Capturing Planned Protests from Open Source Indicators

Sathappan Muthiah, Bert Huang, Jaime Arredondo, David Mares, Lise Getoor, Graham Katz and Naren Ramakrishnan Civil unrest events (protests, strikes, and "occupy" events) are common occurrences in both democracies and authoritarian regimes. The study of civil unrest is a key topic for political scientists as it helps capture an important mechanism by which citizenry express themselves. In countries where civil unrest is lawful, qualitative analysis has revealed that more than 75% of the protests are planned, organized, and/or announced in advance; therefore detecting references to future planned events in relevant news and social media is a direct way to develop a protest forecasting system. We report on a system for doing that in this paper. It uses a combination of keyphrase learning to identify what to look for, probabilistic soft logic to reason about location occurrences in extracted results, and time normalization to resolve future time mentions. We illustrate the application of our system to 10 countries in Latin America, viz. Argentina, Brazil, Chile, Colombia, Ecuador, El Salvador, Mexico, Paraguay, Uruguay, and Venezuela. Results demonstrate our successes in capturing significant societal unrest in these countries with an average lead time of 4.08 days. We also study the selective superiorities of news media versus social media (Twitter, Facebook) to identify relevant trade-offs.

Civil unrest events (protests, strikes, and "occupy" events) are common occurrences in both democracies and in authoritarian regimes. Although we typically associate civil unrest with disruptions and instability, social scientists believe that civil unrest reflects the democratic process by which citizenry communicate their views and preferences to those in authority. The advent of social media has afforded citizenry new mechanisms for organization and mobilization, and online news sources and social networking sites like Facebook and Twitter can provide a window into civil unrest happenings in a particular country.

Why study and forecast protests? Our primary region of interest is Latin America (secondary regions of interest include the Middle East and North Africa), and protest is an important topic of study in this region, as many countries here are democracies struggling to consolidate themselves. The combination of weak channels of

Figure 1: An example article describing plans for a future protest (Venezuela, June 11, 2014).

communication between citizen and government, and a citizenry that still has not grasped the desirability of elections as the means to affect politics means that public protest will be an especially attractive option. To illustrate the power of protest in Latin America we need only recall that between 1985 and 2011, 17 presidents resigned or were impeached under pressure from demonstrations, usually violent, in the streets. Protests have also resulted in the rollback of price increases for public services, such as during the 'Brazilian Spring' of June 2013.

Forecasting protests is an important capability in many domains. For the tourism industry, forecasting protests can support the issuance of travel warnings. For law enforcement, forecasting protests can aid in preparedness. For social scientists, forecasting protests will provide insight into how citizens express themselves. For governments, a protest forecasting system can help prioritize citizen grievances. Finally, protests can have a debilitating effect on multiple industries (especially those that rely on worldwide supply chain management) and thus a protest forecasting system can aid in planning and design of alternative travel and shipping routes.

Planned protests Our basic hypothesis is that protests that are larger will be more disruptive and communicate support for its cause better than smaller protests. Mobilizing large numbers of people is more likely to occur if a protest is organized and the time and place announced in advance. Because protest is costly and more likely to succeed if it is large, we should expect planned, rather than spontaneous, protests to be the norm. Indeed, in a sample of 288 events from our study selected for qualitative review of their antecedents, for 225 we located

communications regarding the upcoming occurrence of the event in media, and only 49 could be classified as spontaneous (we could not determine whether communications had or had not occurred in the remaining 14 cases).

EMBERS (Early Model Based Event Recognition using Surrogates) We are an industry-university partnership charged with developing an automatic protest forecasting system for 10 countries in Latin America (LA) and 7 countries in the Middle East and North Africa region (MENA). Our system, called EMBERS, has been deployed since Nov 2012 and has been generating forecasts (called warnings or alerts) automatically, without a human-in-the-loop, since then (the MENA region was added in July 2014). These forecasts are emailed to a third party (MITRE) for evaluation. Analysts at MITRE organize a reference database of protests (called the Gold Standard Report, or GSR) by surveying newspapers for reports of protests, and compare our warnings against the GSR to generate a scoring report, using evaluation criteria described later.

The full EMBERS system has been described elsewhere (Ramakrishnan et al. 2014;

Doyle et al. 2014), including the overall system architecture, data sources used for analysis, and the various forecasting models that make up the system. EMBERS adopts a multi-model approach, wherein different models are leveraged for their selective superiorities to generate a fused set of alerts. One of the best performing models in EMBERS is the planned protest model that detects ongoing organizational activity and generates warnings accordingly. This paper is the first to present this model in detail, including the research issues involved, and how we addressed them in EMBERS.

