Water-Resources Engineering, Second Edition

DAVID A. CHIN

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# Chapter 2

# Flow in Closed Conduits

# 2.1 Introduction

Flow in closed conduits includes all cases where the flowing fluid completely fills the conduit. The cross-sections of closed conduits can be of any shape or size and can be made of a variety of materials. Engineering applications of the principles of flow in closed conduits include the design of municipal water-supply systems and transmission lines. The basic equations governing the flow of fluids in closed conduits are the continuity, momentum, and energy equations. The most useful forms of these equations for application to pipe flow problems are derived in this chapter. The governing equations are presented in forms that are applicable to any fluid flowing in a closed conduit, but particular attention is given to the flow of water.

The computation of flows in pipe networks is a natural extension of the flows in single pipelines, and methods of calculating flows and pressure distributions in pipeline systems are also described here. These methods are particularly applicable to the analysis and design of municipal water distribution systems, where the engineer is frequently interested in assessing the effects of various modifications to the system. Because transmission of water in closed conduits is typically accomplished using pumps, the fundamentals of pump operation and performance are also presented in this chapter. A sound understanding of pumps is important in selecting the appropriate pump to achieve the desired operational characteristics in water transmission systems. The design protocol for municipal water distribution systems is presented as an example of the application of the principles of flow in closed conduits. Methods for estimating water demand, design of the functional components of distribution systems, network analysis, and the operational criteria for municipal water distribution systems are all covered.

# 2.2 Single Pipelines

The governing equations for flows in pipelines are derived from the conservation laws of mass, momentum, and energy; and the forms of these equations that are most useful for application to closed-conduit flow are derived in the following sections.

### 2.2.1 Continuity Equation

Consider the application of the continuity equation to the control volume illustrated in Figure 2.1. Fluid enters and leaves the control volume normal to the control surfaces, with the inflow velocity

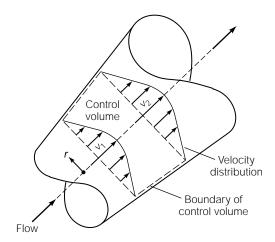


Figure 2.1: Flow Through Closed Conduit

denoted by  $v_1(\mathbf{r})$  and the outflow velocity by  $v_2(\mathbf{r})$ . Both the inflow and outflow velocities vary across the control surface. The steady-state continuity equation for an incompressible fluid can be written as

$$\int_{A_1} v_1 \, dA = \int_{A_2} v_2 \, dA \tag{2.1}$$

Defining  $V_1$  and  $V_2$  as the average velocities across  $A_1$  and  $A_2$ , respectively, where

$$V_1 = \frac{1}{A_1} \int_{A_1} v_1 \, dA \tag{2.2}$$

and

$$V_2 = \frac{1}{A_2} \int_{A_2} v_2 \, dA \tag{2.3}$$

the steady-state continuity equation becomes

$$V_1 A_1 = V_2 A_2 (= Q) \tag{2.4}$$

The terms on each side of Equation 2.4 are equal to the volumetric flowrate, Q. The steady-state continuity equation simply states that the volumetric flowrate across any surface normal to the flow is a constant.

#### Example 2.1.

Water enters a pump through a 150-mm diameter intake pipe and leaves the pump through a 200-mm diameter discharge pipe. If the average velocity in the intake pipeline is 1 m/s, calculate the average velocity in the discharge pipeline. What is the flowrate through the pump?

#### Solution.

In the intake pipeline,  $V_1 = 1 \text{ m/s}$ ,  $D_1 = 0.15 \text{ m}$  and

$$A_1 = \frac{\pi}{4}D_1^2 = \frac{\pi}{4}(0.15)^2 = 0.0177 \text{ m}^2$$

In the discharge pipeline,  $D_2 = 0.20$  m and

$$A_2 = \frac{\pi}{4}D_2^2 = \frac{\pi}{4}(0.20)^2 = 0.0314 \text{ m}^2$$

According to the continuity equation,

$$V_1 A_1 = V_2 A_2$$

Therefore,

$$V_2 = V_1 \left(\frac{A_1}{A_2}\right) = (1) \left(\frac{0.0177}{0.0314}\right) = 0.56 \text{ m/s}$$

The flowrate, Q, is given by

$$Q = A_1 V_1 = (0.0177)(1) = 0.0177 \text{ m}^3/\text{s}$$

The average velocity in the discharge pipeline is 0.56 m/s, and the flowrate through the pump is 0.0177 m<sup>3</sup>/s.

# 2.2.2 Momentum Equation

Consider the application of the momentum equation to the control volume illustrated in Figure 2.1. Under steady-state conditions, the component of the momentum equation in the direction of flow (x-direction) can be written as

$$\sum F_x = \int_A \rho v_x \mathbf{v} \cdot \mathbf{n} \ dA \tag{2.5}$$

where  $\sum F_x$  is the sum of the x-components of the forces acting on the fluid in the control volume,  $\rho$  is the density of the fluid,  $v_x$  is the flow velocity in the x-direction, and  $\mathbf{v} \cdot \mathbf{n}$  is the component of the flow velocity normal to the control surface. Since the unit normal vector,  $\mathbf{n}$ , in Equation 2.5 is directed outward from the control volume, then the momentum equation for an incompressible fluid ( $\rho = \text{constant}$ ) can be written as

$$\sum F_x = \rho \int_{A_2} v_2^2 dA - \rho \int_{A_1} v_1^2 dA$$
 (2.6)

where the integral terms depend on the velocity distributions across the inflow and outflow control surfaces. The velocity distribution across each control surface is generally accounted for by the momentum correction coefficient,  $\beta$ , defined by the relation

$$\beta = \frac{1}{AV^2} \int_A v^2 dA \tag{2.7}$$

where A is the area of the control surface and V is the average velocity over the control surface. The momentum coefficients for the inflow and outflow control surfaces,  $A_1$  and  $A_2$ , are then given by  $\beta_1$  and  $\beta_2$ , where

$$\beta_1 = \frac{1}{A_1 V_1^2} \int_{A_1} v_1^2 dA \tag{2.8}$$

$$\beta_2 = \frac{1}{A_2 V_2^2} \int_{A_2} v_2^2 dA \tag{2.9}$$

Substituting Equations 2.8 and 2.9 into Equation 2.6 leads to the following form of the momentum equation

$$\sum F_x = \rho \beta_2 V_2^2 A_2 - \rho \beta_1 V_1^2 A_1 \tag{2.10}$$

Recalling that the continuity equation states that the volumetric flowrate, Q, is the same across both the inflow and outflow control surfaces, where

$$Q = V_1 A_1 = V_2 A_2 \tag{2.11}$$

then combining Equations 2.10 and 2.11 leads to the following form of the momentum equation

$$\sum F_x = \rho \beta_2 Q V_2 - \rho \beta_1 Q V_1 \tag{2.12}$$

or

$$\sum F_x = \rho Q(\beta_2 V_2 - \beta_1 V_1) \tag{2.13}$$

In many cases of practical interest, the velocity distribution across the cross-section of the closed conduit is approximately uniform, in which case the momentum coefficients,  $\beta_1$  and  $\beta_2$ , are approximately equal to unity and the momentum equation becomes

$$\sum F_x = \rho Q(V_2 - V_1) \tag{2.14}$$

Consider the common case of flow in a straight pipe with a uniform circular cross-section illustrated in Figure 2.2, where the average velocity remains constant at each cross section,

$$V_1 = V_2 = V (2.15)$$

then the momentum equation becomes

$$\sum F_x = 0 \tag{2.16}$$

The forces that act on the fluid in a control volume of uniform cross-section are illustrated in Figure 2.2. At Section 1, the average pressure over the control surface is equal to  $p_1$  and the elevation

