1 Computational Geometry 74

75

77

1.1 Geometry

```
78
  const double PI=atan2(0.0,-1.0);
  template<tvpename T>
  struct point{
    T x,y;
                                                 81
    point(){}
                                                  82
    point(const T&x,const T&y):x(x),y(y){}
                                                 83
    point operator+(const point &b)const{
                                                 84
    return point(x+b.x,y+b.y); }
point operator-(const point &b)const{
                                                 85
    return point(x-b.x,y-b.y); }
point operator*(const T &b)const{
    return point(x*b,y*b); }
point operator/(const T &b)const{
                                                  86
                                                 87
    return point(x/b,y/b); }
bool operator==(const point &b)const{
      return x==b.x&&y==b.y; }
    T dot(const point &b)const{
       return x*b.x+y*b.y; }
19
    T cross(const point &b)const{
                                                 90
      return x*b.y-y*b.x; }
                                                 91
20
    point normal()const{//求法向量
21
                                                 93
22
       return point(-y,x); }
    T abs2()const{//向量長度的平方
23
       return dot(*this); }
24
    T rad(const point &b)const{//兩向量的弧
25
  return fabs(atan2(fabs(cross(b)),dot(b)))
                                                 98
                                                 99
27
    T getA()const{//對x軸的弧度
      T A=atan2(y,x);//超過180度會變負的
if(A<=-PI/2)A+=PI*2;
                                                 100
28
                                                 101
                                                 102
      return A;
                                                 103
                                                 104
  template<tvpename T>
33
  struct line{
    line(){}
                                                 105
35
                                                 106
    point(T> p1,p2;
                                                 107
     T a,b,c;//ax+by+c=0
                                                 108
    line(const point<T>&x,const point<T>&y)
          :p1(x),p2(y){}
    void pton(){//轉成一般式
                                                 110
      a=p1.y-p2.y;
                                                 111
41
      b=p2.x-p1.x;
                                                 112
      c=-a*p1.x-b*p1.y;
42
                                                 113
43
    T ori(const point<T> &p)const{//點和有
44
                                                 115
          向直線的關係, >0左邊、=0在線上<0右
                                                 116
                                                 117
      return (p2-p1).cross(p-p1);
                                                 118
                                                 119
47
    T btw(const point<T> &p)const{//點投影
                                                 120
          落在線段上<=0
                                                 121
      return (p1-p).dot(p2-p);
                                                 122
    bool point_on_segment(const point<T>&p)
50
                                                 123
          const{//點是否在線段上
                                                 124
       return ori(p)==0&&btw(p)<=0;</pre>
                                                 125
                                                 126
53
    T dis2(const point<T> &p,bool
          is_segment=0)const{//點跟直線/線段
          的距離平方
                                                 129
       point<T> v=p2-p1,v1=p-p1;
       if(is_segment){
                                                 130
                                                 131
         point<T> v2=p-p2;
         if(v.dot(v1)<=0)return v1.abs2();</pre>
                                                 132
                                                 133
         if(v.dot(v2)>=0)return v2.abs2();
       T tmp=v.cross(v1);
                                                 135
      return tmp*tmp/v.abs2();
    T seg_dis2(const line<T> &1)const{//兩
          線段距離平方
                                                 137
       return min({dis2(l.p1,1),dis2(l.p2,1)
                                                 138
            ,l.dis2(p1,1),l.dis2(p2,1)});
    point<T> projection(const point<T> &p)
66
          const{//點對直線的投影
                                                 140
       point<T> n=(p2-p1).normal();
       return p-n*(p-p1).dot(n)/n.abs2();
                                                 141
69
    point<T> mirror(const point<T> &p)const
70
                                                 143
                                                 144
       //點對直線的鏡射,要先呼叫pton轉成-
71
                                                 145
            般式
       point<T> R:
       T d=a*a+b*b;
```

```
R.x=(b*b*p.x-a*a*p.x-2*a*b*p.y-2*a*c) 147
    R.y=(a*a*p.y-b*b*p.y-2*a*b*p.x-2*b*c)
         `/d;
    return R;
                                              150
  bool equal(const line &1)const{//直線相
                                              151
                                              152
    return ori(1.p1)==0&&ori(1.p2)==0;
  bool parallel(const line &1)const{
    return (p1-p2).cross(l.p1-l.p2)==0;
                                              155
                                              156
  bool cross seg(const line &1)const{
                                              157
    return (p2-p1).cross(1.p1-p1)*(p2-p1) 158
         .cross(1.p2-p1)<=0;//直線是否交
                                              159
  //直線相交情況 · -1無限多點 · 1交於
       一點、0不相交
    return parallel(1)?(ori(1.p1)
                                              163
         ==0?-1:0):1;
                                              164
                                              165
  int seg_intersect(const line &l)const{
    T c1=ori(l.p1), c2=ori(l.p2);
T c3=l.ori(p1), c4=l.ori(p2);
                                              166
    if(c1==0&&c2==0){//共線
                                              167
      bool b1=btw(1.p1)>=0,b2=btw(1.p2)
                                              168
      T a3=1.btw(p1),a4=1.btw(p2);
if(b1&&b2&&a3==0&&a4>=0) return 2;
if(b1&&b2&&a3>=0&&a4==0) return 3;
                                              170
      if(b1&&b2&&a3>=0&&a4>=0) return 0;
    return -1;//無限交點
}else if(c1*c2<=0&&c3*c4<=0)return 1;
                                              171
                                              172
    return 0;//不相交
                                              173
                                              174
  point<T> line_intersection(const line &
                                              175
       point<T> a=p2-p1,b=1.p2-1.p1,s=1.p1-
         p1;
      'if(a.cross(b)==0)return INF;
    return p1+a*(s.cross(b)/a.cross(b));
  point<T> seg_intersection(const line &1
       )const{//線段交點
                                              179
    int res=seg_intersect(1);
                                              180
    if(res<=0) assert(0);</pre>
                                              181
    if(res==2) return p1;
if(res==3) return p2;
                                              182
    return line_intersection(1);
                                              183
template<typename T>
                                              184
struct polygon{
                                              185
  polygon(){}
  vector<point<T> > p;//逆時針順序
                                              186
  T area()const{//面積
    T ans=0;
                                              187
    for(int i=p.size()-1,j=0;j<(int)p.</pre>
                                              188
         size();i=j++)
                                              189
      ans+=p[i].cross(p[j]);
                                              190
    return ans/2;
                                              191
  point<T> center_of_mass()const{//重心
                                              192
    T cx=0,cy=0,w=0;
                                              193
    for(int i=p.size()-1,j=0;j<(int)p.</pre>
                                              194
         size();i=j++){
      T a=p[i].cross(p[j]);
                                              195
      cx+=(p[i].x+p[j].x)*a;
cy+=(p[i].y+p[j].y)*a;
                                              196
                                              197
                                              198
                                              199
    return point<T>(cx/3/w,cy/3/w);
                                              200
                                              201
  char ahas(const point<T>& t)const{//點
                                              202
       是否在簡單多邊形內,是的話回傳1、
                                              203
       在邊上回傳-1、否則回傳0
                                              204
                                              205
    bool c=0:
    for(int i=0,j=p.size()-1;i<p.size();j</pre>
                                              206
                                              207
      if(line<T>(p[i],p[j]).
                                              208
           point_on_segment(t))return -1;
      else if((p[i].y>t.y)!=(p[j].y>t.y)
           &&
                                              210
      t.x<(p[j].x-p[i].x)*(t.y-p[i].y)/(p
                                              211
           [j].y-p[i].y)+p[i].x)
                                              212
        c=!c;
    return c:
                                              213
                                              214
  char point_in_convex(const point<T>&x)
       const{
    int l=1,r=(int)p.size()-2;
```

```
while(1<=r){//點是否在凸多邊形內,是
       的話回傳1、在邊上回傳-1、否則回
       傳0
    int mid=(1+r)/2;
    T a1=(p[mid]-p[0]).cross(x-p[0])
    T a2=(p[mid+1]-p[0]).cross(x-p[0]);
    if(a1>=0&&a2<=0){
      Tres=(p[mid+1]-p[mid]).cross(x-p
          [mid]);
      return res>0?1:(res>=0?-1:0);
    }else if(a1<0)r=mid-1;</pre>
    else l=mid+1;
  return 0:
vector<T> getA()const{//凸包邊對x軸的夾
  vector<T>res;//一定是遞增的
  for(size_t i=0;i<p.size();++i)</pre>
    res.push_back((p[(i+1)%p.size()]-p[
         i]).getA());
  return res:
bool line_intersect(const vector<T>&A,
    const line<T> &l)const{//O(logN)
  int f1=upper_bound(A.begin(),A.end()
     ,(1.p1-1.p2).getA())-A.begin();
  int f2=upper_bound(A.begin(),A.end()
  (1.p2-1.p1).getA())-A.begin();
return 1.cross_seg(line<T>(p[f1],p[f2
      ]));
polygon cut(const line<T> &l)const{//△
     包對直線切割,得到直線L左側的凸包
  polygon ans;
  for(int n=p.size(),i=n-1,j=0;j<n;i=j</pre>
    if(1.ori(p[i])>=0){
      ans.p.push_back(p[i]);
      if(l.ori(p[j])<0)</pre>
        ans.p.push_back(1.
             line_intersection(line<T>(
             p[i],p[j])));
    }else if(l.ori(p[j])>0)
      ans.p.push_back(1.
           line_intersection(line<T>(p[
           i],p[j])));
  return ans;
static bool monotone_chain_cmp(const
    point<T>& a, const point<T>& b){//
     凸包排序函數
  return (a.x<b.x)||(a.x==b.x&&a.y<b.y)</pre>
void monotone_chain(vector<point<T> > &
    s){//凸包
  sort(s.begin(),s.end(),
      monotone_chain_cmp);
  p.resize(s.size()+1);
  int m=0:
  for(size_t i=0;i<s.size();++i){</pre>
    while(m \ge 2\&\&(p[m-1]-p[m-2]).cross(s
         [i]-p[m-2])<=0)--m;
    p[m++]=s[i];
  for(int i=s.size()-2.t=m+1:i>=0:--i){
    while(m>=t&&(p[m-1]-p[m-2]).cross(s
         [i]-p[m-2])<=0)--m;
    p[m++]=s[i];
  if(s.size()>1)--m;
  p.resize(m);
T diam(){//直徑
  int n=p.size(),t=1;
  T ans=0;p.push_back(p[0]);
  for(int i=0;i<n;i++){</pre>
    point<T> now=p[i+1]-p[i];
    while(now.cross(p[t+1]-p[i])>now.
         cross(p[t]-p[i]))t=(t+1)%n;
    ans=max(ans,(p[i]-p[t]).abs2());
  return p.pop_back(),ans;
T min_cover_rectangle(){//最小覆蓋矩形
  int n=p.size(),t=1,r=1,l;
  if(n<3)return 0;//也可以做最小周長矩
  T ans=1e99;p.push_back(p[0]);
  for(int i=0;i<n;i++){</pre>
    point<T> now=p[i+1]-p[i];
    while(now.cross(p[t+1]-p[i])>now.
         cross(p[t]-p[i]))t=(t+1)%n;
```

```
217
          while (now.dot(p[r+1]-p[i]) > now.dot(292)
                                                            T A=sqrt((b-c).abs2()),B=sqrt((a-c).
                                                                                                       364
                                                                                                              point3D<T> line_intersection(const
                                                            abs2()),C=sqrt((a-b).abs2());
return point<T>(A*a.x+B*b.x+C*c.x,A*a 365
          p[r]-p[i]))r=(r+1)%n;
if(!i)l=r;
                                                                                                                   line3D<T> &1)const{
                                                                                                                  tmp=n.dot(1.p2-1.p1);//等於0表示平
218
                                                   293
          while(now.dot(p[l+1]-p[i])<=now.dot
                                                                  .y+B*b.y+C*c.y)/(A+B+C);
219
                                                                                                                      行或重合該平面
                (p[l]-p[i]))l=(l+1)%n;
                                                                                                                return 1.p1+(1.p2-1.p1)*(n.dot(p0-1.
          T d=now.abs2();
220
                                                          p1)/tmp);
22
          T tmp=now.cross(p[t]-p[i])*(now.dot _{296}
                                                            return barycenter()*3-circumcenter()
                                                                                                        367
                (p[r]-p[i])-now.dot(p[l]-p[i])
                                                                 *2;
                                                                                                              line3D<T> plane_intersection(const
                                                                                                        368
                )/d:
                                                                                                                   plane &pl)const{
          ans=min(ans,tmp);
                                                                                                                point3D<T> e=n.cross(pl.n),v=n.cross(
223
                                                    298
                                                       };
                                                                                                        369
223
                                                       template<typename T>
                                                    299
224
        return p.pop_back(),ans;
                                                       struct point3D{
                                                    300
                                                                                                        370
                                                                                                                T tmp=pl.n.dot(v);//等於 Ø表示平行或重
225
                                                          T x, y, z;
                                                    301
                                                                                                                      合該平面
      T dis2(polygon &pl){//凸包最近距離平方
                                                          point3D(){}
220
                                                                                                                point3D < T > q = p0 + (v*(pl.n.dot(pl.p0-p0
                                                                                                        371
        vector<point<T> > &P=p,&Q=p1.p;
                                                          point3D(const T&x,const T&y,const T&z):
227
                                                    303
                                                                                                                     ))/tmp);
228
        int n=P.size(),m=Q.size(),l=0,r=0;
                                                               x(x),y(y),z(z)\{\}
                                                                                                                return line3D<T>(q,q+e);
229
      for(int i=0;i<n;++i)if(P[i].y<P[1].y)l= 304</pre>
                                                          point3D operator+(const point3D &b)
                                                                                                        373
                                                               const{
                                                                                                        374
      for(int i=0;i<m;++i)if(Q[i].y<Q[r].y)r=</pre>
                                                            return point3D(x+b.x,y+b.y,z+b.z);}
230
                                                                                                           template<typename T>
                                                                                                        375
                                                          point3D operator-(const point3D &b)
                                                                                                           struct triangle3D{
                                                                                                        376
        P.push_back(P[0]),Q.push_back(Q[0]);
                                                               const{
23
                                                                                                        377
                                                                                                              point3D<T> a,b,c;
                                                         return point3D(x-b.x,y-b.y,z-b.z);}
point3D operator*(const T &b)const{
  return point3D(x*b,y*b,z*b);}
        T ans=1e99;
232
                                                    307
                                                                                                              triangle3D(){}
                                                                                                        378
        for(int i=0:i<n:++i){</pre>
233
                                                    308
                                                                                                              triangle3D(const point3D<T> &a,const
                                                                                                        379
          while((P[1]-P[1+1]).cross(Q[r+1]-Q[
234
                                                   309
                                                                                                                   point3D<T> &b, const point3D<T> &c)
                                                          point3D operator/(const T &b)const{
               r])<0)r=(r+1)%m;
                                                                                                             :a(a),b(b),c(c){}
bool point_in(const point3D<T> &p)const
                                                    310
          ans=min(ans,line<T>(P[1],P[1+1])
                                                            return point3D(x/b,y/b,z/b);}
                                                                                                        380
                seg_dis2(line<T>(Q[r],Q[r+1]))
                                                          bool operator==(const point3D &b)const{
                                                                                                                   {//點在該平面上的投影在三角形中
                                                            return x==b.x&&y==b.y&&z==b.z;}
                                                    313
                                                                                                                return line3D<T>(b,c).same_side(p,a)
    &&line3D<T>(a,c).same_side(p,b)
                                                         T dot(const point3D &b)const{
  return x*b.x+y*b.y+z*b.z;}
point3D cross(const point3D &b)const{
                                                                                                        381
          1=(1+1)%n:
236
                                                    314
237
                                                    315
                                                                                                                     &&line3D<T>(a,b).same_side(p,c);
        return P.pop_back(),Q.pop_back(),ans;
238
                                                   316
                                                                                                             }
                                                            return point3D(y*b.z-z*b.y,z*b.x-x*b.
239
                                                    317
                                                                                                        383
240
      static char sign(const point<T>&t){
                                                                 z,x*b.y-y*b.x);}
                                                                                                        384
                                                                                                           template<typename T>
                                                          T abs2()const{//向量長度的平方
241
        return (t.y==0?t.x:t.y)<0;</pre>
                                                    318
                                                                                                           struct tetrahedron{//四面體
                                                                                                        385
242
                                                            return dot(*this);}
                                                    319
                                                                                                        386
                                                                                                              point3D<T> a,b,c,d;
243
      static bool angle_cmp(const line<T>& A,
                                                          T area2(const point3D &b)const{//和b
                                                   320
           const line<T>& B){
                                                                                                        387
                                                                                                              tetrahedron(){}
                                                               原點圍成面積的平方
                                                                                                              tetrahedron(const point3D<T> &a,const
        point<T> a=A.p2-A.p1,b=B.p2-B.p1;
                                                                                                        388
244
                                                            return cross(b).abs2()/4;}
                                                    321
                                                                                                                   point3D<T> &b, const point3D<T> &c,
245
        return sign(a)<sign(b)||(sign(a)==</pre>
                                                    322
                                                                                                                   const point3D<T> &d):a(a),b(b),c(c
             sign(b)&&a.cross(b)>0);
                                                    323
                                                        template<typename T>
                                                                                                                   ),d(d){}
246
                                                       struct line3D{
                                                                                                              T volume6()const{//體積的六倍
247
     int halfplane intersection(vector<line<</pre>
                                                                                                        389
                                                    325
                                                          point3D<T> p1,p2;
                                                                                                                return (d-a).dot((b-a).cross(c-a));
           T> > &s){//半平面交
                                                                                                        390
                                                          line3D(){}
248
        sort(s.begin(),s.end(),angle_cmp);//
                                                          line3D(const point3D<T> &p1,const
                                                    327
                                                                                                        392
                                                                                                              point3D<T> centroid()const{
              線段左側為該線段半平面
                                                          point3D<T> &p2):p1(p1),p2(p2){}
T dis2(const point3D<T> &p,bool
                                                                                                        393
                                                                                                                return (a+b+c+d)/4;
        int L,R,n=s.size();
249
                                                    328
                                                                                                        394
        vector<point<T> > px(n);
vector<line<T> > q(n);
250
                                                               is_segment=0)const{//點跟直線/線段
                                                                                                              bool point_in(const point3D<T> &p)const
                                                                                                        395
251
                                                               的距離平方
        q[L=R=0]=s[0];
252
                                                            point3D < T > v = p2 - p1, v1 = p - p1;
                                                    329
                                                                                                                return triangle3D<T>(a,b,c).point_in(
                                                                                                        396
        for(int i=1;i<n;++i){</pre>
25
                                                            if(is_segment){
                                                    330
                                                                                                                     p)&&triangle3D<T>(c,d,a).
254
          while(L<R&&s[i].ori(px[R-1])<=0)--R</pre>
                                                              point3D<T> v2=p-p2;
                                                    331
                                                                                                                     point_in(p);
                                                               f(v.dot(v1)<=0)return v1.abs2();
                                                                                                        397
                                                                                                             }
25
          while(L<R&&s[i].ori(px[L])<=0)++L;
                                                              if(v.dot(v2)>=0)return v2.abs2();
                                                    333
                                                                                                        398
256
          a[++R]=s[i]:
                                                    334
                                                                                                           template<typename T>
                                                                                                        399
          if(q[R].parallel(q[R-1])){
25
                                                    335
                                                            point3D<T> tmp=v.cross(v1);
return tmp.abs2()/v.abs2();
                                                                                                           struct convexhull3D{
258
                                                    336
                                                                                                        40
                                                                                                              static const int MAXN=1005;
             if(q[R].ori(s[i].p1)>0)q[R]=s[i];
259
                                                    337
                                                                                                              struct face{
                                                                                                        402
260
                                                          pair<point3D<T>,point3D<T> >
                                                    338
                                                                                                        403
                                                                                                                int a,b,c;
261
          if(L < R)px[R-1] = a[R-1].
                                                               closest_pair(const line3D<T> &1)
                                                                                                                face(int a,int b,int c):a(a),b(b),c(c
                                                                                                        404
                line_intersection(q[R]);
                                                                                                                     ){}
262
                                                            point3D<T> v1=(p1-p2), v2=(1.p1-1.p2);
                                                    339
        while(L<R&&q[L].ori(px[R-1])<=0)--R;</pre>
263
                                                            point3D<T> N=v1.cross(v2),ab(p1-l.p1)
                                                    340
                                                                                                              vector<point3D<T>> pt;
        p.clear();
                                                                                                        407
                                                                                                              vector<face> ans
        if(R-L<=1)return 0;
                                                                                                              int fid[MAXN][MAXN];
void build(){
                                                            //if(N.abs2()==0)return NULL;平行或重
                                                    341
                                                                                                        408
266
        px[R]=q[R].line_intersection(q[L]);
267
        for(int i=L;i<=R;++i)p.push_back(px[i</pre>
                                                                                                                int n=pt.size();
                                                                                                       410
                                                    342
                                                            T tmp=N.dot(ab),ans=tmp*tmp/N.abs2();
             1);
                                                                                                                ans.clear();
                                                                  //最近點對距離
        return R-L+1;
268
                                                                                                                memset(fid,0,sizeof(fid));
                                                                                                       412
                                                            point3D < T > d1=p2-p1, d2=1.p2-1.p1, D=d1
                                                    343
269
                                                                                                                ans.emplace_back(0,1,2);//注意不能共
                                                            .cross(d2),G=l.p1-p1;
T t1=(G.cross(d2)).dot(D)/D.abs2();
T t2=(G.cross(d1)).dot(D)/D.abs2();
                                                                                                        413
270
   template<typename T>
                                                    344
271
                                                                                                                ans.emplace_back(2,1,0);
272
   struct triangle{
                                                    345
                                                                                                        414
                                                            return make_pair(p1+d1*t1,l.p1+d2*t2)
                                                                                                                int ftop = \overline{0};
     point<T> a,b,c;
                                                                                                       415
273
                                                                                                                for(int i=3, ftop=1; i<n; ++i,++ftop)</pre>
      triangle(){}
274
275
      triangle(const point<T> &a,const point< 347</pre>
           T> &b, const point<T> &c):a(a),b(b) 348
                                                         417
                                                                                                                  vector<face> next;
                                                                                                                  for(auto &f:ans)
           ,c(c){}
                                                                                                        418
                                                            return (p2-p1).cross(a-p1).dot((p2-p1 419
                                                                                                                     T d=(pt[i]-pt[f.a]).dot((pt[f.b]-
276
     T area()const{
                                                    349
                                                                                                                          pt[f.a]).cross(pt[f.c]-pt[f.
                                                                 ).cross(b-p1))>0;
277
        T t=(b-a).cross(c-a)/2;
        return t>0?t:-t;
                                                                                                                          a]));
                                                    350
278
                                                       };
                                                                                                                     if(d<=0) next.push_back(f);</pre>
279
                                                    351
                                                                                                        420
                                                                                                                    int ff=0;
if(d>0) ff=ftop;
else if(d<0) ff=-ftop;</pre>
                                                    352
                                                       template<typename T>
                                                                                                        421
     point<T> barycenter()const{//重心 return (a+b+c)/3;
280
                                                    353
                                                       struct plane{
                                                                                                        422
281
                                                          point3D<T> p0,n;//平面上的點和法向量
                                                                                                        423
                                                    354
282
                                                                                                                     fid[f.a][f.b]=fid[f.b][f.c]=fid[f
                                                                                                        424
                                                    355
                                                          plane(){}
     point<T> circumcenter()const{//外心
283
                                                                                                                          .c][f.a]=ff;
        static line<T> u,v;
                                                    356
                                                          plane(const point3D<T> &p0,const
284
                                                               point3D<T> &n):p0(p0),n(n){}
                                                                                                        425
        u.p1=(a+b)/2;
                                                                                                                  for(auto &f:ans){
   if(fid[f.a][f.b]>0 && fid[f.a][f.
                                                                                                        426
        u.p2=point<T>(u.p1.x-a.y+b.y,u.p1.y+a 357
                                                          T dis2(const point3D<T> &p)const{//點到
280
                                                                                                        427
              .x-b.x);
                                                               平面距離的平方
                                                                                                                         b]!=fid[f.b][f.a])
        v.p1=(a+c)/2:
287
                                                            T tmp=(p-p0).dot(n);
                                                                                                                     next.emplace_back(f.a,f.b,i);
if(fid[f.b][f.c]>0 && fid[f.b][f.
    c]!=fid[f.c][f.b])
                                                                                                        428
        v.p2=point<T>(v.p1.x-a.y+c.y,v.p1.y+a
                                                            return tmp*tmp/n.abs2();
288
                                                   359
                                                                                                        429
              .x-c.x);
                                                    360
289
        return u.line_intersection(v);
                                                          point3D<T> projection(const point3D<T>
                                                    361
                                                                                                                       next.emplace_back(f.b,f.c,i);
                                                                                                        430
                                                                                                                     431
                                                            return p-n*(p-p0).dot(n)/n.abs2();
     point<T> incenter()const{//内心
291
```

```
432
               next.emplace_back(f.c,f.a,i);
433
          ans=next;
434
435
        }
436
      point3D<T> centroid()const{
437
438
        point3D<T> res(0,0,0);
        .
T vol=0;
439
                                                      11
        for(auto &f:ans){
440
          T tmp=pt[f.a].dot(pt[f.b].cross(pt[
441
                                                      13
                f.c]));
442
           res=res+(pt[f.a]+pt[f.b]+pt[f.c])*
                tmp;
          vol+=tmp;
443
                                                      17
444
                                                      18
        return res/(vol*4);
445
446
447 };
                                                      19
                                                      20
```