Capturing mentions of protest planning and organization is not as easy as it might appear. First, articles of interest are written in different languages (Spanish, Portuguese, French, Dutch, and English). Second, multiple locations are often mentioned in a given article, leading to (natural language) ambiguity about the intended location of the event. Significant reasoning is required to discern the correct protest location. Finally, identifying the date of a planned event in Latin America involves significant multilingual temporal-semantic natural language processing as dates are often described with vague, relative, or otherwise context-dependent expressions (e.g., Sunday or in two days).

Our detection approach combines shallow linguistic analysis to identify relevant documents (articles, tweets) with targeted deep semantic analysis of the selected documents. Despite its simplicity, this approach is capable of detecting indicators of event planning with surprisingly high accuracy.

Our contributions are:

- 1. We present a protest forecasting system that couples three key technical ideas: keyphrase learning to identify what to look for, probabilistic soft logic to reason about location occurrences in extracted results, and date normalization to resolve future tense mentions. We demonstrate how the integration of these ideas achieves objectives in precision, recall, and quality (accuracy).
- 2. We illustrate the application of our system to 10 countries in Latin America, viz. Argentina, Brazil, Chile, Colombia, Ecuador, El Salvador, Mexico, Paraguay, Uruguay, and Venezuela. Our system predicts the *when* of the protest as well as *where* of the protest (down to a city level granularity). We conduct ablation studies to identify the relative contributions of news media (news + blogs) versus social media (Twitter, Facebook) to identify future happenings of civil unrest. Through these studies we illustrate the selective superiorities of different sources for specific countries.
- 3. Unlike many studies of retrospective forecasting of protests, our system has been **deployed and in operation for nearly three years.** The end consumers of our alerts are analysts studying Latin America. Our results demonstrate that we are able to capture significant societal unrest in the above countries with an average lead time of 4.08 days.

Related Work

Five categories of related work are briefly discussed here (see also Table 1).

Event detection via text extractions is an extensively studied topic in the literature. Document clustering techniques are used in, e.g., (Gabrilovich, Dumais, and Horvitz 2004) to identify events retrospectively or as the stories arrive. Works like (Banko et al. 2007;

Chambers and Jurafsky 2011;

Riloff and Wiebe 2003) focus on extraction patterns (templates) to extract information from text.

Temporal information extraction is another well studied topic. The TempEval challenge (Verhagen et al. 2009) led to a significant amount of algorithmic development for temporal NLP. For instance a specification language for temporal and event expressions in natural language text is described in (Pustejovsky et al. 2003). References (Llorens et al. 2012) and (Mani and Wilson 2000) provide methods to resolve temporal expressions in text (our own work here uses the TIMEN package (Llorens et al. 2012) and more recently the HeidelTime package (Strötgen et al. 2014)).

Event forecasting: Radinsky and Horvitz (2013) find event sequences from a corpora and then use these sequences to determine if an event of interest (e.g., a disease outbreak, or a riot) will occur sometime in the future. This work predicts only if a potential event will happen given a historical event sequence but does not geolocate the event to a city-level resolution, as we do here. Kallus (2014) make use of event data from RecordedFuture (Truvé 2011) to determine if a significant protest event will occur in the subsequent three days and casts this as a classification problem. This work only focuses on prediction of significant events (suitably defined) and the forecast is limited to a fixed time window of the next three days.

Future retrieval: Baeza-Yates (2005) provides one of the earliest discussions of this topic; here future temporal information in text is found and used to retrieve content from search queries that combine both text and time with a simple ranking scheme. Kawai et al. (2010) present a search engine (ChronoSeeker) for searching future and past events. RecordedFuture (Truvé 2011), introduced earlier, conducts real-time analysis of news and tweets to identify mentions of events along with associated times. Anecdotally it is estimated that approximately (only) 5--7% of events extracted by RecordedFuture are about the future.

Planned protest detection: Two publications---Compton et al. (2013) and Xu et al. (2014)---align very closely to our own work as their emphasis is on protest forecasting. Both works are aimed at forecasting protests but emphasize different data sources and different methodologies. For instance, the work in (Compton et al. 2013) filters the Twitter stream for keywords of interest and searches for future date mentions in only absolute terms, i.e., explicit mentions of a month name and a number (date) less than 31. Such an approach will not be capable of extracting the more common way in which future dates are referenced, e.g., phrases like "tomorrow," "next tuesday." The work in (Xu et al. 2014) by the same group of authors uses the Tumblr feed with a smaller set of keywords but again is restricted to the use of absolute time identifiers.