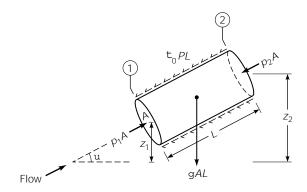


Figure 2.2: Forces on Flow in Closed Conduit

of the midpoint of the section relative to a defined datum is equal to  $z_1$ , at Section 2, located a distance L downstream from Section 1, the pressure is  $p_2$ , and the elevation of the midpoint of the section is  $z_2$ . The average shear stress exerted on the fluid by the pipe surface is equal to  $\tau_o$ , and the total shear force opposing flow is  $\tau_o PL$ , where P is the perimeter of the pipe. The fluid weight acts vertically downward and is equal to  $\gamma AL$ , where  $\gamma$  is the specific weight of the fluid and A is the cross-sectional area of the pipe. The forces acting on the fluid system that have components in the direction of flow are the shear force,  $\tau_o PL$ ; the weight of the fluid in the control volume,

 $\gamma AL$ ; and the pressure forces on the upstream and downstream faces,  $p_1A$  and  $p_2A$ , respectively. Substituting the expressions for the forces into the momentum equation, Equation 2.16, yields

$$p_1 A - p_2 A - \tau_o P L - \gamma A L \sin \theta = 0 \tag{2.17}$$

where  $\theta$  is the angle that the pipe makes with the horizontal and is given by the relation

$$\sin \theta = \frac{z_2 - z_1}{L} \tag{2.18}$$

Combining Equations 2.17 and 2.18 yields

$$\frac{p_1}{\gamma} - \frac{p_2}{\gamma} - z_2 + z_1 = \frac{\tau_o PL}{\gamma A} \tag{2.19}$$

Defining the total head, or energy per unit weight, at Sections 1 and 2 as  $h_1$  and  $h_2$ , where

$$h_1 = \frac{p_1}{\gamma} + \frac{V^2}{2g} + z_1 \tag{2.20}$$

and

$$h_2 = \frac{p_2}{\gamma} + \frac{V^2}{2g} + z_2 \tag{2.21}$$

then the head loss between Sections 1 and 2,  $\Delta h$ , is given by

$$\Delta h = h_1 - h_2 = \left(\frac{p_1}{\gamma} + z_1\right) - \left(\frac{p_2}{\gamma} + z_2\right)$$
 (2.22)

Combining Equations 2.19 and 2.22 leads to the following expression for head loss

$$\Delta h = \frac{\tau_o PL}{\gamma A} \tag{2.23}$$

In this case, the head loss,  $\Delta h$ , is entirely due to pipe friction and is commonly denoted by  $h_f$ . In the case of pipes with circular cross-sections, Equation 2.23 can be written as

$$h_f = \frac{\tau_o(\pi D)L}{\gamma(\pi D^2/4)} = \frac{4\tau_o L}{\gamma D}$$
(2.24)

where D is the diameter of the pipe. The ratio of the cross-sectional area, A, to the perimeter, P, is defined as the *hydraulic radius*, R, where

$$R = \frac{A}{P} \tag{2.25}$$

and the head loss can be written in terms of the hydraulic radius as

$$h_f = \frac{\tau_o L}{\gamma R} \tag{2.26}$$

The form of the momentum equation given by Equation 2.26 is of limited utility in that the head loss,  $h_f$ , is expressed in terms of the boundary shear stress,  $\tau_o$ , which is not a measurable quantity.

However, the boundary shear stress,  $\tau_o$ , can be expressed in terms of measurable flow variables using dimensional analysis, where  $\tau_o$  can be taken as a function of the mean flow velocity, V; density of the fluid,  $\rho$ ; dynamic viscosity of the fluid,  $\mu$ ; diameter of the pipe, D; characteristic size of roughness projections,  $\epsilon$ ; characteristic spacing of the roughness projections,  $\epsilon'$ ; and a (dimensionless) form factor, m, that depends on the shape of the roughness elements on the surface of the conduit. This functional relationship can be expressed as

$$\tau_o = f_1(V, \rho, \mu, D, \epsilon, \epsilon', m) \tag{2.27}$$

According to the Buckingham pi theorem, this relationship between eight variables in three fundamental dimensions can also be expressed as a relationship between five nondimensional groups. The following relation is proposed

$$\frac{\tau_o}{\rho V^2} = f_2\left(\text{Re}, \frac{\epsilon}{D}, \frac{\epsilon'}{D}, m\right) \tag{2.28}$$

where Re is the Reynolds number defined by

$$Re = \frac{\rho VD}{\mu} \tag{2.29}$$

The relationship given by Equation 2.28 is as far as dimensional analysis goes, and experiments are necessary to determine an empirical relationship between the nondimensional groups. Nikuradse (1932; 1933) conducted a series of experiments in pipes in which the inner surfaces were roughened with sand grains of uniform diameter,  $\epsilon$ . In these experiments, the spacing,  $\epsilon'$ , and shape, m, of the roughness elements (sand grains) were constant and Nikuradse's experimental data fitted to the following functional relation

$$\frac{\tau_o}{\rho V^2} = f_3 \left( \text{Re}, \frac{\epsilon}{D} \right) \tag{2.30}$$

It is convenient for subsequent analysis to introduce a factor of 8 into this relationship, which can then be written as

$$\frac{\tau_o}{\rho V^2} = \frac{1}{8} f\left(\text{Re}, \frac{\epsilon}{D}\right) \tag{2.31}$$

or simply

$$\frac{\tau_o}{\rho V^2} = \frac{f}{8} \tag{2.32}$$

where the dependence of the friction factor, f, on the Reynolds number, Re, and relative roughness,  $\epsilon/D$ , is understood. Combining Equations 2.32 and 2.24 leads to the following form of the momentum equation for flows in circular pipes

$$h_f = \frac{fL}{D} \frac{V^2}{2g} \tag{2.33}$$

This equation, called the *Darcy-Weisbach equation*,\* expresses the frictional head loss,  $h_f$ , of the fluid over a length L of pipe in terms of measurable parameters, including the pipe diameter (D),

<sup>\*</sup>Henry Darcy (1803–1858) was a nineteenth-century French engineer; Julius Weisbach (1806 – 1871) was a German engineer of the same era. Weisbach proposed the use of a dimensionless resistance coefficient, and Darcy carried out the tests on water pipes.

average flow velocity (V), and the friction factor (f) that characterizes the shear stress of the fluid on the pipe. Some references name Equation 2.33 simply as the Darcy equation, however this is inappropriate since it was Julius Weisbach who first proposed the exact form of Equation 2.33 in 1845, with Darcy's contribution on the functional dependence of f on V and D in 1857 (Brown, 2002; Rouse and Ince, 1957). The occurrence and differences between laminar and turbulent flow was later quantified by Osbourne Reynolds<sup>†</sup> in 1883 (Reynolds, 1883).

