

# Eduardo Hernández Valdez

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## EDUCATION

<b>Instituto Tecnológico y de Estudios Superiores de Monterrey</b> <i>Engineering in Robotics and Digital Systems; Avg 90.26/100</i>	Monterrey, México June 2026
<b>PrepaTec Eugenio Garza Lagüera</b> <i>High School Diploma; 90/100</i>	Monterrey, México Aug 2019 – Jun 2022

## RESEARCH EXPERIENCE

<b>VantTec - Self Driving Vehicle</b> <i>Embedded and Electronics Research and Development Member</i>	Monterrey, México Jan 2023 – Present
<ul style="list-style-type: none"><li>Worked on pcb design regarding the vehicle's security and redundancy system requirements, using KiCAD. Translated prototypes to pcb boards needed as functional systems inside the vehicle. (STM32, Electric circuitry)</li><li>Created a "from-scratch" python library to receive data from CANbus based sensors, such as rotary encoders and radars. To be used for the vehicle as an interface through ROS 2. (Briter Encoder, Ainstein T-79 Radar)</li><li>Create documentation regarding the vehicles already existing subsystems in order to integrate them into the autonomous arrangement, and assure the project's future continuation.</li></ul>	
<b>VantTec - Unmanned Surface Vehicle</b> <i>Perception Research and Development Member</i>	Monterrey, México Aug 2022 – Present
<ul style="list-style-type: none"><li>Created datasets for the training of a neural network to detect and classify objects in water, aiding to the vehicle's self navigation for the Roboboat competition, and published the results as an academic paper, participating at a recognized engineering expo.</li><li>Developed on-demand computer vision algorithms regarding the vehicle's needs in each section of the competition using OpenCV and ROS 1. (Dice number and color recognition, special symbology recollection, etc)</li><li>Arranged environment running on specialized hardware to support the vehicle's perception system. (Nvidia Jetson TX2, Raspberry Pi)</li><li>Worked on a platform to support the boat's shooting system using ROS2, modelling the system using Gazebo.</li></ul>	

## WORK EXPERIENCE

<b>Freelance</b> <i>General Purpose Programming – <a href="https://www.fiverr.com/eduarch42">https://www.fiverr.com/eduarch42</a></i>	Remote Summer 2019, 2020, 2021, 2022
<ul style="list-style-type: none"><li>Developed solutions in various fields, including Data Science, Backend Development, GUI Desktop Applications, with an overall 4.9/5 rating.</li><li>Worked with clients from more than 10 countries around the world.</li></ul>	

## AWARDS & ACHIEVEMENTS

**HackMTY 2022 Hackathon** – 1<sup>st</sup> Place in Chubb's sponsored challenge.  
**Hackathon Banorte 2023** – Finalist team.  
**International Collegiate Programming Contest** – Top 7 within ITESM MTY.  
**Concurso Internacional de Ciencias** – Finalist in Computer Science category.  
**AWS Deep Racer** – Participation in the AWS Deep Racer League and first generation at ITESM.

## SKILLS

**Programming:** *Proficient;* Python, Go. *Intermediate;* C, Rust, Javascript, Matlab. *Beginner;* C++  
**Technologies/Software:** Linux, Docker, GNU Debugger, (C)Make, Git, KiCAD, ROS[1,2], FreeCAD, OpenCV  
**Languages:** Spanish (Native), English (B2 - PTEG), German (Elementary)



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