

Hiding Computations in Projection

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Notation: A and B are the extremities of the segment; C is the centre of the sphere; R is the radius of the sphere; K is the location of the camera.

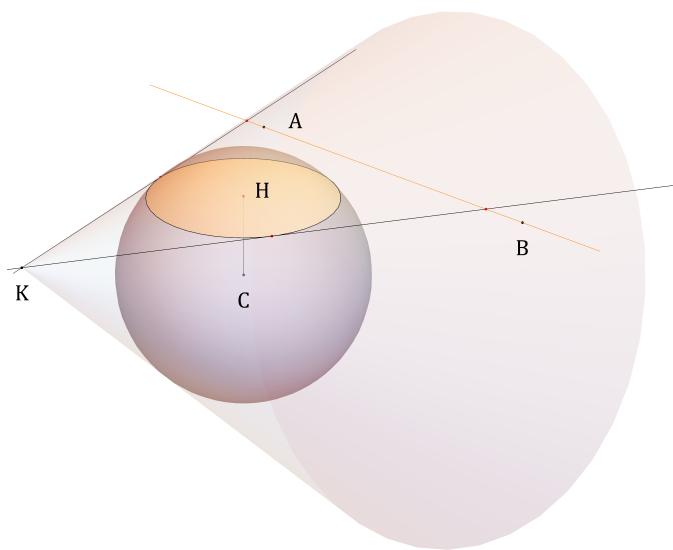


Figure 1. Presentation of the problem.

Camera inside the sphere

We start our analysis by eliminating a case that would cause anomalies in the computations below. If

$$\vec{KC} \cdot \vec{KC} < R^2$$

then the camera is inside the sphere and the segment is hidden irrespective of its position.

Next, consider the plane that contains K and is orthogonal to \vec{KC} ; it separates the entire space into two half-spaces. If the segment \overline{AB} is entirely within the half-space that does not contain C then the segment is not hidden. This is the case if the following inequalities are both true

$$\begin{aligned}\vec{KA} \cdot \vec{KC} &< 0 \\ \vec{KB} \cdot \vec{KC} &< 0.\end{aligned}$$

For simplicity we will do the rest of our analysis in the plane KAB. We will use (\vec{KA}, \vec{KB}) as a basis of that plane. Let H be the orthogonal projection of C on KAB. Define α, β to be its coordinates in KAB

$$\vec{KH} = \alpha \vec{KA} + \beta \vec{KB}.$$

Note that $\vec{KH} = \vec{KC} + \vec{CH}$. By its definition, \vec{CH} is orthogonal to both \vec{KA} and \vec{KB}

$$\vec{KA} \cdot \vec{CH} = 0$$

$$\vec{KB} \cdot \vec{CH} = 0,$$

or

$$\vec{KA} \cdot \vec{KH} = \vec{KA} \cdot \vec{KC}$$

$$\vec{KB} \cdot \vec{KH} = \vec{KB} \cdot \vec{KC}.$$

Expanding \vec{KH} gives a linear system of two equations with two unknowns

$$\alpha \vec{KA} \cdot \vec{KA} + \beta \vec{KA} \cdot \vec{KB} = \vec{KA} \cdot \vec{KC}$$

$$\alpha \vec{KA} \cdot \vec{KB} + \alpha \vec{KB} \cdot \vec{KB} = \vec{KB} \cdot \vec{KC}.$$

The determinant of this system is

$$D = (\vec{KA} \cdot \vec{KA})(\vec{KB} \cdot \vec{KB}) - (\vec{KA} \cdot \vec{KB})^2,$$

which is non-zero if and only if $A \neq B$. The solutions are thus

$$\alpha = \frac{(\vec{KB} \cdot \vec{KB})(\vec{KA} \cdot \vec{KC}) - (\vec{KA} \cdot \vec{KB})(\vec{KB} \cdot \vec{KC})}{D}$$

$$\beta = \frac{(\vec{KA} \cdot \vec{KA})(\vec{KB} \cdot \vec{KC}) - (\vec{KA} \cdot \vec{KB})(\vec{KA} \cdot \vec{KC})}{D}.$$

Now that \vec{KH} is determined we can compute $\vec{CH} = \vec{KH} - \vec{KC}$. If $\vec{CH} \cdot \vec{CH} \geq R^2$, the sphere is either tangent to the plane KAB or doesn't intersect it. Thus, there is no hiding.