Based on Nikuradse's (1932, 1933) experiments on sand-roughened pipes, Prandl and von Kármán established the following empirical formulae for estimating the friction factor in turbulent pipe flows

Smooth pipe 
$$\left(\frac{k}{D} \approx 0\right)$$
:  $\frac{1}{\sqrt{f}} = -2\log\left(\frac{2.51}{\text{Re}\sqrt{f}}\right)$ 
Rough pipe  $\left(\frac{k}{D} \gg 0\right)$ :  $\frac{1}{\sqrt{f}} = -2\log\left(\frac{k/D}{3.7}\right)$  (2.34)

where k is the roughness height of the sand grains on the surface of the pipe. Turbulent flow in pipes is generally present when Re > 4,000; transition to turbulent flow begins at about Re = 2,300. The pipe behaves like a smooth pipe when the friction factor does not depend on the height of the roughness projections on the wall of the pipe and therefore depends only on the Reynolds number. In rough pipes, the friction factor is determined by the relative roughness, k/D, and becomes independent of the Reynolds number. The smooth pipe case generally occurs at lower Reynolds numbers, when the roughness projections are submerged within the viscous boundary layer. At higher values of the Reynolds number, the thickness of the viscous boundary layer decreases and eventually the roughness projections protrude sufficiently far outside the viscous boundary layer that the shear stress of the pipe boundary is dominated by the hydrodynamic drag associated with the roughness projections into the main body of the flow. Under these circumstances, the flow in the pipe becomes fully turbulent, the friction factor is independent of the Reynolds number, and the pipe is considered to be (hydraulically) rough. The flow is actually turbulent under both smooth-pipe and rough-pipe conditions, but the flow is termed fully turbulent when the friction factor is independent of the Reynolds number. Between the smooth- and rough-pipe conditions, there is a transition region in which the friction factor depends on both the Reynolds number and the relative roughness. Colebrook (1939) developed the following relationship that asymptotes to the Prandl and von Kármán relations

$$\left| \frac{1}{\sqrt{f}} = -2\log\left(\frac{k/D}{3.7} + \frac{2.51}{\text{Re}\sqrt{f}}\right) \right| \tag{2.35}$$

This equation is commonly referred to as the Colebrook equation or Colebrook-White equation. Equation 2.35 can be applied in the transition region between smooth-pipe and rough-pipe conditions, and values of friction factor, f, predicted by the Colebrook equation are generally accurate to within 10–15% of experimental data (Finnemore and Franzini, 2002; Alexandrou, 2001).

Commercial pipes differ from Nikuradse's experimental pipes in that the heights of the roughness projections are not uniform and are not uniformly distributed. In commercial pipes, an *equivalent* sand roughness,  $k_s$ , is defined as the diameter of Nikuradse's sand grains that would cause the same head loss as in the commercial pipe. The equivalent sand roughness,  $k_s$ , of several commercial pipe materials are given in Table 2.1. These values of  $k_s$  apply to clean new pipe only; pipe that has been

<sup>&</sup>lt;sup>†</sup>Osbourne Reynolds (1842 to 1912).

Table 2.1: Typical Equivalent Sand Roughness for Various New Materials

Sand Roughi	Equivalent sand
	roughness, $k_s$
Material	(mm)
Asbestos cement:	
Coated	0.038
Uncoated	0.076
Brass	0.0015 – 0.003
Brick	0.6
Concrete:	
General	0.3 – 3.0
Steel forms	0.18
Wooden forms	0.6
Centrifugally spun	0.13 – 0.36
Copper	0.0015 – 0.003
Corrugated metal	45
Glass	0.0015 – 0.003
Iron:	
Cast iron	0.19 – 0.26
Ductile iron:	
Lined with bitumen	0.12 – 0.03
Lined with spun concrete	0.030 – 038
Galvanized iron	0.013 – 0.15
Wrought iron	0.046-0.06
Lead	0.0015
Plastic (PVC)	0.0015 – 0.03
Steel	
Coal-tar enamel	0.0048
New unlined	0.045 – 0.076
Riveted	0.9 – 9.0
Wood stave	0.18

Sources: Haestad Methods, Inc. (2002), Moody (1944), Sanks (1998)).

in service for a long time usually experiences corrosion or scale buildup that results in values of  $k_s$  that are orders of magnitude larger than the values given in Table 2.1 (Echávez, 1997; Gerhart et al., 1992). The rate of increase of  $k_s$  with time depends primarily on the quality of the water being transported, and the roughness coefficients for older water mains are usually determined through field testing (AWWA, 1992). The expression for the friction factor derived by Colebrook (Equation 2.35) was plotted by Moody (1944) in what is today commonly referred to as the *Moody diagram*,\* reproduced in Figure 2.3. The Moody diagram indicates that for Re  $\leq$  2,000, the flow is laminar

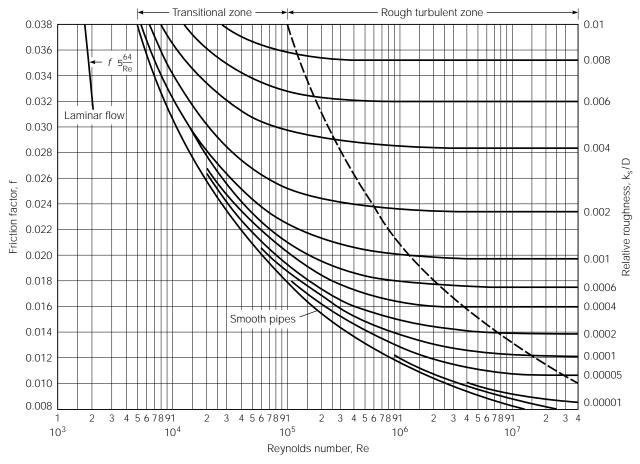


Figure 2.3: Moody Diagram
Source: Moody, L. F. "Friction Factors for Pipe Flow" 66(8), 1944, ASME, New York.

and the friction factor is given by

$$f = \frac{64}{\text{Re}} \tag{2.36}$$

which can be derived theoretically based on the assumption of laminar flow of a Newtonian fluid (Daily and Harleman, 1966). For  $2000 < \text{Re} \le 4000$  there is no fixed relationship between the friction factor and the Reynolds number or relative roughness, and flow conditions are generally uncertain (Wilkes, 1999). Beyond a Reynolds number of 4000, the flow is turbulent and the friction

<sup>\*</sup>This type of diagram was originally suggested by Blasius in 1913 and Stanton in 1914 (Stanton and Pannell, 1914). The Moody diagram is sometimes called the *Stanton diagram* (Finnemore and Franzini (2002).

factor is controlled by the thickness of the laminar boundary layer relative to the height of the roughness projections on the surface of the pipe. The dashed line in Figure 2.3 indicates the boundary between the fully turbulent flow regime, where f is independent of Re, and the transition regime, where f depends on both Re and the relative roughness,  $k_s/D$ . The equation of this dashed line is given by Mott (1994) as

$$\frac{1}{\sqrt{f}} = \frac{\text{Re}}{200(D/k_s)} \tag{2.37}$$

The line in the Moody diagram corresponding to a relative roughness of zero describes the friction factor for pipes that are hydraulically smooth.

