

Physical DB Design

- Hashed Files

- Records are divided into **buckets** according to the value of the key.
- A **hash function h** takes as argument a value for the key and produces an integer in the range **0** to **$B-1$** , where **B** is the number of buckets.
- Each bucket consists of a (usually small) number of blocks. The blocks in each bucket are organized as a heap.
- The **bucket directory** is an array of pointers indexed from **0** to **$B-1$** . The entry for **i** in the directory is a pointer to the first block of bucket **i** , called the **bucket header**. The blocks in a bucket form a linked list.

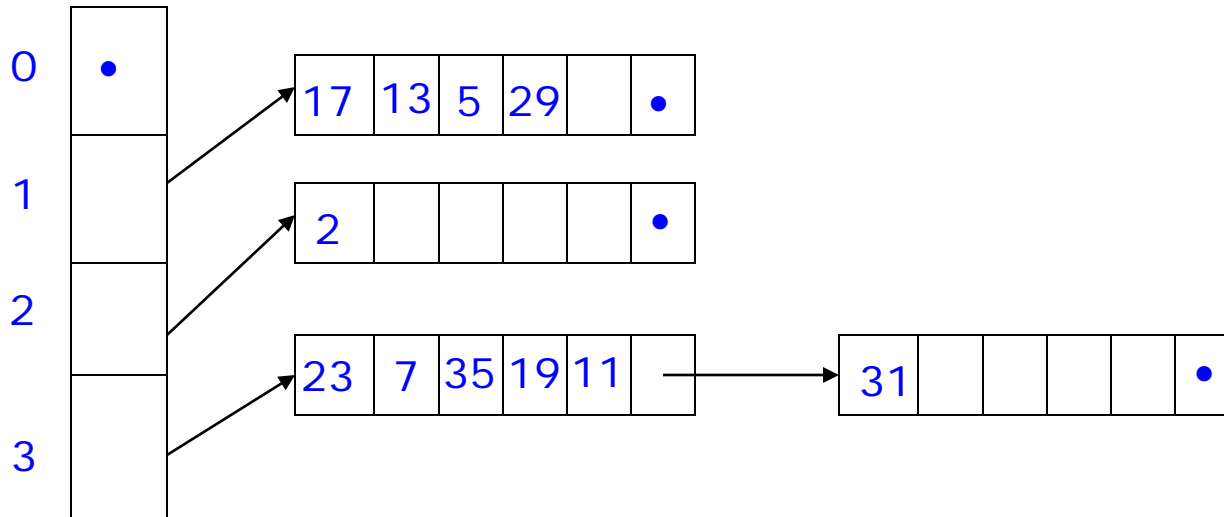
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- Hash Functions

- A hash function's range should be the set $\{0,1,\dots,B-1\}$. Moreover, it should take each value in the set with roughly equal probability.
- A simple hash function :
 - Convert each key value into an integer and then take the remainder of that integer modulo B .
- If the key value v is an integer, then $h(v) = v \bmod B$
- If the key value is a character string, convert it into an integer by treating the bytes representing the characters as integers and taking the sum of these integers.

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- **Example:** a file of numbers organized in a hashed file with 4 buckets. The hash function is $h(v) = v \bmod 4$.



- All numbers stored are prime. Hence, no number appears in bucket 0 and only number 2 appears in bucket 2.

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- Operations on Hashed Files

1. **Lookup** a record with key value v :

compute $h(v)$ and find the bucket header with that value; examine the list of blocks in the bucket, as if the bucket were a heap; if the desired record is not found there, there is no point in searching other buckets.

2. **Insert** a record with key value v :

compute $h(v)$ and find the bucket header with that value; locate the last block of the bucket (either by traversing the list of blocks or by following a pointer to the last block); if there is space on the last block, the record is placed there; otherwise a new block is linked at the end.

