

# Periodic task scheduling

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Static priority scheduling

Rate monotonic priority assignment

Derivation of the RM utilization bound

# Impact of GRMS

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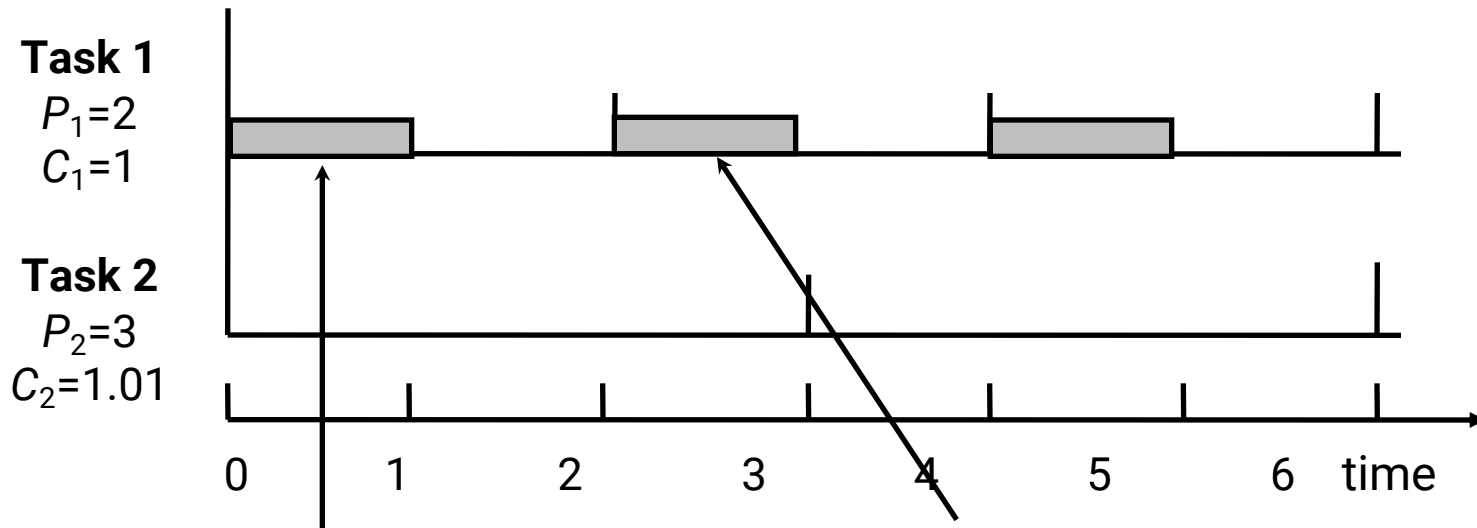
- GRMS: Generalized Rate Monotonic Scheduling
- Cited in the Selected Accomplishment section of the National Research Council's report on A Broader Agenda for Computer Science and Engineering in 1992.
- “Through the development of Rate Monotonic Scheduling [theory], we now have a system that will allow [Space Station] Freedom's computers to budget their time, to choose between a variety of tasks, and decide not only which one to do first but how much time to spend in the process.” [Deputy Administrator of NASA, Aaron Cohen]
- “The navigation payload software for the next block of Global Positioning System upgrade recently completed testing. ... This design would have been difficult or impossible prior to the development of rate monotonic theory.” [L. Doyle, and J. Elzey, “Successful Use of Rate Monotonic Theory on A Formidable Real-Time System”]

# Review

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- Terminology
  - Definitions of tasks, task invocations, release/arrival time, absolute deadline, relative deadline, period, start time, finish time, ...
  - Preemptive versus non-preemptive scheduling
  - Priority-based scheduling
  - Static versus dynamic priorities
- Utilization ( $U$ ) and schedulability
  - Main problem: Find *Bound* for scheduling policy such that
    - $U < \text{Bound} \rightarrow$  All deadlines met!
- Optimality of EDF scheduling
  - $\text{Bound}_{EDF} = 100\%$

# A quick refresher



Job 1 of Task 1

Release time = 0

Relative deadline = 2

Absolute deadline =  $0+2 = 2$

Job 2 of Task 1

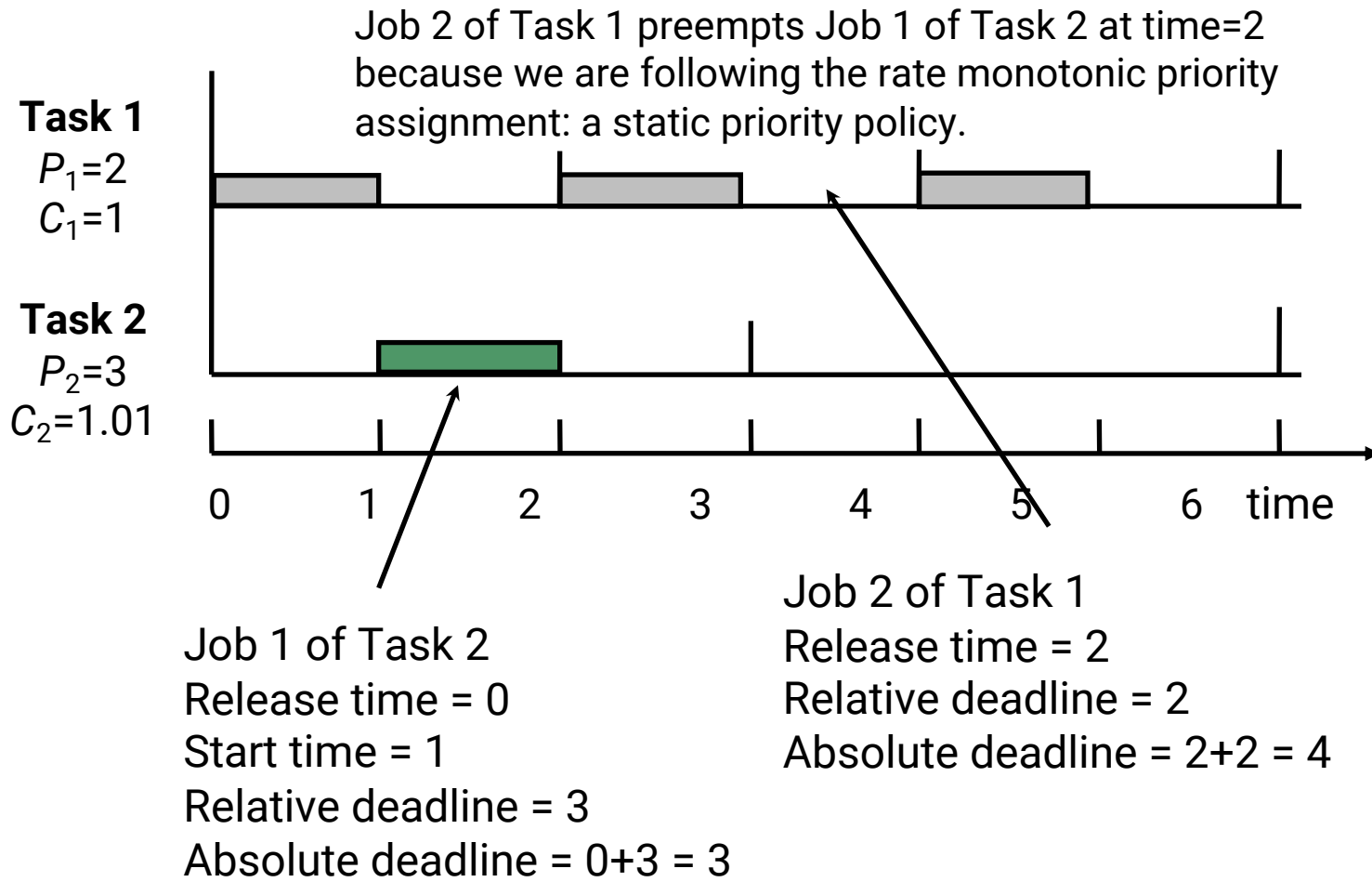
Release time = 2

Relative deadline = 2

Absolute deadline =  $2+2 = 4$

The release time of the first job of a task is also known as the **phase** of the task. The phase of Task 1 is 0.