Table 1: Comparison of our approach against other techniques.

| | Relative date resolution | Ingest multiple sources? | Reasoning about location | Learning word/phrase filters |
|--------------------------------------------------------------------------------------------------------------------|--------------------------------|--------------------------------|--------------------------------|------------------------------------|
| 'Future' Search Engines (Kawai et al. 2010; Jatowt and Au Yeung 2011; Baeza-Yates 2005) | ✓ | | | |
| Time-to-Event Recognition (Tops, van den Bosch, and Kunneman 2013; Hurriyetoglu, Kunneman, and van den Bosch 2013) | √ | | | |
| Planned Protest Detection (Xu et al. 2014; Compton et al. 2013) | | ✓ | | |
| This paper | \checkmark | \checkmark | \checkmark | ✓ |

Probabilistic Soft Logic

In this section, we briefly describe probabilistic soft logic (PSL) (Kimmig et al. 2012), a key component of our geocoding strategy. PSL is a framework for collective probabilistic reasoning on relational domains. PSL represents the domain of interest as logical atoms. It uses first order logic rules to capture the dependency structure of the domain, based on which it builds a joint probabilistic model over all atoms. Instead of hard truth values of 0 (false) and 1 (true), PSL uses soft truth values relaxing the truth values to the interval [0,1]. The logical connectives are adapted accordingly.

User defined *predicates* are used to encode the relationships and attributes and *rules* capture the dependencies and constraints. The rules can also be labeled with non-negative weights which are used during the inference process. The set of predicates and weighted rules thus make up a PSL program where known truth values of ground atoms are derived from observed data and unknown truth values for the remaining atoms are learned using the PSL inference.

Example 1. We will follow a running example throughout this section. In our geocoding subtask, we create a PSL program that reasons about the predicate REFERSTO, which maps a text string to real-world locations. For example, REFERSTO("DC", washingtonDC) evaluates to true if the knowledge base believes that the article refers to Washington D.C. as "DC." This predicate gets used in rules that define dependencies between predicates, such as the rule

```
ENTITY(L, location) \land REFERSTO(L, locID) \rightarrow PSLLOCATION(Article, locID),
```

which states that an entity extracted from an article text that matches a known Refersto mapping implies that the PSL program's predicted location will follow that mapping. Some of these logical atoms will be known as parts of a knowledge base, while others will be unknown and will be inferred by PSL.

Given a set of atoms $\ell = \{\ell_1, \dots, \ell_n\}$, an interpretation defined as $I : \ell \to [0,1]^n$ is a mapping from atoms to soft truth values. PSL defines a probability distribution over all such interpretations such that those that satisfy more ground rules are more probable. *Lukasiewicz t-norm* and its corresponding co-norm are used for defining relaxations of the logical AND and OR respectively to determine the degree to which a ground rule is satisfied. Given an interpretation I, PSL defines the formulas for the relaxation of the logical conjunction (\land), disjunction (\lor), and negation (\neg) as follows:

$$\ell_1 \wedge \ell_2 = \max\{0, I(\ell_1) + I(\ell_2) - 1\},$$

$$\ell_1 \vee \ell_2 = \min\{I(\ell_1) + I(\ell_2), 1\},$$

$$\neg l_1 = 1 - I(\ell_1),$$

The interpretation I determines whether the rules are satisfied. A rule $r \equiv r_{body} \rightarrow r_{head}$ is satisfied if and only if the truth value of head is at least that of the body. Otherwise, PSL uses a *distance to satisfaction*, which measures the degree to which this condition is violated

$$d_r(I) = \max\{0, I(r_{body}) - I(r_{head})\}.$$

Example 2. Continuing the previous example, if we have the rule

```
Entity("Washington", location) \land

RefersTo("Washington", washingtonDC)

\rightarrow PSLLOCATION(Article, washingtonDC),
```

and the truth values of the known atoms are

```
ENTITY ("Washington", location): 1.0
```

and

REFERSTO("Washington", washingtonDC): 0.6,

Figure 2: Schematic of the planned protest detector that ingests five different types of data sources.

then following the relaxation of logical AND, the truth value of the antecedent is $\max\{0, 1.0 + 0.6 - 1\} = 0.6$. Moreover, if the truth value of the atom to be inferred, PSLLOCATION(Article, washingtonDC), is 0.1, then the distance to satisfaction of this rule is $\max\{0, 0.6 - 0.1\} = 0.5$. On the other hand, if the truth value of the head is 0.7, then the distance to satisfaction is $\max\{0, 0.6 - 0.7\} = 0$, meaning the rule is satisfied.

PSL then induces a probability distribution over possible interpretations I over the given set of ground atoms l in the domain. If R is the set of all ground rules that are instances of a rule from the system and uses only the atoms in I then, the probability density function f over I is defined as

$$f(I) = \frac{1}{Z} \exp\left(-\sum_{r \in R} \lambda_r (d_r(I))^p\right)$$
 (1)

$$Z = \int_{I} \exp\left(-\sum_{r \in R} \lambda_r (d_r(I))^p\right)$$
 (2)

where λ_r is the weight of the rule r,Z is a normalization constant, and $p \in 1,2$ provides a choice between linear or quadratic loss functions, which produce different modeling behavior. PSL further allows inclusion of linear equality and inequality constraints, which enable modeling of functional constraints on the domains and ranges of predicates.