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- Operations on Hashed Files

3. **Delete** a record with key value v :

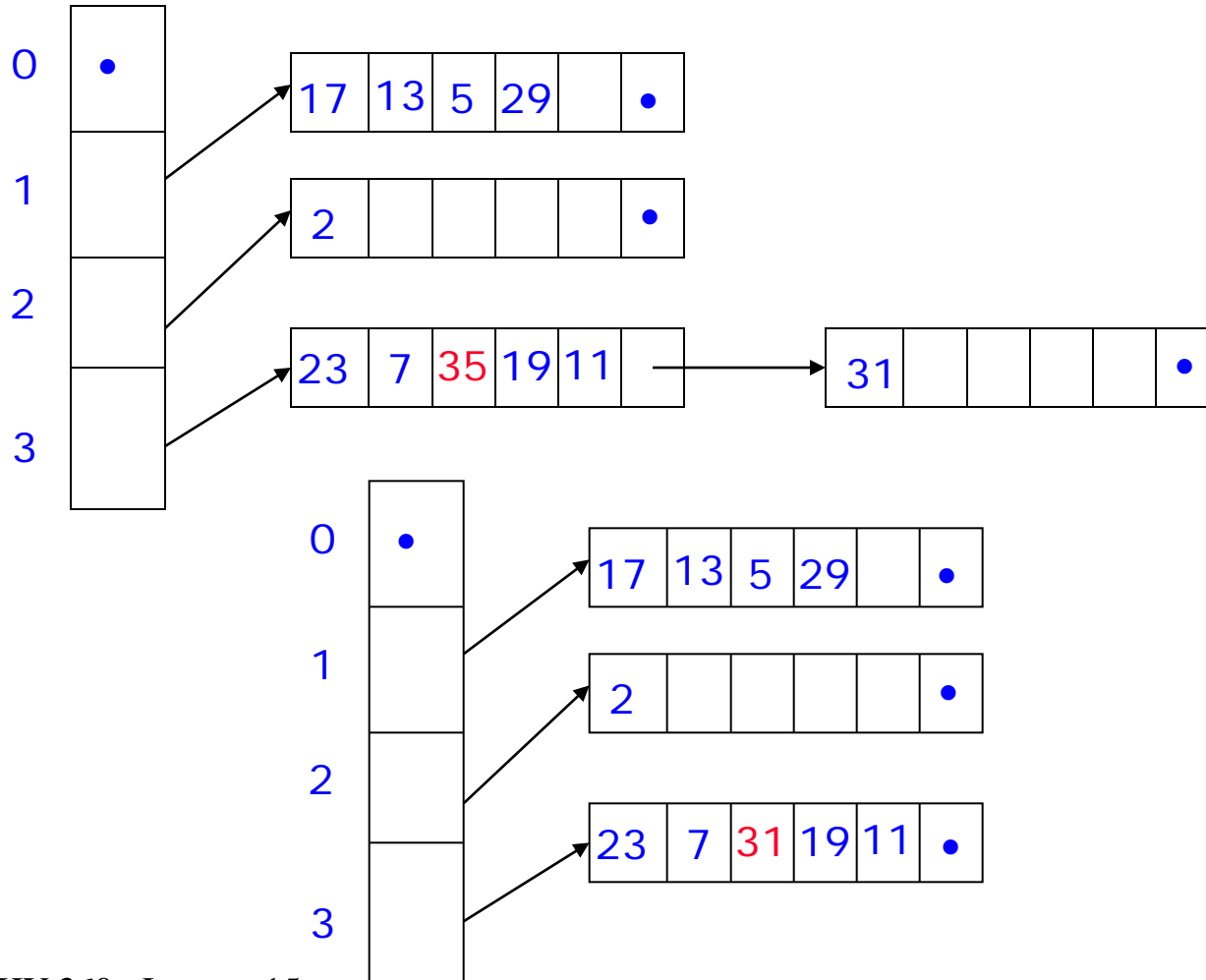
locate the record to be deleted as in the lookup operation; if the records are pinned, set the deleted bit in the record; if they are unpinned, records may be compacted.

4. **Modify** a record with key value v :

locate the record to be deleted as in the lookup operation; change the field(s) in the record; if the record is of variable length, it may have to be moved among the blocks in the bucket

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- **Example:** delete record with key value 35



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- Efficiency of Hashing

- A hashed file with B buckets behaves as if it were a heap approximately B times shorter. Thus, we can speed-up operations by a factor of B .
- For a file of n records, of which R fit in a block, and for a hashed organization with B buckets (whose headers are kept in main memory) we require on average:
 - $\lceil n/2BR \rceil$ for a successful lookup, deletion or modification of an existing record
 - $\lceil n/BR \rceil$ for an unsuccessful lookup

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- **Example:** A file contains 1,000,000 records of 200 bytes each. Blocks are $2^{12}=4096$ bytes long. $R=20$.
 - If $B=1000$, then the average bucket holds $n/B=1000$ records. These are distributed over $n/BR=50$ blocks.
 - If each block address requires 4 bytes, the bucket directory requires 4000 bytes.
 - An unsuccessful lookup takes 50 block accesses.
 - A successful lookup requires 26 block accesses on the average.

