

## SC3.316: Mathematical Methods in Biology

### Midterm 2 solutions

1. (15 points) Find the reduced echelon form of the following matrix:

$$A = \begin{pmatrix} 1 & 2 & 1 & 9 \\ 2 & 4 & 1 & 18 \\ 3 & 5 & 1 & 24 \end{pmatrix}$$

**Solution:**

1.  $R_2 = R_2 - 2R_1$ : (2 marks)

$$\begin{pmatrix} 1 & 2 & 1 & 9 \\ 0 & 0 & -1 & 0 \\ 3 & 5 & 1 & 24 \end{pmatrix}$$

2.  $R_3 = R_3 - 3R_1$ : (2 marks)

$$\begin{pmatrix} 1 & 2 & 1 & 9 \\ 0 & 0 & -1 & 0 \\ 0 & -1 & -2 & -3 \end{pmatrix}$$

3. Swap the second and third rows: (2 marks)

$$\begin{pmatrix} 1 & 2 & 1 & 9 \\ 0 & -1 & -2 & -3 \\ 0 & 0 & -1 & 0 \end{pmatrix}$$

4.  $R_2 = -R_2$  (2 marks)

$$\begin{pmatrix} 1 & 2 & 1 & 9 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & -1 & 0 \end{pmatrix}$$

5.  $R_1 = R_1 - 2R_2$  (2 marks)

$$\begin{pmatrix} 1 & 0 & -3 & 3 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & -1 & 0 \end{pmatrix}$$

6.  $R_3 = -R_3$  (2 marks)

$$\begin{pmatrix} 1 & 0 & -3 & 3 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

7.  $R_1 = R_1 + 3R_3$  (2 marks)

$$\begin{pmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

8.  $R_2 = R_2 - 2R_3$  (1 mark)

$$\begin{pmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

2. (10 points) State the Deficiency Zero Theorem.

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**Solution:**

Let  $(S, C, R)$  be a reaction network of deficiency zero.

1. If the network is not weakly reversible, then for any arbitrary choice of kinetics, the differential equations for the kinetic system  $(S, C, R, K)$  cannot admit a positive equilibrium. (4 marks)
2. If the network is weakly reversible, then assuming mass-action kinetics, the following holds: (2 marks)
  - (a) Within each positive stoichiometric compatibility class, there exists exactly one positive equilibrium. (2 marks)
  - (b) The equilibrium is asymptotically stable. (2 marks)
3. (15 points) Consider a reaction network with  $l$  linkage classes. Let  $\delta_i$  denote the deficiency of the  $i^{\text{th}}$  linkage class and let  $\delta$  denote the deficiency of the whole network. If  $\delta = 0$ , then  $\delta_i = 0$  for every linkage class.

**Solution:**

Note that  $\sum_{i=1}^l \delta_i = \sum_{i=1}^l (n_i - 1 - s_i) = n - l - \sum_{i=1}^l s_i$ . (7 marks)

In addition,  $\delta = n - l - s$ . Since  $\sum_{i=1}^l s_i \geq s$ , we get  $\delta \geq \sum_{i=1}^l \delta_i$ . (5 marks)

This implies that if  $\delta = 0$ , then  $\delta_i = 0$  for every linkage class. (3 marks)

4. (15 points) A reaction network is “forest-like” if every direct link connecting two complexes in a linkage class is a cut-link. Show that every forest-like weakly reversible reaction network is reversible.

**Solution:**

For contradiction, assume that the forest-like weakly reversible reaction network is not reversible. (3 marks)

Then there exists complexes  $y_0, y'_0$  such that there is a reaction from  $y_0$  to  $y'_0$ , no reaction from  $y'_0$  to  $y_0$  (5 marks)

and a reaction pathway from  $y'_0$  to  $y_0$  (due to weak reversibility). (5 marks)

Then the link from  $y_0$  to  $y'_0$  is not a cut-link, contradicting the fact that the reaction network is “forest-like”. (2 marks)

5. (15 points) A reaction network is consistent if there exists positive real numbers  $c_{y \rightarrow y'}$  such that

$$\sum_{y \rightarrow y'} c_{y \rightarrow y'} (y' - y) = 0. \quad (1)$$

Show that a weakly reversible reaction network is consistent.

**Solution:**

Consider a weakly reversible consisting of a single cycle. (3 marks)

In this case, we can choose  $c_{y \rightarrow y'} = 1$  for each reaction  $y \rightarrow y' \in E$  so that the network is consistent. (7 marks)

Repeating this argument for multiple cycles, we get that a weakly reversible reaction network is consistent. (5 marks)

6. (15 points) Show that a reversible star-like network (as in Figure 1) is quasi-thermodynamic.

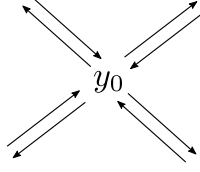


Figure 1: Star-like network.

