# **Homework 2**

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# **Problem-1**

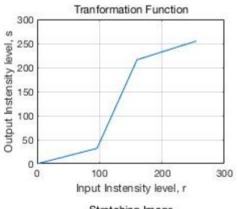
#### 1.1 Function

$$s = \frac{s1}{r1}r(0 \le r \le r1) \tag{1}$$

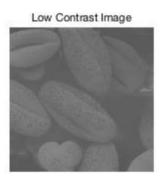
$$s = \frac{s2 - s1}{r2 - r1}r + s1(r1 \le r \le r2) \tag{1}$$

$$s = \frac{255 - s2}{255 - r2}r + s2(r2 \le r \le 255) \tag{1}$$

# 1.2 Visualization Results



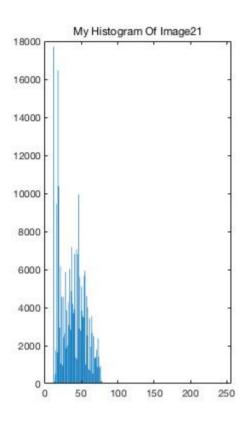


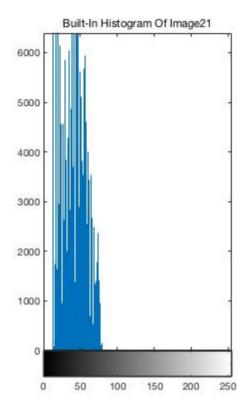




# **Problem-2**

# 2.1 Visualization Results

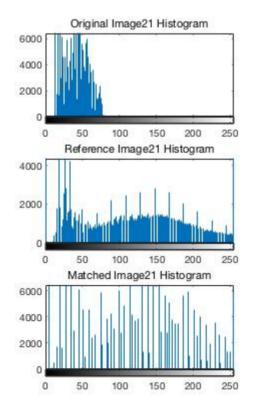












#### 2.2 Code

#### 2.2.1 Histogram

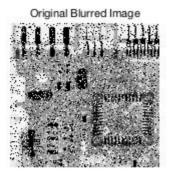
```
function [ hist_value, hist_value_prob ] = Histogram(image)
   % Calculate Histogram
   % Args:
       image:
   %
            image matrix
   % Return:
       hist value:
            histogram value (number of each gray level)
      hist vale:
            histogram value (percentage of each gray level)
   % Get Statistics of Image
    image = image(:);
   hist_value = zeros(256,1);
   % Calculate number of each intensity level
    length = size(image, 1);
    for i = 1: length
        hist value(image(i)) = hist value(image(i))+ 1;
   end
   hist_value_prob = hist_value';
   % Calculate percentage of each intenstiy level
    for i = 1:256
        hist_value_prob(i) = hist_value_prob(i) / length;
    end
end
```

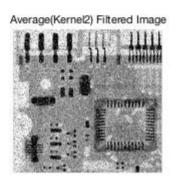
#### 2.2.2 Histogram Mapping

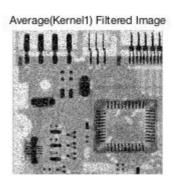
```
function [mapping] = HistogramMatch(image, image_ref)
   % Histogram Matching
   % Args:
       image:
           image matrix
      image_ref:
            reference image matrix
   % Return:
       mapping
   %
   % Compute the hist of two images
   hist = imhist(image);
   hist_ref = imhist(image_ref);
   % Compute CDFs
    image_cdf = cumsum(hist)' / numel(image);
    image_cdf_ref = cumsum(hist_ref)' / numel(image_ref);
   % Get Mapping
   mapping = zeros(256,1);
    for i = 1: 256
        [value, index] = min(abs(image_cdf(i) - image_cdf_ref));
        mapping(i) = index - 1;
    end
end
```

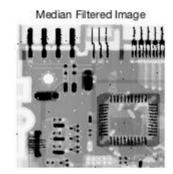
### **Problem-3**

#### 3.1 Visualization Results









Use kernel2 will get more clear image than kernel1, the centeral pixel of each patch is much more important.

# 3.2 Median Filter Code

```
function [ image ] = MedianFilter(image, shape)
    % Median Filtering for image
    % Args:
       image:
            image matrix
        shape:
            'same': use padding
    % Return:
        image
    %
    % Get image size
    w = size(image, 1);
    h = size(image, 2);
    % Padding the image
    new_image = zeros(w+2, h+2);
    new_image(2:1+w,2:1+h) = image;
    % Get Median value for each 3x3 patch
    for i = 1:w
        for j = 1:h
            patch = new_image(i:i+2,j:j+2);
            mid_patch = median(patch(:));
            image(i,j) = mid_patch;
        end
    end
end
```

# **Problem-4**

## 4.1 Visualization Results

### **4.1.1 Figure**

Original Blurred Image



Sharpening (Kernel1) Image



Sharpening (Kemel3) Image



Sharpening (Kernel2) Image



Sharpening (Kernel4) Image



4.1.2 Edge

Original Blurred Image



Sharpening (Kernel1) Image



Sharpening (Kernet2) Image



Sharpening (Kemel3) Image



Sharpening (Kernel4) Image



Use Kernel2 and Kernel4 can get more sharpen images than Kernel1 and Kernel3

# **4.2 Code**

```
function [image] = LaplaceSharpen(image, laplace_kernel)
    % Laplace Sharpening
    % Args:
        image:
       laplace_kernel:
            kernel matrix
    % Return:
       image
    %
    w = size(image, 1);
    h = size(image, 2);
    % Padding the image
    new_image = zeros(w+2, h+2);
    new_image(2:1+w,2:1+h) = image;
    for i = 1:w
        for j = 1:h
            patch = new_image(i:i+2,j:j+2);
            value = sum(sum(patch.*laplace_kernel));
            image(i,j) = value;
        end
    end
end
```