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- Indexed Sequential Access Method (ISAM)
 - File records are assumed to have unique keys.
 - File records must be kept sorted according to their key values.
- Sorting Keys
 - Independently of their domains, keys can be compared
 - Numerical order is used to compare integers or reals
 - Lexicographic order is used for character strings
 - To sort keys containing more than one field, an order must be imposed on the keys; then records are sorted according to the value of the first field, forming sequences of clusters.
 - Each cluster consists of records with the same value in the first field; clusters are sorted by the value of the second field, etc.

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- **Example:** assume record keys consist of two integer-valued fields. Sorting the list of key values (2,3), (1,2), (2,2), (3,1), (1,3) results in the list (1,2),(1,3),(2,2),(2,3),(3,1).
- **Accessing Sorted Files**
 - The knowledge of the order of records in a sorted file can be exploited for providing efficient access to the file records.
 - A file called a **sparse index** is created for a sorted file. The index contains pairs of the form: (<key value>,<block address>).
 - For every block **b** of the file, there is a record (**v**,**b**) in the index; **v** is a key value that is at least as low as any key value on **b**, but higher than any key value on any block preceding **b**. If **b** is the first block, **v**= $-\infty$ is used.

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- Accessing Sorted Files

- The key for the index file is the first field of (v,b) and it is kept sorted according to this field.
- Index files differ from general files in that index file records are not pinned by pointers from elsewhere.
- Index files must be organized so that queries of the following sort can be answered efficiently:

Given a key value $v1$ for the file being indexed, find that record $(v2,b)$ in the index such that $v2 \leq v1$ and either $(v2,b)$ is the last record in the index, or the next record $(v3,b')$ in the index has $v1 < v3$. Value $v2$ is said to **cover** $v1$.

- The result of the query is the block b that contains the record with key value $v1$, since the index is sorted at all times.

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- **Note:** certain file organizations cannot provide such functionality. E.g., hashed files cannot be used, since the entire file must be searched in order to find the required values.
- **Searching Index Files:**
 1. **Linear Search:** scan the index from the beginning, examining each record until the one that covers the one searched for is found
 - Inefficient for large indices: half the index blocks will have to be examined on average in a successful lookup
 - Linear search of the index is preferable over linear search of the file: if R records are on a block, the main file has R times as many records as the index file.
 - Index records are usually shorter than file records.

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- Searching Index Files:
 2. **Binary Search:** assume B_1, B_2, \dots, B_n are the blocks of the index file and v_1, v_2, \dots, v_n are the keys of the first records in the respective blocks. To locate record with key v :
 - Retrieve index block $B_{\lceil n/2 \rceil}$ and let w be the value of its key: if $v < w$, repeat the search for the blocks $B_1, B_2, \dots, B_{\lceil n/2 \rceil - 1}$; if $v \geq w$, repeat the search for the blocks $B_{\lceil n/2 \rceil} \dots B_n$; when only one block remains, use linear search to find the record.
 - Roughly $\log_2 n$ block accesses are needed.

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- **Example:** A file contains 1,000,000 records of 200 bytes each. Blocks are $2^{12}=4096$ bytes long. The length of the key fields is 20 bytes.
 - $R=20$, hence the main file uses 50,000 blocks. The same number of records is needed for the index file.
 - An index record used 24 bytes: 20 bytes for the key, 4 for a pointer to a block. 170 index records can fit in one block if no additional bits are used. Then $50,000/170=294$ blocks are needed for the index file.
 - Linear search would require about 147 block accesses on average for a successful lookup.
 - Binary search requires about $\log_2 294 = 9$ block accesses.

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- Example(cont'd):
 - Hashed organization would only require 3 accesses: (1 to read the bucket directory, and 2 to read/write the block)
 - However, binary search is preferable to hashed organization for answering range queries, i.e., queries of the form “retrieve all records with keys in the range (a,b)”. A hashed organization would require examining practically all buckets.

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- Operations on Sorted Files with Unpinned Records
 - The operations insertion, deletion and modification require insertions, deletions and modifications to the index file.
 - Assumptions:
 - The original sorted file is kept on the sequence of blocks B_1, B_2, \dots, B_k .
 - The records in each block are kept in sorted order.
 - The records of block B_i precede those of block B_{i+1}
 - Used/unused information is kept in a known area in the beginning of the file.

