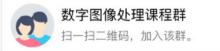
Lecture 1 - Introduction

Digital Image Processing





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Lecture 1 - Introduction

- What is a digital image?
- What is digital image processing?
- Examples of digital image processing
- Steps of digital image processing
- Methods of digital image processing



Goal

Why do we need image processing

- > Improvement of pictorial information for human interpretation
- > Processing of image data for autonomous machine perception
 - Storage
 - Transmission
 - Representation
 - Description
 - Recognition
 - Many more.

Image processing is ubiquitous!



Stage of DIP

Low level process

INPUT: Image **OUTPUT:** Image

EXAMPLE:

Denoise

Contrast enhancement

Image sharpening

Mid level process

INPUT: Image

OUTPUT: Attributes

EXAMPLE:

Segmentation

Description

Recognition

High level process

INPUT: Attributes

OUTPUT: Understanding

EXAMPLE:

Image analysis

Image understanding

There are no clear-cut boundaries from image processing to computer vision



Fundamental Steps in DIP

- > Image acquisition
- > Image enhancement
- ➤ Image restoration
- ➤ Image reconstruction
- > Image compression
- > Image segmentation
- > Image representation and description
- ➤ Object recognition



Applied methods in DIP

Spatial domain

- Pixel processing grey processing
- Neighborhood processing gradient algorithm, Laplacian operator, smoothing operator, convolution algorithm

Frequency domain

- Discrete Fourier Transform (DFT)
- Discrete Cosine Transform (DCT)
- Discrete Wavelet Transform (DWT)
- Walsh-Hadamard Transform (WHT)

Tools: Orthogonal transformation, Filtering, Convolution, Statistics etc.



Lecture 2 - Image Fundamentals

- Image acquisition (图像获取)
- Sampling and Quantization (取样和量化)
- Pixels (像素)
- Image operation (图像的基本操作)
- Color space (彩色基础)



Image Operations

- ➤ Array and Matrix Operation (阵列与矩阵操作)
- ➤ Vector and Matrix Operation (向量矩阵操作)
- ➤ Linear and Nonlinear Operation (线性非线性操作)
- ➤ Set and Logical Operation (集合和逻辑操作)
- ➤ Arithmetic Operation (算数运算)
- ➤ Spatial Operation (空间运算)
- ➤ Image Transformation (图像变换操作)
- ➤ Probabilistic Methods (概率方法)



Lecture 3 – Spatial Filtering (空间滤波)

- Spatial domain (空间域)
- Intensity Transformation (灰度变换)
- Histogram (直方图)
- Spatial Filtering (空间滤波器)
 - ✓ Smoothing (平滑)
 - ✓ Sharpening (锐化)



Intensity Transformation

> Simplest image processing techniques

$$s = T(r)$$

- > Types of Intensity Transformation
 - Image Negatives (图像反转)
 - Log Transformation (对数变换)
 - Power-law (gamma) Transformation(幂律/伽马变换)
 - Piecewise-Linear Transformation(分段线性变换)



Histogram Processing

- ➤ Histogram Equalization (直方图均衡)
- ➤ Histogram Matching (Specification) (直方图匹配/规定化)
- ➤ Local Histogram Processing (局部处理)
- ➤ Histogram Statistics for Image Enhancement (直方图统计)



Spatial Filtering

A Spatial filter

- is directly applied on the image
- ➢ is also called spatial masks (掩模)、kernels (核)、templates (模板)、windows (窗口)
- consists of
 - 1) neighborhood 2) a predefined operation
- can be linear and nonlinear
 - Linear spatial filter corresponds to spectral filter in frequency domain
 - Nonlinear spatial filter cannot be accomplished in frequency domain



Smooth Filters (平滑滤波器)

- > Blurring for preprocessing tasks
- Noise deduction
 - Linear filter: average filtering lowpass filter in frequency domain
 - Nonlinear filter



Sharpening Filter (锐化滤波器)

- ➤ Spatial differentiation (空间微分)
- > Sharpening filter
 - Laplacian filtering (拉普拉斯算子)
 - Unsharp Masking (非锐化掩蔽)
 - Gradient filtering (梯度算子)



Lecture 4 – Frequency Domain Transform (频率域变换)

- 2D Discrete Fourier Transform (傅里叶变换)
- Frequency Domain Filtering (频率域滤波)
 - Lowpass Filtering (低通滤波器)
 - Highpass Filtering (高通滤波器)
 - Selective Filtering (选择性滤波)
- Other Transform
 - Discrete Cosine Transform (余弦变换)
 - Walsh-Hadamard Transform
 - Discrete Wavelet Transform (小波变换)