Although the Colebrook equation (Equation 2.35) can be used to calculate the friction factor in lieu of the Moody diagram, this equation has the drawback that it is an *implicit equation* for the friction factor and must be solved iteratively. This minor inconvenience was circumvented by Jain (1976), who suggested the following explicit equation for the friction factor

$$\frac{1}{\sqrt{f}} = -2\log\left(\frac{k_s/D}{3.7} + \frac{5.74}{\text{Re}^{0.9}}\right), \qquad 10^{-6} \le \frac{k_s}{D} \le 10^{-2}, \ 5,000 \le \text{Re} \le 10^8$$
 (2.38)

where, according to Jain (1976), Equation 2.38 deviates by less than 1% from the Colebrook equation within the entire turbulent flow regime, provided that the restrictions on  $k_s/D$  and Re are honored. According to Franzini and Finnemore (1997) and Granger (1985), values of the friction factor calculated using the Colebrook equation are generally accurate to within 10% to 15% of experimental data, while Potter and Wiggert (2001) put the accuracy of the Moody diagram at no more than 5%. The Jain equation (Equation 2.38) can be more conveniently written as

$$f = \frac{0.25}{\left[\log\left(\frac{k_s}{3.7D} + \frac{5.74}{\text{Re}^{0.9}}\right)\right]^2}, \quad 10^{-6} \le \frac{k_s}{D} \le 10^{-2}, \ 5,000 \le \text{Re} \le 10^8$$
(2.39)

Uncertainties in relative roughness and in the data used to produce the Colebrook equation make the use of several-place accuracy in pipe flow problems unjustified. As a rule of thumb, an accuracy of 10% in calculating friction losses in pipes is to be expected (Munson et al., 1994; Gerhart et al., 1992).

#### Example 2.2.

Water from a treatment plant is pumped into a distribution system at a rate of 4.38 m<sup>3</sup>/s, a pressure of 480 kPa, and a temperature of 20°C. The diameter of the pipe is 750 mm and is made of ductile iron. Estimate the pressure 200 m downstream of the treatment plant if the pipeline remains horizontal. Compare the friction factor estimated using the Colebrook equation to the friction factor estimated using the Jain equation. After 20 years in operation, scale buildup is expected to cause the equivalent sand roughness of the pipe to increase by a factor of 10. Determine the effect on the water pressure 200 m downstream of the treatment plant.

#### Solution.

According to the Darcy-Weisbach equation, the difference in total head,  $\Delta h$ , between the upstream section (at exit from treatment plant) and the downstream section (200 m downstream from the upstream section) is given by

$$\Delta h = \frac{fL}{D} \frac{V^2}{2q}$$

where f is the friction factor, L is the pipe length between the upstream and downstream sections (= 200 m), D is the pipe diameter (= 750 mm), and V is the velocity in the pipe. The velocity, V, is given by

$$V = \frac{Q}{A}$$

where Q is the flowrate in the pipe (=  $4.38 \text{ m}^3/\text{s}$ ) and A is the area of the pipe cross-section given by

$$A = \frac{\pi}{4}D^2 = \frac{\pi}{4}(0.75)^2 = 0.442 \text{ m}^2$$

The pipeline velocity is therefore

$$V = \frac{Q}{A} = \frac{4.38}{0.442} = 9.91 \text{ m/s}$$

The friction factor, f, in the Darcy-Weisbach equation is calculated using the Colebrook equation

$$\frac{1}{\sqrt{f}} = -2\log\left[\frac{k_s}{3.7D} + \frac{2.51}{\text{Re}\sqrt{f}}\right]$$

where Re is the Reynolds number and  $k_s$  is the equivalent sand roughness of ductile iron (= 0.26 mm). The Reynolds number is given by

$$Re = \frac{VD}{\nu}$$

where  $\nu$  is the kinematic viscosity of water at 20°C, which is equal to  $1.00 \times 10^{-6}$  m<sup>2</sup>/s. Therefore

$$Re = \frac{VD}{\nu} = \frac{(9.91)(0.75)}{1.00 \times 10^{-6}} = 7.43 \times 10^{6}$$

Substituting into the Colebrook equation leads to

$$\frac{1}{\sqrt{f}} = -2\log\left[\frac{0.26}{(3.7)(750)} + \frac{2.51}{7.43 \times 10^6 \sqrt{f}}\right]$$

or

$$\frac{1}{\sqrt{f}} = -2\log\left[9.37 \times 10^{-5} + \frac{3.38 \times 10^{-7}}{\sqrt{f}}\right]$$

This is an implicit equation for f, and by trial and error the solution is

$$f = 0.016$$

The head loss,  $\Delta h$ , between the upstream and downstream sections can now be calculated using the Darcy-Weisbach equation as

$$\Delta h = \frac{fL}{D} \frac{V^2}{2g} = \frac{(0.016)(200)}{0.75} \frac{(9.91)^2}{(2)(9.81)} = 21.4 \text{ m}$$

Using the definition of head loss,  $\Delta h$ ,

$$\Delta h = \left(\frac{p_1}{\gamma} + z_1\right) - \left(\frac{p_2}{\gamma} + z_2\right)$$

where  $p_1$  and  $p_2$  are the upstream and downstream pressures,  $\gamma$  is the specific weight of water, and  $z_1$  and  $z_2$  are the upstream and downstream pipe elevations. Since the pipe is horizontal,  $z_1 = z_2$  and  $\Delta h$  can be written in terms of the pressures at the upstream and downstream sections as

$$\Delta h = \frac{p_1}{\gamma} - \frac{p_2}{\gamma}$$

In this case,  $p_1 = 480 \text{ kPa}$ ,  $\gamma = 9.79 \text{ kN/m}^3$ , and therefore

$$21.4 = \frac{480}{9.79} - \frac{p_2}{9.79}$$

which yields

$$p_2 = 270 \text{ kPa}$$

Therefore, the pressure 200 m downstream of the treatment plant is 270 kPa. The Colebrook equation required that f be determined iteratively, but the explicit Jain approximation for f is given by

$$\frac{1}{\sqrt{f}} = -2\log\left[\frac{k_s}{3.7D} + \frac{5.74}{\text{Re}^{0.9}}\right]$$

Substituting for  $k_s$ , D, and Re gives

$$\frac{1}{\sqrt{f}} = -2\log\left[\frac{0.26}{(3.7)(750)} + \frac{5.74}{(7.43 \times 10^6)^{0.9}}\right]$$

which leads to

$$f = 0.016$$

This is the same friction factor obtained using the Colebrook equation within an accuracy of two significant digits. After 20 years, the equivalent sand roughness,  $k_s$ , of the pipe is 2.6 mm, the (previously calculated) Reynolds number is  $7.43 \times 10^6$ , and the Colebrook equation gives

$$\frac{1}{\sqrt{f}} = -2\log\left[\frac{2.6}{(3.7)(750)} + \frac{2.51}{7.43 \times 10^6 \sqrt{f}}\right]$$

or

$$\frac{1}{\sqrt{f}} = -2\log\left[9.37 \times 10^{-4} + \frac{3.38 \times 10^{-7}}{\sqrt{f}}\right]$$

which yields

$$f = 0.027$$

The head loss,  $\Delta h$ , between the upstream and downstream sections is given by the Darcy-Weisbach equation as

$$\Delta h = \frac{fL}{D} \frac{V^2}{2g} = \frac{(0.027)(200)}{0.75} \frac{(9.91)^2}{(2)(9.81)} = 36.0 \text{ m}$$

Hence the pressure,  $p_2$ , 200 m downstream of the treatment plant is given by the relation

$$\Delta h = \frac{p_1}{\gamma} - \frac{p_2}{\gamma}$$

where  $p_1 = 480 \text{ kPa}$ ,  $\gamma = 9.79 \text{ kN/m}^3$ , and therefore

$$36.0 = \frac{480}{9.79} - \frac{p_2}{9.79}$$

which yields

$$p_2 = 128 \text{ kPa}$$

Therefore, pipe aging over 20 years will cause the pressure 200 m downstream of the treatment plant to decrease from 270 kPa to 128 kPa. This is quite a significant drop and shows why velocities of 9.91 m/s are not used in these pipelines, even for short lengths of pipe.