Let's look at a figure in the plane KAB when the sphere intersects that plane. Let r be the radius of the intersection circle; it is such that $r^2 = R^2 - \vec{CH} \cdot \vec{CH}$.

If the circle doesn't intersect the wedge KAB then the segment AB is entirely visible. To find if this is the case, first observe that, if θ is the angle between \vec{KA} and \vec{KB} , we have

$$\vec{KA} \cdot \vec{KB} = |\vec{KA}| |\vec{KB}| \cos \theta$$

Assume that H is outside the wedge KAB and in a position where the circle is tangent to KB at point N . Let M be the point where H projects on \vec{KB} parallel to \vec{KA} . We have

$$\vec{HM} = \alpha \vec{KA}$$

and

$$\vec{HM} \cdot \vec{HM} = \frac{r^2}{\sin^2 \theta} = \frac{r^2}{1 - \cos^2 \theta}$$

Eliminating \vec{HM} we obtain the following conditions on α for H to be in the position indicated above

$$\alpha < 0$$

$$\alpha^2 > r^2 \frac{\vec{KB} \cdot \vec{KB}}{(\vec{KA} \cdot \vec{KA})(\vec{KB} \cdot \vec{KB}) - (\vec{KA} \cdot \vec{KB})^2}.$$

We have similar conditions on β for the circle to be outside the wedge KAB and tangent to \vec{KA} .

The next step is to find out the extension of the wedge formed by the circle when seen from K . Let P be a point where a line going through K is tangent to the circle, and let Q be the point where KP intersects AB ; it may be between K and P or behind P .

We need to find P . It is defined by two equations

$$\vec{PH} \cdot \vec{PH} = r^2$$

$$\vec{PH} \cdot \vec{KP} = 0.$$

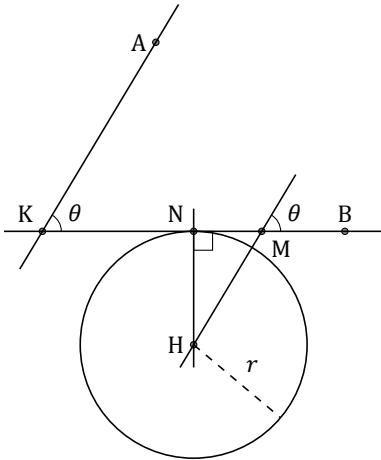


Figure 2. Circle outside of the wedge KAB .

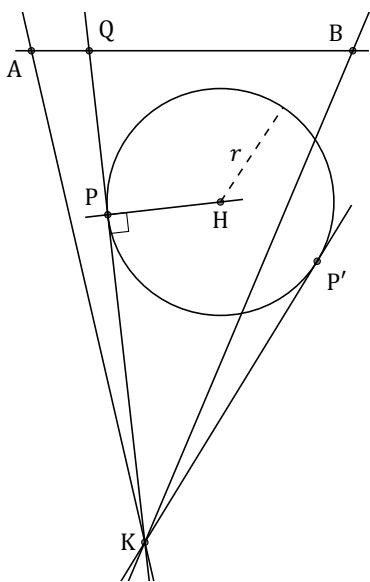


Figure 3. Construction of P .