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- Initialization:

1. The initial file of records must be sorted and distributed among blocks.
2. Create the index file by examining the first record in each block of the main file. Form the records of the index file by combining the key values of the file records with the block addresses.
3. Distribute the index file records among blocks.
4. Create a directory containing the addresses of the index blocks.

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■ Operations:

1. **Lookup:** find the record with key value $v1$

examine the index to find the record with a value $v2$ that covers $v1$. The index record containing $v2$ also contains a pointer to a block of the main file. If the record with key value $v1$ exists, it will be on that block.

2. **Modification:** modify the record with key value $v1$

use the lookup procedure to find the record. If the modification changes the key, treat the operation as a deletion followed by an insertion. If not, make the modification and rewrite the record.

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■ Operations:

1. **Insertion:** insert a record with key value v_1

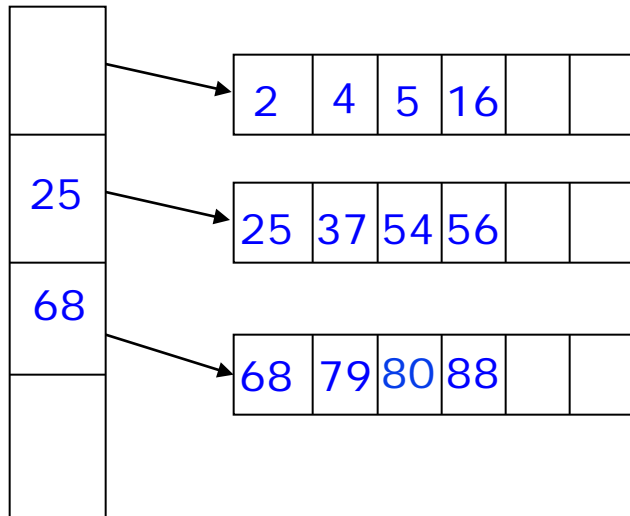
use the lookup procedure to find the block B_i of the main file, on which a record with key value v_1 would be found. Place the new record in B_i keeping the records sorted. If B_i does not have space for the new record, a new block must be created. One option is to use the next block (if it has space). Then the new record must become the block's first record.

2. **Deletion:** delete the record with key value v_1

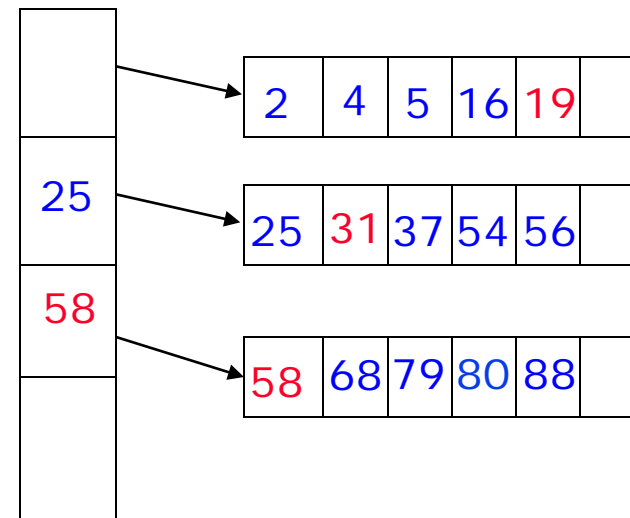
use the lookup procedure to find the record. Shift the records that are located to the right of the deleted record one position to the left. If the block becomes empty after the deletion, the record for the block must be deleted from the index.

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- **Example:** sorted list of numbers: 2,4,5,16,25,37,54,68,79,80,88

