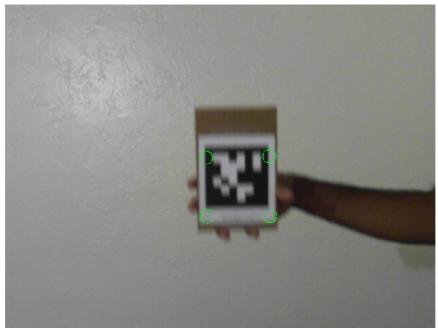
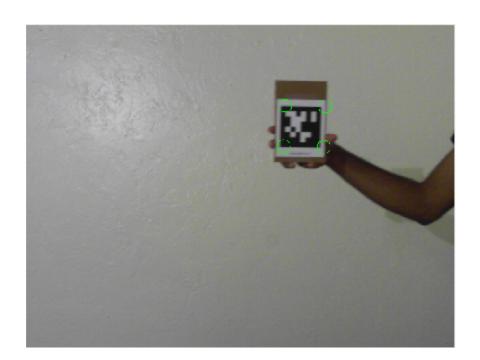
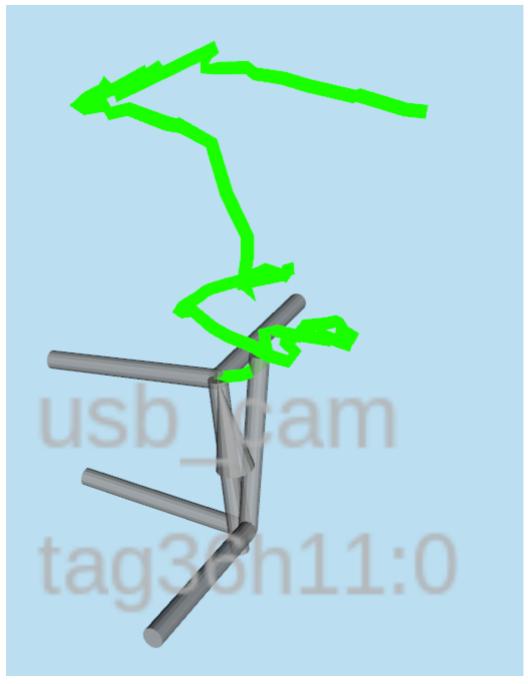
Task 7.3: Programming Familiarization Part 3 - ROS Libraries

Screenshots

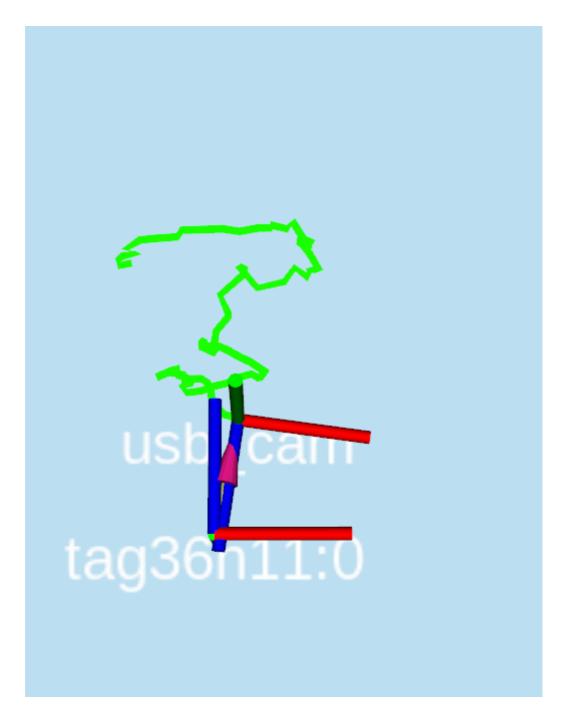










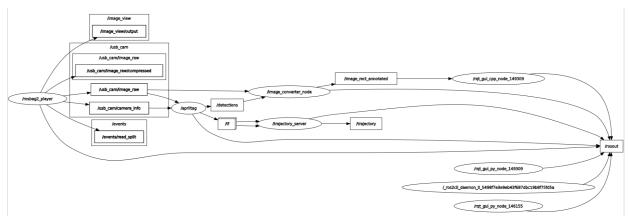


Video

https://www.youtube.com/watch?v=yL1-ai5ovhE

Short question answers

1. ROS graph:



- 2. When planting seedlings, we could add paper collars with tags to each seedling stem. This would allow us to detect each seedling, use the April tag's ID to identify the species, and even to use the seedlings as landmarks in a localization scheme.
- 3. I have no original feedback. I am already an experienced ROS developer, so this was, to be frank, a waste of my time.