vec, inversevec, diag, svd from linearalgebra

## ElementSets from MeshConnectivity

NeighborVerticesInFace, Faces, VertexOneRing, OrientedVertices from Neighborhoods(M)

$$\begin{split} &M\colon \text{TriangleMesh}\\ &\bar{x}_i\in\mathbb{R}^3\text{ rest pos in 3D}\\ &x_i\in\mathbb{R}^2\text{ current pos in 2D}\\ &\varepsilon\in\mathbb{R}\text{ eps}\\ &psd:\mathbb{R}^{p\times p}\to\mathbb{R}^{p\times p},\text{ sparse} \\ \\ &V,E,F=ElementSets(M)\\ &mr(f)=\left[br-ar\ cr-ar\right]\\ &\text{where}\\ &f\in F\\ &a,b,c=OrientedVertices(f)\\ &n=(\bar{x}_b-\bar{x}_a)\times(\bar{x}_c-\bar{x}_a)\\ &b1=\frac{\bar{x}_b-\bar{x}_a}{\|\bar{x}_b-\bar{x}_a\|}\\ &b2=\frac{\bar{n}\times b1}{\|n\times b1\|}\\ &ar=\begin{pmatrix}0\\0\end{pmatrix}\\ &br=\begin{pmatrix}(\bar{x}_b-\bar{x}_a)\cdot b1\\(\bar{x}_c-\bar{x}_a)\cdot b1\end{pmatrix}\\ &cr=\begin{pmatrix}(\bar{x}_c-\bar{x}_a)\cdot b1\\(\bar{x}_c-\bar{x}_a)\cdot b2\end{pmatrix}\\ &S(f,x)=\begin{cases}\infty &\text{if }|m|<=0\\A\left(\|\mathcal{J}\|^2+\|\mathcal{J}^{-1}\|^2\right)&\text{otherwise}\\ &\text{where}\\ &f\in F\\ &x_i\in\mathbb{R}^2\\ &a,b,c=OrientedVertices(f)\\ &m=[x_b-x_a\ x_c-x_a]\\ &A=\frac{1}{2}\ |mr(f)|\\ &\mathcal{J}=m\ mr(f)^{-1}\\ &e=\sum_{i\in F}S(i,x)\\ &H=\sum_{i\in F}psd\left(\frac{\partial^2S(i,x)}{\partial x^2}\right)\\ &G=\frac{\partial e}{\partial x} \end{split}$$