The probability distribution in Equation (1) is an example of a *hinge-loss Markov* random field (Bach et al. 2013), which has a form of energy function that makes inference of the most probable explanation an efficient convex optimization. The expressiveness of PSL and the efficiency of inference in its models allows us to encode dependencies between various aspects of geolocation that are jointly inferred.

Example 3. The joint probability distribution enables PSL to reason about conflicting evidence, for example if we additionally have the atom

REFERSTO("Washington", Washington State) in our knowledge base with truth value 0.2, we would have two conflicting PSLLOCATION implications. The probabilistic, weighted rules, as well as the soft truth values of known atoms control how much PSL considers each piece of evidence, and additional corroborating or conflicting evidence would also be incorporated into the final joint inference.

Approach

The general approach we adopt is to identify open-source documents that appear to indicate civil unrest event planning, extract relevant information from identified documents and use that as the basis for a structured warning about the planned event. Each of these processing steps (see Fig. 2) is outlined next.

Linguistic Preprocessing

Since our region of interest is Latin America as well as the Middle East and North Africa, the collection of text harvested is inherently multilingual, with Spanish, Portuguese, Arabic, and English as the dominating languages. Ingested documents are subjected to shallow linguistic processing prior to analysis. This initial processing involves identifying the language of the document, distinguishing the words (tokenization), normalizing words for inflection (lemmatization), and identifying expressions referring to people, places, dates and other entities. We use Basis Technology's Rosette Linguistics Platform (RLP) suite of multilingual commercial tools (http://www.basistech.com/text-analytics/rosette/) for this processing. The output of this linguistic preprocessing serves as input to subsequent deeper analysis in which date expressions are normalized, sentences

that appear to be describing protest planning are identified, and the geographic focus of the text computed.

Date Normalization

Date processing is particularly crucial to the identification and interpretation of statements about future events. We used the TIMEN (Llorens et al. 2012) date normalization package to normalize date expressions in English, Spanish and Portuguese (extended the system to cover Portuguese) and the HeidelTime (Strötgen et al. 2014) to do the same for Arabic (extending the set of rules to handle Hijri dates). Both systems rules were extended to improve coverage and accuracy on our document collection.

The systems make use of meta-data such as the day of publication and other information about the linguistic context to determine for each date expression, what day (or week, month or year) it refers to. For example in a tweet produced on June 10, 2014, the occurrence of the term *Friday* used in a future-tense sentence *We'll get together on Friday* will be interpreted as June 13, 2014. Each expression identified as a date by the RLP preprocessor is normalized in this way, with accuracy of just over 80% on our data set.

Phrase filtering

In order to identify relevant documents, input documents are filtered on a set of keyphrases, i.e., the text of the document is searched for the presence of one or more keyphrases in a list of phrases which are indicative of an article's focus being a planned civil unrest event. The list of keyphrases indicating civil unrest planning was obtained in a semi-automatic manner, as detailed below. Articles which do match are processed further, those that do not are ignored.

Phrase matching Our keyphrase matching is highly general and linguistically sophisticated. The phrases in our list are general rules for matching, rather than literal string sequences. Typically a phrase specification comprises: two or more word lemmas, a language specification, and a separation threshold. This indicates that words---potentially inflected forms---in a given sequence potentially separated by one or more other words, should be taken to be a match. We determined that this kind of multi-word keyphrases was more accurate than simple keywords for extracting events of interest from the data stream.

The presence of a keyphrase is checked by searching for the presence of individual lemmas of the keyphrase within the same sentence separated by at most a number of words that is fewer than the separation threshold. This method allows for linguistically sophisticated and flexible matching, so, for example, the keyphrase [plan protest, 4, English] would match the sentence *The students are planning a couple big protests tomorrow* in an input document.

Phrase list development The set of keyphrases was tailored (slightly) to the genre of the input. In particular different phrases were used to identify relevant news articles and blogs from those used to filter tweets. The lists themselves were generated semi-automatically.

Initially, a few seed phrases were obtained manually with the help of subject matter experts. An analysis of news reports for planned protests in the print media helped create a minimum set of words to use in the query. We choose four nouns from the basic query that is used predominantly to indicate a civil unrest in the print media - *demonstration*, *march*, *protest* and *strike*. We translated them into Spanish and Portuguese, including synonyms. We then combined these with future-oriented verbs, e.g., *to organize*, *to prepare*, *to plan*, and *to announce*. For Twitter, shorter phrases were identified, and these had a more direct call for action, e.g., *marchar*, *manhã de mobilização*, *vamos protestar*, *huelga*.