# A quick refresher



# Schedulability analysis of periodic tasks

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- Main problem
  - Given a set of periodic tasks, can they meet their deadlines?
  - Depends on scheduling policy
- Solution approaches
  - Utilization bounds (simplest)
  - Exact analysis (NP-Hard)
  - Approximation schemes with provable bounds on approximation error
  - (Meta)Heuristics
- Two most important scheduling policies
  - Earliest deadline first (dynamic)
  - Rate monotonic (static)

# Schedulability analysis of periodic tasks

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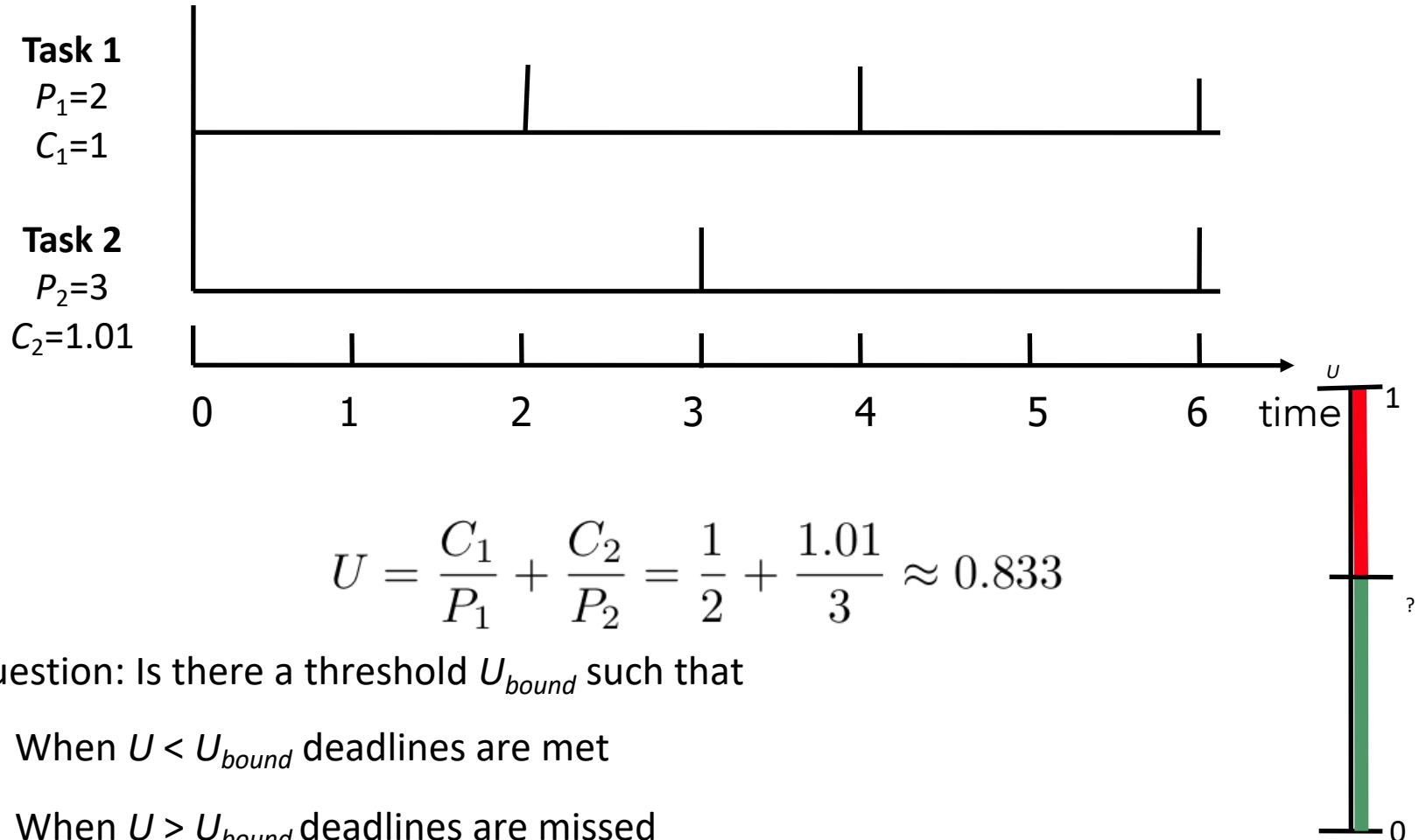
# Utilization bounds

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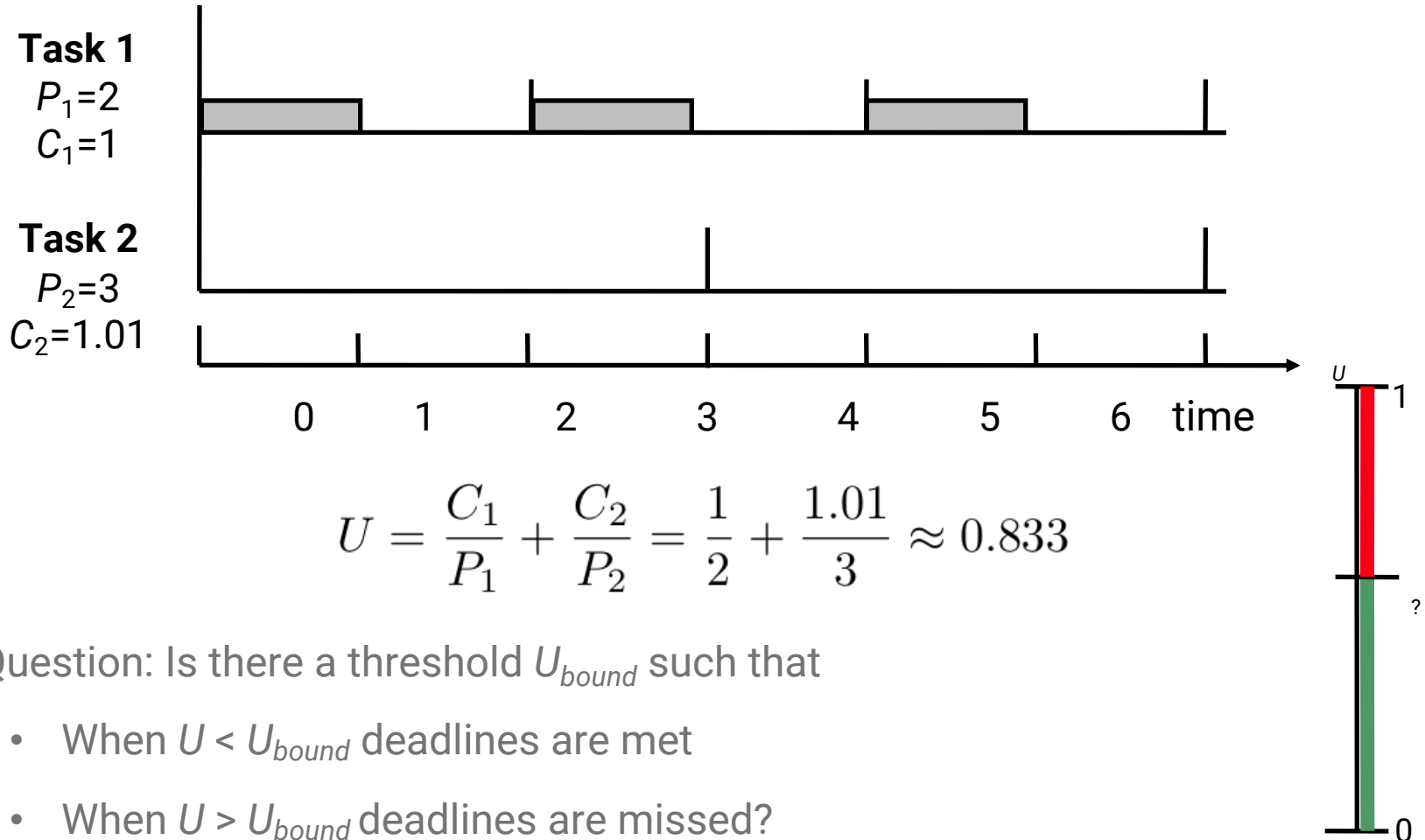
- Intuitively,
  - The lower the processor utilization,  $U$ , the easier it is to meet deadlines.
  - The higher the processor utilization,  $U$ , the more difficult it is to meet deadlines.
- **Question:** Is there a threshold  $U_{bound}$  such that
  - When  $U < U_{bound}$  deadlines are met
  - When  $U > U_{bound}$  deadlines are missed



