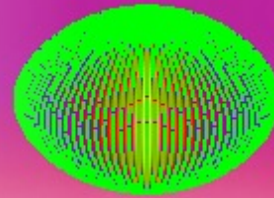


# Self-gravitating neutron star-disks in general relativity

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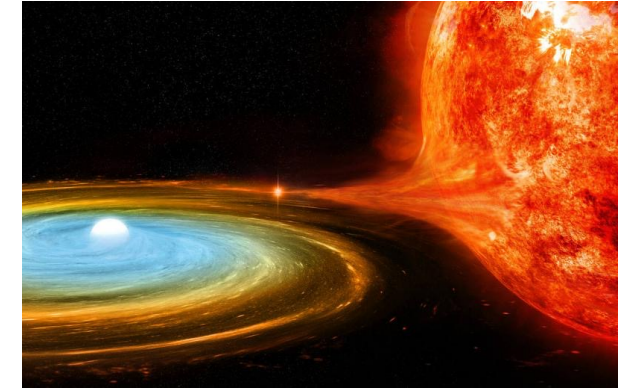
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# Why we study neutron star-disks (NSDs)?

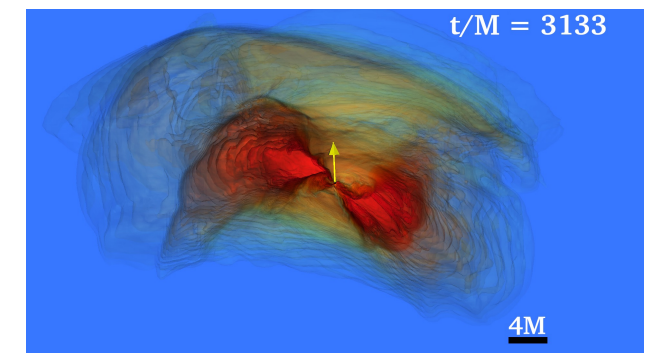
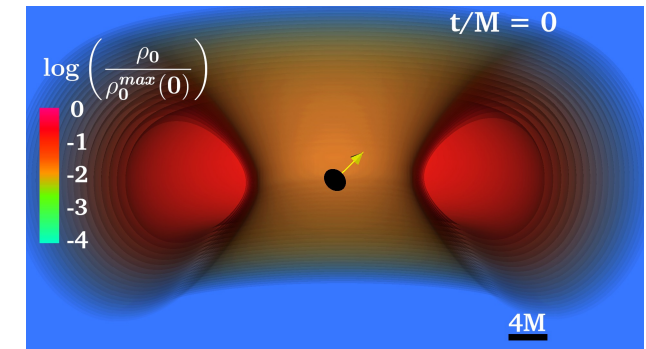
- NSNS merger leads to BH-disk (GW170817?) or NS-disk
- X-ray binary where accretor is an NS
- Collapse of supermassive star into an NS-disk



Credit: NASA/CXC/M. Weiss

# Why is disk self-gravity important?

- Eccentric NSNS mergers result in disk up to 10% mass of initial (Gold 2012)
- Certain mass ratios, NS spins, and NS EOS result in large disk mass (Krüger 2020)
- Precession of angular momenta if compact object and disk are misaligned (Tsokaros 2022)
- Gravitational waves from disk instabilities (Wessel 2023)



Credit: Eric Yu, Mit Kotak,

# How do we compute NSDs?

## General relativity

4 dimensional spacetime

$$ds^2 = g_{\alpha\beta} dx^\alpha dx^\beta$$

$$dx^\alpha = (dt, dx, dy, dz)$$

$$G_{\alpha\beta} = \frac{8\pi G}{c^4} T_{\alpha\beta}$$

## Numerical relativity

3+1 decomposition into space + time

$$ds^2 = -\alpha^2 dt^2 + \psi^4 \tilde{\gamma}_{ab} (dx^a + \beta^a dt)(dx^b + \beta^b dt)$$

$$dx^a = (dx, dy, dz)$$

$$\dot{\Delta}\psi = \mathcal{S}_H, \dot{\Delta}\tilde{\beta}_a = \mathcal{S}_a, \dot{\Delta}(\alpha\psi) = \mathcal{S}_{\text{tr}}, \dot{\Delta}h_{ab} = \mathcal{S}_{ab}$$

$$\tilde{\gamma}_{ab} = f_{ab} + h_{ab}, \tilde{\beta}_a = \tilde{\gamma}_{ab}\beta^b$$