1.2 SmallestCircle

```
using PT=point<T>; using CPT=const PT;
PT circumcenter(CPT &a,CPT &b,CPT &c){
    PT u=b-a, v=c-a;
     T c1=u.abs2()/2,c2=v.abs2()/2;
     T d=u.cross(v);
     return PT(a.x+(v.y*c1-u.y*c2)/d,a.y+(u.
          x*c2-v.x*c1)/d);
   void solve(PT p[],int n,PT &c,T &r2){
    random_shuffle(p,p+n);
c=p[0]; r2=0; // c,r2 = 圓心,半徑平方
   for(int i=1;i<n;i++)if((p[i]-c).abs2()>r2
11
       c=p[i]; r2=0;
13
   for(int j=0;j<i;j++)if((p[j]-c).abs2()>r2
        ){
         c.x=(p[i].x+p[j].x)/2;
         c.y=(p[i].y+p[j].y)/2;
r2=(p[j]-c).abs2();
15
17
   for(int k=0;k<j;k++)if((p[k]-c).abs2()>r2
        ){
            c=circumcenter(p[i],p[j],p[k]);
            r2=(p[i]-c).abs2();
20
       }
21
    }
22
23 }
```

1.3 最近點對

```
template < typename _IT = point < T >* >
T cloest_pair(_IT L, _IT R) {
   if(R-L <= 1) return INF;</pre>
      _{\rm IT} mid = L+(R-L)/2;
        x = mid -> x;
      T d = min(cloest_pair(L,mid),
             cloest_pair(mid,R));
     inplace_merge(L, mid, R, ycmp);
static vector<point> b; b.clear();
for(auto u=L;u<R;++u){</pre>
        if((u->x-x)*(u->x-x)>=d) continue;
         for(auto v=b.rbegin();v!=b.rend();++v 12
            T dx=u->x-v->x, dy=u->y-v->y; if(dy*dy>=d) break;
13
            d=min(d,dx*dx+dy*dy);
        b.push_back(*u);
17
18
      return d;
19
   T closest pair(vector<point<T>> &v){
20
      sort(v.begin(),v.end(),xcmp);
21
      return closest_pair(v.begin(),v.end());
```

2 Data Structure

2.1 01 背包

2.2 binary search

21

22

```
| LL BS(LL left,LL right){
      if(left+1 >= right)//break condition
           return -1;
       LL mid = (left+right)/2;
       if(arr[mid] == target)
           return mid:
       else if(arr[mid] < target){</pre>
           left = mid+1;
           BS(left,right);
       else if(arr[mid] > target){
11
           right = mid:
12
           BS(left,right);
13
      }
15 }
```

2.3 discretization

2.4 LCS

2.5 LIS

```
i int main(){
       //freopen("file name", "r", stdin);
//input redirection
       LL n,i,length = 0,num;
       cin >> n;
        LL last[RSIZE];//@?«?°it@@3p¥i~?§?
        for(i = 0; i < n; i++){
            cin >> num;
            LL it = lower bound(last, last+
                  length,num)-last;
            last[it] = num;
if(it == length) length++;
11
12
13
        cout << length;</pre>
14
        return 0;
15 }
```

2.6 skew heap

```
1    node *merge(node *a,node *b){
2         if(!a||!b)         return a?a:b;
3         if(b->data<a->data)         swap(a,b);
4         swap(a->1,a->r);
5         a->1=merge(b,a->1);
6         return a;
7     }
```