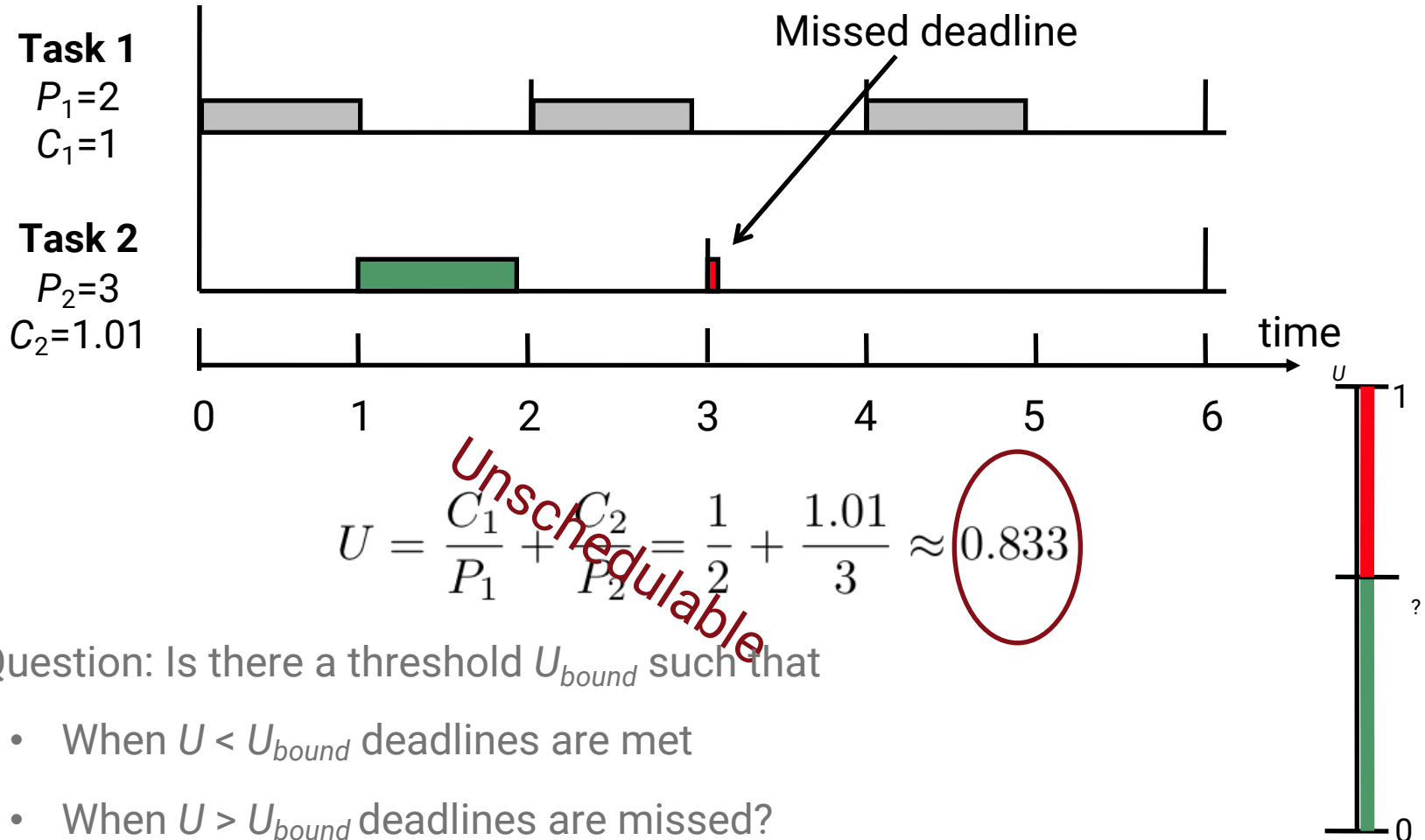
# Example (Rate monotonic scheduling)



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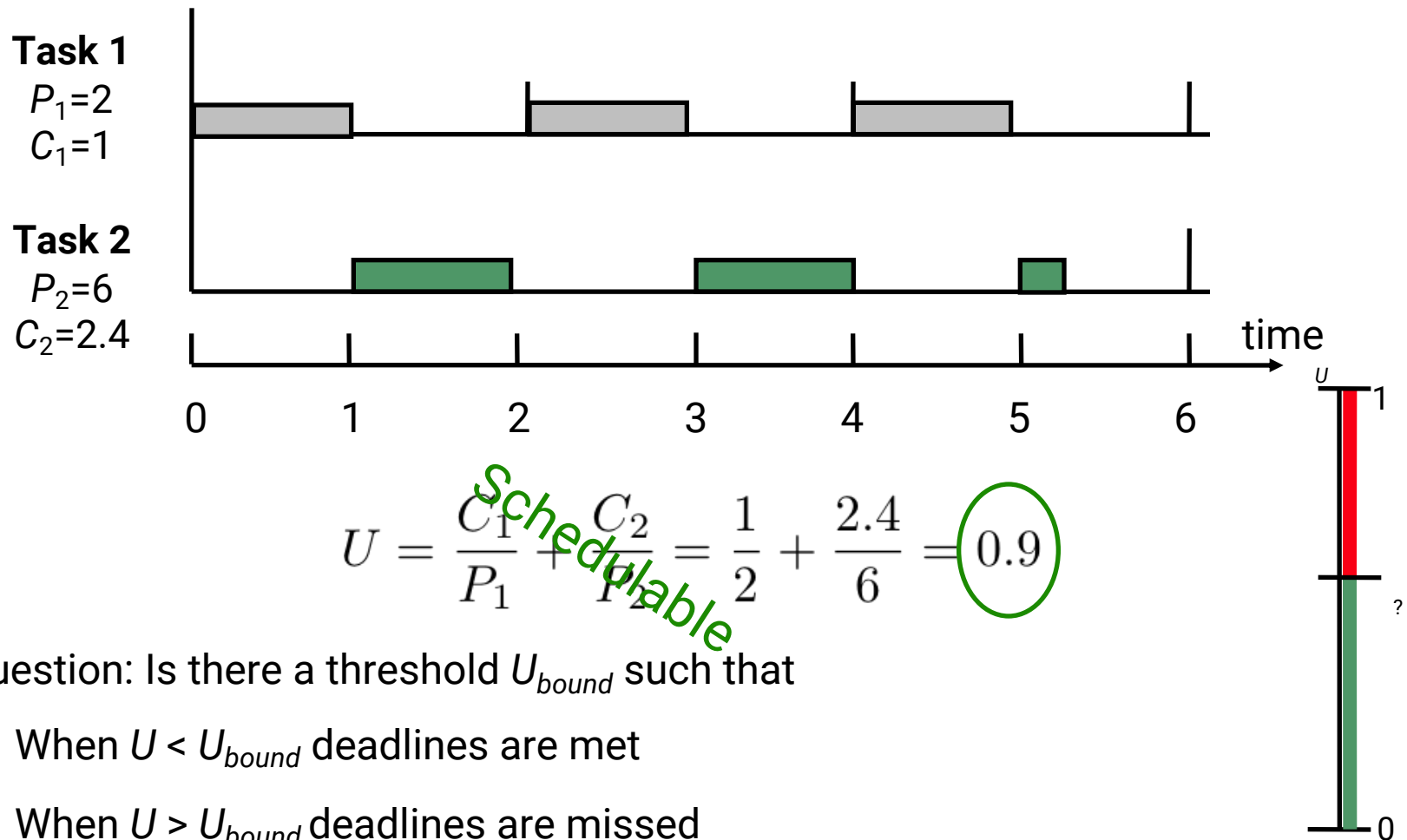