# How do we compute NSDs?

$$\mathcal{S}_H := -h^{ab} \mathring{D}_a \mathring{D}_b \psi + \tilde{\gamma}^{ab} C_{ab}^c \mathring{D}_c \psi + \frac{\psi}{8} {}^3\tilde{R} \\ - \frac{\psi^5}{8} \left( \tilde{A}_{ab} \tilde{A}^{ab} - \frac{2}{3} K^2 \right) - 2\pi\psi^5 \rho_H,$$

$$\mathcal{S}_{\text{tr}} := -h^{ab} \mathring{D}_a \mathring{D}_b (\alpha\psi) + \tilde{\gamma}^{ab} C_{ab}^c \mathring{D}_c (\alpha\psi) + \frac{\alpha\psi}{8} {}^3\tilde{R} \\ + \psi^5 \mathcal{L}_\omega K + \alpha\psi^5 \left( \frac{7}{8} \tilde{A}_{ab} \tilde{A}^{ab} + \frac{5}{12} K^2 \right) \\ + 2\pi\alpha\psi^5 (\rho_H + 2S),$$

$$\mathcal{S}_a := -h^{bc} \mathring{D}_b \mathring{D}_c \tilde{\beta}_a + \tilde{\gamma}^{bc} \mathring{D}_b (C_{ca}^d \tilde{\beta}_d) + \tilde{\gamma}^{bc} C_{bc}^d \mathring{D}_d \tilde{\beta}_a \\ + \tilde{\gamma}^{bc} C_{ba}^d \mathring{D}_c \tilde{\beta}_d - \frac{1}{3} \mathring{D}_a (h^{bc} \mathring{D}_b \tilde{\beta}_c - \tilde{\gamma}^{bc} C_{bc}^d \tilde{\beta}_d) \\ - \frac{1}{3} \mathring{D}_a \mathring{D}^b \tilde{\beta}_b - {}^3\tilde{R}_{ab} \tilde{\beta}^b - 2\alpha \tilde{A}_a{}^b \frac{\alpha}{\psi^6} \mathring{D}_b \left( \frac{\psi^6}{\alpha} \right) \\ + \frac{4}{3} \alpha \mathring{D}_a K + 16\pi\alpha j_a,$$

$$\mathcal{S}_{ab} := 2\bar{\mathcal{S}}_{ab}^{\text{TF}} - \frac{1}{3} \tilde{\gamma}_{ab} \mathring{D}^e h^{cd} \mathring{D}_e h_{cd},$$

# How do we compute NSDs? (pt. 2)

Initial data: at a fixed ‘time’, construct a system that satisfies:

Einstein’s equations

$$\psi, \alpha, \tilde{\beta}_a, h_{ab}$$

$$\dot{\Delta}\psi = \mathcal{S}_H, \dot{\Delta}\tilde{\beta}_a = \mathcal{S}_a$$

$$\dot{\Delta}(\alpha\psi) = \mathcal{S}_{\text{tr}}, \dot{\Delta}h_{ab} = \mathcal{S}_{ab}$$

Hydrostatic equilibrium

$$\nabla_a(\rho u^\alpha) = 0, u^\alpha \nabla_\alpha s = 0$$

$$u^\beta \omega_{\beta\alpha} - T \nabla_\alpha s = 0$$

+EOS

Assumptions

Axisymmetry

Stationary

Circular flow

Homentropic flow

$$\frac{h}{u^t} \exp \left[ \int j(\Omega) d\Omega \right] = \mathcal{E}$$

# How do we compute NSDs? (pt. 3)

1. Start with initial data for a rotating neutron star (Uryū, Tsokaros 2016)
2. Initialize a massless disk around the neutron star (Abramowicz 1977, ‘Polish doughnut’)
  1. the equation of state (piecewise polytrope),  $P_i = K_i \rho_0^{\Gamma_i}$
  2. the rotation law,  $\Omega = \eta \lambda^q$  where  $\lambda := \ell / \Omega$
  3. and the location and angular momentum at the inner edge of the disk.



Then solve hydrostatic equilibrium  $\frac{h}{u^t} \exp \left[ \int j(\Omega) d\Omega \right] = \mathcal{E}$

3. To add self-gravitation, iterate:
  1. first, **update source terms** with new contributions from disk and update gravitational potential by resolving Einstein's equations
  2. resolve hydrostatic equilibrium for **both NS and disk**
  3. repeat until change in variables between iterations falls below threshold

$$\begin{aligned} \psi, \alpha, \tilde{\beta}_a, h_{ab} \\ \dot{\Delta} \psi = \mathcal{S}_H, \dot{\Delta} \tilde{\beta}_a = \mathcal{S}_a \\ \dot{\Delta}(\alpha \psi) = \mathcal{S}_{\text{tr}}, \dot{\Delta} h_{ab} = \mathcal{S}_{ab} \end{aligned}$$