2.7 sliding window

```
//same size
  for(i = 0; i < m; i++){//making first</pre>
        window
       LL color = discret[a[right]];
       cnt[color]++;
if(cnt[color] == 1) n_color++;
       right++;
  while(right < n){</pre>
       if(n_color == m)
10
            ans++;
       LL l_remove = discret[a[left]];
cnt[l_remove]--;//remove left one
11
12
       left++;
13
       if(cnt[l_remove] == 0) n_color--;
       LL add = discret[a[right]];
       cnt[add]++,right++;//add next one
17
       if(cnt[add] == 1) n_color++;
18 }
```

2.8 undo disjoint set

12

13

17

18

19

22

25

```
struct DisjointSet {
  // save() is like recursive
// undo() is like return
  int n, fa[MXN], sz[MXN];
vector<pair<int*,int>> h;
  vector<int> sp;
void init(int tn) {
     n=tn;
     for (int i=0; i<n; i++) sz[fa[i]=i</pre>
     sp.clear(); h.clear();
  void assign(int *k, int v) {
     h.PB({k, *k});
  void save() { sp.PB(SZ(h)); }
void undo() {
     assert(!sp.emptv());
     int last=sp.back(); sp.pop_back();
while (SZ(h)!=last) {
        auto x=h.back(); h.pop_back();
        *x.F=x.S;
     }
  int f(int x) {
     while (fa[x]!=x) x=fa[x];
   void uni(int x, int y) {
     x=f(x); y=f(y);
if (x==y) return;
```

3 Graph

3.1 BFS

```
LL val;//unnecessary
   bool visited[5000] = {false};
   vector<LL> graph[5000];
void BFS(LL start) {
   queue<LL> q;
        q.push(start);
         visited[start] = true;
        while (!q.empty()){
              LL curr = q.front();
              q.pop();
for(auto it: graph[curr]){
    if(!visited[it]){
11
12
                         q.push(it);
                         visited[it] = true;
15
              }
17
        }
18 }
```

3.2 DFS

```
#include<bits/stdc++.h>
   #define good ios_base::sync_with_stdio(0)
         ;cin.tie(0);cout.tie(0)
   typedef long long LL;
   using namespace std;
int fa[100000],d[100000] = {0};//
         unnecessary
   bool visit[100000] = {false};
   vector<LL> v[100000];
void dfs(LL now,LL depth){
        for(auto x:v[now]){
    if(!visit[x]){
        cout << x << ' '
        visit[x] = true;
11
                    d[x] = depth;
fa[x] = now;
                    dfs(x,depth+1);
              }
16
        }
17
18
   int main(){
        good;
21
        LL i,n,a,b;
        cin >> n;
for(i = 0; i < n; i++){</pre>
22
23
24
              cin >> a >> b;
               v[a].push_back(b);
25
               v[b].push_back(a);
27
28
29
         dfs(0,1);
         return 0:
30 }
```

3.3 dijkstra

```
#include < bits / stdc++.h>
  #define good ios_base::sync_with_stdio(0)
        ;cin.tie(0)
  #define N 10002
  #define oo 1000000001//1e9+1
typedef long long LL;
  using namespace std;
  vector<pair<LL,LL>> adjacent[N];//out
        neighbor, weight of edge
  LL dis[N],parent[N];
  bool visit[N] = {false};
  int main(){
       LL i,n,m;
       cin >> n >> m;
for(i = 0; i < m; i++){</pre>
15
            LL x,y,w;
16
17
            cin >> x >> y >> w;
```

```
adjacent[x].push_back({y,w});
adjacent[y].push_back({x,w});
19
          }
20
21
          LL source = 0;
          memset(dis,oo,sizeof(dis));
23
          memset(parent,-1,sizeof(parent));
priority_queue<pair<LL,LL>> PQ;//-dis
   [],vertex;A$@@@@@@ ³ p @pop
24
25
                                                                         13
                                                                         14
          PQ.push({dis[source] = 0, source});
26
                                                                         15
27
          //dijkstra
          while (!PQ.empty()){
28
                                                                         17
                 auto p = PQ.top();
29
                                                                         18
                 PQ.pop();
30
                                                                         19
                 LL v = p.second;//vertex
if(visit[v]) continue;
31
                                                                         20
32
                                                                         21
                 visit[v] = true;
                 for(auto it : adjacent[v]){
    LL e = it.first,w = it.second
35
                                                                        24
                                                                         25
                       if(w + dis[v] < dis[e]){
    dis[e] = w + dis[v];
    parent[e] = v;</pre>
                                                                         26
37
                                                                         28
                              PQ.push({-dis[e],e});
                                                                         30
41
                }
                                                                         31
42
                                                                         32
          LL maxd = -1,cnt = 0,far;
for(i = 0; i < n; i++){
    if(dis[i] < 00){
43
                                                                         33
                                                                         34
                       if(dis[i] > maxd)
47
                             maxd = dis[i],far = i;
48
                                                                         38
49
                 else
                                                                         39
50
                       cnt++;//for can't reach
          cout << maxd << endl << cnt;</pre>
53
          return 0;
                                                                         43 };
54 }
```

3.4 graphISO

```
const int MAXN=1005,K=30;//K要夠大
   const long long A=3,B=11,C=2,D=19,P=0
        xdefaced;
  long long f[K+1][MAXN];
vector<int> g[MAXN],rg[MAXN];
   int n;
   void init(){
     for(int i=0;i<n;++i){</pre>
       f[0][i]=1;
       g[i].clear(), rg[i].clear();
    }
10
  }
11
   void add_edge(int u,int v){
    g[u].push_back(v), rg[v].push_back(u);
15
  long long point_hash(int u){//O(N)
     for(int t=1;t<=K;++t){
  for(int i=0;i<n;++i){</pre>
16
17
18
          f[t][i]=f[t-1][i]*A%P
          19
          for(int j:rg[i])f[t][i]=(f[t][i]+f[
20
              t-1][j]*C%P)%P;
          if(i==u)f[t][i]+=D;//如果圖太大的
21
               話,把這行刪掉,執行一次後f[K]
               就會是所有點的答案
22
          f[t][i]%=P;
23
     return f[K][u];
25
  }
26
  vector<long long> graph_hash(){
  vector<long long> ans;
  for(int i=0;i<n;++i)ans.push_back(</pre>
27
28
29
          point_hash(i));//O(N^2)
     sort(ans.begin(),ans.end());
31
     return ans:
32 }
```

3.5 MaximumClique

3.6 MinimumMeanCycle

void init(int n){

memset(g,0,sizeof(g));

void add_edge(int u,int v){

memcpy(sol,tmp,sizeof tmp);

g[u][v]=g[v][u]=1;

if(dep>ans){

àns=dep;

return 1;

tmp[dep]=u;

return 0:

int clique(){

int u,v,ns;

return ans:

}else return 0;

for(int i=0;i<ns;++i){</pre>

if(dep+ns-i<=ans)return 0;</pre>

if(dep+dp[u]<=ans)return 0;</pre>

if(dfs(cnt,dep+1))return 1;

for(ans=0,u=N-1;u>=0;--u){

dfs(ns,1),dp[u]=ans;

for(int j=i+1;j<ns;++j){
 int v=stk[dep][j];
 if(g[u][v])stk[dep+1][cnt++]=v;</pre>

for(ns=0,tmp[0]=u,v=u+1;v<N;++v)
 if(g[u][v])stk[1][ns++]=v;</pre>

int u=stk[dep][i],cnt=0;

int dfs(int ns,int dep){

N=n://0-base

if(!ns){

```
#include<cfloat> //for DBL_MAX
int dp[MAXN][MAXN]; // 1-base,O(NM)
vector<tuple<int,int,int>> edge;
   double mmc(int n){//allow negative weight
      const int INF=0x3f3f3f3f3f;
      for(int t=0;t<n;++t){</pre>
         memset(dp[t+1],0x3f,sizeof(dp[t+1]));
         for(const auto &e:edge){
            int u,v,w;
tie(u,v,w) = e;
            dp[t+1][v]=min(dp[t+1][v],dp[t][u]+
11
12
         }
13
      double res = DBL_MAX;
for(int u=1;u<=n;++u){</pre>
14
15
         if(dp[n][u]==INF) continue;
double val = -DBL_MAX;
16
         for(int t=0;t<n;++t)</pre>
           val=max(val,(dp[n][u]-dp[t][u])
     *1.0/(n-t));
         res=min(res,val);
      return res;
23 }
```

3.7 topology sort

10

11

13

14

15

16

17

18

19

```
int main(){
    good;
    LL indeg[1002] = {0};
    vector<LL> graph[1002];
    LL n,m,a,b;
    cin >> n >> m;
    for(LL i = 0; i < m; i++){</pre>
        cin >> a >> b;
        graph[a].push_back(b);
        indeg[b]++;
    LL topo[1002], head = 0, tail = 0; //??
    queue
for(LL i = 0; i < n; i++)</pre>
        if(indeg[i] == 0)
            topo[tail++] = i;
    while(head < tail){</pre>
        LL v = topo[head++];//get data
             and pop
        for(LL u : graph[v]){
             if(--indeg[u] == 0)
                 topo[tail++] = u;
```

```
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21
            }
22
23
        if(tail < n) cout << "not a DAG" <<</pre>
             end1;
25
             for(LL i = 0; i < n; i++)</pre>
26
                 cout << topo[i] <<</pre>
27
28
        return 0:
   3.8
          treeISO
  const int MAXN=100005;
  const long long X=12327,P=0xdefaced;
vector<int> g[MAXN];
  bool vis[MAXN];
long long dfs(int u){//hash ver
     vis[u]=1;
     vector<long long> tmp;
           ));
10
```

```
for(auto v:g[u])if(!vis[v])tmp.PB(dfs(v
      if(tmp.empty())return 177;
long long ret=4931;
sort(tmp.begin(),tmp.end());
for(auto v:tmp)ret=((ret*X)^v)%P;
11
14
   string dfs(int x,int p){
16
      vector<string> c;
      for(int y:g[x])
         if(y!=p)c.emplace_back(dfs(y,x));
      sort(c.begin(),c.end());
string ret("(");
21
      for(auto &s:c)ret+=s;
ret+=")";
23
      return ret;
```

3.9 一般圖最小權完美匹配

25 }

```
struct Graph {
     // Minimum General Weighted Matching (
     Perfect Match) 0-base
static const int MXN = 105;
      int n, edge[MXN][MXN];
      int match[MXN],dis[MXN],onstk[MXN];
      vector<int> stk;
      void init(int _n) {
       for (int i=0; i<n; i++)
  for (int j=0; j<n; j++)
   edge[i][j] = 0;</pre>
      void add_edge(int u, int v, int w) {
        edge[u][v] = edge[v][u] = w;
15
      bool SPFA(int u){
        if (onstk[u]) return true;
17
        stk.push_back(u);
         onstk[u] = 1;
        for (int v=0; v<n; v++){
  if (u != v && match[u] != v && !</pre>
20
21
              onstk[v]){
int m = match[v];
22
              if (dis[m] > dis[u] - edge[v][m]
23
                     + edge[u][v]){
                 dis[m] = dis[u] - edge[v][m] +
                       edge[u][v];
                onstk[v] = 1;
stk.push_back(v);
                 if (SPFA(m)) return true;
                 stk.pop_back();
                onstk[v] = 0;
30
             }
           }
31
32
        onstk[u] = 0;
33
        stk.pop_back();
return false;
36
     int solve() {
    // find a match
    for (int i=0; i<n; i+=2){
        match[i] = i+1, match[i+1] = i;
}</pre>
37
38
        for(;;){
  int found = 0;
43
           for (int i=0; i<n; i++) dis[i] =
44
                 onstk[i] = 0;
```

```
for (int i=0; i<n; i++){</pre>
46
            stk.clear();
            if (!onstk[i] && SPFA(i)){
47
48
               found = \bar{1};
               while (stk.size()>=2){
                 int u = stk.back(); stk.
50
                       pop_back();
                 int v = stk.back(); stk.
51
                 pop_back();
match[u] = v;
                 match[v] = u;
            }
55
56
          if (!found) break;
57
58
        int ret = 0;
        for (int i=0; i<n; i++)</pre>
       ret += edge[i][match[i]];
ret /= 2;
61
62
63
       return ret;
64
65 }graph;
```

全局最小割 3.10

const int INF=0x3f3f3f3f;

template<typename T>

```
struct stoer_wagner{// 0-base
    static const int MAXN=150;
     T g[MAXN][MAXN],dis[MAXN];
     int nd[MAXN],n,s,t;
     void init(int _n){
        n=_n;
        for(int i=0;i<n;++i)</pre>
          for(int j=0;j<n;++j)g[i][j]=0;</pre>
10
11
      void add_edge(int u,int v,T w){
        g[u][v]=g[v][u]+=w;
14
15
     T min cut(){
        T ans=INF;
16
        for(int i=0;i<n;++i)nd[i]=i;</pre>
17
        for(int ind,tn=n;tn>1;--tn){
          for(int i=1;i<tn;++i)dis[nd[i]]=0;</pre>
          for(int i=1;i<tn;++i){</pre>
21
             ind=i:
             for(int j=i;j<tn;++j){
  dis[nd[j]]+=g[nd[i-1]][nd[j]];</pre>
22
23
               if(dis[nd[ind]]<dis[nd[j]])ind=</pre>
24
25
26
             swap(nd[ind],nd[i]);
27
          if(ans>dis[nd[ind]])ans=dis[t=nd[
28
                ind]],s=nd[ind-1];
          for(int i=0;i<tn;++i)</pre>
             g[nd[ind-1]][nd[i]] = g[nd[i]][nd[
30
                   ind-1]]+=g[nd[i]][nd[ind]];
31
        return ans;
32
33
```