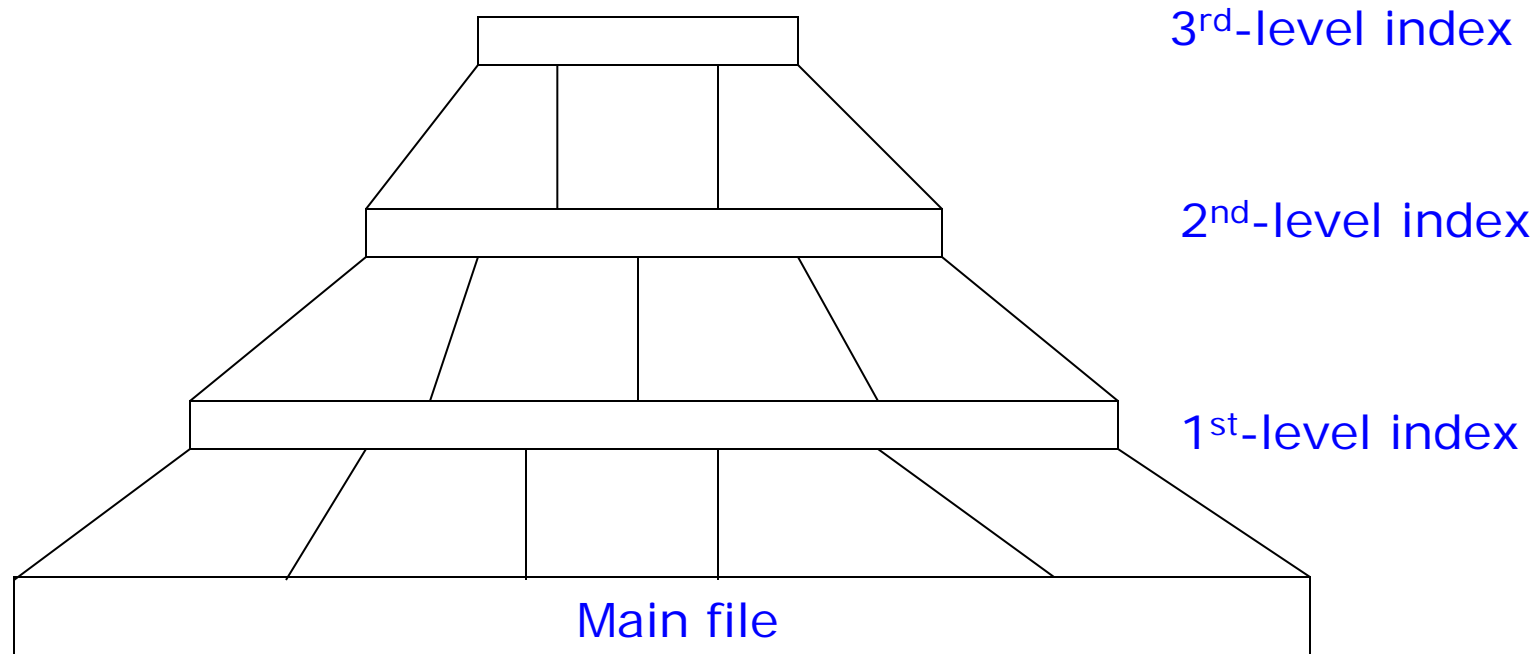


After insertion of numbers
19,58,31:



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- B-Trees
 - Index files can become quite large for large main files
 - Indices on index files are possible



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- The 1st-level index consists of pairs (v,b), where b is a pointer to a block B of the main file and v is the key of the first record in the block. The index is also sorted by key values.
- The 2nd-level index consists of pairs (v,b) where b points to a block of the 1st-level index whose first key is v, and so on.
- Multilevel indexing can be considerably more efficient than a single level of indexing.
- A multilevel index structure can have many forms. These are collectively referred to as **balanced trees (B-trees)**.
- The main file is part of the B-tree and it is assumed that the file contains unpinned records.

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- Although the insertion / deletion procedures of single-level index structures can be used, they do not result in the optimum organization of the B-tree: nodes can have between one and the maximum possible number of records.
- B-trees use a particular insertion / deletion strategy that ensures that **no node, except possibly the root, is less than half full**.
- A B-tree is characterized by two parameters **d,e**:
 - **d** and **e** are integers such that, the number of index records a block can hold is $2*d-1$ and the number of records of the main file a block can hold is $2*e-1$.
- Convention: the key value in the first record is omitted. It is assumed that all values that are less than the key value of the second record are covered by the missing value.

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- Operations on B-trees:

1. **Lookup**: to search for a record with key value **v**, find a path from the root of the B-tree to some leaf node where the desired record will be found if it exists
- **Paths in B-trees**: every search path begins at the root. When a block **B** is reached during the search, if **B** is a leaf node, then **B** has to be examined for a record with key value **v**. If **B** is not a leaf, then it is an index record. The key value that covers **v** has to be found and the associated pointer must be followed, leading to another index block or main file block.
 - **Property**: the key value in record **i** of block **B** is the lowest key value of any leaf descending from the **i-th** child of **B**.

