Prabin Kumar Rath

PERSONAL DATA

DATE OF BIRTH: 20 September 1998

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CAREER OBJECTIVE

Software engineer with expertise in product development looking to join an organization where strong project management and analytic skills will be useful in the delivery of products which meet user needs.

EDUCATION

CURRENT B.Tech COMPUTER SCIENCE AND ENGINEERING,

National Institute Of Technology, Rourkela

Advisor: Dr. Sambit BAKSHI

CGPA: 8.72/10

2016 Intermediate in SCIENCE,

Mother's Public School, Bhubaneswar

Percentage: 94.2

2014 Matriculation,

St.Xavier's High School

PERCENTAGE: 95 (CGPA-10)

COLLABORATIVE PROJECTS

AUV (AUTONOMOUS UNDERWATER VEHICLE) | DECEMBER 2016 - PRESENT

Worked on the software development for the AUV (Team Tiburon)

Contributed in development of :-

Real Time Dynamic Thrust Vectoring. On board IMU data acquisition for self positioning. UI for remote monitoring. Computer Vision algorithms implementation for under water

image processing.

AUTONOMOUS CHESS PLAYING BOT | OCTOBER 2017 - PRESENT

Developed the control system for the bot.

Contributed in development of :-

Computer Vision algorithms for user move detection from an overhead camera. UI for user-system interaction. Usual game feature implementations like Save,Undo,Restart along with a robust software to handle system crash. Arduino codes for Autonomous

piece movement on the physical board.

PERSONAL PROJECTS

2D DOT MATRIX PRINTER DIY PROIECT

Developed a 2D printer that can print letters and emojis on paper.

8*8*8 LED CUBE DIY PROJECT

Developed a LED cube for various 3D pattern visualization.

ROOM AUTOMATION MODULE DIY PROJECT

A Room Automation Module facilitating Web, Bluetooth, and IR control to user for con-

trolling Home electrical appliances remotely.

UNDER-WATER ROV

Developed an under-water bot capable of moving freely and picking up objects inside

water.

LINE FOLLOWER BOT WITH IR CONTROL DIY PROJECT

Developed an autonomous bot capable of following black/white lines (curved, straight, looped etc.) on white/black surface. IR control bot can be controlled from IR remotes.

SEMI AUTONOMOUS BOT DIY PROJECT

A Bluetooth controlled wireless bot that could transfer blocks of variable weights by

sensing them with the help of a FSR(for weight detection).

DIY PROJECT ADAPTIVE ROUGH TERRAN BOT

Developed a manual bot capable of changing inter-wheel distance so as to cover roads

of variable width and capable of gripping and lifting objects.

WORK EXPERIENCE

PHOENIX ROBOTIX DECEMBER 2017 - JANUARY 2018

Worked for the development of a pollution monitoring device to be deployed in cities

for real time pollution data analysis.

TECHNICAL SKILLS

General Programming: C++, Core Java, C, Python

Oracle XE, MySQL Databases:

Frameworks: ROS(Robot Operating System), Qt, Open CV, AWT-Swing Other Software: Matlab, Arduino, MS Office, MS Powerpoint, MS Excel, Latex

SOFT SKILLS

LANGUAGES English - Professional Fluency

Hindi - Basic Fluency Odia - Mother Tongue

Teamwork SOFT SKILLS

Leadership Creative thinking Critical Analysis

EXTRA CURRICULAR ACTIVITIES

CYBORG ROBOTICS AND AUTOMATION SOCIETY

Senior Member , 2016 - Present IGV(Intelligent Ground Vehicle) - Project Leader

OPENCODE Vice President

Open Source Community of NIT Rourkela

INNOVISION 2017 Event Organizer

Tread-O-Quest Line Following Event

CREATE CLASSES Instructor

Annual Robotics learning classes by Cyborg

MICROSOFT CAMPUS CLUB

Volunteered in organizing Treasherlocked online cryptic hunt event

SCHOLARSHIPS AND CERTIFICATES

January 2017 KSHITIJ 2017 Semi Autonomous Robotics event, IIT Kharagpur - 3rd

MARCH 2017 MINARE 2017 Manual Robotics event, NIT Rourkela - 3rd Aerial Robotics(Coursera.org), University of Pennsylvania Inter Collage Physics Exhibition - 1st JUNE 2018

January 2015

SCHOOL LEVEL 2010-2014 Won in several quiz and debate competitions.

INTERESTS AND ACTIVITIES

Robotics, Software Development, Teaching INTEREST:

HOBBIES: DIY(Do It Yourself) Projects, Reading blogs, Listening music, Playing Computer Games