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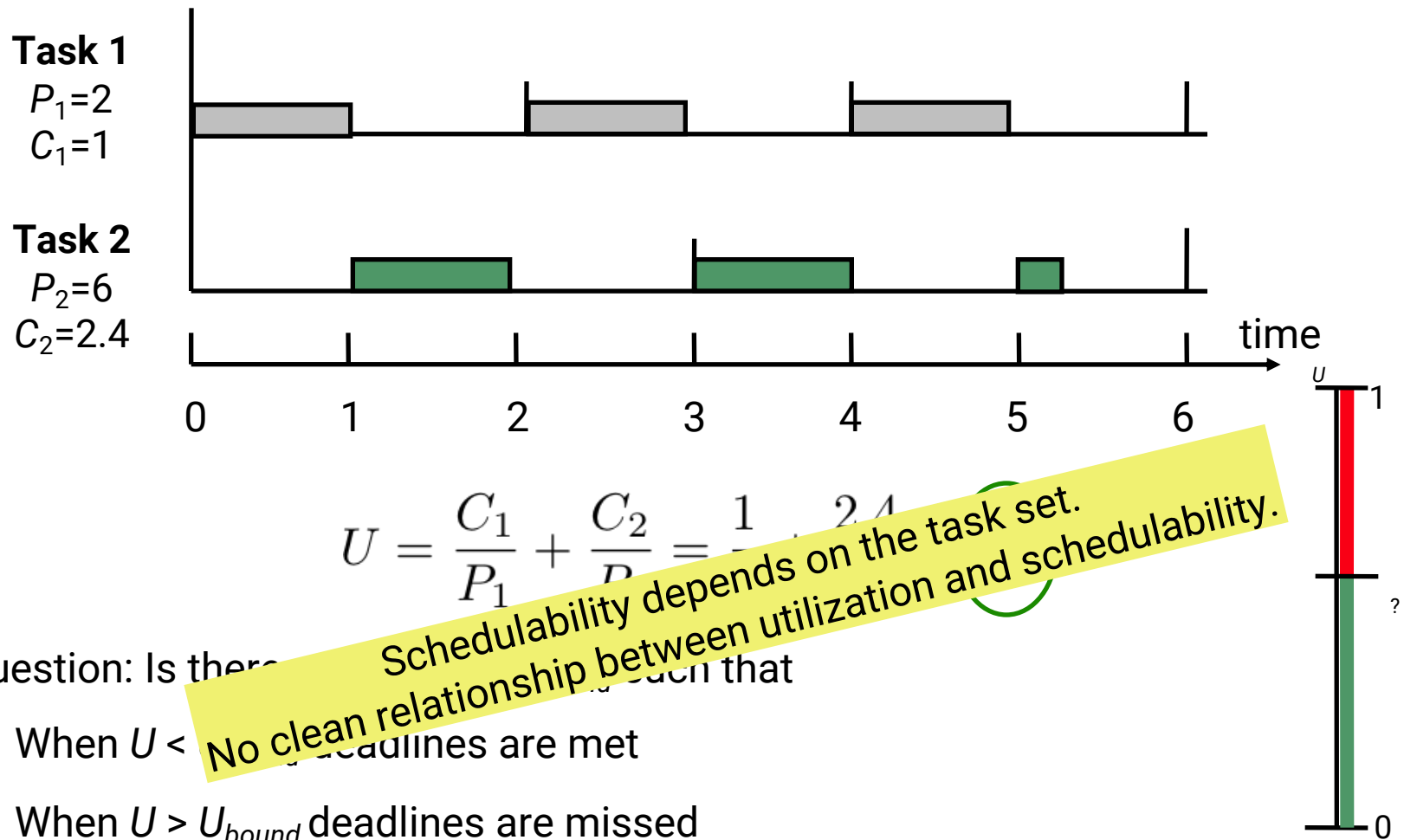


- Question: Is there a threshold  $U_{bound}$  such that
  - When  $U < U_{bound}$  deadlines are met
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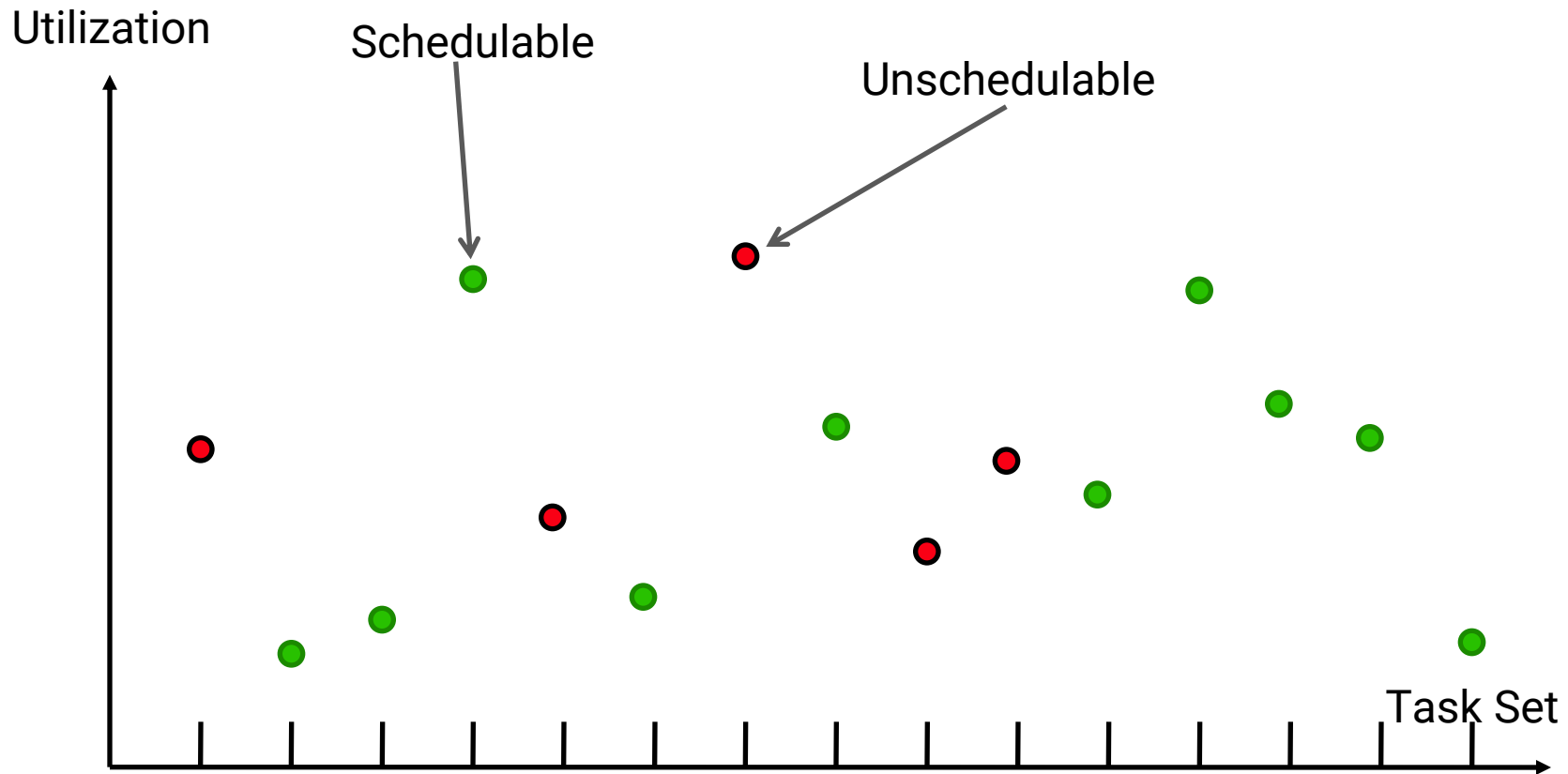
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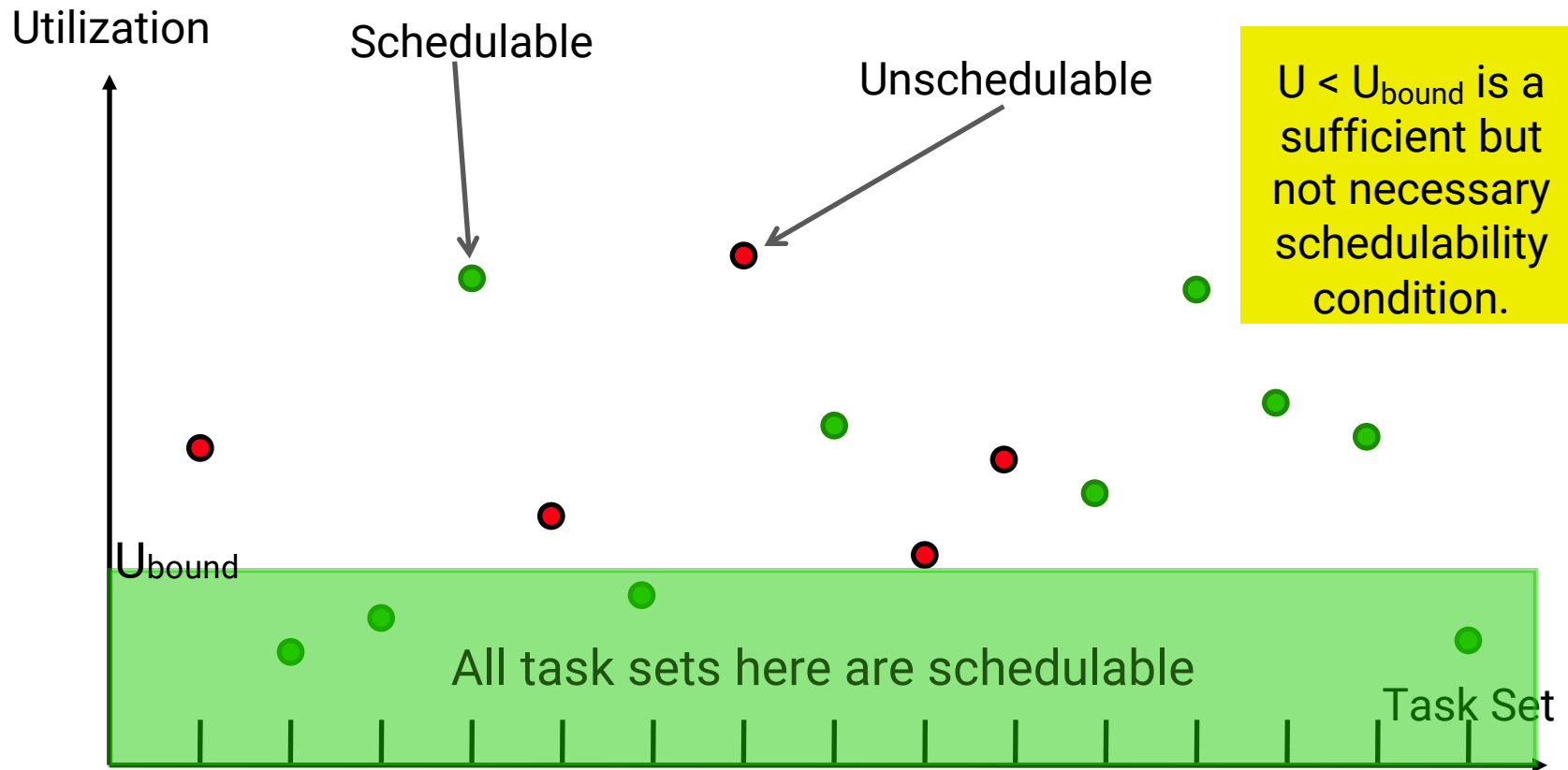