**Solution:**

Since the network is reversible, it is weakly reversible and hence a positive equilibrium exists. Let us call the positive equilibrium  $c^*$ . Let  $C^*$  denote the set of all complexes except  $y_0$ . Therefore, we have

$$\sum_{y \in C^*} k_{y \rightarrow y_0} (c^*)^y (y_0 - y) + \sum_{y \in C^*} k_{y_0 \rightarrow y} (c^*)^{y_0} (y - y_0) = 0 \quad (2 \text{ marks})$$

This implies that

$$\sum_{y \in C^*} k_{y \rightarrow y_0} (c^*)^y (y_0 - y) = \sum_{y \in C^*} k_{y_0 \rightarrow y} (c^*)^{y_0} (y_0 - y) \quad (2 \text{ marks}) \quad (2)$$

Define  $\mu(c) = \log(c) - \log(c^*)$ . (1 mark)

This means that the rate function can be written as

$$\begin{aligned} f(c) &= \sum_{y \rightarrow y' \in \mathcal{R}} k_{y \rightarrow y'} c^y (y' - y) \\ &= \sum_{y \rightarrow y' \in \mathcal{R}} k_{y \rightarrow y_0} (c^*)^y e^{y \cdot \mu(c)} (y_0 - y) \\ &= \sum_{y \in C^*} k_{y \rightarrow y_0} (c^*)^y e^{y \cdot \mu(c)} (y_0 - y) - e^{y_0 \cdot \mu(c)} \sum_{y \in C^*} k_{y_0 \rightarrow y} (c^*)^{y_0} (y_0 - y) \quad (4 \text{ marks}) \end{aligned}$$

Using Equation 2, we get that

$$f(c) = \sum_{y \in C^*} k_{y \rightarrow y_0} (c^*)^y (e^{y \cdot \mu(c)} - e^{y_0 \cdot \mu(c)}) (y_0 - y)$$

$$\text{Hence } \log(c) - \log(c^*) \cdot f(c) = \sum_{y \in C^*} k_{y \rightarrow y_0} (c^*)^y (e^{y \cdot \mu(c)} - e^{y_0 \cdot \mu(c)}) (y_0 \cdot \mu(c) - y \cdot \mu(c)). \quad (2 \text{ marks})$$

Since the exponential function is increasing, we have  $(x_2 - x_1)(e^{x_1} - e^{x_2}) \leq 0$ . This implies that

$$\mu(c) \cdot f(c) \leq 0.$$

with equality holding iff  $(y - y_0) \cdot \mu(c)$  for all  $y \in C^*$ . (1 mark)

We still need to show that the dynamical system is quasi-static, i.e., show that the set of equilibria is identical to the set  $E = \{c \in \mathbb{R}_{>0}^S : \log(c) - \log(c^*) \in S^\perp\}$ . If  $c$  is an equilibrium, then we have equality in Equation 3. This implies that  $\log(c) - \log(c^*) \in S^\perp$ . Conversely, if  $\log(c) - \log(c^*) \in S^\perp$ , then we have equality in Equation 3. Therefore, the dynamical system is quasi-thermodynamic. (3 marks)

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7. (15 points) Let  $A_{n \times n}$  be a square matrix and let  $x \in \mathbb{R}^n$ . Show that the following are equivalent

1. For every vector  $b \in \mathbb{R}^n$ , the system  $Ax = b$  has at least one solution.
2. For every vector  $b \in \mathbb{R}^n$ , the system  $Ax = b$  has exactly one solution.

**Solution:**

(1  $\Rightarrow$  2) This is certainly true since if for every  $b \in \mathbb{R}^n$ , the system  $Ax = b$  has a unique solution, then it has at least one solution. (2 marks)

(2  $\Rightarrow$  1) Take  $b = e_j$ , where  $e_j$  is the  $j^{\text{th}}$  column vector of the identity matrix. Then the consistency of  $Ax = e_j$  yields a vector  $x_j$  such that  $Ax_j = e_j$ . (3 marks)

Let  $B$  be the matrix with vectors  $[x_1, x_2, \dots, x_n]$ . Then

$$\begin{aligned} AB &= A[x_1, x_2, \dots, x_n] \\ &= [Ax_1, Ax_2, \dots, Ax_n] \\ &= [e_1, e_2, \dots, e_n] \end{aligned} \tag{3}$$

This implies that  $AB = I$ . (5 marks)

We now show that the matrix  $B$  is invertible. Towards this we show that  $Bx = 0$  has only the trivial solution ( $x_1 = x_2 = \dots, = x_n = 0$ ). If  $Bx = 0$ , then  $A(Bx) = 0 = A0 = 0$ , which implies  $x = 0$ . So  $B$  is invertible. (3 marks)

This implies that  $ABB^{-1} = IB^{-1}$  so that  $A = B^{-1}$ . Thus  $A$  is invertible and the system  $Ax = b$  has the unique solution  $x = A^{-1}b$ . (2 marks)