

# Lecture 2 - Image Fundamentals

This lecture will cover:

- Image acquisition
- Sampling and Quantization
- **Pixels**
- Image operation
- Color space

# Pixels

- **Neighbors of Pixel**
- **Relationship between Pixels**
  - Adjacency
  - Connectivity
  - Regions
  - Boundaries
- **Distance measures**
  - Euclidean distance
  - City-block distance
  - Chessboard distance

# Pixels

## ➤ Neighbors of Pixel

## ➤ Relationship between Pixels

- Adjacency
- Connectivity
- Regions
- Boundaries

## ➤ Distance measures

- Euclidean distance
- City-block distance
- Chessboard distance

# Neighbors of Pixel

If a pixel  $p$  at coordinate  $(x, y)$

➤  $N_4(p)$

➤  $N_D(p)$

➤  $N_8(p)$

# Neighbors of Pixel

If a pixel  $p$  at coordinate  $(x, y)$

➤  $N_4(p)$

$(x+1, y), (x-1, y), (x, y+1), (x, y-1)$

➤  $N_D(p)$

➤  $N_8(p)$

	$q_1$	
$q_2$	$p$	$q_3$
	$q_4$	

# Neighbors of Pixel

If a pixel  $p$  at coordinate  $(x, y)$

➤  $N_4(p)$

$(x+1, y), (x-1, y), (x, y+1), (x, y-1)$

➤  $N_D(p)$

$(x+1, y+1), (x+1, y-1), (x-1, y+1),$   
 $(x-1, y-1)$

➤  $N_8(p)$

$r_1$		$r_2$
	$p$	
$r_3$		$r_4$

# Neighbors of Pixel

If a pixel  $p$  at coordinate  $(x, y)$

➤  $N_4(p)$

$(x+1, y), (x-1, y), (x, y+1), (x, y-1)$

➤  $N_D(p)$

$(x+1, y+1), (x+1, y-1), (x-1, y+1),$   
 $(x-1, y-1)$

➤  $N_8(p) : N_4(p) \cup N_D(p)$

$r_1$	$q_1$	$r_2$
$q_2$	$p$	$q_3$
$r_3$	$q_4$	$r_4$

# Pixels

- Neighbors of Pixel
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# Adjacency

To define adjacency of pixels, we need identify

## ➤ Type of Neighbor

$$N_4(p), N_D(p), N_8(p)$$

## ➤ The set of intensity values $V$

- Binary image:  $V = \{1\}$
- Gray-scale image:  $V = [L_{\min}, L_{\max}]$

$q_1$	$p$	$q_2$

0	1	1

Adjacency in a binary image

	$q_1$	
$q_2$	$p$	$q_3$

	39	
11	13	16

Adjacency in a gray-scale image

# Adjacency

## Types of Adjacency:

- 4-adjacency
- 8-adjacency
- M-adjacency (mixed adjacency)

# Adjacency

## Types of Adjacency:

### ➤ 4-adjacency

- $p, q \in V$
- $q \in N_4(p)$

### ➤ 8-adjacency

### ➤ M-adjacency (mixed adjacency)

$r_{11}$	$r_{12}$	$r_{13}$
$r_{21}$	$r_{22}$	$r_{23}$
$r_{31}$	$r_{32}$	$r_{33}$

0	1	..... 1
0	1	0
0	0	1

# Adjacency

## Types of Adjacency:

➤ 4-adjacency

➤ 8-adjacency

- $p, q \in V$
- $q \in N_8(p)$

➤ M-adjacency (mixed adjacency)

$r_{11}$	$r_{12}$	$r_{13}$
$r_{21}$	$r_{22}$	$r_{23}$
$r_{31}$	$r_{32}$	$r_{33}$

0	1	1
0	1	0
0	0	1

# Adjacency

## Types of Adjacency:

- 4-adjacency
- 8-adjacency
- **M-adjacency (mixed adjacency)**
  - $p, q \in V$
  - $q \in N_4(p)$  or  $q \in N_D(p)$  and  $N_4(p) \cap N_4(q) \notin V$

$r_{11}$	$r_{12}$	$r_{13}$
$r_{21}$	$r_{22}$	$r_{23}$
$r_{31}$	$r_{32}$	$r_{33}$

0	1	1
0	1	0
0	0	1

# Connectivity

Important concept used in establishing boundaries of objects and components of regions in an image