# Visualizing schedulability



- Question: is there a threshold  $U_{bound}$  such that
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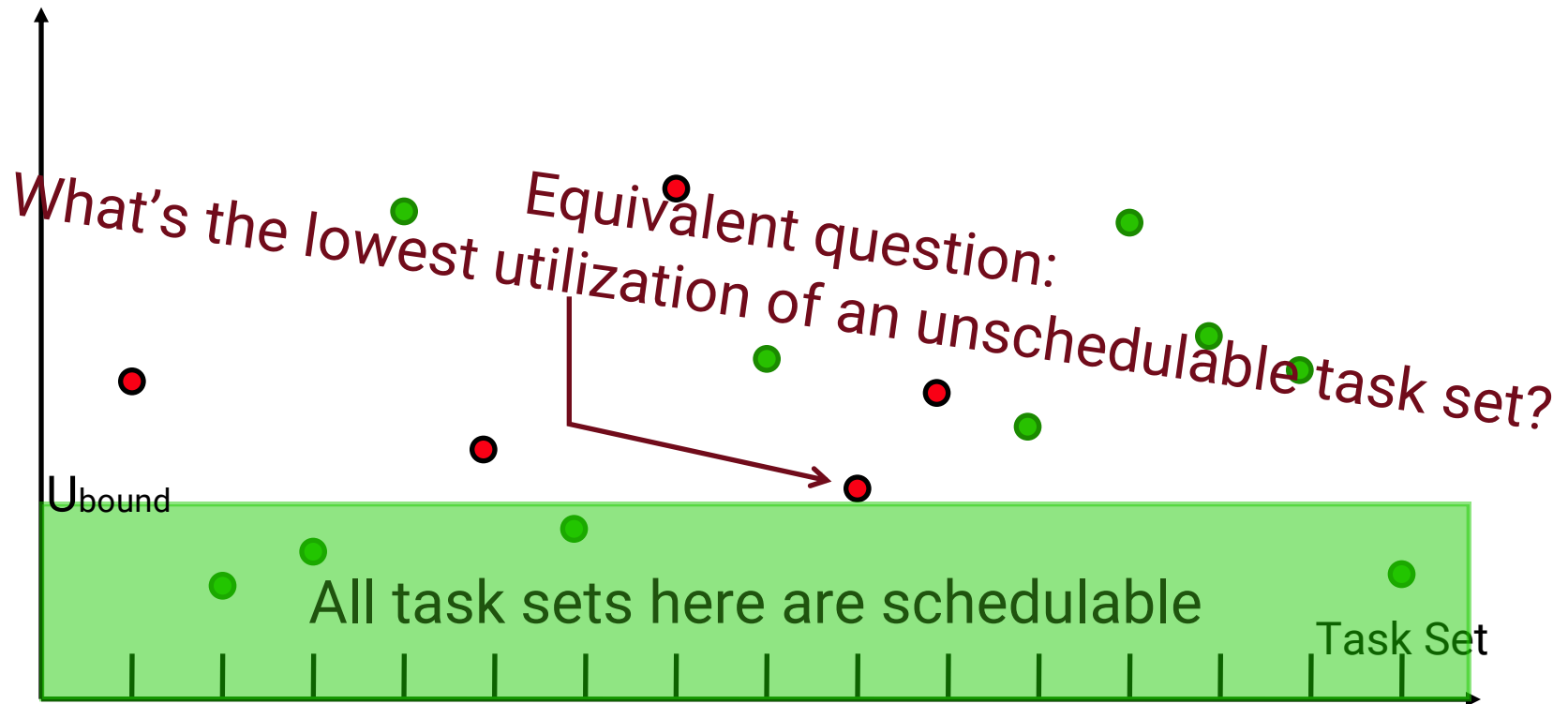
# Visualizing schedulability



- **Modified** question: Is there a threshold  $U_{\text{bound}}$  such that
  - When  $U < U_{\text{bound}}$  deadlines are met (false negatives are OK, but false positives are NOT OK)
  - When  $U > U_{\text{bound}}$  deadlines **might or might not be** missed