The second equation may be rewritten

$$\overrightarrow{PH} \cdot (\overrightarrow{KH} + \overrightarrow{HP}) = 0$$

from which we obtain

$$\overrightarrow{PH} \cdot \overrightarrow{KH} = r^2.$$

Let γ and δ be the coordinates of \overrightarrow{PH} in KAB

$$\overrightarrow{PH} = \gamma \overrightarrow{KA} + \delta \overrightarrow{KB}.$$

The second equation is linear

$$\gamma \overrightarrow{KA} \cdot \overrightarrow{KH} + \delta \overrightarrow{KB} \cdot \overrightarrow{KH} = r^2,$$

thus

$$\gamma = \frac{r^2 - \delta \overrightarrow{KB} \cdot \overrightarrow{KH}}{\overrightarrow{KA} \cdot \overrightarrow{KH}}.$$

Note that $\overrightarrow{KA} \cdot \overrightarrow{KH}$ and $\overrightarrow{KB} \cdot \overrightarrow{KH}$ cannot both be 0 unless K is on AB. The first equation is quadratic

$$(\gamma \overrightarrow{KA} + \delta \overrightarrow{KB})^2 = r^2.$$

Plugging the value of γ above we get

$$\begin{aligned} & \delta^2((\overrightarrow{KB} \cdot \overrightarrow{KB})(\overrightarrow{KA} \cdot \overrightarrow{KH})^2 + 2(\overrightarrow{KA} \cdot \overrightarrow{KB})(\overrightarrow{KA} \cdot \overrightarrow{KH})(\overrightarrow{KB} \cdot \overrightarrow{KH}) + \overrightarrow{KA} \cdot \overrightarrow{KA}(\overrightarrow{KB} \cdot \overrightarrow{KH})^2) + \\ & 2\delta r^2((\overrightarrow{KA} \cdot \overrightarrow{KB})(\overrightarrow{KA} \cdot \overrightarrow{KH}) - (\overrightarrow{KA} \cdot \overrightarrow{KA})(\overrightarrow{KB} \cdot \overrightarrow{KH})) + \\ & r^2(r^2(\overrightarrow{KA} \cdot \overrightarrow{KA}) - (\overrightarrow{KA} \cdot \overrightarrow{KH})^2) = 0. \end{aligned}$$

This equation always has two solutions because the sphere intersects KAB. Having determined \overrightarrow{PH} , we can find Q. Q is on the line AB, thus

$$\overrightarrow{AQ} = \lambda \overrightarrow{AB},$$

which can be written

$$\overrightarrow{KQ} - \overrightarrow{KA} = \lambda \overrightarrow{AB}.$$

Noting that \overrightarrow{KQ} is orthogonal to \overrightarrow{PH} we have

$$-\overrightarrow{KA} \cdot \overrightarrow{PH} = \lambda \overrightarrow{AB} \cdot \overrightarrow{PH}, \text{ or, } \lambda = -\frac{\overrightarrow{KA} \cdot \overrightarrow{PH}}{\overrightarrow{AB} \cdot \overrightarrow{PH}}.$$

Having determined the values of λ we need to find out where Q is located with respect to the segment \overrightarrow{AB} . Let S be the intersection of AB with the line orthogonal to KH at K. We locate S on AB as follows

$$\overrightarrow{KS} = \overrightarrow{KA} + \sigma \overrightarrow{AB}.$$

Noting that $\overrightarrow{KS} \cdot \overrightarrow{KH} = 0$ we obtain

$$\sigma = -\frac{\overrightarrow{KA} \cdot \overrightarrow{KH}}{\overrightarrow{AB} \cdot \overrightarrow{KH}}$$

Now let T be the intersection of AB with the line orthogonal to KH at P. We locate T on AB similarly

$$\overrightarrow{KT} = \overrightarrow{KA} + \tau \overrightarrow{AB}.$$

We have

$$\overrightarrow{PT} = \overrightarrow{KA} + \tau \overrightarrow{AB} - \overrightarrow{KH} + \overrightarrow{PH}$$

Noting that $\overrightarrow{PT} \cdot \overrightarrow{KH} = 0$ we obtain

$$\tau = \frac{\overrightarrow{KH} \cdot \overrightarrow{KH} - \overrightarrow{PH} \cdot \overrightarrow{KH} - \overrightarrow{KA} \cdot \overrightarrow{KH}}{\overrightarrow{AB} \cdot \overrightarrow{KH}}$$