To generalize this set of phrases, the phrases were then parsed using a dependency parser (Padró and Stanilovsky 2012) and the grammatical relationship between the core nominal focus word (e.g., protest, manifestación, huelga) and any accompanying word (e.g., plan, call, anunciar) was extracted. These grammatical

Figure 3: An example of phrase learning for detecting planned protests.

relations were used as extraction patterns as in (Riloff and Wiebe 2003) to learn more phrases from a corpora of sentences extracted from the data stream of interest (either news/blogs or tweets). This corpus consists of sentences that contained any one of the nominal focus words and also had mentions of a future date. The separation threshold for a phrase was also learned, being set to the average number of words separating the nominal focus and the accompanying word.

The set of learned phrases is then reviewed by a subject matter expert for quality control. Using this approach, we learned 112 phrases for news articles and blogs and 156 for tweets. This phrase learning process is illustrated in Fig. 3.

Geocoding

After linguistic preprocessing and suitable phrase filtering, messages are geocoded with a specification of the geographical focus of the text---specified as a city, state, country triple---that indicates the locality that the text is about. We make use of different geocoding methodologies for Twitter messages, for Facebook Events pages, and for news articles and blogs. These are described below.

Twitter and Facebook For tweets, the geographic focus of the message is generated by a fairly simple set of heuristics involving i) the most reliable but least available source, i.e., the geotag (latitude, longitude) of the tweet itself, ii) Twitter *places* metadata, and iii) if the above are not available, the text fields contained in the user profile (location, description) as well as the tweet text itself to find mentions of relevant locations. Additional toponym disambiguation heuristics are used to identify the actual referent of the mention. Similar methods are used to geocode event data extracted from Facebook event pages.

News and Blogs For longer articles such as news articles, the geographic focus of the message is identified using much more complex methods to extract the protest location from news articles. We use PSL to build a probabilistic model that infers the intended location of a protest by weighing evidence coming from entities extracted by the RLP preprocessor and information in the World Gazetteer.

The primary rules in the model encode the effect that RLP extracted location strings that match to gazetteer aliases are indicators of the article's location, whether they be country, state, or city aliases. Each of these implications is conjuncted with a prior for ambiguous, overloaded aliases that is proportional to the population of the gazetteer location. For example, if the string "Los Angeles" appears in the article, it could refer to either Los Angeles, California, or Los Ángeles in Argentina or Chile. Given no other information, our model would infer a higher truth value for the article referring to Los Angeles, California, because it has a much higher population than the other options.

```
ENTITY(L, location) \land REFERSTO(L, locID) \rightarrow PSLLOCATION(Article, locID)
```

 $\mathsf{ENTITY}(C,\mathsf{location}) \land \mathsf{IsCountry}(C)$

 \rightarrow ARTICLECOUNTRY(Article, C)

 $Entity(S, location) \land IsState(S)$

 \rightarrow ARTICLESTATE(Article, S)

(Note that the above are not deterministic rules; e.g., they do not use the logical conjunction but rather the Lukasiewicz t-norm based relaxation. Further, these rules do not fire deterministically but are instead simultaneously solved for satisfying assignments as described in the section on Probabilistic Soft Logic (PSL).)

The secondary rules, which are given half the weight of the primary rules, perform the same mapping of extracted strings to gazetteer aliases, but for

Figure 4: An example of location inference using PSL. Red circles denote named entities identified as locations and blue denotes other types of entities. The article describes students planning a march on Sunday. It identifies multiple locations, e.g., Chacao, El Roso, and the Francisco Fajardo highway where protests have been happening. There is also a reference to a quote by the mayor of Baruto. Mentions of such multiple locations are resolved using our PSL program to the intended location, here Caracas.

extracted persons and organizations. Strings describing persons and organizations often include location clues (e.g., "mayor of Buenos Aires"), but intuition suggests the correlation between the article's location and these clues may be lower than with location strings.

 $\begin{tabular}{l} Entity(O, organization) \land RefersTo(O, locID) \\ \rightarrow PSLLocation(Article, locID) \end{tabular}$

 $\mathsf{ENTITY}(O, \mathsf{organization}) \land \mathsf{IsCountry}(O)$

 \rightarrow ARTICLECOUNTRY(Article, O)

 ${\tt ENTITY}(O, {\tt organization}) \land {\tt ISSTATE}(O)$

 \rightarrow ARTICLESTATE(Article, O)

Finally, the model includes rules and constraints to require consistency between the different levels of geolocation, making the model place higher probability on states with its city contained in its state, which is contained in its country. As a post-processing step, we enforce this consistency explicitly by using the inferred city and its enclosing state and country, but adding these rules into the model make the probabilistic inference prefer consistent predictions, enabling it to combine evidence at all levels.