# Visualizing schedulability

Utilization

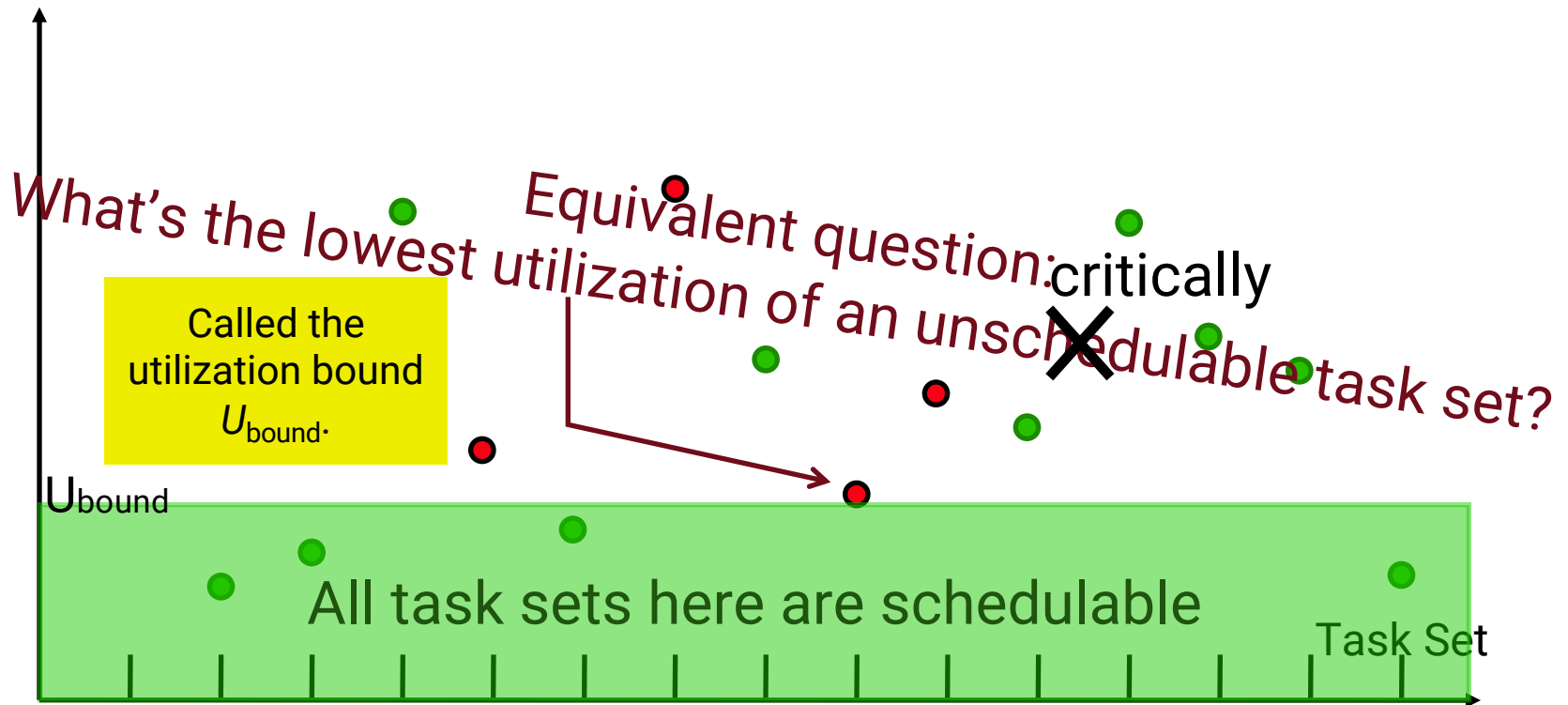


- **Modified** question: Is there a threshold  $U_{bound}$  such that
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# Visualizing schedulability

Utilization



- **Modified** question: Is there a threshold  $U_{bound}$  such that
  - When  $U < U_{bound}$  deadlines are met
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# Utilization bound: The Plan

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1. Consider a fixed priority assignment  $S$
2. Consider a task set  $\Gamma$  with utilization  $U = \sum_{i=1}^n c_i/P_i$  that is **feasible** under  $S$
3. **Inflate** execution times of the tasks until  $\Gamma$  **fully utilizes** the processor under  $S$ 
  - **Meaning:** If execution times of inflated  $\Gamma$  are further increased by any  $\epsilon > 0$ , then the inflated  $\Gamma$  will become infeasible under  $S$
  - Inflated  $\Gamma$  is said to **fully utilize** the processor under  $S$ 
    - Also called **critically schedulable** under  $S$

# Utilization bound: The Plan


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4. Now given the set

$$\mathcal{U} = \{U(\Gamma) : \Gamma \text{ critically schedulable under } S\}$$

**Q:** What utilization value  $U$  is such that all task sets whose utilization is  $\leq U$  are feasible under  $S$ ?

$$U_{\text{lub}}(S) = \inf \mathcal{U}$$

  
least upper bound

**Intuition:** Any taskset that is generated from  $\mathcal{U}$  by reducing execution times and holding the periods fixed is feasible (less workload  $\rightarrow$  less interference)

