## **Lecture 6 Report Requirement**

### The report only needs to answer the questions below.

Send your report in PDF format to 1430090453@qq.com, named as "report6\_[first name][last name].pdf" (e.g., report6\_ZhangChen.pdf). Please also include your name (both English and Chinese) in the report. The report is due on 10 am, China Standard Time, April 9, 2020.

# **Report Questions:**

## "FlatCam: Thin, Lensless Cameras Using Coded Aperture and Computation"

- 1. What is the relationship between pinhole camera and FlatCam? What is the improvement from pinhole camera to coded aperture camera and finally FlatCam?
- 2. What factors should be concerned about when choosing a mask pattern?
- 3. What is the disadvantage of the linear model with single transfer matrix Φ? How to improve it?
- 4. Why do we use separable scene *X* when calibrating?
- 5. Express image reconstruction problem as a least-squares problem and a regularized least-squares problem. What is the solution to such problems? Express image reconstruction problem as a least-squares problem with total variation regularizing. Is this problem convex?

#### "DiffuserCam: Lensless Single-exposure 3D Imaging"

- 6. What is the improvement of DiffuserCam compared with existing lensless camera, light field camera and scattering imaging camera?
- 7. What is the benefit of cropped convolution model?
- 8. What is the complexity of algorithm to the inverse problem? Which step is the computation cost mainly from?
- 9. Compared with traditional cameras, what is the unique factor that determines the performance of computational camera?
- 10. Simply explain why the distance between sources will affect the performance of DiffuserCam?