 $\begin{aligned} \mathsf{PSLLocation}(\mathsf{Article}, \mathsf{locID}) \wedge \mathsf{Country}(\mathsf{locID}, C) \\ & \to \mathsf{ArticleCountry}(\mathsf{Article}, C) \end{aligned}$

 $\begin{aligned} \mathsf{PSLLocation}(\mathsf{Article}, \mathsf{locID}) \land \mathsf{ADMIN1}(\mathsf{locID}, S) \\ \rightarrow \mathsf{ARTICLESTATE}(\mathsf{Article}, S) \end{aligned}$

As an example of how PSL aids in location identification, the protest from Fig. 1 is revisited in Fig. 4, which illustrates the evidence that the PSL model gathers from the news article and the inferred locations.

We evaluate our planned protest detection system for Latin America using metrics similar to those described in Ramakrishnan et al. (2014). Given a set of alerts issued by the system and the GSR comprising actual protest incidents, we aim to identify a correspondence between the two sets via a bipartite matching. An alert can be matched to a GSR event only if i) they are both issued for the same country, ii) the alert's predicted location and the event's reported location are within 300km of each other (the distance offset), and iii) the forecast event date is within a given interval of the true event date (the date offset). Once these inclusion criteria apply, the quality score (QS) of the match is defined as a combination of the location score (LS) and date score (DS):

$$QS = (LS + DS) * 2$$
(3)

where

$$LS = 1 - \frac{\min(distance offset, 300)}{300}$$
 (4)

and

$$DS = 1 - \frac{\min(\text{date offset, INTERVAL})}{\text{INTERVAL}}$$
 (5)

Figure 5: Distribution of alerts and GSR events across the Latin American countries studied in this paper.

Here, we explore INTERVAL values from 0 to 7. If an alert (conversely, GSR event) cannot be matched to any GSR event (alert, respectively), these unmatched alerts (and events) will negatively impact the precision (and recall) of the system. The lead time, for a matched alert-event pair, is calculated as the difference between the date on which the forecast was made and the date on which the event was reported (this should not be confused with the date score, which is the difference between the predicted event date and the actual event date). Lead time concerns itself with reporting and forecasting, whereas the date score is concerned with quality or accuracy.

We conduct a series of experiments to evaluate the performance of our system. How does the distribution of protests detected by the system compare with the actual distribution of protests in the GSR? Fig. 5 reveals pie charts of both distributions. As shown, Mexico, Brazil, and Venezuela experience the lion's share of protests in our region of interest, and the protests detected also match these modes although not the specific percentages. Smaller countries like Ecuador, El Salvador, and Uruguay do experience protests but which are not as prominently detected as those for other countries; we attribute this to their smaller social media footprint (relative to countries like Brazil and Venezuela).

Table 2: Country-wise breakdown of forecasting performance for different data sources. QS=Quality Score; Pr=Precision; Rec=Recall; LT=Lead Time. AR=Argentina; BR=Brazil; CL=Chile; CO=Colombia; EC=Ecuador; SV=El Salvador; MX=Mexico; PY=Paraguay; UY=Uruguay; VE=Venezuela. A — indicates that the source did not produce any warnings for that country in the studied period.

| News/Blogs | | | | Twitter | | | | Facebook | | | | Combined | | | | |
|------------|------|------|------|---------|------|------|------|----------|------|------|------|----------|------|------|------|-------|
| | QS | Pr. | Rec. | LT | QS | Pr. | Rec. | LT | QS | Pr. | Rec. | LT | QS | Pr. | Rec. | LT |
| AR | 3.14 | 0.32 | 0.69 | 3.94 | 3.52 | 0.78 | 0.14 | 3.14 | 3.70 | 0.50 | 0.04 | 3.00 | 3.02 | 0.36 | 0.80 | 4.50 |
| BR | 3.14 | 0.48 | 0.54 | 5.85 | - | - | - | - | 3.62 | 0.76 | 0.18 | 2.46 | 3.28 | 0.49 | 0.65 | 5.15 |
| CL | 3.06 | 0.91 | 0.67 | 5.40 | 3.52 | 1.00 | 0.23 | 4.29 | - | - | - | - | 3.16 | 0.83 | 0.80 | 5.92 |
| CO | 2.74 | 0.90 | 0.56 | 7.44 | 3.30 | 1.00 | 0.15 | 2.43 | 4.00 | 1.00 | 0.02 | 2.00 | 2.88 | 0.84 | 0.65 | 6.47 |
| EC | - | - | - | - | 2.32 | 1.00 | 0.06 | 17.00 | - | - | - | - | 2.32 | 0.50 | 0.06 | 17.00 |
| MX | 2.96 | 0.88 | 0.25 | 3.69 | 3.14 | 1.00 | 0.02 | 1.43 | 3.72 | 0.67 | 0.01 | 2.00 | 3.00 | 0.87 | 0.27 | 3.51 |
| SV | 3.22 | 1.00 | 0.03 | 1.00 | - | - | - | - | - | - | - | - | 3.22 | 1.00 | 0.03 | 1.00 |
| PY | 3.38 | 1.00 | 0.16 | 9.11 | 3.84 | 1.00 | 0.04 | 11.40 | 3.96 | 1.00 | 0.01 | 2.00 | 3.60 | 0.96 | 0.20 | 9.35 |
| UY | 3.24 | 1.00 | 0.29 | 2.40 | - | - | - | - | - | - | - | - | 3.24 | 1.00 | 0.29 | 3.24 |
| VE | 3.80 | 1.00 | 0.36 | 3.27 | 3.68 | 0.97 | 0.33 | 2.39 | - | - | - | - | 3.64 | 0.99 | 0.69 | 2.88 |
| ALL | 3.34 | 0.69 | 0.35 | 4.57 | 3.62 | 0.97 | 0.15 | 2.82 | 3.66 | 0.74 | 0.03 | 2.44 | 3.36 | 0.73 | 0.51 | 4.08 |