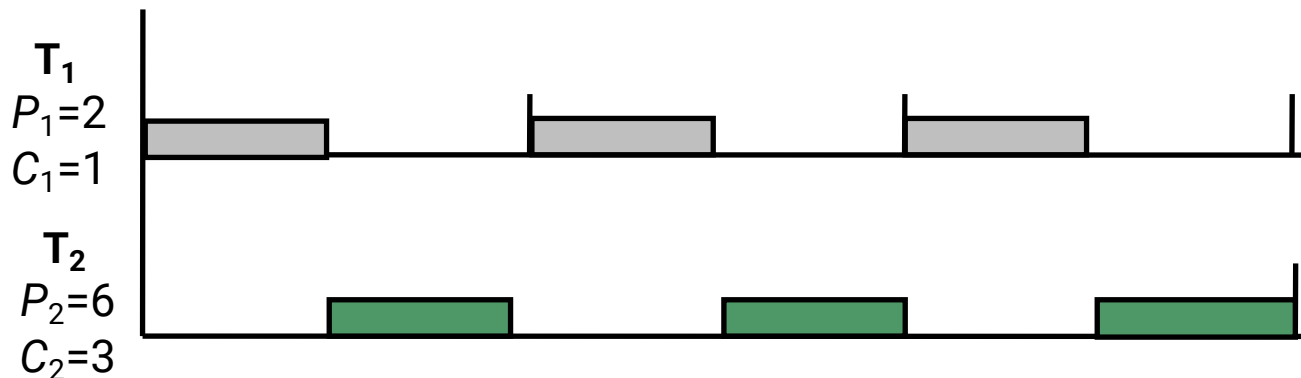
# Utilization bound: The Plan

$$\mathcal{U} = \{U(\Gamma) : \Gamma \text{ critically schedulable under } S\}$$

$$U_{\text{lub}}(S) = \inf \mathcal{U}$$

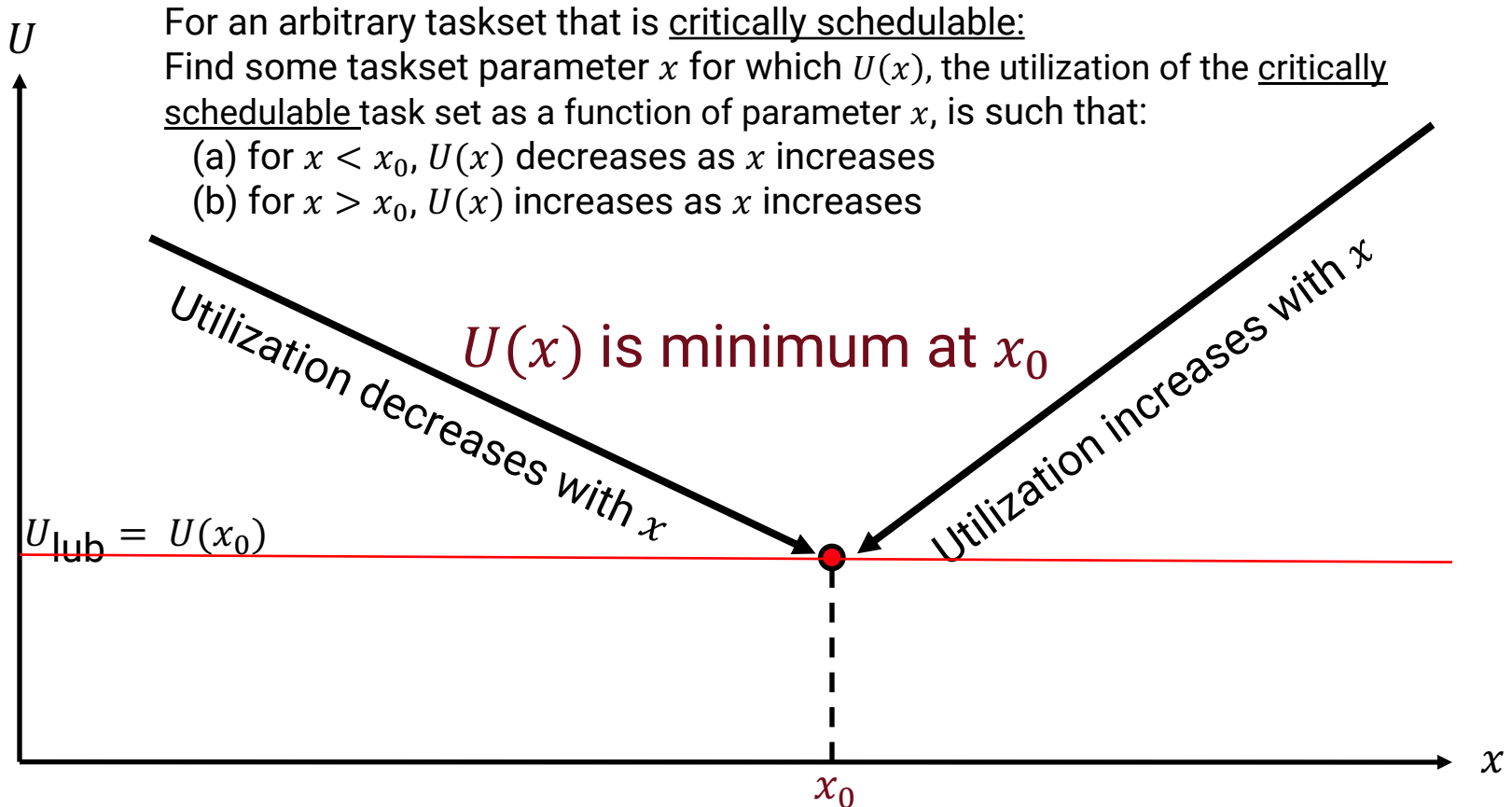
Why not take the sup (max) of the critically schedulable set instead of inf (min)?

Consider two tasks  $T_1 = (1, 2)$  and  $T_2 = (3, 6) \rightarrow U = 1$  (critically schedulable and achieves the sup)



But we saw that taskset  $T_1 = (1, 2)$  and  $T_2 = (2.4, 6)$  with  $U = 0.833$  is NOT schedulable under RM!

# How we will carry out the plan



# Deriving $U_{\text{lub}}(\text{RM})$

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- Two tasks case first
- Consider the same two cases as in proof of optimality in previous lecture

# Finding the utilization bound for RM scheduling

$U(x)$ : utilization of critically schedulable taskset

Find some taskset parameter  $x$

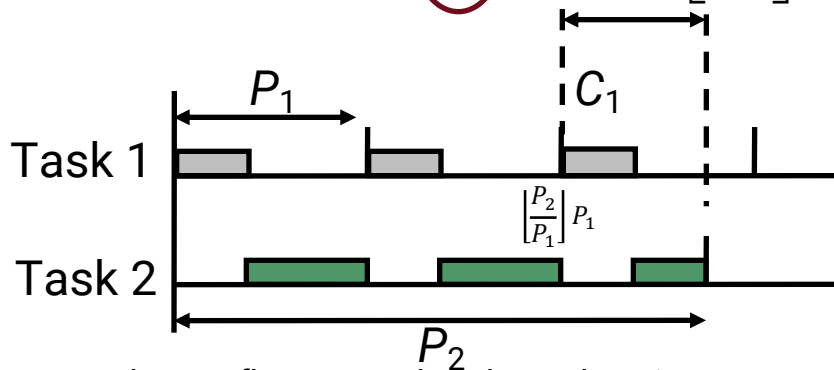
such that

Case (a):  $x < x_0$  such that  $U(x)$  decreases as  $x$  increases

Case (b):  $x > x_0$  such that  $U(x)$  increases as  $x$  increases

Thus  $U(x)$  is minimum when  $x = x_0 \rightarrow$  Find  $U(x_0)$

$$C_1 \leq P_2 - \left\lfloor \frac{P_2}{P_1} \right\rfloor P_1$$

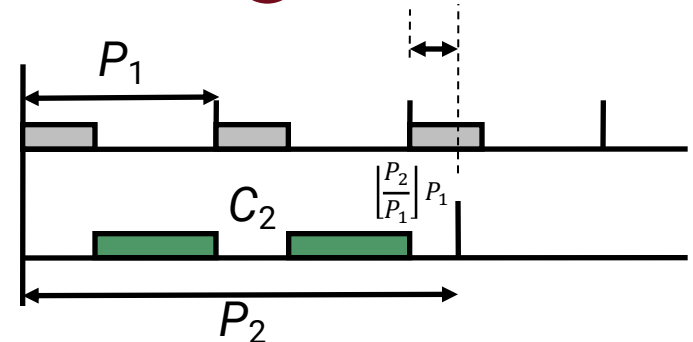


For such  $C_1$ : Inflate  $C_2$  so that the taskset is critically schedulable

$$C_2 = P_2 - C_1 \left\lfloor \frac{P_2}{P_1} \right\rfloor = P_2 - C_1 \left( \left\lfloor \frac{P_2}{P_1} \right\rfloor + 1 \right)$$

$$U = \frac{C_1}{P_1} + \frac{C_2}{P_2} = 1 + \frac{C_1}{P_2} \left( \frac{P_2}{P_1} - \left\lfloor \frac{P_2}{P_1} \right\rfloor - 1 \right)$$

$$C_1 > P_2 - \left\lfloor \frac{P_2}{P_1} \right\rfloor P_1$$



$$C_2 = (P_1 - C_1) \left\lfloor \frac{P_2}{P_1} \right\rfloor$$

$$U = \frac{P_1}{P_2} \left\lfloor \frac{P_2}{P_1} \right\rfloor + \frac{C_1}{P_2} \left( \frac{P_2}{P_1} - \left\lfloor \frac{P_2}{P_1} \right\rfloor \right)$$

# Finding the utilization bound for RM scheduling

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Case 1:

$$C_1 \leq P_2 - \left\lfloor \frac{P_2}{P_1} \right\rfloor P_1$$

$$C_2 = P_2 - C_1 \left\lceil \frac{P_2}{P_1} \right\rceil = P_2 - C_1 \left( \left\lfloor \frac{P_2}{P_1} \right\rfloor + 1 \right)$$

$$U = \frac{C_1}{P_1} + \frac{C_2}{P_2} = 1 + \frac{C_1}{P_2} \left( \frac{P_2}{P_1} - \left\lfloor \frac{P_2}{P_1} \right\rfloor - 1 \right)$$

$$U = 1 + \frac{P_1}{P_2} \left( \frac{P_2}{P_1} - \left\lfloor \frac{P_2}{P_1} \right\rfloor \right) \left( \frac{P_2}{P_1} - \left\lfloor \frac{P_2}{P_1} \right\rfloor - 1 \right)$$

What value of  $C_1$  minimizes  $U$ ?