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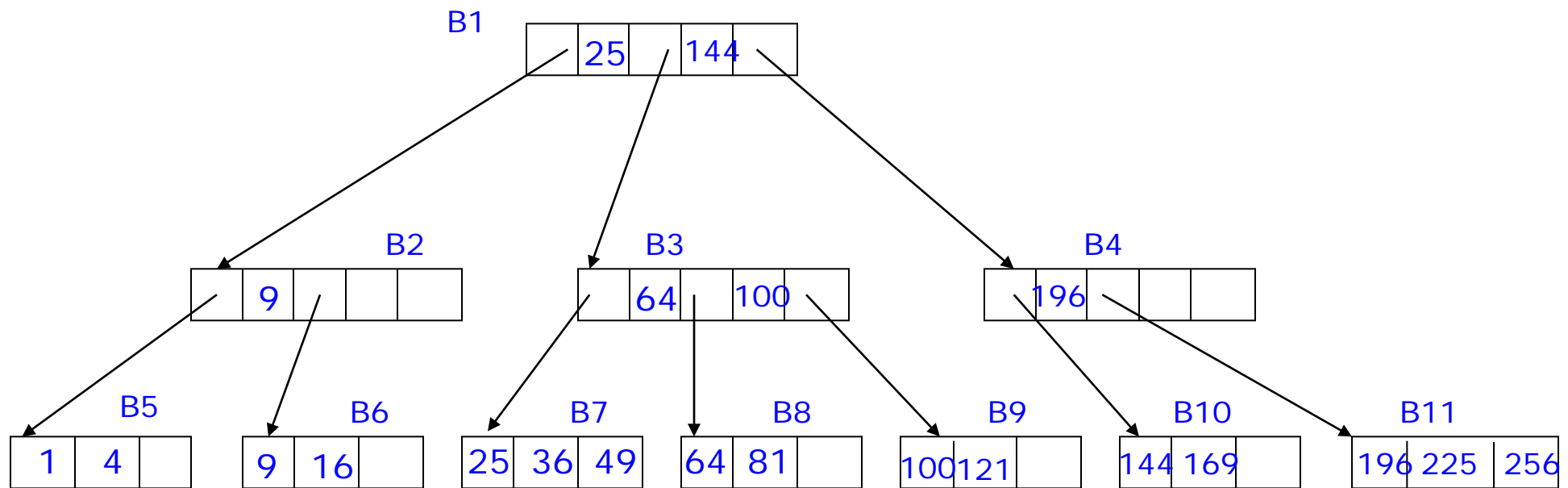
- This property and the fact that the main file is sorted, guarantee that, if a record exists in a leaf node, then it can only be found by following the pointers as described above.

2. Modification:

- If a key field is to be modified, then modification is performed by a deletion followed by an insertion.
- Otherwise, modification is a lookup followed by the rewriting of the record involved.

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- Example: $d=e=2$, i.e., 3 records in blocks of the index and main files.



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3. **Insertion:** to insert a record with key value v
- Apply the lookup procedure to find the block B in which this record belongs
 - If there are fewer than $2e-1$ records in B , insert the new record in sorted order
 - If there are already $2e-1$ records in B , create a new block $B1$ and divide the records of B and the inserted record in two groups of e records each. The first e go to block B and the remaining e to block $B1$.
 - A record for $B1$ needs to be inserted in the parent record of B . The insertion procedure is applied recursively (with d in place of e) for inserting a record for $B1$ to the right of the record for B .

