OpenMP for GPU

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- recent OpenMP supports offloading to GPU (target directive)
- official home page: http://openmp.org/
- specification: http://openmp.org/wp/openmp-specifications/
- latest version is 5.0 (https://www.openmp.org/spec-html/5.0/openmp.html)
- section numbers below refer to those in OpenMP spec 5.0

Compiling OpenMP programs for GPUs

• LLVM (clang/clang++) : compile with -fopenmp -fopenmp-targets=nvptx64

```
$ clang -Wall -fopenmp -fopenmp-targets=nvptx64 program.c
```

- you need to set LD_LIBRARAY_PATH environment variable when you run the executable (details on Jupyter notebook)
- NVIDIA HPC SDK (nvc/nvc++) : compile with -mp -target-gpu

```
1 $ nvc -Wall -mp=gpu program.c
```

Directives overview

- move control
 - target : moves the execution to GPU
- parallelize
 - teams and distribute
 - teams : creates a number of teams executing the same statement (≈ parallel pragma)
 - distribute : distribute iterations of a for loop among teams (≈ for pragma)
 - parallel and for
 - parallel: creates a number of threads executing the same statement in a team
 - for: distribute iterations of a for loop among threads in a team
 - think of teams + distribute another layer outside parallel + for
- move (or sync) data
 - target data: move/sync data between CPU and GPU

Implementation note

- while not specified anywhere in the spec (and there are cases they behave differently to below), you can think of
 - a team \sim a thread block
 - a thread \sim a CUDA thread
- it at least helps you understand why things look so redundant ...

Frequently-used combined idioms

all combined

• teams + distributed to outer loop and parallel + for to outer loop

```
#pragma omp target teams distribute
for (int i = start; i < end; i += incr) {
    #pragma omp parallel for
    for (int j = start'; j < end'; j += incr') {
        S
     }
}</pre>
```

- \bullet similar to launching a kernel doing S, but
 - you don't have to adjust thread block size
 - the program is orthogonal to thread count

Data mapping (in CUDA)

a major headache when programming in CUDA is data management

• the only "transparent" data transfer is argument passing

```
1 f<<<nb,bs>>>(a, b, c, ...);
```

• getting the result back from GPU is already painful

```
cudaMalloc(&r_dev, ...);
f<<<nb,bs>>>(a, b, c, ..., r);
cudaMemcpy(r, r_dev, ...);
```

- for persistent data,
 - maintain two pointers to logically same data (CPU version and GPU version)
 - get them synched when necessary (before and after a kernel launche)

"data mapping" of OpenMP alleviates the pain

OpenMP data mapping example

```
#pragma target data map(to:u) map(from:v)
S
```

- u, v: variable name, range expression (e.g., a[p:q])
- send u to GPU before S if necessary
- ullet send v from GPU after S if necessary
- you can combine to: and from: into tofrom:
- somewhat "declarative" way of understanding this
 - u becomes valid ("mapped") on GPU during S
 - \bullet v becomes valid on CPU after S
- note: you can specify map clauses as part of target (not target data) directive, too
- learn details with the notebook