3.11 最小樹形圖朱劉

```
template<typename T>
   struct zhu_liu{
     static const int MAXN=110,MAXM=10005;
     struct node{
       node *1,*r;
node(int u=0,int v=0,T w=0):u(u),v(v)
,w(w),tag(0),1(0),r(0){}
        void down(){
          w+=tag;
          if(1)1->tag+=tag;
12
          if(r)r->tag+=tag;
          tag=0;
13
       }
14
     }mem[MAXM];//靜態記憶體
15
     node *pq[MAXN*2],*E[MAXN*2];
int st[MAXN*2],id[MAXN*2],m;
17
     void init(int n){
18
        for(int i=1;i<=n;++i){</pre>
          pq[i]=E[i]=0, st[i]=id[i]=i;
22
     node *merge(node *a,node *b){//skew
           heap
```

```
a->down(),b->down();
if(b->w<a->w)return merge(b,a);
25
26
       swap(a->1,a->r);
27
28
       a->1=merge(b,a->1);
29
       return a:
30
     void add edge(int u,int v,T w){
31
       if(u!=v)pq[v]=merge(pq[v],&(mem[m++]=
32
            node(u,v,w)));
34
     int find(int x,int *st){
       return st[x]==x?x:st[x]=find(st[x],st
35
36
37
     T build(int root, int n){
38
       T ans=0; int N=n, all=n;
       for(int i=1;i<=N;++i){</pre>
40
         if(i==root||!pq[i])continue;
         while(pq[i]){
41
           pq[i]->down(),E[i]=pq[i];
pq[i]=merge(pq[i]->1,pq[i]->r);
if(find(E[i]->u,id)!=find(i,id))
42
43
         if(find(E[i]->u,id)==find(i,id))
46
               continue;
         ans+=E[i]->w;
47
          if(find(E[i]->u,st)==find(i,st)){
48
            if(pq[i])pq[i]->tag-=E[i]->w;
            pq[++N]=pq[i];id[N]=N;
50
            51
              if(pq[u])pq[u]->tag-=E[u]->w;
52
              id[find(u,id)]=N;
              pq[N]=merge(pq[N],pq[u]);
56
            st[N]=find(i,st);
            id[find(i,id)]=N;
57
         }else st[find(i,st)]=find(E[i]->u,
58
               st), -- all;
       return all==1?ans:-INT_MAX;//圖不連通
60
             就無解
61
62 };
```

if(!a||!b)return a?a:b;

Language

CNF 4.1

11

12

13

14

15

16

17

18

21

23

25

26

2.7

30

31

```
#define MAXN 55
  struct CNF{
    int s,x,y;//s->xy \mid s->x, if y==-1
    int cost;
    CNF(){}
    CNF(int s,int x,int y,int c):s(s),x(x),
         y(y),cost(c){}
  };
  int state;//規則數量
9 map<char,int> rule;//每個字元對應到的規
       則,小寫字母為終端字符
  vector<CNF> cnf;
  void init(){
    state=0;
    rule.clear();
    cnf.clear();
  void add_to_cnf(char s,const string &p,
       int cost){
     //加入一個s -> 的文法,代價為cost
    if(rule.find(s)==rule.end())rule[s]=
         state++:
    for(auto c:p)if(rule.find(c)==rule.end
         ())rule[c]=state++;
    if(p.size()==1){
      cnf.push_back(CNF(rule[s],rule[p
       [0]],-1,cost));
    }else{
      int left=rule[s];
      int sz=p.size();
      for(int i=0;i<sz-2;++i){</pre>
        cnf.push_back(CNF(left,rule[p[i]],
             state,0));
        left=state++;
      cnf.push_back(CNF(left,rule[p[sz-2]],
           rule[p[sz-1]],cost));
    }
32 vector<long long> dp[MAXN][MAXN];
```

```
33 vector<bool> neg_INF[MAXN][MAXN];//如果花 44
        費是負的可能會有無限小的情形
  void relax(int 1,int r,const CNF &c,long
    long cost,bool neg_c=0){
    if(!neg_INF[1][r][c.s]&&(neg_INF[1][r][c.x])|
        c.x]||cost<dp[1][r][c.s])){</pre>
35
       if(neg_c||neg_INF[1][r][c.x]){
          dp[1][r][c.s]=0;
       neg_INF[l][r][c.s]=true;
}else dp[l][r][c.s]=cost;
    }
40
41
   void bellman(int l,int r,int n){
     for(int k=1;k<=state;++k)</pre>
       for(auto c:cnf)
45
         if(c.y==-1)relax(l,r,c,dp[l][r][c.x
               ]+c.cost,k==n);
   void cyk(const vector<int> &tok){
     for(int i=0;i<(int)tok.size();++i){</pre>
       50
          neg_INF[i][j]=vector<bool>(state+1,
51
               false);
       dp[i][i][tok[i]]=0;
       bellman(i,i,tok.size());
     for(int r=1;r<(int)tok.size();++r){</pre>
       for(int l=r-1;l>=0;--1){
          for(int k=1;k<r;++k)</pre>
            for(auto c:cnf)
              if(~c.y)relax(1,r,c,dp[1][k][c.
60
                    x]+dp[k+1][r][c.y]+c.cost)
         bellman(l,r,tok.size());
62
63
64 }
```

5 Linear Programming

5.1 simplex

```
/*target:
      max \setminus sum_{j=1}^n A_{0,j}*x_j
   condition:
       \sum_{j=1}^n A_{i,j}*x_j \iff A_{i,0} i
        <_j >= 0 |j=1~n
   VDB = vector<double>*/
   template < class VDB >
VDB simplex(int m, int n, vector < VDB > a){
      vector<int> left(m+1), up(n+1);
iota(left.begin(), left.end(), n);
      iota(qup.begin(), up.end(), 0);
auto pivot = [&](int x, int y){
  swap(left[x], up[y]);
  auto k = a[x][y]; a[x][y] = 1;
         vector<int> pos;
for(int j = 0; j <= n; ++j){
   a[x][j] /= k;</pre>
             if(a[x][j] != 0) pos.push_back(j);
         for(int i = 0; i <= m; ++i){
  if(a[i][y]==0 || i == x) continue;
  k = a[i][y], a[i][y] = 0;
  for(int)[y], a[i][y] = 0;</pre>
             for(int j : pos) a[i][j] -= k*a[x][
         }
25
      26
         if(a[x][0]>=0) break;
for(int j=y=1; j <= n; ++j)
    if(a[x][j]<a[x][y]) y = j;
if(a[x][y]>=0) return VDB();//
31
                 infeasible
         pivot(x, y);
35
       for(int x,y;;){
         for(int j=y=1; j <= n; ++j)
  if(a[0][j] > a[0][y]) y = j;
37
         if(a[0][y]<=0) break;
          for(int i=1; i<=m; ++i) if(a[i][y] >
                 0)
             if(x == -1 || a[i][0]/a[i][y]
         42
```

void gcd(const T &a,const T &b,T &d,T &x,

6 Number Theory

6.1 basic

template<typename T>

if(!b) d=a,x=1,y=0;

T &y){

```
else gcd(b,a%b,d,y,x), y-=x*(a/b);
   long long int phi[N+1];
void phiTable(){
     for(int i=1;i<=N;i++)phi[i]=i;
for(int i=1;i<=N;i++)for(x=i*2;x<=N;x+=</pre>
          i)phi[x]-=phi[i];
   // dosomething;
14
   }
   const int MAXPRIME = 1000000;
   int iscom[MAXPRIME], prime[MAXPRIME],
        primecnt;
   int phi[MAXPRIME], mu[MAXPRIME];
   void sieve(void){
     memset(iscom,0,sizeof(iscom));
     primecnt = 0;
     phi[1] = mu[1] = 1;
for(int i=2;i<MAXPRIME;++i) {
23
        if(!iscom[i]) {
24
25
          prime[primecnt++] = i;
          mu[i] = -1;
          phi[i] = i-1;
        for(int j=0;j<primecnt;++j) {
  int k = i * prime[j];
  if(k>=MAXPRIME) break;
          iscom[k] = prime[j];
          if(i%prime[j]==0) {
            mu[k] = 0;
phi[k] = phi[i] * prime[j];
35
            break:
          } else {
37
            mu[k] = -mu[i];
38
            phi[k] = phi[i] * (prime[j]-1);
     }
42
   }
43
   bool g_test(const LL &g, const LL &p,
        const vector<LL> &v) {
     for(int i=0;i<v.size();++i)</pre>
       if(modexp(g,(p-1)/v[i],p)==1)
  return false;
48
     return true;
49
   LL primitive_root(const LL &p) {
     if(p==2) return 1;
     vectorally v:
53
     Factor(p-1,v);
v.erase(unique(v.begin(), v.end()), v.
54
55
           end());
     for(LL g=2;g<p;++g)</pre>
       if(g_test(g,p,v))
          return g;
58
     puts("primitive_root NOT FOUND");
59
     return -1;
60
61
   int Legendre(const LL &a, const LL &p) {
62
         return modexp(a%p,(p-1)/2,p); }
   LL inv(const LL &a, const LL &n) {
     LL d,x,y;
65
     gcd(a,n,d,x,y);
return d==1 ? (x+n)%n : -1;
   int inv[maxN];
70
71 LL invtable(int n,LL P){
72 inv[1]=1;
```

```
75
   }
77
   LL log_mod(const LL &a, const LL &b,
     const LL &p) {
// a ^ x = b ( mod p )
int m=sqrt(p+.5), e=1;
     LL v=inv(modexp(a,m,p), p);
     map<LL,int> x;
      x[1]=0;
      for(int i=1;i<m;++i) {</pre>
          = LLmul(e,a,p);
        if(!x.count(e)) x[e] = i;
85
      for(int i=0;i<m;++i) {</pre>
        if(x.count(b)) return i*m + x[b];
        b = LLmul(b, v, p);
     return -1:
   LL Tonelli_Shanks(const LL &n, const LL &
      p) {
// x^2 = n ( mod p )
     int S = 0;
     LL Q = p-1;
      while( !(Q&1) ) { Q>>=1; ++S; }
      if(S==1) return modexp(n%p,(p+1)/4,p);
     LL z = 2:
     for(;Legendre(z,p)!=-1;++z)
LL c = modexp(z,Q,p);
LL R = modexp(n%p,(Q+1)/2,p), t =
103
104
           modexp(n%p,Q,p);
     int M = S;
106
      while(1) {
107
        if(t==1) return R;
108
        LL b = modexp(c,1L<<(M-i-1),p);
109
        R = LLmul(R,b,p);
        t = LLmul( LLmul(b,b,p), t, p);
        c = LLmul(b,b,p);
112
113
        M = i;
114
     return -1:
115
116
118
   template<typename T>
119
   T Euler(T n){
120
     T ans=n;
      for(T i=2;i*i<=n;++i){</pre>
121
        if(n%i==0){
          ans=ans/i*(i-1);
          while(n%i==0)n/=i;
125
126
     if(n>1)ans=ans/n*(n-1);
127
     return ans;
128
129
130
131
   //Chinese_remainder_theorem
   template < typename T>
T pow_mod(T n,T k,T m){
132
133
      T ans=1;
134
135
      for(n=(n>=m?n%m:n);k;k>>=1){
        if(k&1)ans=ans*n%m;
        n=n*n%m;
137
138
     return ans:
139
140
   template<typename T>
   T crt(vector<T> &m, vector<T> &a){
     T M=1,tM,ans=0;
      for(int i=0;i<(int)m.size();++i)M*=m[i</pre>
144
      for(int i=0;i<(int)a.size();++i){</pre>
145
        tM=M/m[i];
146
        ans=(ans+(a[i]*tM%M)*pow_mod(tM,Euler
             (m[i])-1,m[i])%M)%M;
        /*如果m[i]是質數·Euler(m[i])-1=m[i
             ]-2 · 就不用算Euler了*/
150
      return ans;
152
153 //java code
   //求sqrt(N)的 連分數
   public static void Pell(int n){
  BigInteger N,p1,p2,q1,q2,a0,a1,a2,g1,g2
     ,h1,h2,p,q;
g1=q2=p1=BigInteger.ZERO;
      h1=q1=p2=BigInteger.ONE;
      a0=a1=BigInteger.valueOf((int)Math.sqrt
           (1.0*n));
```

for(int i=2;i<n;++i)</pre>

74

inv[i]=(P-(P/i))*inv[P%i]%P;

```
160
      BigInteger ans=a0.multiply(a0);
      if(ans.equals(BigInteger.valueOf(n))){
   System.out.println("No solution!");
161
162
163
164
       while(true){
         g2=a1.multiply(h1).substract(g1);
h2=N.substract(g2.pow(2)).divide(h1);
a2=g2.add(a0).divide(h2);
166
167
168
         p=a1.multiply(p2).add(p1);
169
          q=a1.multiply(q2).add(q1);
170
          if(p.pow(2).substract(N.multiply(q.
                pow(2))).compareTo(BigInteger.
                ONE)==0)break;
          g1=g2;h1=h2;a1=a2;
172
         p1=p2;p2=p;
173
174
         q1=q2;q2=q;
      System.out.println(p+" "+q);
176
177 }
```

6.2 bit set

```
| void sub_set(int S) {
| int sub=S; | do {
| //對某集合的子集合的處理 | sub=(sub-1)&S; | } while(sub!=S); | }
| void k_sub_set(int k,int n) {
| int comb=(1<<k)-1,S=1<<n; | while(comb<S) {
| //對大小為k的子集合的處理 | int x=comb&-comb,y=comb+x; | comb=((comb&~y)/x>>1) | y; | }
| }
```

6.3 cantor expansion

```
int factorial[MAXN];
   void init(){
     factorial[0]=1;
     for(int i=1;i<=MAXN;++i)factorial[i]=</pre>
           factorial[i-1]*i;
  int encode(const vector<int> &s){
     int n=s.size(),res=0;
     for(int i=0;i<n;++i){</pre>
       int t=0;
       for(int j=i+1;j<n;++j)
  if(s[j]<s[i])++t;
res+=t*factorial[n-i-1];</pre>
11
12
13
     return res;
   vector<int> decode(int a,int n){
16
     vector<int> res;
vector<bool> vis(n,0);
18
     for(int i=n-1;i>=0;--i){
        int t=a/factorial[i],j;
        for(j=0;j<n;++j)</pre>
          if(!vis[j]){
23
            if(t==0)break;
24
             --t;
25
        res.push_back(j);
        vis[j]=1;
       a%=factorial[i];
30
     return res;
```

6.4 find real root

```
12 double find(const vector<double>&coef,
     int n, double lo, double hi){
double sign_lo, sign_hi;
     if( !(sign_lo = sign(get(coef,lo))) )
14
           return lo;
     if( !(sign_hi = sign(get(coef,hi))) )
          return hi:
     17
       double m = (lo+hi)/2.0;
       int sign_mid = sign(get(coef,m));
if(!sign_mid) return m;
19
20
       if(sign_lo*sign_mid < 0) hi = m;
else lo = m;</pre>
21
22
     return (lo+hi)/2.0;
  }
25
   vector<double> cal(vector<double>coef,
2.7
        int n){
     vector<<mark>double</mark>>res;
     if(n == 1){
       if(sign(coef[1])) res.pb(-coef[0]/
30
            coef[1]);
       return res:
31
32
     vector<double>dcoef(n);
33
     for(int i = 0; i < n; ++i) dcoef[i] =
    coef[i+1]*(i+1);</pre>
     vector<double>droot = cal(dcoef, n-1);
     droot.insert(droot.begin(), -INF);
36
     droot.pb(INF);
37
     for(int i = 0; i+1 < droot.size(); ++i)</pre>
38
       double tmp = find(coef, n, droot[i],
            droot[i+1]);
       if(tmp < INF) res.pb(tmp);</pre>
40
41
     return res;
42
  }
43
45 int main () {
     vector<double>ve;
     vector<double>ans = cal(ve, n);
     // 視情況把答案 +eps · 避免 -0
```