# Massless disks

Range of valid disk solutions

$$\ell_{\text{in,min}}/M < \ell_{\text{in}}/M < \ell_{\text{in,max}}/M$$

	BH	NS
$\chi_1$	$3.532 < \ell_{\text{in}}/M < 3.843$	$0.570 < \ell_{\text{in}}/M < 0.636$
$\chi_2$	$3.153 < \ell_{\text{in}}/M < 3.602$	$0.455 < \ell_{\text{in}}/M < 0.520$

$$\chi = a/M_{\text{BH}}$$

$$= J_{\text{NS}}/M_{\text{NS}}^2$$

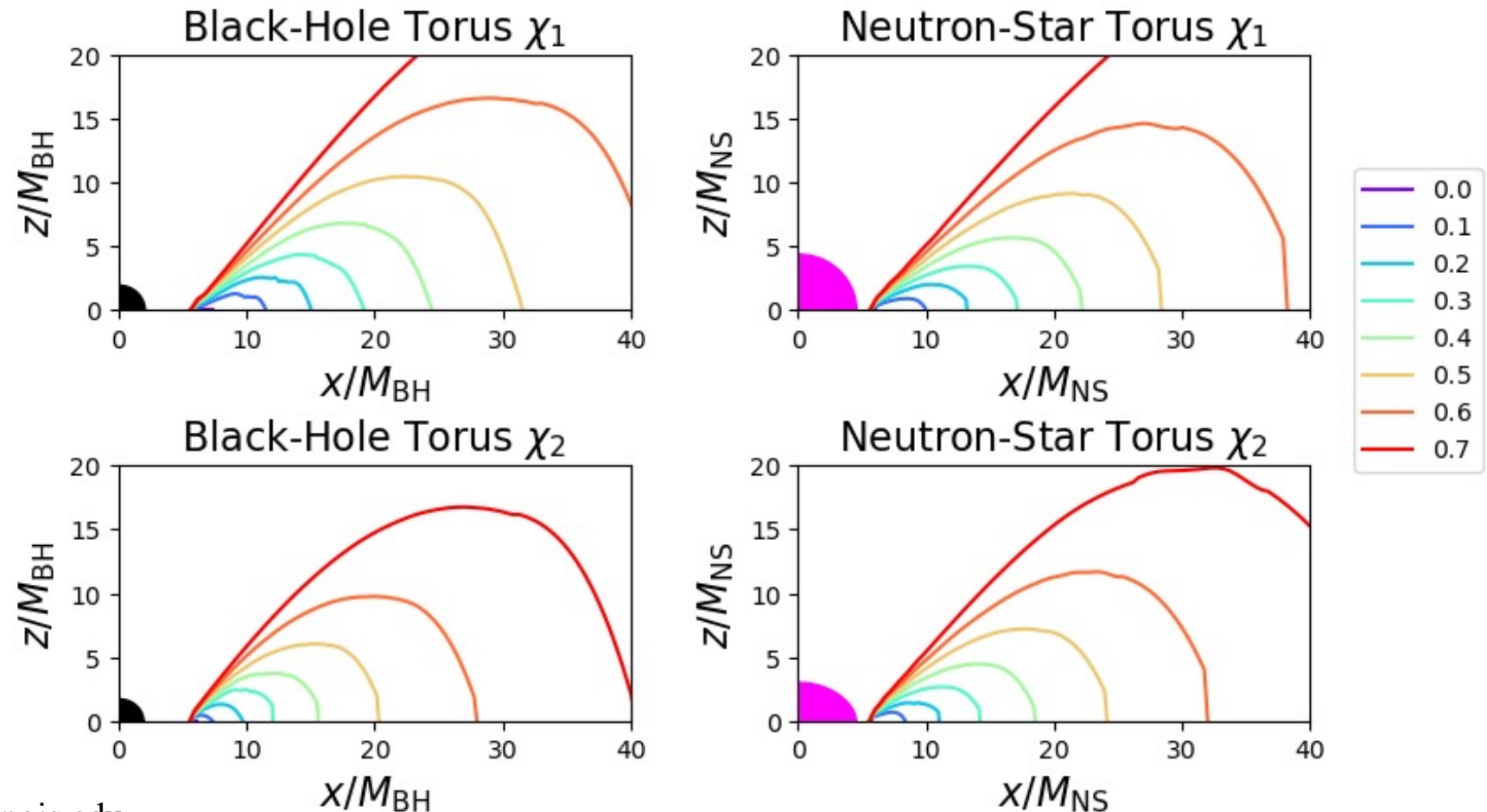
$$\chi_1 = 0.13$$

$$\chi_2 = 0.63$$

$$\beta = \frac{\ell_{\text{in}} - \ell_{\text{in,min}}}{\ell_{\text{in,max}} - \ell_{\text{in,min}}}$$