- Term in ( ) is  $< 0$
- $C_1 \mapsto U$  is a decreasing map  $\downarrow$

$$C_1 = P_2 - \left\lfloor \frac{P_2}{P_1} \right\rfloor P_1 = P_1 \left( \frac{P_2}{P_1} - \left\lfloor \frac{P_2}{P_1} \right\rfloor \right)$$

The same  $C_1$  minimizes  $U$  of **case 2**  
and the resulting  $U(C_1)$  for case 2 is  
the same as that of case 1



# Finding the utilization bound for RM scheduling

Case 1:

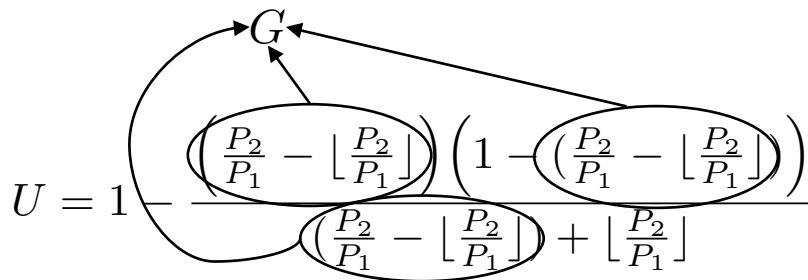
$$U = 1 + \frac{P_1}{P_2} \left( \frac{P_2}{P_1} - \left\lfloor \frac{P_2}{P_1} \right\rfloor \right) \left( \frac{P_2}{P_1} - \left\lfloor \frac{P_2}{P_1} \right\rfloor - 1 \right)$$

To minimize  $U$ , we must have

$$\left\lfloor \frac{P_2}{P_1} \right\rfloor = 1$$

Why?

$$U = 1 - \frac{\left( \frac{P_2}{P_1} - \left\lfloor \frac{P_2}{P_1} \right\rfloor \right) \left( 1 - \left( \frac{P_2}{P_1} - \left\lfloor \frac{P_2}{P_1} \right\rfloor \right) \right)}{P_2/P_1}$$



The diagram illustrates the simplification of the utilization bound formula. The original formula is shown with the terms  $\left( \frac{P_2}{P_1} - \left\lfloor \frac{P_2}{P_1} \right\rfloor \right)$  and  $\left( 1 - \left( \frac{P_2}{P_1} - \left\lfloor \frac{P_2}{P_1} \right\rfloor \right) \right)$  circled. A green arrow points to the simplified formula, where the denominator is  $G + \left\lfloor \frac{P_2}{P_1} \right\rfloor$ .

$0 \leq G < 1$  and so is  $1 - G \Rightarrow G(1 - G) \geq 0$

Then  $\left\lfloor \frac{P_2}{P_1} \right\rfloor \mapsto U$  is increasing  $\uparrow$

$U$  minimized at minimum possible  $\left\lfloor \frac{P_2}{P_1} \right\rfloor$

But  $P_2 \geq P_1$  (RM)  $\Rightarrow \left\lfloor \frac{P_2}{P_1} \right\rfloor \geq 1$

Then min. possible  $\left\lfloor \frac{P_2}{P_1} \right\rfloor$  is 1

$$U = 1 - \frac{G(1 - G)}{G + \left\lfloor \frac{P_2}{P_1} \right\rfloor}$$

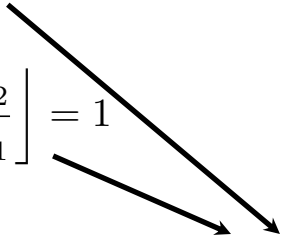
# Finding the utilization bound for RM scheduling

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The minimum utilization case

$$U = 1 - \frac{\left(\frac{P_2}{P_1} - \lfloor \frac{P_2}{P_1} \rfloor\right) \left(1 - \left(\frac{P_2}{P_1} - \lfloor \frac{P_2}{P_1} \rfloor\right)\right)}{P_2/P_1}$$

To minimize  $U$ , we must have  $\left\lfloor \frac{P_2}{P_1} \right\rfloor = 1$


$$U = 1 + \frac{(P_2/P_1 - 1)(P_2/P_1 - 2)}{P_2/P_1}$$

Real-valued function  
in one variable  $P_2/P_1$

Differentiable!

Then  $\frac{dU}{d(P_2/P_1)} = 0 \Rightarrow \frac{P_2}{P_1} = \sqrt{2}$

Finally,  $U = 0.83$

# Finding the utilization bound for RM scheduling

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$$U = 1 + \frac{P_1}{P_2} \left( \frac{P_2}{P_1} - \left\lfloor \frac{P_2}{P_1} \right\rfloor \right) \left( \frac{P_2}{P_1} - \left\lfloor \frac{P_2}{P_1} \right\rfloor - 1 \right)$$

**Observe:**

If  $P_2$  is an integer multiple of  $P_1 \Rightarrow \frac{P_2}{P_1} = \left\lfloor \frac{P_2}{P_1} \right\rfloor \Rightarrow U = 1$

# Generalization for $n$ tasks

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What were the worst case conditions for the 2-task case?

$$\left\{ \begin{array}{l} \lfloor \frac{P_2}{P_1} \rfloor = 1 \\ C_1 = P_2 - \lfloor \frac{P_2}{P_1} \rfloor P_1 = P_2 - P_1 \\ C_2 = (P_1 - C_1) \lfloor \frac{P_2}{P_1} \rfloor = P_1 - C_1 \end{array} \right. \iff \left\{ \begin{array}{l} P_1 < P_2 < 2P_1 \\ C_1 = P_2 - P_1 \\ C_2 = P_1 - C_1 = 2P_1 - P_2 \end{array} \right.$$

Generalizing to  $n$  tasks

$$\left\{ \begin{array}{l} P_1 < P_n < 2P_1 \\ C_1 = P_2 - P_1 \\ C_2 = P_3 - P_2 \\ C_3 = P_4 - P_3 \\ \vdots \\ C_{n-1} = P_n - P_{n-1} \\ C_n = P_1 - (C_1 + \dots + C_{n-1}) = 2P_1 - P_n \end{array} \right.$$

# Generalization for n tasks

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$$\begin{cases} P_1 < P_n < 2P_1 \\ C_1 = P_2 - P_1 \\ C_2 = P_3 - P_2 \\ C_3 = P_4 - P_3 \\ \vdots \\ C_{n-1} = P_n - P_{n-1} \\ C_n = P_1 - (C_1 + \dots + C_{n-1}) = 2P_1 - P_n \end{cases}$$

$$\begin{aligned} U &= \frac{C_1}{P_1} + \frac{C_2}{P_2} + \dots + \frac{C_n}{P_n} \\ &= \frac{P_2 - P_1}{P_1} + \frac{P_3 - P_2}{P_2} + \dots + \frac{2P_1 - P_n}{P_n} \\ &= \frac{P_2}{P_1} + \frac{P_3}{P_2} + \dots + \frac{2P_1}{P_n} - n \end{aligned}$$

# Generalization for n tasks

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$$U = \frac{P_2}{P_1} + \frac{P_3}{P_2} + \dots + \frac{2P_1}{P_n} - n$$

$$\frac{\partial U}{\partial(P_2/P_1)} = 0; \frac{\partial U}{\partial(P_3/P_2)} = 0; \dots; \frac{\partial U}{\partial(P_n/P_1)} = 0$$

We can then obtain

Liu & Layland, 1973

$$\frac{P_{i+1}}{P_i} = 2^{1/n} \Rightarrow U = n(2^{1/n} - 1)$$

For large  $n$ :  $\lim_{n \rightarrow \infty} U = \lim_{n \rightarrow \infty} n(2^{1/n} - 1) = \ln 2 \approx 0.69$

# Sanity check

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Let  $b_n = \inf\{U(\Gamma) : \Gamma \text{ is a critically schedulable set of } n \text{ tasks}\}$

Let  $U_n$  be utilization factor of  $n$  tasks

**Question:** If  $U_n \leq b_n$ , is the task set schedulable?

# Lecture summary

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- Understanding utilization bounds
- The utilization bound for rate-monotonic scheduling
- For RM scheduling the bound decreases with the number of tasks, approaching an asymptotic limit of 0.69
- Coming up: Why is RM priority assignment the optimal static priority policy? Are there better schedulability tests?