6.5 LinearCongruence

```
pair<LL,LL> LinearCongruence(LL a[],LL b
     [],LL m[],int n) {
// a[i]*x = b[i] ( mod m[i] )
     for(int i=0;i<n;++i) {</pre>
       LL x, y, d = extgcd(a[i],m[i],x,y);
       if(b[i]%d!=0) return make_pair(-1LL,0
            LL);
       m[i] /= d;
       b[i] = LLmul(b[i]/d,x,m[i]);
     LL lastb = b[0], lastm = m[0];
     for(int i=1;i<n;++i) {</pre>
       LL x, y, d = extgcd(m[i],lastm,x,y);
if((lastb-b[i])%d!=0) return
11
12
            make_pair(-1LL,0LL);
       lastb = LLmul((lastb-b[i])/d,x,(lastm
13
            /d))*m[i];
       lastm = (lastm/d)*m[i];
       lastb = (lastb+b[i])%lastm;
16
     return make pair(lastb<0?lastb+lastm:</pre>
17
          lastb, lastm);
18 }
```

6.6 Lucas

6.7 Matrix

1 template < tvpename T>

return res*f[n%p]%p; //(p-1)!%p=-1

```
struct Matrix{
      using rt = std::vector<T>;
      using mt = std::vector<rt>;
      using matrix = Matrix<T>;
      int r,c;
      mt m;
      Matrix(int r,int c):r(r),c(c),m(r,rt(c)
            ){}
      rt& operator[](int i){return m[i];}
      matrix operator+(const matrix &a){
        matrix rev(r,c);
for(int i=0;i<r;++i)
  for(int j=0;j<c;++j)
    rev[i][j]=m[i][j]+a.m[i][j];</pre>
12
13
14
17
      matrix operator-(const matrix &a){
        matrix rev(r,c);
for(int i=0;i<r;++i)
   for(int j=0;j<c;++j)
    rev[i][j]=m[i][j]-a.m[i][j];</pre>
18
19
20
         return rev
23
      matrix operator*(const matrix &a){
24
        matrix rev(r,a.c);
matrix tmp(a.c,a.r);
         for(int i=0;i<a.r;++i)</pre>
           for(int j=0;j<a.c;++j)
  tmp[j][i]=a.m[i][j];</pre>
29
        for(int i=0;i<r;++i)
  for(int j=0;j<a.c;++j)
    for(int k=0;k<c;++k)</pre>
30
31
32
                 rev.m[i][j]+=m[i][k]*tmp[j][k];
33
35
      bool inverse(){
36
        Matrix t(r,r+c);
for(int y=0;y<r;y++){
  t.m[y][c+y] = 1;</pre>
37
38
41
              t.m[y][x]=m[y][x];
        if(!t.gas())
43
           return false;
         for(int y=0;y<r;y++)</pre>
            for(int x=0;x<c;++x)</pre>
              m[y][x]=t.m[y][c+x]/t.m[y][y];
         return true;
      T gas(){
         vector<T> lazy(r,1);
         bool sign=false;
         for(int i=0;i<r;++i){</pre>
           if( m[i][i]==0 ){
55
              int j=i+1;
              while(j<r&&!m[j][i])j++;</pre>
56
              if(j==r)continue;
              m[i].swap(m[j]);
              sign=!sign;
           for(int j=0;j<r;++j){</pre>
              if(i==j)continue
62
              lazy[j]=lazy[j]*m[i][i];
63
              T mx=m[j][i];
for(int k=0;k<c;++k)
                 \texttt{m[j][k]=m[j][k]*m[i][i]-m[i][k]}
                       ]*mx;
           }
67
68
         T det=sign?-1:1;
         for(int i=0;i<r;++i){</pre>
           det = det*m[i][i];
           det = det/lazy[i];
72
           for(auto &j:m[i])j/=lazy[i];
         return det;
```

6.8 MillerRobin

```
1 ULL LLmul(ULL a, ULL b, const ULL &mod) {
2     LL ans=0;
3     while(b) {
4     if(b&1) {
```

```
ans+=a;
          if(ans>=mod) ans-=mod;
       a<<=1, b>>=1;
       if(a>=mod) a-=mod;
10
11
     return ans;
12
  ULL mod_mul(ULL a,ULL b,ULL m){
    a%=m,b%=m;/* fast for m < 2^58 */
    ULL y=(ULL)((double)a*b/m+0.5);
13
     ULL r=(a*b-y*m)%m;
     return r<0?r+m:r;
18
   template<typename T>
19
  T pow(T a,T b,T mod){//a^b\%mod}
20
     T ans=1:
     for(;b;a=mod_mul(a,a,mod),b>>=1)
23
       if(b&1)ans=mod_mul(ans,a,mod);
     return ans;
25
  }
  int sprp[3]={2,7,61};//int範圍可解
26
27
  int llsprp
        [7]={2,325,9375,28178,450775,9780504,
  1795265022};//至少unsigned Long long範圍
   template<typename T>
   bool isprime(T n,int *sprp,int num){
     if(n==2)return 1;
     if(n<2||n%2==0)return 0;
33
     int t=0;
     T u=n-1;
34
     for(;u%2==0;++t)u>>=1;
35
     for(int i=0;i<num;++i){</pre>
       T a=sprp[i]%n;
if(a==0||a==1||a==n-1)continue;
39
       T x=pow(a,u,n);
40
       if(x==1||x==n-1)continue;
       for(int j=0;j<t;++j){</pre>
41
          x=mod_mul(x,x,n);
42
          if(x==1)return 0;
          if(x==n-1)break;
       if(x==n-1)continue;
46
47
       return 0;
     return 1:
```

6.9 NTT

6.10 Simpson

wi=wi*wn%P:

out[N-i]);

invn%P:

}

if(is_inv){

37

38

39

41

42

43

45 };

```
double simpson(double a,double b){
    double c=a+(b-a)/2;
    return (F(a)+4*F(c)+F(b))*(b-a)/6;
}
double asr(double a,double b,double eps,
    double A){
    double c=a+(b-a)/2;
    double L=simpson(a,c),R=simpson(c,b);
    if(abs(L+R-A)<15*eps)
    return L+R+(L+R-A)/15.0;
    return asr(a,c,eps/2,L)+asr(c,b,eps/2,R
    );
}
double asr(double a,double b,double eps){
    return asr(a,b,eps,simpson(a,b));
}</pre>
```

for(int i=1;i<N/2;++i)swap(out[i],</pre>

T invn=pow_mod(N,P-2,P);
for(int i=0;i<N;++i)out[i]=out[i]*</pre>

6.11 SpeedExpo

6.12 外星模運算

```
1 //a[0]^(a[1]^a[2]^...)
                                                        #define maxn 1000000
  2615053605667*(2^18)+1,3
                                                        int euler[maxn+5];
  15*(2^27)+1,31
                                                        bool is_prime[maxn+5];
  479*(2^21)+1.3
                                                        void init_euler(){
   7*17*(2^23)+1,3
                                                           is_prime[1]=1;//一不是質數
   3*3*211*(2<sup>1</sup>9)+1,5
                                                           for(int i=1;i<=maxn;i++)euler[i]=i;
for(int i=2;i<=maxn;i++){</pre>
   25*(2^22)+1,3
   template < typename T, typename VT = vector < T >
                                                             if(!is_prime[i]){//是質數
   struct NTT{
                                                                euler[i]--
                                                                for(int j=i<<1;j<=maxn;j+=i){</pre>
     const T P.G:
                                                                 is prime[j]=1;
     NTT(T p=(1<<23)*7*17+1,T g=3):P(p),G(g)
10
                                                    12
          {}
                                                                  euler[j]=euler[j]/i*(i-1);
     unsigned bit_reverse(unsigned a,int len
11
          ) {
                                                             }
                                                      15
       //Look FFT.cpp
                                                          }
                                                        }
13
                                                     17
     T pow_mod(T n,T k,T m){
                                                        LL pow(LL a, LL b, LL mod){//a^b\%mod}
                                                     18
                                                           LL ans=1;
15
       T ans=1;
                                                     19
       for(n=(n>=m?n%m:n);k;k>>=1){
                                                           for(;b;a=a*a%mod,b>>=1)
          if(k&1)ans=ans*n%m;
                                                             if(b&1)ans=ans*a%mod;
18
         n=n*n%m;
                                                     22
                                                           return ans:
19
                                                     23
                                                        bool isless(LL *a,int n,int k){
20
       return ans;
                                                     24
                                                           if(*a==1)return k>1;
21
     void ntt(bool is_inv,VT &in,VT &out,int
                                                           if(--n==0)return *a<k;</pre>
                                                           int next=0;
           N){
23
       int bitlen=
                      _lg(N);
                                                           for(LL b=1;b<k;++next)</pre>
       for(int i=0;i<N;++i)out[bit_reverse(i</pre>
                                                             b*=*a:
24
                                                     29
             ,bitlen)]=in[i];
                                                           return isless(a+1,n,next);
                                                     30
       for(int step=2,id=1;step<=N;step</pre>
25
                                                     31
             <<=1,++id){
                                                        LL high_pow(LL *a, int n, LL mod){
          T wn=pow_mod(G,(P-1)>>id,P),wi=1,u,
                                                           if(*a==1||--n==0)return *a%mod;
26
                                                           int k=0,r=euler[mod];
               t;
                                                     34
         const int mh=step>>1;
for(int i=0;i<mh;++i){
  for(int j=i;j<N;j+=step){
    u=out[j],t=wi*out[j+mh]%P;</pre>
                                                           for(LL tma=1;tma!=pow(*a,k+r,mod);++k)
   tma=tma*(*a)%mod;
                                                     35
28
                                                     36
                                                           if(isless(a+1,n,k))return pow(*a,
                                                     37
                                                                high_pow(a+1,n,k),mod);
                                                           int tmd=high\_pow(a+1,n,r), t=(tmd-k+r)%
              out[j]=u+t;
              out[j+mh]=u-t;
if(out[j]>=P)out[j]-=P;
33
                                                     39
                                                           return pow(*a,k+t,mod);
              if(out[j+mh]<0)out[j+mh]+=P;</pre>
                                                        }
34
                                                     40
35
                                                     41 LL a[1000005];
```

6.13 大數取模

```
LL exp(LL x,LL y,LL p){
    if(y == 0) return 1;
    if(y & 1) return (exp(x,y-1,p)*x) % p
        ;//y is odd

else{
    LL temp = exp(x,y/2,p);
    return (temp*temp) % p;
}

LL calcmod(LL index,LL p){
    if(index == 0) return base[index]-'0'
    ;
LL single = calcmod(index-1,p)*10;
    return (single%p + base[index]-'0')%p
    ;
}
```

6.14 數位統計

```
ı | 11 d[65], dp[65][2];//up區間是不是完整
2 11 dfs(int p,bool is8,bool up){
     if(!p)return 1; // 回傳0是不是答案
if(!up&&~dp[p][is8])return dp[p][is8];
     int mx = up?d[p]:9;//可以用的有那些
     11 ans=0;
     for(int i=0;i<=mx;++i){
   if( is8&&i==7 )continue;
   ans += dfs(p-1,i==8,up&&i==mx);</pre>
10
     if(!up)dp[p][is8]=ans;
     return ans;
14
   11 f(11 N){
15
     int k=0;
     while(N){ // 把數字先分解到陣列
d[++k] = N%10;
16
17
        N/=10:
18
     return dfs(k,false,true);
```

6.15 質因數分解

```
I LL func(const LL n,const LL mod,const int
     return (LLmul(n,n,mod)+c+mod)%mod;
  }
  LL pollorrho(const LL n, const int c) {//
        循環節長度
    LL a=1, b=1;
a=func(a,n,c)%n;
b=func(b,n,c)%n; b=func(b,n,c)%n;
     while(gcd(abs(a-b),n)==1) {
       a=func(a,n,c)%n;
11
       b=func(b,n,c)%n; b=func(b,n,c)%n;
12
     return gcd(abs(a-b),n);
13
14
15
  void prefactor(LL &n, vector<LL> &v) {
     for(int i=0;i<12;++i) {</pre>
17
       while(n%prime[i]==0)
         v.push_back(prime[i]);
         n/=prime[i];
    }
  }
24
  void smallfactor(LL n, vector<LL> &v) {
    if(n<MAXPRIME) {</pre>
```

```
while(isp[(int)n]) {
          v.push_back(isp[(int)n]);
n/=isp[(int)n];
28
                                                        24
29
                                                        25
                                                        26
31
        v.push_back(n);
32
        for(int i=0;i<primecnt&&prime[i]*</pre>
33
                                                        29
             prime[i]<=n;++i) {</pre>
                                                        30
          while(n%prime[i]==0)
                                                        31
            v.push_back(prime[i]);
35
                                                        32
            n/=prime[i];
                                                        34
                                                        35
        if(n!=1) v.push_back(n);
39
                                                        36
     }
40
                                                        37
  }
41
   void comfactor(const LL &n, vector<LL> &v
     if(n<1e9) {
44
                                                        42
        smallfactor(n,v);
45
                                                        43
46
       return;
     if(Isprime(n)) {
                                                        45
49
       v.push_back(n);
50
       return;
51
                                                       47
52
     LL d:
                                                        48
     for(int c=3;;++c) {
                                                        49
       d = pollorrho(n,c);
55
        if(d!=n) break;
                                                       51
57
     comfactor(d,v);
                                                        52
     comfactor(n/d,v);
58
                                                        53
59
  }
   void Factor(const LL &x, vector<LL> &v) {
                                                       56
     LL n = x;
62
     if(n==1) { puts("Factor 1"); return; }
63
                                                        57
     prefactor(n,v);
64
                                                        58
     if(n==1) return;
65
                                                        59
     comfactor(n,v);
66
67
     sort(v.begin(),v.end());
                                                        60
68
  }
                                                        61
69
                                                        62
   void AllFactor(const LL &n, vector<LL> &v)
70
     vector<LL> tmp;
     Factor(n,tmp);
                                                        65
73
     v.clear();
                                                        66
     v.push_back(1);
                                                        67
75
     int len:
     LL now=1;
76
     for(int i=0;i<tmp.size();++i) {</pre>
       if(i==0 || tmp[i]!=tmp[i-1]) {
                                                        69
          len = v.size();
                                                        70
80
          now = 1;
                                                        71
81
                                                        72
       now*=tmp[i];
for(int j=0;j<len;++j)
   v.push_back(v[j]*now);</pre>
82
                                                        74
85
                                                        75
86 }
                                                        76
                                                        77
                                                        78
                                                        79
                                                        80
```