The problem in Example 3.2 illustrates the case where the flowrate through a pipe is known and the objective is to calculate the head loss and pressure drop over a given length of pipe. The approach is summarized as follows: (1) calculate the Reynolds number, Re, and the relative roughness,  $k_s/D$ , from the given data; (2) use the Colebrook equation (Equation 2.35) or Jain equation (Equation 2.38) to calculate f; and (3) use the calculated value of f to calculate the head loss from the Darcy-Weisbach equation (Equation 2.33), and the corresponding pressure drop from Equation 2.22.

Flowrate for a Given Head Loss. In many cases, the flowrate through a pipe is not controlled but attains a level that matches the pressure drop available. For example, the flowrate through faucets in home plumbing is determined by the gage pressure in the water main, which is relatively insensitive to the flow through the faucet. A useful approach to this problem that utilizes the

Colebrook equation has been suggested by Fay (1994), where the first step is to calculate  $\text{Re}\sqrt{f}$  using the rearranged Darcy-Weisbach equation

$$\operatorname{Re}\sqrt{f} = \left(\frac{2gh_f D^3}{\nu^2 L}\right)^{\frac{1}{2}} \tag{2.40}$$

Using this value of  $\text{Re}\sqrt{f}$ , solve for Re using the rearranged Colebrook equation

$$Re = -2.0(Re\sqrt{f})\log\left(\frac{k_s/D}{3.7} + \frac{2.51}{Re\sqrt{f}}\right)$$
(2.41)

Using this value of Re, the flowrate, Q, can then be calculated by

$$Q = \frac{1}{4}\pi D^2 V = \frac{1}{4}\pi D\nu \text{Re}$$
 (2.42)

This approach must necessarily be validated by verifying that Re > 2,300, which is required for the application of the Colebrook equation. Swamee and Jain (1976) combine Equations 2.40 to 2.42 to yield

$$Q = -0.965D^2 \sqrt{\frac{gDh_f}{L}} \ln \left( \frac{k_s/D}{3.7} + \frac{1.784\nu}{D\sqrt{gDh_f/L}} \right)$$
 (2.43)

#### Example 2.3.

A 50-mm diameter galvanized iron service pipe is connected to a water main in which the pressure is 450 kPa gage. If the length of the service pipe to a faucet is 40 m and the faucet is 1.2 m above the main, estimate the flowrate when the faucet is fully open.

#### Solution.

The head loss,  $h_f$ , in the pipe is estimated by

$$h_f = \left(rac{p_{ ext{main}}}{\gamma} + z_{ ext{main}}
ight) - \left(rac{p_{ ext{outlet}}}{\gamma} + z_{ ext{outlet}}
ight)$$

where  $p_{\text{main}} = 450$  kPa,  $z_{\text{main}} = 0$  m,  $p_{\text{outlet}} = 0$  kPa, and  $z_{\text{outlet}} = 1.2$  m. Therefore, taking  $\gamma = 9.79$  kn/m<sup>3</sup> (at  $20^{\circ}$ C) gives

$$h_f = \left(\frac{450}{9.79} + 0\right) - (0 + 1.2) = 44.8 \text{ m}$$

Also, since D=50 mm, L=40 m,  $k_s=0.15$  mm (from Table 2.1),  $\nu=1.00\times10^{-6}$  m<sup>2</sup>/s (at 20°C), the Swamee-Jain equation (Equation 2.43) yields

$$Q = -0.965D^{2}\sqrt{\frac{gDh_{f}}{L}}\ln\left(\frac{k_{s}/D}{3.7} + \frac{1.784\nu}{D\sqrt{gDh_{f}/L}}\right)$$

$$= -0.965(0.05)^{2}\sqrt{\frac{(9.81)(0.05)(44.8)}{40}}\ln\left[\frac{0.15/50}{3.7} + \frac{1.784(1.00 \times 10^{-6})}{(0.05)\sqrt{(9.81)(0.05)(44.8)/40}}\right]$$

$$= 0.0126 \text{ m}^{3}/\text{s} = 12.6 \text{ L/s}$$

The faucet can therefore be expected to deliver 12.6 L/s when fully open.

Diameter for a Given Flowrate and Head Loss. In many cases, an engineer must select a size of pipe to provide a given level of service. For example, the maximum flowrate and maximum allowable pressure drop may be specified for a water delivery pipe, and the engineer is required to calculate the minimum diameter pipe that will satisfy these design constraints. Solution of this problem necessarily requires an iterative procedure. Streeter and Wylie (1985) have suggested the following steps

- 1. Assume a value of f.
- 2. Calculate D from the rearranged Darcy-Weisbach equation,

$$D = \sqrt[5]{\left(\frac{8LQ^2}{h_f g \pi^2} f\right)} \tag{2.44}$$

where the term in parentheses can be calculated from given data.

3. Calculate Re from

$$Re = \frac{VD}{\nu} = \left(\frac{4Q}{\pi\nu}\right)\frac{1}{D} \tag{2.45}$$

where the term in parentheses can be calculated from given data.

- 4. Calculate  $k_s/D$ .
- 5. Use Re and  $k_s/D$  to calculate f from the Colebrook equation.
- 6. Using the new f, repeat the procedure until the new f agrees with the old f to the first two significant digits.

### Example 2.4.

A galvanized iron service pipe from a water main is required to deliver 200 L/s during a fire. If the length of the service pipe is 35 m and the head loss in the pipe is not to exceed 50 m, calculate the minimum pipe diameter that can be used.

#### Solution.

Step 1: Assume f = 0.03

Step 2: Since  $Q = 0.2 \text{ m}^3/\text{s}$ , L = 35 m, and  $h_f = 50 \text{ m}$ , then

$$D = \sqrt[5]{\left[\frac{8LQ^2}{h_f g \pi^2}\right] f} = \sqrt[5]{\left[\frac{8(35)(0.2)^2}{(50)(9.81)\pi^2}\right] (0.03)} = 0.147 \text{ m}$$

Step 3: Since  $\nu = 1.00 \times 10^{-6} \text{ m}^2/\text{s}$  (at 20°C), then

Re = 
$$\left[\frac{4Q}{\pi\nu}\right] \frac{1}{D} = \left[\frac{4(0.2)}{\pi(1.00 \times 10^{-6})}\right] \frac{1}{0.147} = 1.73 \times 10^{6}$$

Step 4: Since  $k_s = 0.15$  mm (from Table 2.1, for new pipe), then

$$\frac{k_s}{D} = \frac{1.5 \times 10^{-4}}{0.147} = 0.00102$$

Step 5: Using the Colebrook equation (Equation 2.35) gives

$$\frac{1}{\sqrt{f}} = -2\log\left(\frac{k_s/D}{3.7} + \frac{2.51}{\text{Re}\sqrt{f}}\right) = -2\log\left(\frac{0.00102}{3.7} + \frac{2.51}{1.73 \times 10^6 \sqrt{f}}\right)$$

which leads to

$$f = 0.020$$

Step 6: f = 0.020 differs from the assumed f = 0.03, so repeat the procedure with f = 0.020.

Step 2: For f = 0.020, D = 0.136 m

Step 3: For D = 0.136, Re =  $1.87 \times 10^6$ 

Step 4: For D = 0.136,  $k_s/D = 0.00110$ 

Step 5: f = 0.020

Step 6: The calculated f = 0.020 is equal to the assumed f. The required pipe diameter is therefore equal to 0.136 m or 136 mm. A commercially available pipe with the closest diameter larger than 136 mm should be used.