- *Path*
- *Connected*
- *Connected component*
- *Connected set*

$r_{11}$	$r_{12}$	$r_{13}$
$r_{21}$	$r_{22}$	$r_{23}$
$r_{31}$	$r_{32}$	$r_{33}$

0	1	1
0	1	0
0	0	1

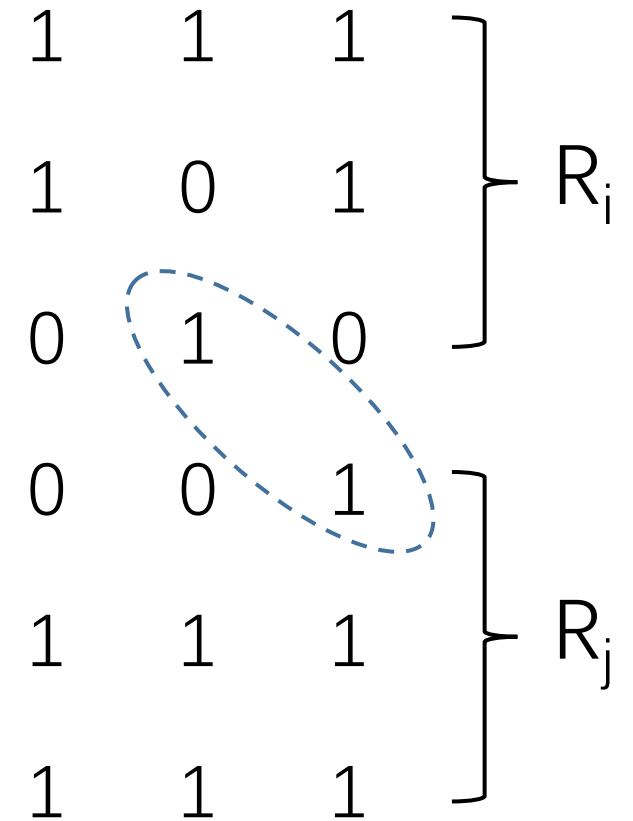
0	1	1
0	1	0
0	0	1

# Region

***R***: a subset of an image which is also a connected set

➤ ***Adjacent region***

➤ ***Disjoint region***



# Boundary

A set of pixels that are adjacent to pixels in the complement of ***R***.

➤ ***Inner border and outer border***

➤ ***Image border***

➤ ***Edge***

0	0	0	0	0
0	1	1	0	0
0	1	1	0	0
0	1	1	1	0
0	1	1	1	0
0	0	0	0	0



# Boundary

A set of pixels that are adjacent to pixels in the complement of ***R***.

- *Inner border and outer border*
- *Image border*
- ***Edge***



# Pixels

- Neighbors of Pixel
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# Distance Measures

For pixels  $p$ ,  $q$  and  $z$ , with coordinates  $(x, y)$ ,  $(s, t)$  and  $(v, w)$ ,  $D$  is a **distance function or metric** if

- $D(p, q) \geq 0$  ( $D(p, q) = 0$  only if  $p = q$ )
- $D(p, q) = D(q, p)$
- $D(p, z) \leq D(p, q) + D(q, z)$

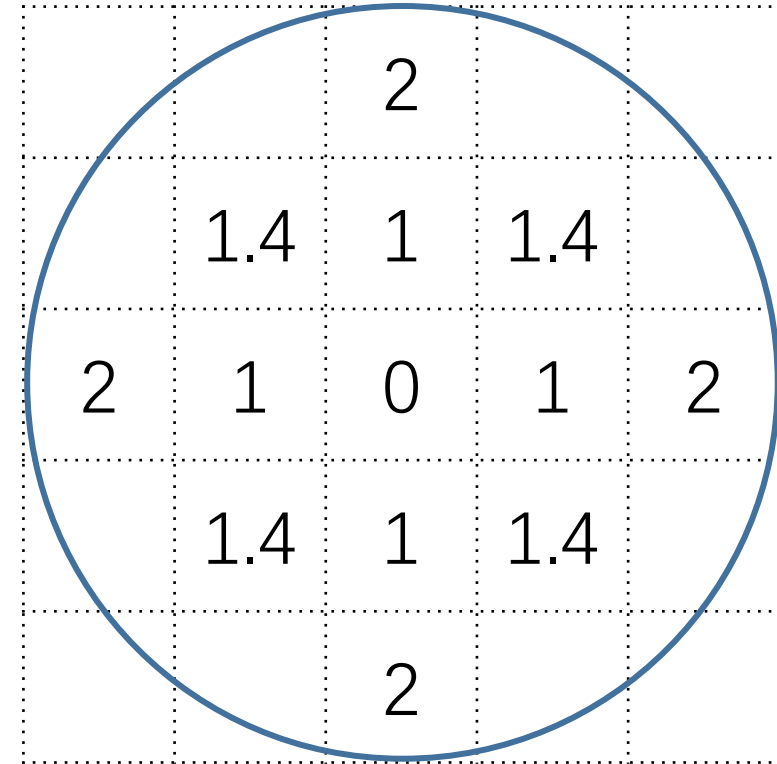
# Distance Measures

➤ Euclidean distance :

$$D_e(p, q) = [ (x-s)^2 + (y-t)^2 ]^{1/2}$$

➤ City-block distance:

➤ Chessboard distance



# Distance Measures

- Euclidean distance :

$$D_e(p, q) = [ (x-s)^2 + (y-t)^2 ]^{1/2}$$

- **City-block distance:**

$$D_4(p, q) = |x-s| + |y-t|$$

- Chessboard distance

			2	
		2	1	2
	2	1	0	1
		2	1	2
			2	

# Distance Measures

- Euclidean distance :

$$D_e(p, q) = [ (x-s)^2 + (y-t)^2 ]^{1/2}$$

2    2    2    2    2

- City-block distance:

$$D_4(p, q) = |x-s| + |y-t|$$

2    1    1    1    2

2    1    0    1    2

- Chessboard distance

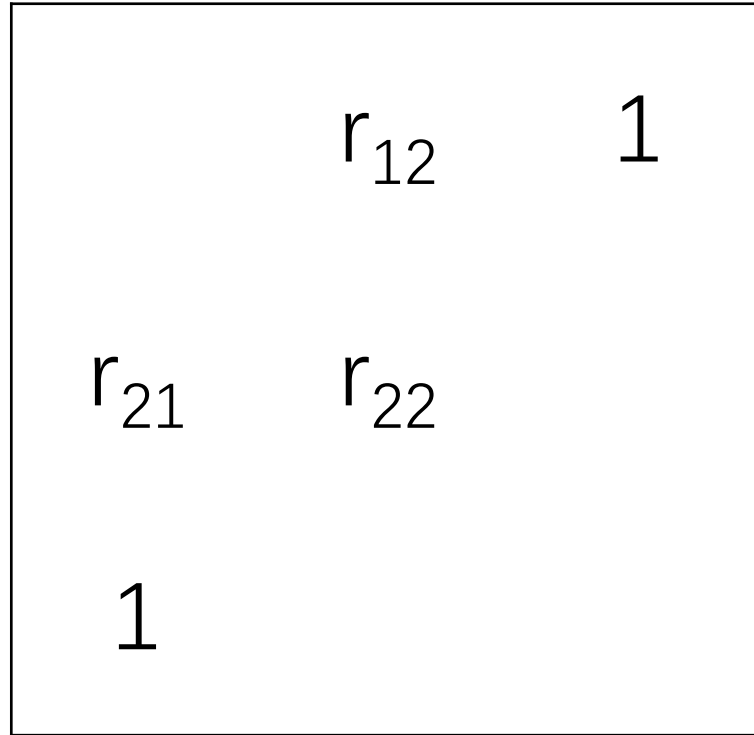
$$D_8(p, q) = \max(|x-s|, |y-t|)$$

2    1    1    1    2

2    2    2    2    2

# Distance Measures

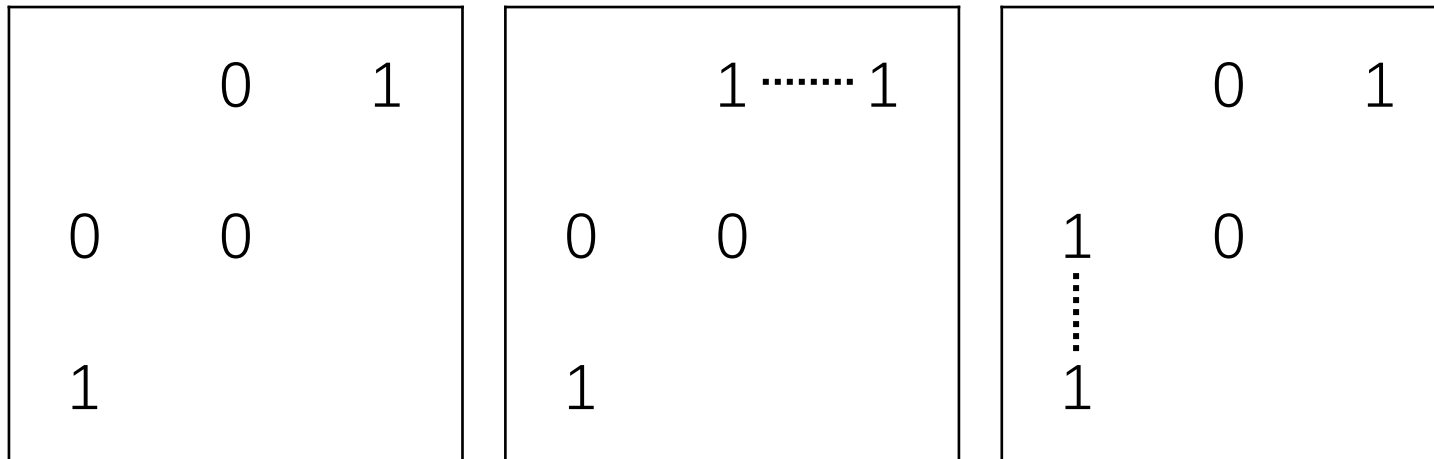
**$D_m$  distance** is defined as the shortest  $m$ -path between the point