Table 3: Comparing the location and date scores of different sources in specific countries. AR=Argentina; BR=Brazil; CL=Chile; CO=Colombia; EC=Ecuador; SV=El Salvador; MX=Mexico; PY=Paraguay; UY=Uruguay; VE=Venezuela. A — indicates that the source did not produce any warnings for that country in the studied period.

| Source | | AR | BR | CL | CO | EC | SV | MX | PY | UY | VE | All |
|------------|----------|---------------------|--------------|--------------|--------------|----|----|--------------|------------------|----|--------------|---------------------|
| News/Blogs | LS DS | | | 0.75 0.78 | | | | | | | 0.95 0.95 | 0.0- |
| Facebook | LS DS | 1.0 0.85 | 0.92 0.89 | | 1.00 1.00 | | - | | 0.98 1.00 | | - | 0.93 0.90 |
| Twitter | LS DS | 0.88 0.88 | - | | 0.81 0.84 | | | 0.71 0.86 | 0.98 0.94 | | 0.91 0.93 | 0.89 0.92 |

(a) Quality Score over the months (b) Venezuelan Protests (c) Lead-Time vs Quality Score

(d) QS vs Matching Interval
Trade-Off (e) Quality Score Distribution (f) Brazilian Spring

Figure 6: Evaluation of planned protest forecasting system

Are there country-specific selective superiorities for the different data sources considered here? Table 2 presents a breakdown of performance, country-wise and source-wise, of our approach for a particular month, viz. March 2014. It is clear that the multiple data sources are necessary to achieve a high recall and that by and large these sources are providing mutually exclusive alerts. (Note also that some data sources do not produce alerts for specific countries.) Between Twitter and Facebook, the former is a better source of alerts for countries like Chile and the latter is a better source for Argentina, Brazil, Colombia, and Mexico. News and blogs achieve higher recall than social media sources indicating that most plans for protests are announced in established media. They are also higher quality sources for alerts in countries like El Salvador, Paraguay, and Uruguay. Finally, note that news and blogs offer a much higher lead time (4.57 days) as compared to that for Facebook (2.44 days) or for Twitter (2.82 days). The quality scores are further broken down in Table 3 into their date and location components.

A longitudinal perspective on quality scores is given in Fig. 6a. Note that in general Twitter tends to have a higher quality score as multiple re-tweets of future event mentions is a direct indicator of the popularity of an event as well as the intent of people to join an event. In contrast, mentions of future events in news do not directly shed any insight into popularity or people's support for the event's causes.

How did our system fare in detecting key country-wide protests?

The recent Venezuelan protests against President Nicolas Maduro and the Brazilian protests during June 2013 against bus fare hikes were two significant protests during our period of evaluation. Fig. 6b and Fig. 6f describe our performance under these two situations illustrating the count of protests detected against the GSR. Notice that our system was able to identify the Venezuelan protests much better than the Brazilian protests. This is because there was a significant amount of spontaneity to the Brazilian protests; they arose as discontent about bus fare increases but later morphed into a broader set of protests against government and most of these subsequent protests were not planned.

What is the trade-off between lead time and quality?

Fig. 6c shows that the QS of the planned protest model decreases (as expected) with lead time, initially, but later rises again. The higher quality scores toward the right of Fig. 6c are primarily due to Facebook event pages.

How does the method perform under stringent matching criteria? Fig. 6d shows the performance of the model when the matching window is varied from 7 to 1 in steps. We can see that the performance degrades quite gracefully even under the strict matching interval of a 1-day difference.

What is the distribution of quality scores? The clear mode toward the right side of the Fig. 6e signifies that a majority of the planned protest alerts are of high quality. Further, the quality score distribution is unimodal suggesting that the careful reasoning of locations and date normalization are crucial to achieving high quality.

