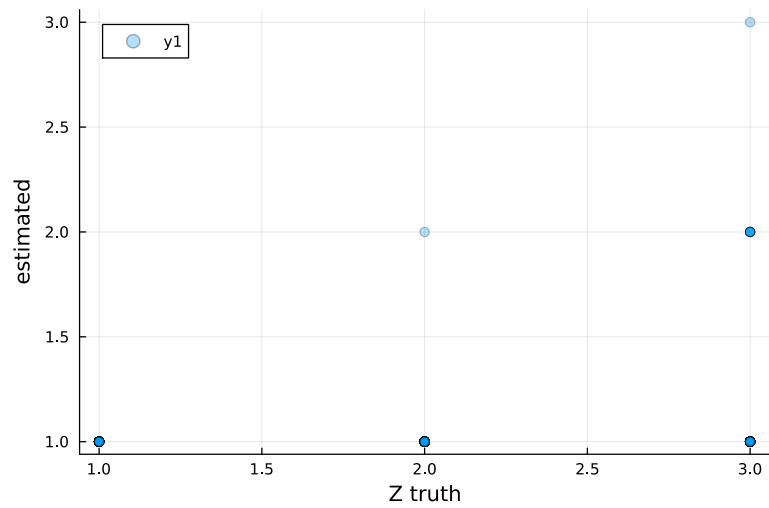
```
1 draw_cluster_no_in_chain(chain_infini_GMM_size_biased)
```



```

1 begin
2   z_estimated_2 = vec(chain_infini_GMM_size_biased[1000,
3     MCMCChains.namesingroup(chain_infini_GMM_size_biased,
4       :z),:].value)
5   scatter(1:300, z_estimated_2)
6 end

```



```

1 scatter(z_truth_vec , z_estimated_2, alpha=0.3, xlab="Z
2 truth", ylab="estimated")

```

1 Enter cell code...

# Conclusions

---

- The infinite mixture models did not fit well.

```
1 md"# Conclusions
2
3 - The infinite mixture models did not fit well."
```