String

7.1 AC 自動機

```
84
  template<char L='a',char R='z'>
                                                   85
  class ac_automaton{
                                                   86
    struct joe{
       int next[R-L+1],fail,efl,ed,cnt_dp,
                                                   87
            vis;
       joe():ed(0),cnt_dp(0),vis(0){
                                                   88
         for(int i=0;i<=R-L;++i)next[i]=0;</pre>
       }
                                                   90
  };
public:
                                                   91
    std::vector<joe> S;
                                                   92
     std::vector<int> q;
                                                   93
11
     int qs,qe,vt;
     ac_automaton():S(1),qs(0),qe(0),vt(0){}
14
     void clear(){
                                                   96
       q.clear();
                                                   97
16
       S.resize(1):
       for(int i=0;i<=R-L;++i)S[0].next[i</pre>
17
                                                   98
            1=0;
                                                   99
       S[0].cnt_dp=S[0].vis=qs=qe=vt=0;
                                                   100
     void insert(const char *s){
20
                                                  101
21
       int o=0;
                                                  102
22
       for(int i=0,id;s[i];++i){
```

81

82

83

```
id=s[i]-L;
   if(!S[o].next[id]){
   S.push_back(joe());
      S[o].next[id]=S.size()-1;
    o=S[o].next[id];
  ++S[o].ed;
void build_fail(){
 S[0].fail=S[0].efl=-1;
  q.clear();
  q.push_back(0);
  ++qe;
  while(qs!=qe){
    int pa=q[qs++],id,t;
    for(int i=0;i<=R-L;++i){</pre>
      t=S[pa].next[i];
      if(!t)continue;
      id=S[pa].fail;
      while(~id&&!S[id].next[i])id=S[id
    ].fail;
      S[t].fail=~id?S[id].next[i]:0;
      S[t].efl=S[S[t].fail].ed?S[t].
          fail:S[S[t].fail].efl;
      q.push_back(t);
      ++qe;
 }
/*DP出每個前綴在字串s出現的次數並傳回所
    有字串被s匹配成功的次數O(N+M)*/
int match 0(const char *s){
  int ans=0,id,p=0,i;
  for(i=0;s[i];++i){
    id=s[i]-L;
    while(!S[p].next[id]&&p)p=S[p].fail
    if(!S[p].next[id])continue;
   p=S[p].next[id];
    ++S[p].cnt_dp;/*匹配成功則它所有後
         綴都可以被匹配(DP計算)*/
  for(i=qe-1;i>=0;--i){
    ans+=S[q[i]].cnt_dp*S[q[i]].ed;
    if(~S[q[i]].fail)S[S[q[i]].fail].
        cnt_dp+=S[q[i]].cnt_dp;
  return ans;
}
/*多串匹配走efl邊並傳回所有字串被s匹配
    成功的次數O(N*M^1.5)*/
int match_1(const char *s)const{
  int ans=0,id,p=0,t;
  for(int i=0;s[i];++i){
  id=s[i]-L;
    while(!S[p].next[id]&&p)p=S[p].fail
    if(!S[p].next[id])continue;
    p=S[p].next[id];
    if(S[p].ed)ans+=S[p].ed;
for(t=S[p].efl;~t;t=S[t].efl){
      ans+=S[t].ed;/*因為都走efl邊所以
          保證匹配成功*/
   }
 }
 return ans;
·
/*枚舉(s的子字串nA)的所有相異字串各恰一
    次並傳回次數O(N*M^(1/3))*/
int match_2(const char *s){
 int ans=0,id,p=0,t;
  ++vt:
  /*把戳記vt+=1,只要vt沒溢位,所有S[p
       ].vis==vt就會變成false
  這種利用vt的方法可以0(1)歸零vis陣列*/
  for(int i=0;s[i];++i){
    id=s[i]-L;
```

while(!S[p].next[id]&&p)p=S[p].fail

for(t=S[p].efl;~t&&S[t].vis!=vt;t=S

ans+=S[t].ed;/*因為都走efl邊所以

if(!S[p].next[id])continue;

if(S[p].ed&&S[p].vis!=vt){

保證匹配成功*/

p=S[p].next[id];

S[p].vis=vt

ans+=S[p].ed;

[t].efl){

S[t].vis=vt;

}

return ans;

```
/*把AC自動機變成真的自動機*/
104
105
     void evolution(){
106
       for(qs=1;qs!=qe;){
          int p=q[qs++];
for(int i=0;i<=R-L;++i)</pre>
107
108
            if(S[p].next[i]==0)S[p].next[i]=S
109
                 [S[p].fail].next[i];
110
111
112 };
   7.2 hash
 1 #define MAXN 1000000
   #define mod 1073676287
```

```
/*mod 必須要是質數*/
  typedef long long T;
char s[MAXN+5];
  T h[MAXN+5];/*hash 陣列*/
  T h_base[MAXN+5];/*h_base[n]=(prime^n)%
       mod*
  void hash_init(int len,T prime){
    h_base[0]=1;
    for(int i=1;i<=len;++i){</pre>
      h[i]=(h[i-1]*prime+s[i-1])%mod;
      h_base[i]=(h_base[i-1]*prime)%mod;
13
14 }
15 | T get_hash(int 1,int r){/*閉區間寫法・設
       編號為0 ~ Len-1*,
    return (h[r+1]-(h[1]*h_base[r-1+1])%mod
         +mod)%mod;
```

7.3 KMP

103

```
/*產生fail function*/
  void kmp_fail(char *s,int len,int *fail){
  int id=-1;
     fail[0]=-1;
     for(int i=1;i<len;++i){</pre>
       while(~id&&s[id+1]!=s[i])id=fail[id];
       if(s[id+1]==s[i])++id;
       fail[i]=id;
    }
10 }
  /*以字串B匹配字串A·傳回匹配成功的數量(用
11
        B的fail)*
  int kmp_match(char *A,int lenA,char *B,
    int lenB,int *fail){
     int id=-1,ans=0;
for(int i=0;i<lenA;++i){</pre>
       while(~id&&B[id+1]!=A[i])id=fail[id];
       if(B[id+1]==A[i])++id;
16
       if(id==lenB-1){/*匹配成功*/
17
          ++ans, id=fail[id];
19
21
     return ans:
```

7.4 manacher

15

```
ı | //原字串: asdsasdsa
 //先把字串變成這樣: @#a#s#d#s#a#s#d#s#a#
 void manacher(char *s,int len,int *z){
   int l=0,r=0;
    for(int i=1;i<len;++i){
  z[i]=r>i?min(z[2*1-i],r-i):1;
      while(s[i+z[i]]==s[i-z[i]])++z[i];
      if(z[i]+i>r)r=z[i]+i,l=i;
           = max(z)-1
```

7.5 minimal string rotation

```
i int min_string_rotation(const string &s){
    int n=s.size(),i=0,j=1,k=0;
    while(i<n&&j<n&&k<n){</pre>
      int t=s[(i+k)%n]-s[(j+k)%n];
      if(t){
```

```
| f(t>0)i+=k;
| else j+=k;
| if(i==j)++j;
| k=0;
| }
| return min(i,j);//最小循環表示法起始位置
```

7.6 reverseBWT

```
const int MAXN = 305, MAXC = 'Z';
int ranks[MAXN], tots[MAXC], first[MAXC];
void rankBWT(const string &bw){
  memset(ranks,0,sizeof(int)*bw.size());
      memset(tots,0,sizeof(tots);
      for(size_t i=0;i<bw.size();++i)</pre>
         ranks[i] = tots[int(bw[i])]++;
   void firstCol(){
  memset(first,0,sizeof(first));
10
      int totc = 0;
for(int c='A';c<='Z';++c){
   if(!tots[c]) continue;
11
14
         first[c] = totc;
         totc += tots[c];
15
      }
16
17
   string reverseBwt(string bw,int begin){
18
      rankBWT(bw), firstCol();
      int i = begin; //原字串最後一個元素的位
20
      string res;
      do{
22
         char c = bw[i];
res = c + res;
23
24
         i = first[int(c)] + ranks[i];
      }while( i != begin );
      return res;
```

7.7 suffix array lcp

```
#define radix_sort(x,y){\
      for(i=0;i<A;++i)c[i]=0;\
for(i=0;i<n;++i)c[x[y[i]]]++;\
for(i=1;i<A;++i)c[i]+=c[i-1];\</pre>
      for(i=n-1;~i;--i)sa[--c[x[y[i]]]]=y[i
   #define AC(r,a,b)\
r[a]!=r[b]||a+k>=n||r[a+k]!=r[b+k]
   int A='z'+1,i,k,id=0;
      for(i=0;i<n;++i)rank[tmp[i]=i]=s[i];</pre>
      radix_sort(rank,tmp);
for(k=1;id<n-1;k<<=1){</pre>
13
         for(id=0,i=n-k;i<n;++i)tmp[id++]=i;</pre>
         for(i=0;i<n;++i)</pre>
15
           if(sa[i]>=k)tmp[id++]=sa[i]-k;
         radix_sort(rank,tmp);
         swap(rank, tmp);
for(rank[sa[0]]=id=0,i=1;i<n;++i)</pre>
18
           rank[sa[i]]=id+=AC(tmp,sa[i-1],sa[i
20
                 1);
        A=id+1;
22
23 }
   //h:高度數組 sa:後綴數組 rank:排名
   void suffix_array_lcp(const char *s,int
len,int *h,int *sa,int *rank){
for(int i=0;i<len;++i)rank[sa[i]]=i;
for(int i=0,k=0;i<len;++i){</pre>
27
         if(rank[i]==0)continue;
         while(s[i+k]==s[sa[rank[i]-1]+k])++k;
31
        h[rank[i]]=k;
32
      h[0]=0;// h[k]=lcp(sa[k],sa[k-1]);
33
```

```
void z_alg(char *s,int len,int *z){
    int l=0,r=0;
    z[0]=len;
    for(int i=1;i<len;++i){
        z[i]=i>r?0:(i-l+z[i-l]<z[l]?z[i-l]:r-i+1);
        while(i+z[i]<len&s[i+z[i]]==s[z[i]])
        ++z[i];
    if(i+z[i]-1>r)r=i+z[i]-1,l=i;
}
```

#define n(X) ((X)+2*N)
vector<int> v[MAXN2], rv[MAXN2], vis_t;

8 Tarjan

8.1 tnfshb017 2 sat

| #include < bits / stdc++.h>

using namespace std;
#define MAXN 8001

#define MAXN2 MAXN*4

int N,M;

```
void addedge(int s,int e){
  v[s].push_back(e);
     rv[e].push_back(s);
11
   int scc[MAXN2];
   bool vis[MAXN2]={false};
13
   void dfs(vector<int> *uv,int n,int k=-1){
      vis[n]=true;
15
      for(int i=0;i<uv[n].size();++i)</pre>
16
        if(!vis[uv[n][i]])
  dfs(uv,uv[n][i],k);
17
      if(uv==v)vis_t.push_back(n);
19
20
      scc[n]=k;
   }
21
   void solve(){
22
      for(int i=1;i<=N;++i){</pre>
        if(!vis[i])dfs(v,i);
        if(!vis[n(i)])dfs(v,n(i));
25
26
      memset(vis,0,sizeof(vis));
27
28
      int c=0;
      for(int i=vis_t.size()-1;i>=0;--i)
        if(!vis[vis_t[i]])
          dfs(rv,vis_t[i],c++);
32
33
   int main(){
      int a,b;
34
      scanf("%d%d",&N,&M);
35
      for(int i=1;i<=N;++i){</pre>
        // (A or B)&(!A & !B) A^B
a=i*2-1;
37
38
        b=i*2;
39
        addedge(n(a),b);
        addedge(n(b),a);
41
        addedge(a,n(b));
        addedge(b,n(a));
43
44
      while(M--){
  scanf("%d%d",&a,&b);
  a = a>0?a*2-1:-a*2;
45
46
47
        b = b>0?b*2-1:-b*2;
48
        addedge(n(a),b);
50
51
        addedge(n(b),a);
53
      solve():
      bool check=true;
      for(int i=1;i<=2*N;++i)</pre>
        if(scc[i]==scc[n(i)])
           check=false;
      if(check){
  printf("%d\n",N);
  for(int i=1;i<=2*N;i+=2){</pre>
58
59
60
           if(scc[i]>scc[i+2*N]) putchar('+');
           else putchar('-');
        puts("");
      }else puts("0");
      return 0;
```

8.2 雙連通分量 **&** 割點

```
#define N 1005
vector<int> G[N];// 1-base
```

```
bool is_cut[N];//是否為割點
int st[N],top;
   void dfs(int u,int pa=-1){//u當前點·pa父
     int t, child=0;
low[u]=vis[u]=++Time;
11
     st[top++]=u;
for(int v:G[u]){
12
       if(!vis[v]){
13
          dfs(v,u),++child;
          low[u]=min(low[u],low[v]);
15
16
          if(vis[u]<=low[v]){</pre>
            is_cut[u]=1;
bcc[++bcc_cnt].clear();
17
18
            do{
19
               bcc_id[t=st[--top]]=bcc_cnt;
21
               bcc[bcc_cnt].push_back(t);
22
            }while(t!=v);
23
            bcc_id[u]=bcc_cnt;
            bcc[bcc_cnt].push_back(u);
24
25
26
       }else if(vis[v]<vis[u]&&v!=pa)//反向
          low[u] = min(low[u], vis[v]);
27
      //u是dfs樹的根要特判
29
     if(pa==-1&&child<2)is_cut[u]=0;</pre>
30
   void bcc init(int n){
31
     Time=bcc_cnt=top=0;
32
     for(int i=1;i<=n;++i){</pre>
       G[i].clear();
35
       is_cut[i]=vis[i]=bcc_id[i]=0;
36
```

3 vector (int > bcc[N]; // 存每塊雙連通分量的點

int low[N], vis[N], Time;
int bcc_id[N], bcc_cnt;// 1-base

9 Tree Problem

9.1 HeavyLight

```
#include<vector>
   #define MAXN 100005
   int siz[MAXN], max_son[MAXN], pa[MAXN], dep[
         MAXN];
   int link_top[MAXN],link[MAXN],cnt;
vector<int> G[MAXN];
void find_max_son(int u){
     siz[u]=\overline{1};
     max_son[u]=-1;
     for(auto v:G[u]){
        if(v==pa[u])continue;
10
       pa[v]=u;
11
        dep[v]=dep[u]+1;
12
        find_max_son(v);
13
        if(max_son[u]==-1||siz[v]>siz[max_son
14
              [u]])max_son[u]=v;
15
        siz[u]+=siz[v];
16
     }
17
   void build_link(int u,int top){
18
     link[u]=++cnt;
19
     link_top[u]=top;
     if(max_son[u]==-1)return;
build_link(max_son[u],top);
for(auto v:G[u]){
21
22
23
        if(v==max_son[u]||v==pa[u])continue;
24
        build_link(v,v);
25
27
   int find_lca(int a,int b){
    //求LCA · 可以在過程中對區間進行處理
28
     int ta=link_top[a],tb=link_top[b];
31
     while(ta!=tb){
       if(dep[ta]<dep[tb]){
  swap(ta,tb);</pre>
32
33
          swap(a,b);
34
35
        //這裡可以對a所在的鏈做區間處理
36
        //區間為(link[ta],link[a])
37
        ta=link_top[a=pa[ta]];
38
39
     //最後a,b會在同一條鏈·若a!=b還要在進行
40
            一次區間處理
     return dep[a]<dep[b]?a:b;</pre>
42 }
```