The iterative procedure demonstrated in the previous example converges fairly quickly, and does not pose any computational difficulty. Swamee and Jain (1976) have suggested the following explicit formula for calculating the pipe diameter, D,

$$D = 0.66 \left[ k_s^{1.25} \left( \frac{LQ^2}{gh_f} \right)^{4.75} + \nu Q^{9.4} \left( \frac{L}{gh_f} \right)^{5.2} \right]^{0.04},$$

$$3,000 \le \text{Re} \le 3 \times 10^8, \ 10^{-6} \le \frac{k_s}{D} \le 2 \times 10^{-2}$$
(2.46)

Equation 2.46 will yield a D within 5% of the value obtained by the method using the Colebrook equation. This method is illustrated by repeating the previous example.

### Example 2.5.

A galvanized iron service pipe from a water main is required to deliver 200 L/s during a fire. If the length of the service pipe is 35 m, and the head loss in the pipe is not to exceed 50 m, use the Swamee-Jain equation to calculate the minimum pipe diameter that can be used.

#### Solution.

Since  $k_s = 0.15$  mm, L = 35 m, Q = 0.2 m<sup>3</sup>/s,  $h_f = 50$  m,  $\nu = 1.00 \times 10^{-6}$  m<sup>2</sup>/s, the Swamee-Jain equation gives

$$D = 0.66 \left[ k_s^{1.25} \left( \frac{LQ^2}{gh_f} \right)^{4.75} + \nu Q^{9.4} \left( \frac{L}{gh_f} \right)^{5.2} \right]^{0.04}$$

$$= 0.66 \left\{ (0.00015)^{1.25} \left[ \frac{(35)(0.2)^2}{(9.81)(50)} \right]^{4.75} + (1.00 \times 10^{-6})(0.2)^{9.4} \left[ \frac{35}{(9.81)(50)} \right]^{5.2} \right\}^{0.04}$$

$$= 0.140 \text{ m}$$

The calculated pipe diameter (140 mm) is about 3% higher than calculated by the Colebrook equation (136 mm).

# 2.2.3 Energy Equation

The steady-state energy equation for the control volume illustrated in Figure 2.4 is given by

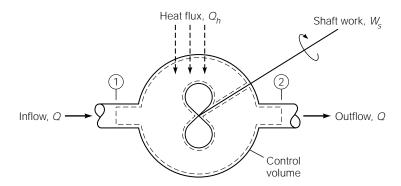


Figure 2.4: Energy Balance in Closed Conduit

$$\frac{dQ_h}{dt} - \frac{dW}{dt} = \int_A \rho e \ \mathbf{v} \cdot \mathbf{n} \ dA \tag{2.47}$$

where  $Q_h$  is the heat added to the fluid in the control volume, W is the work done by the fluid in the control volume, A is the surface area of the control volume,  $\rho$  is the density of the fluid in the control volume, and e is the internal energy per unit mass of fluid in the control volume given by

$$e = gz + \frac{v^2}{2} + u \tag{2.48}$$

where z is the elevation of the fluid mass having a velocity v and internal energy u. By convention, the heat added to a system and the work done by a system are positive quantities. The normal stresses on the inflow and outflow boundaries of the control volume are equal to the pressure, p, with shear stresses tangential to the boundaries of the control volume. As the fluid moves across the control surface with velocity  $\mathbf{v}$ , the power (= rate of doing work) expended by the fluid against the external pressure forces is given by

$$\frac{dW_p}{dt} = \int_A p\mathbf{v} \cdot \mathbf{n} \ dA \tag{2.49}$$

where  $W_p$  is the work done against external pressure forces. The work done by a fluid in the control volume is typically separated into work done against external pressure forces,  $W_p$ , plus work done against rotating surfaces,  $W_s$ , commonly referred to as the *shaft work*. The rotating element is called a *rotor* in a gas or steam turbine, an *impeller* in a pump, and a *runner* in a hydraulic turbine. The rate at which work is done by a fluid system, dW/dt, can therefore be written as

$$\frac{dW}{dt} = \frac{dW_p}{dt} + \frac{dW_s}{dt} = \int_A p\mathbf{v} \cdot \mathbf{n} \ dA + \frac{dW_s}{dt}$$
 (2.50)

Combining Equation 2.50 with the steady-state energy equation (Equation 2.47) leads to

$$\frac{dQ_h}{dt} - \frac{dW_s}{dt} = \int_A \rho \left(\frac{p}{\rho} + e\right) \mathbf{v} \cdot \mathbf{n} \ dA \tag{2.51}$$

Substituting the definition of the internal energy, e, given by Equation 2.48 into Equation 2.51 yields

$$\frac{dQ_h}{dt} - \frac{dW_s}{dt} = \int_A \rho \left( h + gz + \frac{v^2}{2} \right) \mathbf{v} \cdot \mathbf{n} \ dA$$
 (2.52)

where h is the enthalpy of the fluid defined by

$$h = \frac{p}{\rho} + u \tag{2.53}$$

Denoting the rate at which heat is being added to the fluid system by  $\dot{Q}$ , and the rate at which work is being done against moving impervious boundaries (shaft work) by  $\dot{W}_s$ , then the energy equation can be written in the form

$$\dot{Q} - \dot{W}_s = \int_A \rho \left( h + gz + \frac{v^2}{2} \right) \mathbf{v} \cdot \mathbf{n} \ dA$$
 (2.54)

Considering the terms h + gz, where

$$h + gz = \frac{p}{\rho} + u + gz = g\left(\frac{p}{\gamma} + z\right) + u \tag{2.55}$$

and  $\gamma$  is the specific weight of the fluid, then Equation 2.55 indicates that h+gz can be assumed to be constant across the inflow and outflow openings illustrated in Figure 2.4, since a hydrostatic pressure distribution across the inflow/outflow boundaries guarantees that  $p/\gamma+z$  is constant across the inflow/outflow boundaries normal to the flow direction, and the internal energy, u, depends only on the temperature, which can be assumed constant across each boundary. Since  $\mathbf{v} \cdot \mathbf{n}$  is equal to zero over the impervious boundaries in contact with the fluid system, Equation 2.54 can be integrated to yield

$$\dot{Q} - \dot{W}_{s} = (h_{1} + gz_{1}) \int_{A_{1}} \rho \mathbf{v} \cdot \mathbf{n} \ dA + \int_{A_{1}} \rho \frac{v^{2}}{2} \mathbf{v} \cdot \mathbf{n} \ dA + (h_{2} + gz_{2}) \int_{A_{2}} \rho \mathbf{v} \cdot \mathbf{n} \ dA 
+ \int_{A_{2}} \rho \frac{v^{2}}{2} \mathbf{v} \cdot \mathbf{n} \ dA 
= -(h_{1} + gz_{1}) \int_{A_{1}} \rho v_{1} \ dA - \int_{A_{1}} \rho \frac{v_{1}^{3}}{2} \ dA + (h_{2} + gz_{2}) \int_{A_{2}} \rho v_{2} \ dA 
+ \int_{A_{2}} \rho \frac{v_{2}^{3}}{2} \ dA$$
(2.56)

where the subscripts 1 and 2 refer to the inflow and outflow boundaries, respectively, and the negative signs result from the fact that the unit normal points out of the control volume, causing  $\mathbf{v} \cdot \mathbf{n}$  to be negative on the inflow boundary and positive on the outflow boundary.