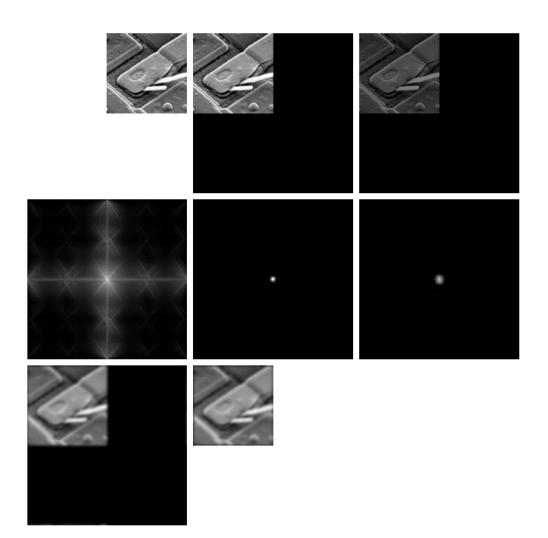


Properties of 2D DFT

- ➤ Spatial and frequency intervals (空间和频率间隔)
- ➤ Translation (平移)
- ➤ Periodicity (周期性)
- ➤ Rotation (旋转)
- ➤ Separability (可分性)
- ➤ Symmetry (对称性)
- ➤ Spectrum and Phase angle (频谱和相角)
- ➤ 2D Convolution theorem (卷积定理)



Steps of Frequency Domain Filtering



- 1. Zero-padding input image $f_p(x, y)$
- $2.f_p(x,y)(-1)^{(x+y)}$ to center its transform
- 3. Compute DFT

4.
$$G(u, v) = H(u, v)F(u, v)$$

5.
$$g_p(x,y) = Re[\mathcal{F}^{-1}[(G(u,v))]] (-1)^{(x+y)}$$

6. Obtain g(x, y) from top-left quadrant



Lowpass Filtering

- ➤ Ideal Lowpass Filter (理想低通滤波器)
- ➤ Butterworth Lowpass Filter (布特沃斯低通滤波器)
- ➤ Gaussian Lowpass Filter (高斯低通滤波器)

Lowpass filters. D_0 is the cutoff frequency and n is the order of the Butterworth filter.

Ideal	Butterworth	Gaussian
$H(u,v) = \begin{cases} 1 & \text{if } D(u,v) \leq D_0 \\ 0 & \text{if } D(u,v) > D_0 \end{cases}$	$H(u, v) = \frac{1}{1 + [D(u, v)/D_0]^{2n}}$	$H(u, v) = e^{-D^2(u, v)/2D_0^2}$



Highpass Filtering

- ➤ Ideal Highpass Filter (理想高通滤波器)
- ➤ Butterworth Highpass Filter(布特沃斯高通滤波器)
- ➤ Gaussian Highpass Filter (高斯高通滤波器)

$$H_{\mathrm{HP}}(u,v) = 1 - H_{\mathrm{LP}}(u,v)$$

Highpass filters. D_0 is the cutoff frequency and n is the order of the Butterworth filter.

Ideal	Butterworth	Gaussian
$H(u, v) = \begin{cases} 1 & \text{if } D(u, v) \leq D_0 \\ 0 & \text{if } D(u, v) > D_0 \end{cases}$	$H(u,v) = \frac{1}{1 + [D_0/D(u,v)]^{2n}}$	$H(u, v) = 1 - e^{-D^2(u, v)/2D_0^2}$



Highpass Filtering

- ➤ Laplacian (拉普拉斯算子)
- ➤ Unsharp Mask (钝化模板)
- ➤ Homomorphic Filtering(同态滤波)

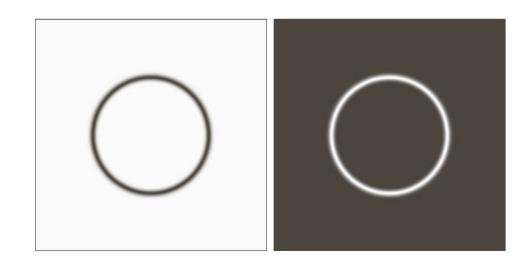


Selective Filtering

➤ Bandreject(带阻) and Bandpass(带通) Filters

$$H_{\rm BP}(u,v) = 1 - H_{\rm BR}(u,v)$$

	Ideal	Butterworth	Gaussian
11(", ")	$dD_0 - \frac{W}{2} \le D \le D_0 + \frac{W}{2}$ therwise	$H(u, v) = \frac{1}{1 + \left[\frac{DW}{D^2 - D_0^2}\right]^{2n}}$	$H(u, v) = 1 - e^{-\left[\frac{D^2 - D_0^2}{DW}\right]^2}$





Selective Filtering

- ➤ Notch Filter (陷波滤波器)
 - Reject or pass frequencies in predefined neighborhood
 - Symmetric about the origin for a zero-phase shift filters
 - Selectively modify local regions of the DFT

$$H_{NR}(u, v) = \prod_{k=1}^{Q} H_k(u, v) H_{-k}(u, v)$$

$$H_{NP}(u, v) = 1 - H_{NR}(u, v)$$

Where $H_k(u, v)$, $H_{-k}(u, v)$ are Highpass filters with center at (u_k, v_k) and (u_{-k}, v_{-k})



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