44

45

48

50

51

52

53

55

56

58

59

60

61

63

64

65

66

68

69 }

70

71

72

75

76

77

78

80

81

94

void make_root(int x){

access(x),splay(x);
nd[x].rev^=1;

void make root(int x){

void cut(int x,int y){

void cut_parents(int x){

nd[nd[x].ch[0]].pa=0;

void link(int x,int y){

int find_root(int x){

int query(int u,int v){

//這種寫法無法求LCA

return access(v);

int query_lca(int u,int v){

[1]].sum

和, data是節點的權重

make_root(u);

access(u); int lca=access(v);

splay(u);

}else{

struct EDGE{

}e[10005];

int a,b,w;

tree

}

if(u==lca){

while(nd[x].ch[0])x=nd[x].ch[0];

//假設求鏈上點權的總和, sum是子樹的權重

//return nd[lca].data+nd[nd[lca].ch

//return nd[lca].data+nd[nd[lca].ch

[1]].sum+nd[u].sum

//first表示子節點, second表示邊的編號

編被存在哪個點裡面的陣列

make_root(x);

nd[y].ch[0]=0;

nd[x].ch[0]=0;

make_root(x);

nd[x].pa=y;

x=access(x);

splay(x);

return x;

access(y);

nd[x].pa=0;

access(x);

splay(x);

splay(y);

splay(x);

nd[access(x)].rev^=1;

9.2 LCA

```
const int MAXN=100000; // 1-base
   const int MLG=17; //Log2(MAXN)+1;
int pa[MLG+2][MAXN+5];
   int dep[MAXN+5];
   vector<int> G[MAXN+5];
   void dfs(int x,int p=0){//dfs(root);
      pa[0][x]=p;
      for(int i=0;i<=MLG;++i)</pre>
        pa[i+1][x]=pa[i][pa[i][x]];
      for(auto &i:G[x]){
10
        if(i==p)continue;
        dep[i]=dep[x]+1;
        dfs(i,x);
14
     }
15
   inline int jump(int x,int d){
  for(int i=0;i<=MLG;++i)</pre>
16
        if((d>>i)&1) x=pa[i][x];
20
   inline int find_lca(int a,int b){
  if(dep[a]>dep[b])swap(a,b);
  b=jump(b,dep[b]-dep[a]);
21
23
      if(a==b)return a;
      for(int i=MLG;i>=0;--i){
26
        if(pa[i][a]!=pa[i][b]){
27
           a=pa[i][a];
b=pa[i][b];
28
        }
29
      return pa[0][a];
```

9.3 link cut tree

```
82
1 struct splay_tree{
                                             83
    int ch[2],pa;//子節點跟父母
    bool rev;//反轉的懶惰標記
    splay\_tree():pa(0),rev(0)\{ch[0]=ch
         [1]=0;}
                                             87
  };
                                             88
  vector<splay_tree> nd;
                                             89
  //有的時候用vector會TLE,要注意
                                             90
8 //這邊以node[0]作為null節點
9 bool isroot(int x){//判斷是否為這棵splay
       tree的 根
10
    return nd[nd[x].pa].ch[0]!=x&&nd[nd[x].
                                             95
        pa].ch[1]!=x;
  }
                                             96
11
  void down(int x){//懶惰標記下推
12
    if(nd[x].rev){
13
      if(nd[x].ch[0])nd[nd[x].ch[0]].rev
14
                                            100
                                            101
      if(nd[x].ch[1])nd[nd[x].ch[1]].rev
15
                                            102
                                            103
      swap(nd[x].ch[0],nd[x].ch[1]);
17
      nd[x].rev=0;
    }
18
                                            106 //傳回uv路徑splay tree的根結點
19
  }
                                            107
  void push_down(int x){//所有祖先懶惰標記
20
                                            108
       下推
    if(!isroot(x))push_down(nd[x].pa);
                                            110
22
    down(x):
23
  }
  void up(int x){}//將子節點的資訊向上更新
24
  void rotate(int x){//旋轉·會自行判斷轉的
25 l
                                            113
    int y=nd[x].pa,z=nd[y].pa,d=(nd[y].ch
26
                                            115
         [1]==x);
                                            116
    nd[x].pa=z;
27
                                            117
    if(!isroot(y))nd[z].ch[nd[z].ch[1]==y]=
28
                                            118
    nd[y].ch[d]=nd[x].ch[d^1];
    nd[nd[y].ch[d]].pa=y
    nd[y].pa=x,nd[x].ch[d^1]=y;
                                            120
32
    up(y),up(x);
                                            121
  }
33
                                            122
  void splay(int x){//將x伸展到splay tree的
34
                                            123
                                            124
    push_down(x);
35
36
    while(!isroot(x)){
                                            vector<pair<int,int>> G[10005];
      int y=nd[x].pa;
37
      if(!isroot(y)){
38
                                            int pa[10005],edge_node[10005];
        int z=nd[y].pa;
39
                                            129 //pa是父母節點·暫存用的·edge_node是每個
        if((nd[z].ch[0]==y)^(nd[y].ch[0]==x
             ))rotate(y);
                                            void bfs(int root){
        else rotate(x);
                                            131 //在建構的時候把每個點都設成一個spLay
42
43
      rotate(x);
```

```
queue<int > q;
for(int i=1;i<=n;++i)pa[i]=0;</pre>
    }
                                               132
                                               133
  int access(int x){
                                                     q.push(root);
                                               134
                                                     while(q.size()){
    int last=0;
                                               135
    while(x){
                                               136
                                                       int u=q.front();
       splay(x)
                                               137
                                                       q.pop();
                                                       for(auto P:G[u]){
      nd[x].ch[1]=last;
                                               138
                                                         int v=P.first;
      up(x);
                                               139
                                                         if(v!=pa[u]){
      last=x
                                               140
                                                           pa[v]=u;
      x=nd[x].pa;
                                               141
                                                           nd[v].pa=u;
                                               143
                                                           nd[v].data=e[P.second].w;
    return last;//access後splay tree的根
                                                           edge_node[P.second]=v;
                                               145
                                                           up(v);
57 void access(int x,bool is=0){//is=0就是
                                                           q.push(v);
                                               146
       般的access
                                               147
    int last=0:
                                               148
                                                       }
    while(x){
                                                    }
       splay(x);
                                               150
       if(is&&!nd[x].pa){
                                                   void change(int x,int b){
                                               151
         152
                                                     splay(x);
                                                     //nd[x].data=b;
                                               153
                                               154
                                                     up(x);
      nd[x].ch[1]=last;
       up(x);
       last=x;
      x=nd[x].pa;
    }
                                                   9.4 POJ tree
  void query_edge(int u,int v){
    access(u):
    access(v,1);
                                                 | #include < bits / stdc++.h>
```

```
using namespace std;
#define MAXN 10005
  int n,k;
  vector<pair<int,int> >g[MAXN];
  int size[MAXN];
  bool vis[MAXN];
  inline void init(){
    for(int i=0;i<=n;++i){</pre>
      g[i].clear();
10
       vis[i]=0;
11
13
  void get_dis(vector<int> &dis,int u,int
       pa, int d){
    dis.push_back(d);
for(size_t i=0;i<g[u].size();++i){</pre>
15
       int v=g[u][i].first,w=g[u][i].second;
17
       if(v!=pa&&!vis[v])get_dis(dis,v,u,d+w
19
20 }
  vector<int> dis;//這東西如果放在函數裡會
21
  int cal(int u,int d){
22
    dis.clear();
23
    get dis(dis,u,-1,d);
     sort(dis.begin(),dis.end());
     int l=0,r=dis.size()-1,res=0;
     while(l<r){
       while(l<r&&dis[l]+dis[r]>k)--r;
28
29
       res+=r-(1++);
    return res;
32
  33
     pair<int,int> res(INT_MAX,-1);
36
     int ma=0;
     for(size_t i=0;i<g[u].size();++i){</pre>
37
       int v=g[u][i].first;
38
       if(v==pa||vis[v])continue;
       res=min(res,tree_centroid(v,u,sz));
40
41
       size[u]+=size[v];
42
       ma=max(ma,size[v]);
43
    ma=max(ma,sz-size[u]);
    return min(res, make_pair(ma,u));
46
47
  int tree_DC(int u,int sz){
48
    int center=tree_centroid(u,-1,sz).
         second;
     int ans=cal(center,0);
     vis[center]=1;
     for(size_t i=0;i<g[center].size();++i){</pre>
      int v=g[center][i].first,w=g[center][
52
       i].second;
if(vis[v])continue;
53
       ans-=cal(v,w);
       ans+=tree_DC(v,size[v]);
55
     return ans;
58
  int main(){
59
    while(scanf("%d%d",&n,&k),n||k){
```

```
init();
for(int i=1;i<n;++i){</pre>
62
         int u,v,w;
scanf("%d%d%d",&u,&v,&w);
63
          g[u].push_back(make_pair(v,w));
          g[v].push_back(make_pair(u,w));
67
       printf("%d\n",tree_DC(1,n));
68
69
     return 0;
```

default

10.1 8 queen

```
LL nqueen(LL n){
        int p[17],total = 0;
         for(int i = 0; i < n; i++)</pre>
             p[i] = i;
              bool valid = true;
for(int i = 0; i < n; i++){
    for(int j = i+1; j < n; j++){</pre>
                         if(abs(p[i]-p[j]) == j-i)
                              {//same diagonal
valid = false;
                              break;
11
                         }
                   }
              if(valid) total++;
        } while (next_permutation(p,p+n));
16
        return total:
17
18 }
```

10.2 debug

```
#ifdef DEBUG
  _PKEIII_.-
_VA_ARGS___);\
   _DO(__VA_ARGS__);\
  template < typename I > void _DO(I&&x){cerr
      <<x<<endl;}
  template<typename I,typename...T> void
      _DO(I&&x,T&&...tail){cerr<<x<<", ";
      DO(tail...):}
  #define dbg(...)
10 #endif
```

10.3 IncStack

```
//Magic
  #pragma GCC optimize "Ofast"
  //stack resize, change esp to rsp if 64-
        bit system
  asm("mov \%0, \%%esp \ " :: "g"(mem+10000000))
   -Wl,--stack,214748364 -trigraphs
                              "/STACK
  #pragma comment(linker,
        :1024000000,1024000000")
  //linux stack resize
  #include<sys/resource.h>
  void increase_stack(){
  const rlim_t ks=64*1024*1024;
  struct rlimit rl;
     int res=getrlimit(RLIMIT_STACK,&rl);
     if(!res&&rl.rlim_cur<ks){</pre>
13
       rl.rlim cur=ks;
       res=setrlimit(RLIMIT_STACK,&rl);
```

10.4 input

```
inline int read(){
  int x=0; bool f=0; char c=getchar();
  while(ch<'0'||'9'<ch)f|=ch=='-',ch=</pre>
                getchar();
```

```
while ('0' <= ch\&\&ch <= '9') x = x*10 - '0' + ch, ch
    =getchar();
return f?-x:x;
6 }
  // #!/bin/bash
8 // g++ -std=c++11 -O2 -Wall -Wextra -Wno-
unused-result -DDEBUG $1 && ./a.out
        -fsanitize=address -fsanitize=
         undefined -fsanitize=return
```

10.5 randomize

```
map<LL,LL> discret;
for(i = 0; i < n; i++){
      cin >> a[i];
         discret[a[i]] = 0;
    LL index = 0;
    for(auto &it : discret)
         it.second = index++;
```

模板 10.6

```
#include<bits/stdc++.h>
  #define good ios_base::sync_with_stdio(0)
       ;cin.tie(0)
  #define RSIZE 101
typedef long long LL;
  using namespace std;
  int main(){
       //freopen("file name", "r", stdin);
            //input redirection
10
       return 0;
11
12 }
```

11 other

11.1 matrix exponential

```
void exp(LL m[2][2], LL x){
   LL c[2][2] = {{1,1},{1,0}},n[2][2];
   n[0][0] = m[0][0]*c[0][0] + m[0][1]*c
               [1][0];
        n[0][1] = m[0][0]*c[0][1] + m[0][1]*c
        [1][1];
n[1][0] = m[1][0]*c[0][0] + m[1][1]*c
               [1][0];
        n[1][1] = m[1][0]*c[0][1] + m[1][1]*c
               [1][1];
        if(x != 1)
              exp(n,x-1);
        else
10
              cout << n[0][0];
11
        LL u[2][2] = \{\{1,1\},\{1,0\}\},n;
        cin >> n; cout << "90 \mu C^2 C^2 << n+2 << "9\mu C^3";
15
16
        exp(u,n);
```

11.2 WhatDay

```
int whatday(int y,int m,int d){
    if(m<=2)m+=12,--y;
if(y<1752||y==1752&&m<9||y==1752&&m
       return (d+2*m+3*(m+1)/5+y+y/4+5)%7;
    return (d+2*m+3*(m+1)/5+y+y/4-y/100+y
         /400)%7;
6 }
```

11.3 上下最大正方形

```
void solve(int n,int a[],int b[]){// 1-
         base
      int ans=0:
     deque<int>da,db;
      for(int l=1,r=1;r<=n;++r){</pre>
        while(da.size()&&a[da.back()]>=a[r]){
           da.pop back();
        da.push_back(r);
while(db.size()&&b[db.back()]>=b[r]){
           db.pop_back();
11
        db.push_back(r);
for(int d=a[da.front()]+b[db.front()
13
               ];r-l+1>d;++1){
           if(da.front()==1)da.pop_front();
if(db.front()==1)db.pop_front();
if(da.size()&&db.size()){
15
              d=a[da.front()]+b[db.front()];
19
        ans=max(ans,r-l+1);
20
21
     printf("%d\n",ans);
```