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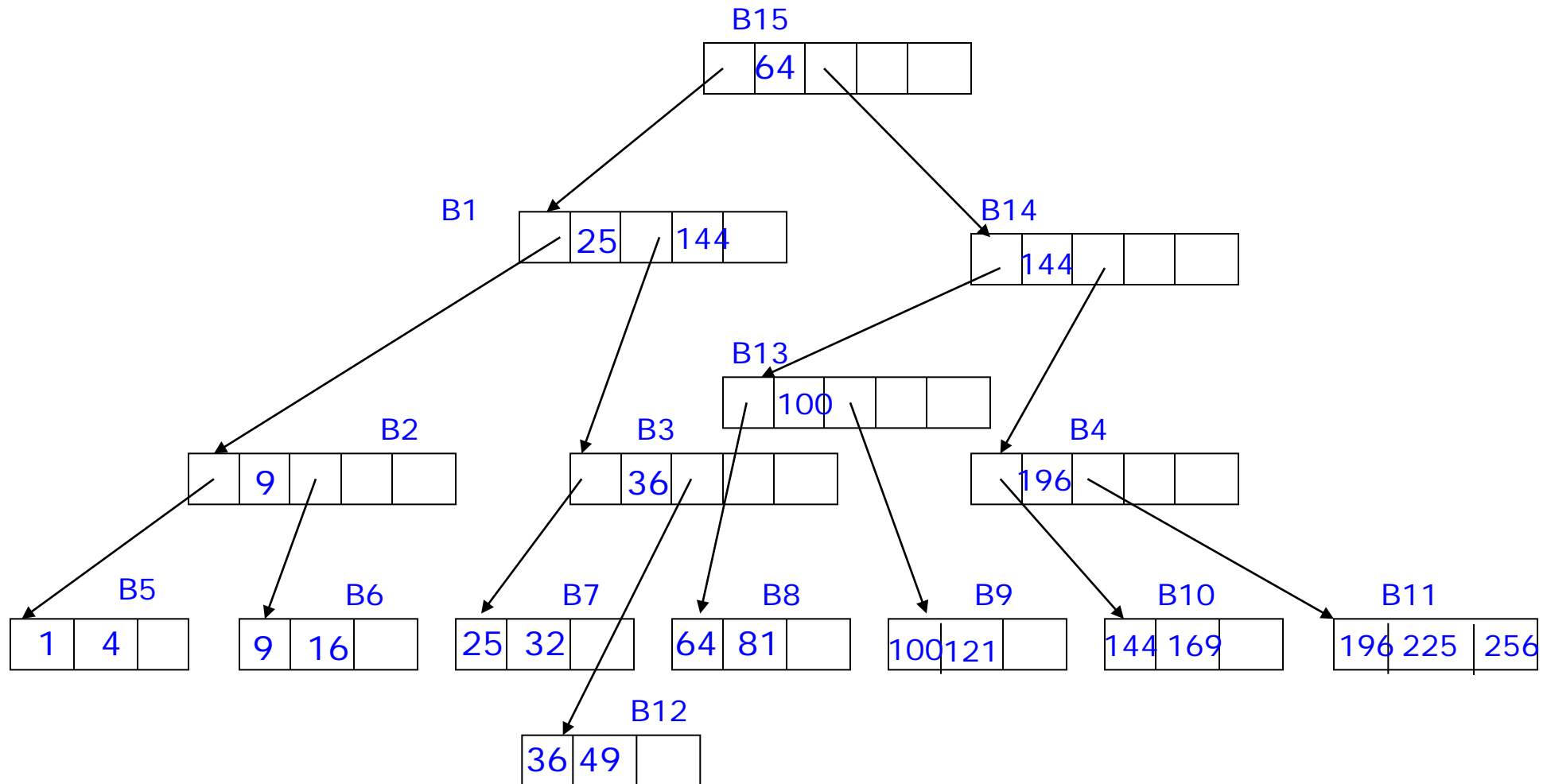
3. **Insertion:** to insert a record with key value v

- If many ancestors of B have the maximum $2d-1$ records, the effects of inserting a record may ripple up the tree. It is only ancestors of B that are affected.
- If the insertion ripples up to the root, then the root node is split and a new node with two children is created.
- **Example:** assume we want to insert the record with key value 32 in the B-tree of the previous example

Record 32 belongs to B7, but B7 is full. A new block (B12) is created and a record for B12 must be inserted in B3.

B3 is also full, so a new block (B13) is created.