Development and Maintenance

The core algorithms behind the planned protest detector were implemented in Python. The PSL geocoder was implemented in Java. Among the external libraries utilized the Basis Rosette Linguistic Platform is the key library. The development process took 3 months (June 2012 to Aug 2012) and was primarily led by the first author with contributions from the other authors. After two months of testing (Sep 2012 and Oct 2012), the system was deployed in Nov 2012 on the commercial AWS

(Amazon Web Services) cloud infrastructure in a cluster configuration. More details about the EMBERS system architecture can be found in Doyle et al. (2014). Alerts generated by the system are automatically emailed to MITRE (for evaluation) as well as to analysts who are subject matter experts in Latin America.

Since there is not an explicit training phase, the system has required minimal re-engineering over time. Key changes made to the system over time was to increase the sources used for data ingest and supporting the inclusion of additional phrases. Agile software engineering methods were used for project management. We estimate the effort to maintain the system as 0.25 persons (software engineer) per year which entails keeping data sources current, ensuring that the phrase list continues to stay relevant, and performing periodic checks and evaluations of the sytem.

Discussion

We have described an approach to forecasting protests by detecting mentions of future events in news and social media. The twin issues of i) resolving the date and ii) resolving the location have been addressed satisfactorily to realize an effective protest forecasting system. As different forms of communication media gain usage, systems like ours will be crucial to understanding the concerns of citizenry.

Our future work is aimed at three aspects. First, to address situations such as nationwide protests and systems of protests, we must generalize our system from generating protests at a single article level to digesting groups of articles. Doing so would require more sophisticated probabilistic reasoning, which we believe can be done using PSL. Second, we would like to generalize our approach that currently does detection of overt plans for protest to not-so-explicitly stated expressions of discontent. Finally, we plan to consider other population-level events of interest than just civil unrest, e.g., domestic political crises, and design detectors to recognize the imminence of such events.

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- **Sathappan Muthiah** is a Ph.D student in Computer Science at Virginia Tech. He is a research assistant at the Discovery Analytics Center. His research interests include spatial and temporal event detection, text mining and information retrieval.

He recieved his B.Tech in Information Technology from National Institute of Technology, Bhopal, India.

Bert Huang is an assistant professor in the Department of Computer Science at Virginia Tech. Bert's research investigates machine learning, with a focus on topics including structured prediction, statistical relational learning, and computational social science. He is an action editor for the Journal of Machine Learning Research, and his papers have been published at conferences including NIPS, ICML, UAI, and AISTATS. He earned his Ph.D. from Columbia University in 2011, and he was a postdoctoral research associate at the University of Maryland, College Park.

Jaime Arredondo is a Ph.D. candidate in global public health at UC San Diego. His research centers on developing more sophisticated analytical skills and research techniques to analyze the effect of policing practices as a major driver of HIV transmission, particularly in the U.S.–Mexico border region.He is collaborating with the UC San Diego Division of Global Public Health on its El Cuete, Phase IV project. Funded by the National Institute of Health, the project aims to identify how formal law enforcement policies can affect HIV risk behavior among injection drug users (IDU) amid improving occupational safety of police officers in Tijuana, Mexico.

David Mares is a professor of Political Science at UCSD. He holds the Institute of the Americas Chair for Inter-American Affairs at UCSD. He is the author or editor of ten books and his publications have appeared in English, Spanish, French, Portuguese, Italian and Chinese. His research and teaching interests include international conflict, Latin American energy politics, the political economy of drug policy, and civil-military relations.

Lise Getoor is a professor in the Computer Science Department at the University of California, Santa Cruz. Her research areas include machine learning, data integration, and reasoning under uncertainty, with an emphasis on graph and network data. She has over 200 publications and extensive experience with machine learning and probabilistic modeling methods. She is a Fellow of the Association for Artificial Intelligence, an elected board member of the International Machine Learning Society, serves on the board of the Computing Research Association (CRA), and was co-chair for ICML 2011. She is a recipient of an NSF Career Award and nine best paper and best student paper awards. She received her PhD from Stanford University in 2001, her MS from UC Berkeley, and her BS from UC Santa Barbara, and was a professor in the Computer Science Department at the University of Maryland, College Park from 2001-2013.

Graham katz earned his PhD in Linguistics and Computational Linguistics from University of Rochester before becoming a professor in the Department of Linguistics at Georgetown university between 2007 and 2012. He held the role of Applied Research Manager at CACI Inc. from 2012-2015, when he contributed greatly to the success of the EMBERS project.

Naren Ramakrishnan is the Thomas L. Phillips Professor of Engineering at Virginia Tech. He directs the Discovery Analytics Center, a university center pursuing advanced research in data mining and knowledge discovery with applications to important areas of national interest. Ramakrishnan is the principal investigator of the ongoing IARPA OSI (Open Source Indicators) project aimed at forecasting significant societal events (disease outbreaks, civil unrest, elections) from open source datasets. He received his PhD in Computer Sciences from Purdue University.