Equation 2.56 can be simplified by noting that the assumption of steady flow requires that rate of mass inflow to the control volume is equal to the mass outflow rate and, denoting the mass flow rate by  $\dot{m}$ , the continuity equation requires that

$$\dot{m} = \int_{A_1} \rho v_1 \ dA = \int_{A_2} \rho v_2 \ dA \tag{2.57}$$

Furthermore, the constants  $\alpha_1$  and  $\alpha_2$  can be defined by the equations

$$\int_{A_1} \rho \frac{v^3}{2} dA = \alpha_1 \rho \frac{V_1^3}{2} A_1 \tag{2.58}$$

$$\int_{A_2} \rho \frac{v^3}{2} dA = \alpha_2 \rho \frac{V_2^3}{2} A_2 \tag{2.59}$$

where  $A_1$  and  $A_2$  are the areas of the inflow and outflow boundaries, respectively, and  $V_1$  and  $V_2$  are the corresponding mean velocities across these boundaries. The constants  $\alpha_1$  and  $\alpha_2$  are determined by the velocity profile across the flow boundaries, and these constants are called *kinetic energy correction factors*. If the velocity is constant across a flow boundary, then it is clear from Equation 2.58 that the kinetic energy correction factor for that boundary is equal to unity; for any other velocity distribution, the kinetic energy factor is greater than unity. Combining Equations 2.56 to 2.59 leads to

$$\dot{Q} - \dot{W}_s = -(h_1 + gz_1)\dot{m} - \alpha_1 \rho \frac{V_1^3}{2} A_1 + (h_2 + gz_2)\dot{m} + \alpha_2 \rho \frac{V_2^3}{2} A_2$$
 (2.60)

Invoking the continuity equation requires that

$$\rho V_1 A_1 = \rho V_2 A_2 = \dot{m} \tag{2.61}$$

and combining Equations 2.60 and 2.61 leads to

$$\dot{Q} - \dot{W}_s = \dot{m} \left[ \left( h_2 + gz_2 + \alpha_2 \frac{V_2^2}{2} \right) - \left( h_1 + gz_1 + \alpha_1 \frac{V_1^2}{2} \right) \right]$$
 (2.62)

which can be put in the form

$$\frac{\dot{Q}}{\dot{m}g} - \frac{\dot{W}_s}{\dot{m}g} = \left(\frac{p_2}{\gamma} + \frac{u_2}{g} + z_2 + \alpha_2 \frac{V_2^2}{2g}\right) - \left(\frac{p_1}{\gamma} + \frac{u_1}{g} + z_1 + \alpha_1 \frac{V_1^2}{2g}\right) \tag{2.63}$$

and can be further rearranged into the useful form

$$\left(\frac{p_1}{\gamma} + \alpha_1 \frac{V_1^2}{2g} + z_1\right) = \left(\frac{p_2}{\gamma} + \alpha_2 \frac{V_2^2}{2g} + z_2\right) + \left[\frac{1}{g}(u_2 - u_1) - \frac{\dot{Q}}{\dot{m}g}\right] + \left[\frac{\dot{W}_s}{\dot{m}g}\right]$$
(2.64)

Two key terms can be identified in Equation 2.64: the (shaft) work done by the fluid per unit weight,  $h_s$ , defined by the relation

$$h_s = \frac{\dot{W}_s}{\dot{m}g} \tag{2.65}$$

and the energy loss per unit weight, commonly called the head loss,  $h_L$ , defined by the relation

$$h_L = \frac{1}{g}(u_2 - u_1) - \frac{Q}{\dot{m}g} \tag{2.66}$$

Combining Equations 2.64 to 2.66 leads to the most common form of the energy equation

$$\left(\frac{p_1}{\gamma} + \alpha_1 \frac{V_1^2}{2g} + z_1\right) = \left(\frac{p_2}{\gamma} + \alpha_2 \frac{V_2^2}{2g} + z_2\right) + h_L + h_s$$
(2.67)

where a positive head loss indicates an increase in internal energy, manifested by an increase in temperature or a loss of heat, and a positive value of  $h_s$  is associated with work being done by the fluid, such as in moving a turbine runner. Many practitioners incorrectly refer to Equation 2.67 as the *Bernoulli equation*, which bears some resemblance to Equation 2.67 but is different in several important respects. Fundamental differences between the energy equation and the Bernoulli equation are that the Bernoulli equation is derived from the momentum equation, which is independent of the energy equation, and the Bernoulli equation does not account for fluid friction.

**Energy and Hydraulic Grade Lines.** The *total head*, h, of a fluid at any cross-section of a pipe is defined by

$$h = \frac{p}{\gamma} + \alpha \frac{V^2}{2g} + z \tag{2.68}$$

where p is the pressure in the fluid at the centroid of the cross-section,  $\gamma$  is the specific weight of the fluid,  $\alpha$  is the kinetic energy correction factor, V is the average velocity across the pipe, and z is the elevation of the centroid of the pipe. The total head measures the average energy per unit weight of the fluid flowing across a pipe cross-section. The energy equation, Equation 2.67, states that changes in the total head along the pipe are described by

$$h(x + \Delta x) = h(x) - (h_L + h_s)$$
(2.69)

where x is the coordinate measured along the pipe centerline,  $\Delta x$  is the distance between two cross-sections in the pipe,  $h_L$  is the head loss, and  $h_s$  is the shaft work done by the fluid over the distance  $\Delta x$ . The practical application of Equation 2.69 is illustrated in Figure 2.5, where the head loss,  $h_L$ , between two sections a distance  $\Delta x$  apart is indicated. At each cross-section, the total

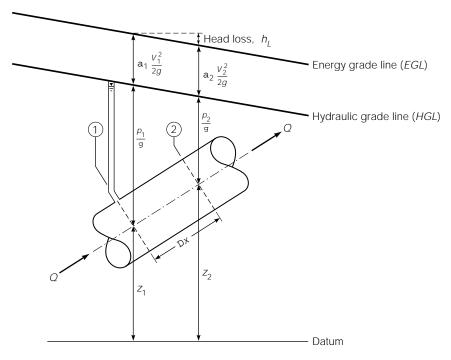


Figure 2.5: Head Loss Along Pipe

energy, h, is plotted relative to a defined datum, and the locus of these points is called the energy grade line. The energy grade line at each pipe cross-section is located a distance  $p/\gamma + \alpha V^2/2g$  vertically above the centroid of the cross-section, and between any two cross-sections the elevation of the energy grade line falls by a vertical distance equal to the head loss caused by pipe friction,  $h_L$ , plus the shaft work,  $h_s$ , done by the fluid. The hydraulic grade line measures the hydraulic head  $p/\gamma + z$  at each pipe cross-section. It is located a distance  $p/\gamma$  above the pipe centerline and indicates the elevation to which the fluid would rise in an open tube connected to the wall of the

pipe section. The hydraulic grade line is therefore located a distance  $\alpha V^2/2g$  below the energy grade line. In most water-supply applications the velocity heads are negligible and the hydraulic grade line closely approximates the energy grade line.