$$D_m = ?$$

# Distance Measures

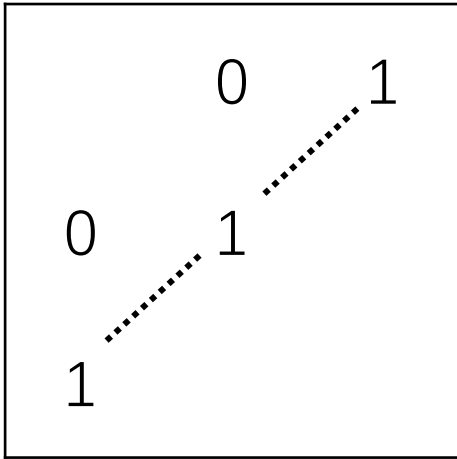
No m-path between the point



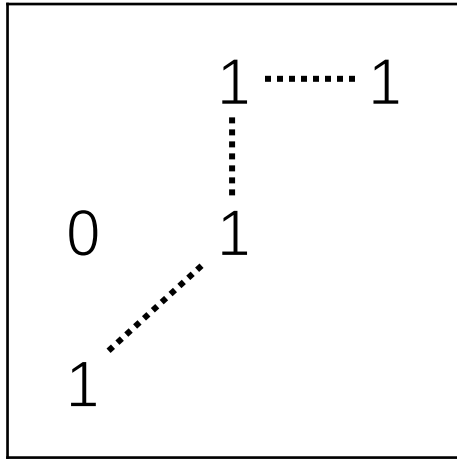


# Distance Measures

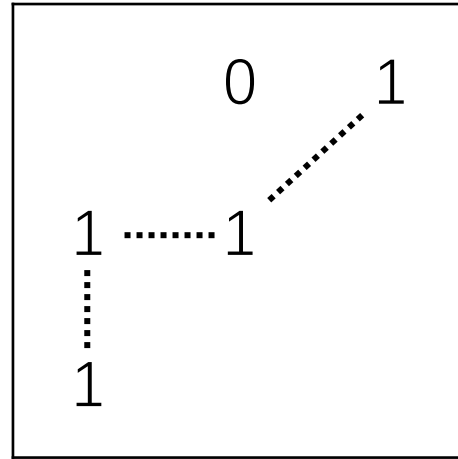
**$D_m$  distance** is different by the values of  $r_{12}$ ,  $r_{21}$  and  $r_{22}$



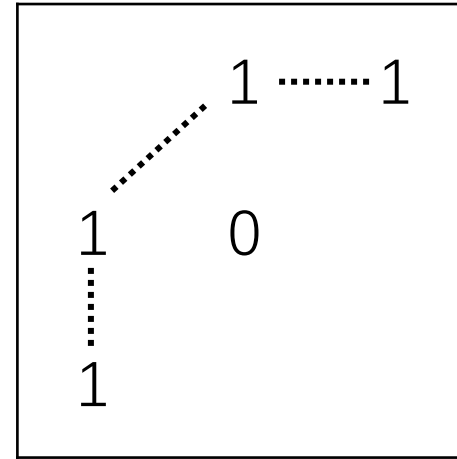
$$D_m = 2$$



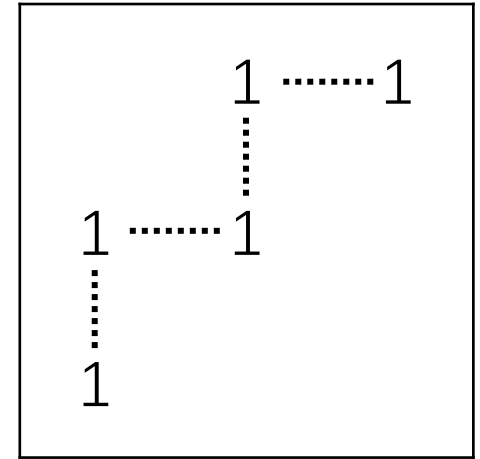
$$D_m = 3$$



$$D_m = 3$$



$$D_m = 3$$



$$D_m = 4$$