11.4 最大矩形

```
i| LL max_rectangle(vector<int> s){
     stack<pair<int,int > > st;
     st.push(make_pair(-1,0));
     s.push_back(0);
    LL ans=0;
for(size_t i=0;i<s.size();++i){
  int h=s[i];</pre>
       pair<int,int > now=make_pair(h,i);
       while(h<st.top().first){</pre>
10
         now=st.top();
11
         st.pop();
         ans=max(ans,(LL)(i-now.second)*now.
12
              first);
13
       if(h>st.top().first){
15
         st.push(make_pair(h,now.second));
16
17
     return ans;
18
```

12 zformula

12.1 formula

12.1.1 Pick 公式

給定頂點坐標均是整點的簡單多邊形,面積 = 內部格點 數 + 邊上格點數/2-1

12.1.2 圖論

- 1. 對於平面圖 $\cdot F = E V + C + 1 \cdot C$ 是連通
- Cv(G) · 最小邊覆蓋設為 Ce(G) · 對於任意連通
 - $\begin{array}{ll} \text{(a)} & I(G)+Cv(G)=|V| \\ \text{(b)} & M(G)+Ce(G)=|V| \end{array}$
- 4. 對於連通二分圖:
 - $\begin{array}{ll} \text{(a)} & I(G) = Cv(G) \\ \text{(b)} & M(G) = Ce(G) \end{array}$
- 5. 最大權閉合圖:
 - $\begin{array}{ll} \text{(a)} & C(u,v) = \infty, (u,v) \in E \\ \text{(b)} & C(S,v) = W_v, W_v > 0 \\ \text{(c)} & C(v,T) = -W_v, W_v < 0 \\ \text{(d)} & \text{ans} = \sum_{W_v > 0} W_v flow(S,T) \end{array}$
- 6. 最大密度子圖:
 - (a) $\forall \max \left(\frac{W_e + W_v}{|V'|} \right), e \in E', v \in V'$
 - (b) $U = \sum_{v \in V} 2W_v + \sum_{e \in E} W_e$

- (c) $C(u,v) = W_{(u,v)}, (u,v) \in E$ · 雙向邊
- (d) $C(S, v) = U, v \in V$
- (e) $D_u = \sum_{(u,v) \in E} W_{(u,v)}$
- (f) $C(v,T) = U + 2g D_v 2W_v, v \in V$
- (g) 二分搜 g: $l = 0, r = U, eps = 1/n^2$ $\mathrm{if}((U\times |V|-flow(S,T))/2>0)\,l=$ midelse r = mid
- (h) ans= $min_cut(S,T)$
- (i) |E|=0 要特殊判斷
- 7. 弦圖:
 - (a) 點數大於 3 的環都要有一條弦
 - (b) 完美消除序列從後往前依次給每個點染 色・給每個點染上可以染的最小顏色
 - (c) 最大團大小 = 色數
 - (d) 最大獨立集: 完美消除序列從前往後能選 就選
 - (e) 最小團覆蓋: 最大獨立集的點和他延伸的 邊構成
 - (f) 區間圖是弦圖
 - (g) 區間圖的完美消除序列: 將區間按造又端 點由小到大排序
 - (h) 區間圖染色: 用線段樹做

12.1.3 dinic 特殊圖複雜度

1. 單位流: $O\left(min\left(V^{3/2}, E^{1/2}\right)E\right)$ 2. 二分圖: $O(V^{1/2}E)$

12.1.4 0-1 分數規劃

 $\{0,1\}\cdot x_i$ 可能會有其他限制・求 = $\max\left(\frac{\sum B_i x_i}{\sum C_i x_i}\right)$

- 1. $D(i,g) = B_i g \times C_i$
- 2. $f(g) = \sum D(i, g)x_i$
- 3. f(g) = 0 時 g 為最佳解 $\cdot f(g) < 0$ 沒有意義
- 4. 因為 f(g) 單調可以二分搜 g
- 5. 或用 Dinkelbach 通常比較快

```
binary_search(){
    while(r-l>eps){
      g=(1+r)/2;
      for(i:所有元素)D[i]=B[i]-g*C[i];//D(i
      ,g)
找出一組合法x[i]使f(g)最大;
      if(f(g)>0) l=g;
      else r=g;
    Ans = r:
11
  Dinkelbach(){
    g=任意狀態(通常設為0);
12
    do{
13
      for(i:所有元素)D[i]=B[i]-g*C[i];//D(i
15
      ,g)
找出一組合法x[i]使f(g)最大;
      p=0,q=0;
17
      for(i:所有元素)
18
      if(x[i])p+=B[i],q+=C[i];
g=p/q;//更新解·注意q=0的情况
19
    }while(abs(Ans-g)>EPS);
21
    return Ans;
22
```

12.1.5 學長公式

- 1. $\sum_{d\mid n}\phi(n)=n$
- 2. $g(n) = \sum_{d \mid n} f(d) => f(n) = \sum_{d \mid n} \mu(d) \times$
- 3. Harmonic series $H_n = \ln(n) + \gamma + 1/(2n)$ $1/(12n^2) + 1/(120n^4)$
- 4. $\gamma = 0.57721566490153286060651209008240243104215$
- 5. 格雷碼 = $n \oplus (n >> 1)$
- 6. $SG(A+B) = SG(A) \oplus SG(B)$
- 7. 選轉矩陣 $M(\theta) = \begin{pmatrix} cos\theta \\ sin\theta \end{pmatrix}$ $-sin\theta$ $cos\theta$

12.1.6 基本數論

- 1. $\sum_{d|n} \mu(n) = [n == 1]$ 2. $g(m) = \sum_{d|m} f(d) \Leftrightarrow f(m) =$ $\sum_{d|m} \mu(d) \times g(m/d)$
- 3. $\sum_{i=1}^{n} \sum_{j=1}^{m} \overline{\Delta}$ 質數量 = $\sum \mu(d) \lfloor \frac{n}{d} \rfloor \lfloor \frac{m}{d} \rfloor$ 4. $\sum_{i=1}^{n} \sum_{j=1}^{n} lcm(i,j) = n \sum_{d|n} d \times \phi(d)$

12.1.7 排組公式

- 1. k 卡特蘭 $\frac{C_n^{kn}}{n(k-1)+1} \cdot C_m^n = \frac{n!}{m!(n-m)!}$ 2. $H(n,m) \cong x_1 + x_2 \dots + x_n = k, num = \sum_{n=1}^{n+1} \frac{n!}{n!}$
- 3. Stirling number of 2^{nd} ,n 人分 k 組方法數目
 - (a) S(0,0) = S(n,n) = 1

 - (b) S(n,0) = 0(c) S(n,k) = kS(n-1,k) + S(n-1,k-1)
- 4. Bell number,n 人分任意多組方法數目
 - (a) $B_0 = 1$

 - (a) $B_0 = 1$ (b) $B_n = \sum_{i=0}^n S(n, i)$ (c) $B_{n+1} = \sum_{k=0}^n C_k^n B_k$ (d) $B_{p+n} \equiv B_n + B_{n+1} mod p$, p is prime (e) $B_{p^m+n} \equiv m B_n + B_{n+1} mod p$, p is
 - prime (f) From $B_0: 1, 1, 2, 5, 15, 52, 203, 877, 4140, 21147, 115975$
- 5. Derangement, 錯排, 沒有人在自己位置上
 - (a) $D_n = n!(1 \frac{1}{1!} + \frac{1}{2!} \frac{1}{3!} \dots +$
 - (b) $D_n = (n-1)(D_{n-1} + D_{n-2}), D_0 = (n-1)(D_{n-1} + D_{n-2})$
 - $\begin{array}{ccc} & D_n & & & \\ & 1, D_1 = 0 & \\ \text{(c) From } D_0: 1, 0, 1, 2, 9, 44, \end{array}$ 265, 1854, 14833, 133496
- 6. Binomial Equality

 - (a) $\sum_{k} \binom{r}{m+k} \binom{s}{n-k} = \binom{r+s}{m+n}$ (b) $\sum_{k} \binom{l}{m+k} \binom{s}{n+k} = \binom{l+s}{l-m+n}$ (c) $\sum_{k} \binom{l}{m+k} \binom{s+k}{n} (-1)^{k}$ $(-1)^{l+m} \binom{s-m}{n-l}$ (d) $\sum_{k \leq l} \binom{l-k}{m} \binom{s}{k-n} (-1)^{k}$ $(-1)^{l+m} \binom{s-m-1}{l-n-m}$ (e) $\sum_{0 \leq k \leq l} \binom{l-k}{m} \binom{q+k}{n} = \binom{l+q+1}{m+n+1}$ (f) $\binom{r}{k} = (-1)^{k} \binom{k-r-1}{k}$ (g) $\binom{r}{m} \binom{m}{k} = \binom{r}{k} \binom{r-k}{m-k}$ (h) $\sum_{k \leq l} \binom{r+k}{m-k} = \binom{r+r+1}{m+1}$

 - (h) $\sum_{k \le n} {r+k \choose k} = {r+n+1 \choose n}$ (i) $\sum_{0 \le k \le n} {k \choose m} = {n+1 \choose m+1}$ (j) $\sum_{k \le m} {m+r \choose k} x^k y^k$ $\sum_{k \le m} {r \choose k} (-x)^k (x+y)^{m-k}$

12.1.8 冪次, 冪次和

- 1. $a^{b}\%P = a^{b\%\varphi(p) + \varphi(p)}, b \ge \varphi(p)$
- 2. $1^3 + 2^3 + 3^3 + \ldots + n^3 = \frac{n^4}{4} + \frac{n^3}{2} + \frac{n^2}{4}$

- 3. $1^4 + 2^4 + 3^4 + \dots + n^4 = \frac{n^5}{5} + \frac{n^4}{2} + \frac{n}{3} \frac{n}{30}$ 4. $1^5 + 2^5 + 3^5 + \dots + n^5 = \frac{n^6}{6} + \frac{n^5}{2} + \frac{5n^4}{12} \frac{n^2}{12}$ 5. $0^k + 1^k + 2^k + \dots + n^k = P(k), P(k) = \frac{(n+1)^{k+1} \sum_{i=0}^{k-1} C_i^{k+1} P(i)}{k+1}, P(0) = n+1$
- 6. $\sum_{k=0}^{m-1} k^n = \frac{1}{n+1} \sum_{k=0}^n C_k^{n+1} B_k m^{n+1-k}$
- 7. $\sum_{i=0}^{m} C_i^{m+1} B_i = 0, B_0 = 1$
- 8. 除了 $B_1 = -1/2$ · 剩下的奇數項都是 0
- $B_1 = 1/2$, and $B_2 = 1/6$, $B_4 = -1/30$, $B_6 = 1/42$, $B_8 = -1/30$, $B_{10} = 5/66$, $B_{12} = -691/2730$, $B_{14} = 7/6$, $B_{16} = -301/7/510$, $B_{18} = 43867/798$, $B_{20} = -301/7/510$ 9. B_2 -174611/330,

12.1.9 Burnside's lemma

- 1. $|X/G| = \frac{1}{|G|} \sum_{g \in G} |X^g|$
- 2. $X^g = t^{c(g)}$
- G 表示有幾種轉法, X^g 表示在那種轉法下,有 幾種是會保持對稱的,t 是顏色數,c(g) 是循環 節不動的面數。
- 8. 正立方體塗三顏色 · 轉 0 有 3^6 個元素不變 · 轉 90 有 6 種 · 每種有 3^3 不變 · 180 有 3×3^4 · 120(角) 有 8×3^2 · 180(邊) 有 6×3^3 · 全部 $\frac{1}{24}(3^6+6\times 3^3+3\times 3^4+8\times 3^2+6\times 3^3)=57$

12.1.10 Count on a tree

- 1. Rooted tree: $s_{n+1} = \frac{1}{n} \sum_{i=1}^{n} (i \times a_i \times a_i)$ $\sum_{i=1}^{\lfloor n/i \rfloor} a_{n+1-i \times j})$
- 2. Unrooted tree:

 - $\begin{array}{ll} \text{(a)} & \text{Odd:} a_n \sum_{i=1}^{n/2} a_i a_{n-i} \\ \text{(b)} & \text{Even:} Odd + \frac{1}{2} a_{n/2} (a_{n/2} + 1) \end{array}$
- 3. Spanning Tree

 - (a) 完全圖 n^n-2 (b) 一般圖 (Kirchhoff's theorem)M[i][i]= $degree(V_i), M[i][j] = -1, if$ have E(i, j), 0 if no edge. delete any one row and col in A, ans = det(A)

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Codebook - ss

C++ Resource Test

```
#include <bits/stdc++.h>
   using namespace std;
   namespace system_test {
  const size_t KB = 1024;
const size_t MB = KB * 1024;
const size_t GB = MB * 1024;
   size_t block_size, bound;
void stack_size_dfs(size_t depth = 1) {
     if (depth >= bound)
12
13
        return;
     int8_t ptr[block_size]; // 若無法編譯將
     block_size 改成常數
memset(ptr, 'a', block_size);
cout << depth << endl;
     stack_size_dfs(depth + 1);
17
  }
18
19
   void stack_size_and_runtime_error(size_t
20
         block_size, size_t bound = 1024) {
     system_test::block_size = block_size;
system_test::bound = bound;
     stack_size_dfs();
```

```
56 void runtime_error_4() {
57   // free(): invalid pointer
58   int *ptr = new int[7122];
   double speed(int iter num) {
      const int block_size = 1024;
                                                                          ptr += 1;
      volatile int A[block_size];
                                                                          delete[] ptr;
      auto begin = chrono::
             high_resolution_clock::now();
      while (iter_num--)
for (int j = 0; j < block_size; ++j)
    A[j] += j;
auto end = chrono::</pre>
                                                                       void runtime_error_5() {
  // maybe illegal instruction
  int a = 7122, b = 0;
  cout << (a / b) << endl;</pre>
31
32
            high_resolution_clock::now();
                                                                    67
      chrono::duration<double> diff = end -
                                                                       void runtime_error_6() {
  // floating point exception
  volatile int a = 7122, b = 0;
             begin:
                                                                    69
      return diff.count();
35
                                                                          cout << (a / b) << endl;
   void runtime_error_1() {
   // Segmentation fault
   int *ptr = nullptr;
39
                                                                   74
                                                                   75 void runtime_error_7() {
      *(ptr + 7122) = 7122;
                                                                         // call to abort.
                                                                          assert(false);
42
   void runtime_error_2() {
   // Segmentation fault
   int *ptr = (int *)memset;
                                                                    80 } // namespace system_test
                                                                   81
      *ptr = 7122;
                                                                       #include <sys/resource.h>
                                                                   82
48 }
                                                                       void print_stack_limit() { // only work
                                                                   83
                                                                              in Linux
   void runtime_error_3() {
   // munmap_chunk(): invalid pointer
   int *ptr = (int *)memset;
                                                                          struct rlimit 1;
                                                                          delete ptr;
                                                                   87 }
```