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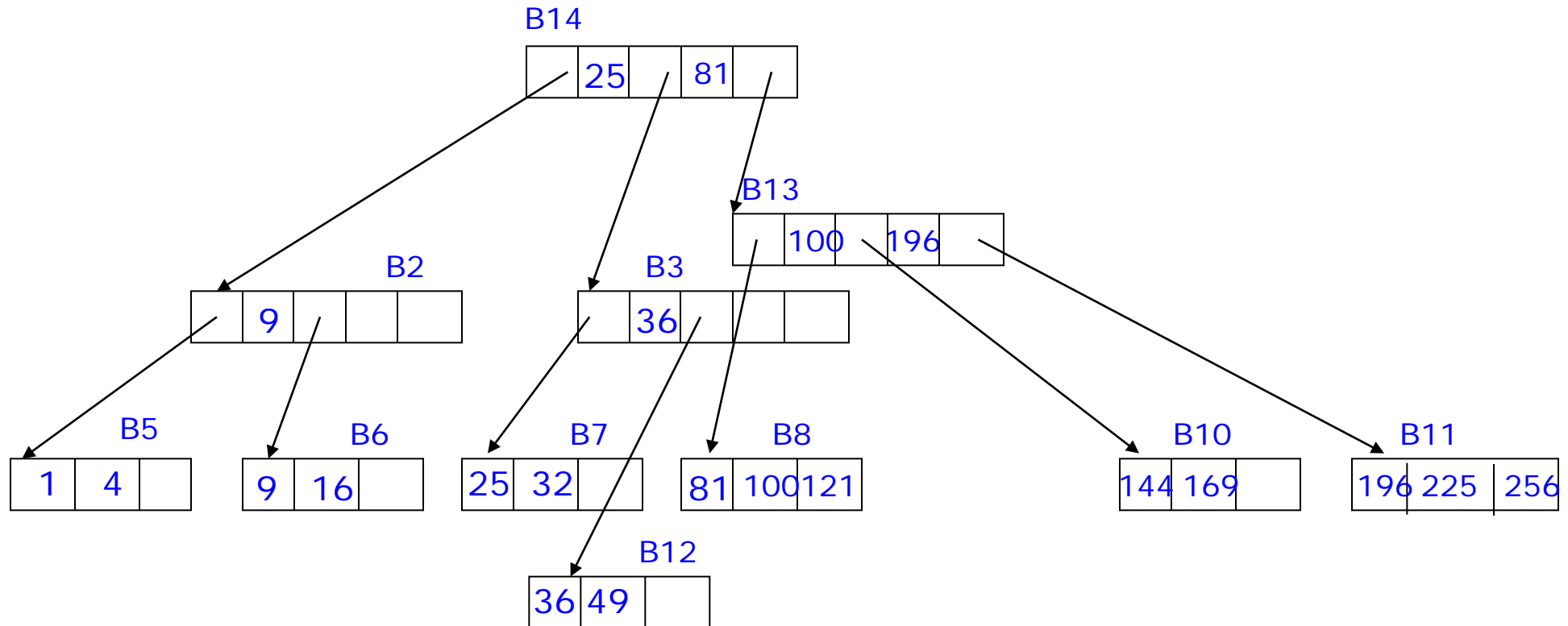
4. **Deletion:** to delete a record with key value v
 - Apply the lookup procedure to find the block B in which this record belongs
 - If after the deletion, B still has e or more records, we're done.
 - If the deleted record was the first in B, the value of the parent record must be changed to contain the value of the new first key of B.
 - If B is the first child of its parent node, the parent has no key value for B, so the parent's parent must be changed. The process continues until an ancestor A1 of B is found that is not the first child of its parent A2. Then, the new lowest value of B goes in the record of A2 that points to A1.

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4. **Deletion:** to delete a record with key value v
 - If after deletion block B has $e-1$ records, we examine the block B1 that has the same parent as B and that is immediately next to B, If B1 has more than e records, we distribute the records of B and B1 as evenly as possible, keeping them sorted.
 - The key values in the parents of B and B1 may need to be modified.
 - If B1 has only e records, then combine the records of B and B1. This requires that a record be deleted from the parent node.
- **Example:** delete the record with key value 64 in the B-tree of the previous example.

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B-tree after the deletion of record 64



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- Cost of Operations on B-trees:
 - Assume that a file of n records is organized as a B-tree with parameters d and e . Then the tree will have at most n/e leaf nodes and n/de parent nodes of leaf nodes, n/d^2e parents of parents of leaf nodes, etc.
 - **Lookup**: if there exist i nodes on a path from the root to a leaf node where a particular record is located, then i block accesses are needed.
 - For insertion, deletion and modification, $2 + \log_d(n/e)$ accesses are required on average
 - We will assume that all operations take $2 + \log_d(n/e)$ block accesses on average.

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- **Example:** A file contains 1,000,000 records of 200 bytes each. Blocks are $2^{12}=4096$ bytes long. The length of the key fields is 20 bytes. Pointers take 4 bytes.
 - $e=10$ (up to 20 records can fit in a block)
 - 171 index records can fit in a block ($171*20 + 171*4 = 4084$). Thus, $d=86$.
 - The expected number of block accessed per operation is $2 + \log_d (n/e) = 2 + \log_{86} (1000000 / 10) < 5$