$$0 < \beta < 1$$

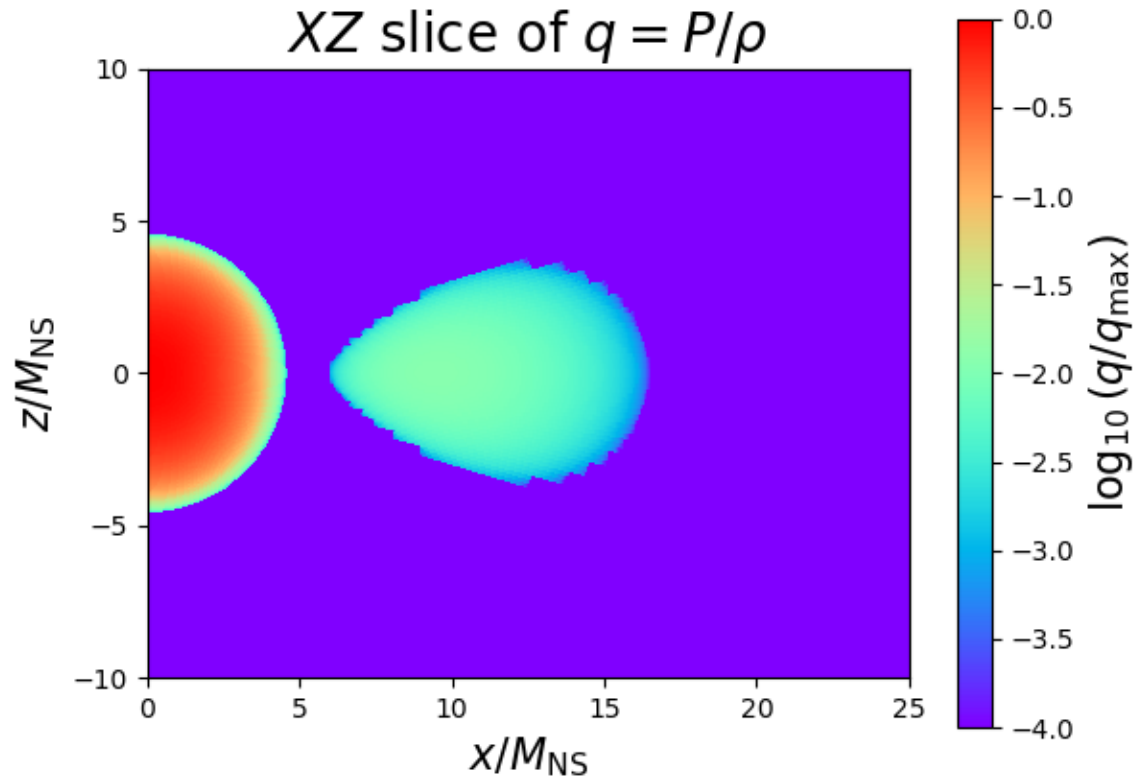
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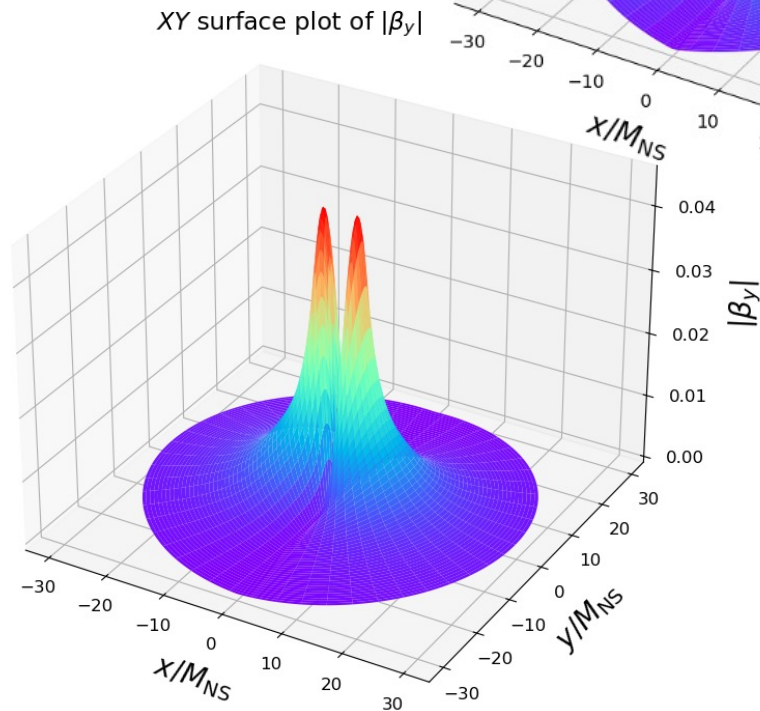
# Self-gravitating disk example

$$M_{0,\text{disk}} = 0.0408 M_{0,\text{ns}}$$

(similar to common NSNS merger)



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XY surface plot of  $|\beta_y - \beta_{y,0}|$  ( $\beta_{y,0}$  from initial RNS data)