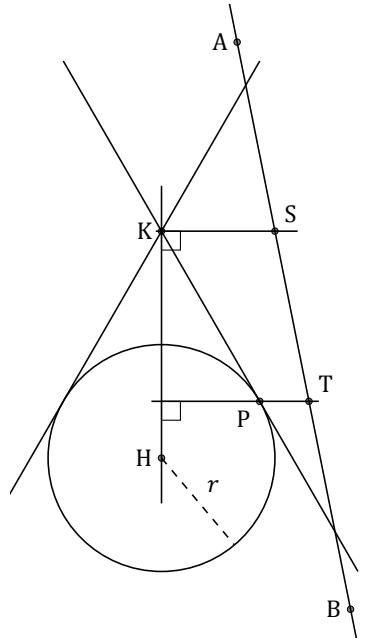


Figure 4. Definition of S and T.

We can now determine if λ is an “interesting” intersection, i.e., one that intersects the cone behind the sphere when seen from the camera. First, assume that A and B are in the same order as S and T on AB. Then we have $\sigma \leq \tau$ and the intersection is farther than T (as seen from the camera) if and only if $\tau < \lambda$. Conversely, if A and B are in the reverse order as S and T on AB we have $\tau \leq \sigma$ and the intersection is farther than T if and only if $\lambda < \tau$

There is another special case to handle: if the line AB is in “hyperbolic” position, i.e. intersects both halves of the cone, then one value of λ is smaller than σ and one value is greater than σ . Exactly one of the values of λ will be retained by the preceding analysis, and we need to add an extra λ equal to an infinity with the sign of $\tau - \sigma$ to account for the fact that all the points farther than T are hidden by the cone.

To complete the analysis we need to compute the intersection Q of the sphere (not the cone) with the line AB. Q is on the sphere, thus

$$\overrightarrow{CQ} \cdot \overrightarrow{CQ} = R^2.$$

It is also on the line AB thus

$$\overrightarrow{KQ} = \overrightarrow{KA} + \mu \overrightarrow{AB}.$$

We have

$$\overrightarrow{CQ} = \overrightarrow{KQ} - \overrightarrow{KC} = \overrightarrow{KA} + \mu \overrightarrow{AB} - \overrightarrow{KC} = \overrightarrow{CA} + \mu \overrightarrow{AB},$$

and therefore

$$R^2 = (\overrightarrow{CA} + \mu \overrightarrow{AB})^2,$$

meaning that μ is a solution of

$$\mu \overrightarrow{AB} \cdot \overrightarrow{AB} + 2\mu \overrightarrow{CA} \cdot \overrightarrow{AB} + \overrightarrow{CA} \cdot \overrightarrow{CA} - R^2 = 0.$$

Depending on the location of the segment with respect to the sphere, there can be 0, 1, or 2 intersections.

If we take the union of the values of λ and μ and order them, it is straightforward to find the visible segments. Remember that $0 < \lambda, \mu < 1$ for points that are in the segment AB.

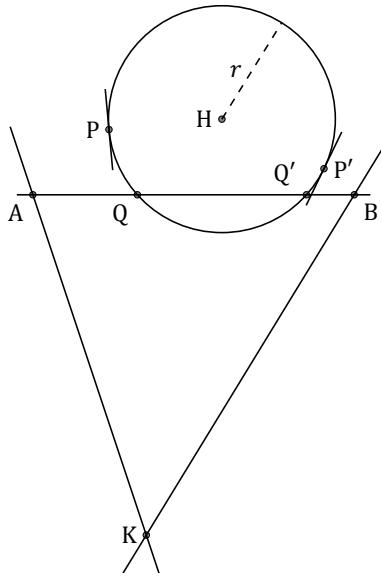


Figure 5. Intersection with the sphere.