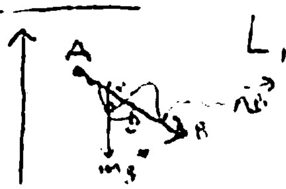
$dW = F_T\, ds = m \frac{dv}{dt}\, ds = m v\, dv$



L forza peso: $L = \int_A^B m\vec{g} \cdot d\vec{s} = \ldots$

$L = mg(z_A - z_B) = E_{pA} - E_{pB}$

L forza elastica 1D: $L = \int_A^B -kx\, dx = -k\frac{x^2}{2}\Big|_A^B$

L forza attrito: $L = \int_A^B \vec{f} \cdot d\vec{s} = \int_A^B \mu_d N \hat{u}_v \cdot d\vec{s} = -\mu_d N \ldots$

$dW = \vec{F} \cdot d\vec{s} = F_x\, dx + F_y\, dy + F_z\, dz = -dE_p$

$\oint dW = 0 \Rightarrow \exists\, f(x,y,z)$ t.c. $F_x = -\frac{\partial f}{\partial x}$, $F_y = -\frac{\partial f}{\partial y}$ …

$F = -\vec{\nabla} E_p \longrightarrow F = mg \Rightarrow \frac{dE_p}{dz} = F \Rightarrow E_p = \int mg\, dz$

$\qquad \longrightarrow F = -kx \Rightarrow \frac{dE_p}{dx} = -kx \quad E_p = \int -kx\, dx$

$\vec{L}_0 = \vec{r}_0 \times \vec{p} = \vec{r}_0 \times m\vec{v} \qquad \vec{r}_0 = \vec{OO'} + \vec{r}_{0'} \Rightarrow \vec{L}_0 = \vec{OO'} \times \vec{p} + \vec{r}_{0'} \times \vec{p} =$

$\vec{L}_0 = \vec{OO'} \times \vec{p} + \vec{L}_{0'}$

$\vec{L} = \vec{r} \times m(\vec{v}_r + \vec{v}_\theta) = \vec{r} \times m\vec{v}_\theta$

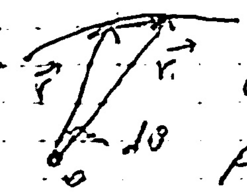
$\vec{M}_0 = \vec{r}_0 \times \vec{F} \qquad \vec{M}_{0'} = \vec{M}_0 + \vec{O'O} \times \vec{F} \qquad \vec{M} = \sum \vec{r}_i \times \vec{F}_i = \vec{r} \times \sum \vec{F}_i = \vec{r} \times \vec{R}$

$$\frac{d\vec{L}}{dt} = \frac{d\vec{r}}{dt} \times \vec{p} + \vec{r} \times \frac{d\vec{p}}{dt} = \cancel{\vec{v} \times m\vec{v}} + \vec{r} \times \vec{F} = \vec{M}$$

$$\vec{v} = \frac{d\vec{r}}{dt} = \frac{dr}{dt}\hat{u}_r + r\frac{d\hat{u}_r}{dt} = v\hat{u}_r + r\frac{d\theta}{dt}\hat{u}_\theta \qquad \vec{L} = \vec{r} \times m r\frac{d\theta}{dt}\hat{u}_\theta$$

Se O sta nel piano del moto, $\vec{r} \perp \hat{u}_\theta \Rightarrow L = mr^2\frac{d\theta}{dt}$

F centrale $\Rightarrow \vec{L} =$ cost. $\Rightarrow \frac{1}{2}r^2\frac{d\theta}{dt}$ cost. $\qquad \frac{dA}{dt} = \frac{1}{2}r^2\frac{d\theta}{dt}$



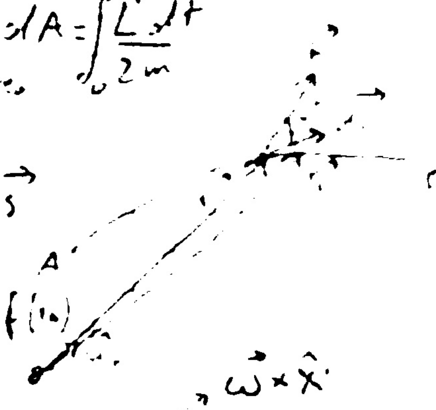
$dA = \frac{1}{2} r\, r\, d\theta \qquad \frac{dA}{dt} =$ cost. $\qquad \frac{dA}{dt} = \frac{L}{2m} \qquad \int_{A_0} dA = \int_0^T \frac{L}{2m}\, dt$

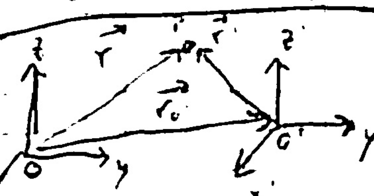
$A = \frac{L}{2m}T \qquad$ periodo: $T = \frac{2mA}{L}$

Lavoro forze centrali: $L = \int_A^B \vec{F} \cdot d\vec{s} = \int_A^B F(r)\, \hat{u}_r \cdot d\vec{s}$

$ds\cos\theta = dr \Rightarrow \hat{u}_r \cdot d\vec{s} = dr \Rightarrow L = \int_A^B F(r)\, dr = f(r_B) - f(r_A)$

$d\vec{r} = r\, d\theta\, \hat{u}_\theta \qquad |d\vec{r}| = r\, d\theta = dr$





$\vec{r} = \vec{r}_0 + \vec{r}'$

$\vec{v} = \frac{d\vec{r}}{dt} = \frac{d\vec{r}_{0'}}{dt} + \frac{dx'}{dt}\hat{x}' + \frac{dy'}{dt}\hat{y}' + \frac{dz'}{dt}\hat{z}' + x'\frac{d\hat{x}}{dt} + y'\frac{d\hat{y}}{dt} + z'\frac{d\hat{z}}{dt}$ $\qquad \vec{\omega} \times \hat{x}$

$= \vec{v}_{0'} + \vec{v}' + \vec{\omega} \times (x'\hat{x}' + y'\hat{y}' + z'\hat{z}') = \vec{v}_{0'} + \vec{v}' + \vec{\omega} \times \vec{r}'$