Both the hydraulic grade line and the energy grade line are useful in visualizing the state of the fluid as it flows along the pipe and are frequently used in assessing the performance of fluid delivery systems. Most fluid delivery systems, for example, require that the fluid pressure remain positive, in which case the hydraulic grade line must remain above the pipe. In circumstances where additional energy is required to maintain acceptable pressures in pipelines, a pump is installed along the pipeline to elevate the energy grade line by an amount  $h_s$ , which also elevates the hydraulic grade line by the same amount. This condition is illustrated in Figure 2.6. In cases where the

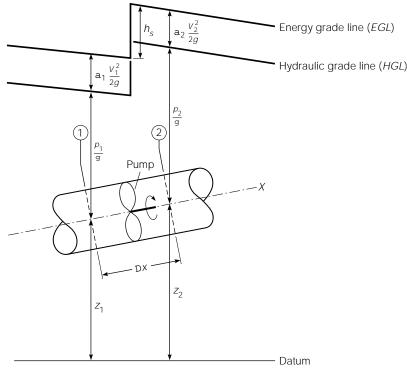


Figure 2.6: Pump Effect on Flow in Pipeline

pipeline upstream and downstream of the pump are of the same diameter, then the velocity heads  $\alpha V^2/2g$  both upstream and downstream of the pump are the same, and the head added by the pump,  $h_s$ , goes entirely to increase the pressure head,  $p/\gamma$ , of the fluid. It should also be clear from Figure 2.5 that the pressure head in a pipeline can be increased by simply increasing the pipeline diameter, which reduces the velocity head,  $\alpha V^2/2g$ , and thereby increases the pressure head,  $p/\gamma$ , to maintain the same total energy at the pipe section.

**Velocity Profile.** The momentum and energy correction factors,  $\alpha$  and  $\beta$ , depend on the cross-sectional velocity distribution. The velocity profile in both smooth and rough pipes of circular cross-section can be estimated by the semi-empirical equation

$$v(r) = \left[ (1 + 1.326\sqrt{f}) - 2.04\sqrt{f}\log\left(\frac{R}{R-r}\right) \right] V$$
 (2.70)

where v(r) is the velocity at a radial distance r from the centerline of the pipe, R is the radius of the pipe, f is the friction factor, and V is the average velocity across the pipe.

The velocity distribution given by Equation 2.70 agrees well with velocity measurements in both smooth and rough pipes. This equation, however, is not applicable within the small region close to the centerline of the pipe and is also not applicable in the small region close to the pipe boundary. This is apparent since at the axis of the pipe dv/dr must be equal to zero, but Equation 2.70 does not have a zero slope at r=0. The pipe boundary v must also be equal to zero, but Equation 2.70 gives a velocity of zero at a small distance from the wall, with a velocity of  $-\infty$  at r=R. The energy and momentum correction factors,  $\alpha$  and  $\beta$ , derived from the velocity profile are (Moody, 1950)

$$\alpha = 1 + 2.7f \tag{2.71}$$

$$\beta = 1 + 0.98f \tag{2.72}$$

Another commonly used equation to describe the velocity distribution in turbulent pipe flow is the empirical *power law* equation given by

$$v(r) = V_o \left( 1 - \frac{r}{R} \right)^{\frac{1}{n}}$$
 (2.73)

where  $V_o$  is the centerline velocity and n is a function of the Reynolds number, Re. Values of n typically range between 6 and 10 and can be approximated by (Fox and McDonald, 1992; Schlichting, 1979)

$$n = 1.83 \log \text{Re} - 1.86 \tag{2.74}$$

The power law is not applicable within 0.04R of the wall, since the power law gives an infinite velocity gradient at the wall. Although the profile fits the data close to the centerline of the pipe, it does not give zero slope at the centerline. The kinetic energy coefficient,  $\alpha$ , derived from the power law equation is given by

$$\alpha = \frac{(1+n)^3 (1+2n)^3}{4n^4 (3+n)(3+2n)} \tag{2.75}$$

For n between 6 and 10,  $\alpha$  varies from 1.08 to 1.03. In most engineering applications,  $\alpha$  and  $\beta$  are taken as unity (see Problem 2.14).

Head Losses in Transitions and Fittings. The head losses in straight pipes of constant diameter are caused by friction between the moving fluid and the pipe boundary and are estimated using the Darcy-Weisbach equation. Flow through pipe fittings, around bends, and through changes in pipeline geometry cause additional head losses,  $h_o$ , that are quantified by an equation of the form

$$h_o = \sum K \frac{V^2}{2g} \tag{2.76}$$

where K is a loss coefficient that is specific to each fitting and transition and V is the average velocity at a defined location within the transition or fitting. The loss coefficients for several fittings and transitions are shown in Figure 2.7. Head losses in transitions and fittings are also called *local head losses* or *minor head losses*. The latter term should be avoided, however, since in some cases

Description	Sketch	Additional Data	K
		r/d	K
Pipe entrance	$\frac{d}{\sqrt{V}} \longrightarrow V$	0.0 0.1 >0.2	0.50 0.12 0.03
Contraction		D <sub>2</sub> /D <sub>1</sub> 0.0	K K u 5 60° u 5 180° 0.08 0.50 0.08 0.49
	$D_1$ $U$ $D_2$ $V_2$	0.20 0.40 0.60 0.80 0.90	0.08
		D <sub>1</sub> /D <sub>2</sub>	к к
Expansion	$V_1 \longrightarrow D$ $U$ $U$ $U$	0.0 0.20 0.40 0.60 0.80	u 5 20° u 5 180° 1.00 0.30 0.87 0.25 0.70 0.15 0.41 0.10 0.15
90° miter bend	Vanes	Without vanes	<i>K</i> 5 1.1
		With vanes	K 5 0.2
90° smooth bend	→ d	r/d	<b>K</b> u 5 90°
		1 2 4 6	0.35 0.19 0.16 0.21
Threaded pipe fittings	Globe valve — wide open Angle valve — wide open Gate valve — wide open Gate valve — half open Return bend Tee		<i>K</i> 10.0 5.0 0.2 5.6 2.2
	straight-through flow side-outlet flow 90° elbow 45° elbow		0.4 1.8 0.9 0.4

Figure 2.7: Loss Coefficients for Transitions and Fittings Source: Roberson, John A. and Crowe, Clayton T., *Engineering Fluid Mechanics*. Copyright © 1997 by John Wiley & Sons, Inc. Reprinted by permission of John Wiley & Sons, Inc.

these head losses are a significant portion of the total head loss in a pipe. Detailed descriptions of local head losses in various valve geometries can be found in Mott (1994), and additional data on local head losses in pipeline systems can be found in Brater and colleagues (1996).

#### Example 2.6.

A pump is to be selected that will pump water from a well into a storage reservoir. In order to fill the reservoir in a timely manner, the pump is required to deliver 5 L/s when the water level in the reservoir is 5 m above the water level in the well. Find the head that must be added by the pump. The pipeline system is shown in Figure 2.8. Assume

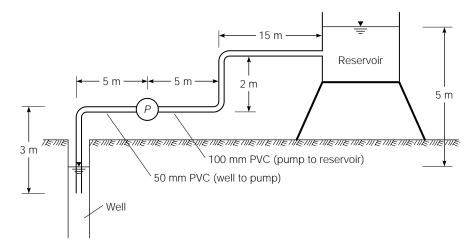


Figure 2.8: Pipeline System

that the minor loss coefficient for each of the bends is equal to 0.25 and that the temperature of the water is 20°C.

#### Solution.

Taking the elevation of the water surface in the well to be equal to 0 m, and proceeding from the well to the storage reservoir (where the head is equal to 5 m), the energy equation (Equation 2.67) can be written as

$$0 - \frac{V_1^2}{2g} - \frac{f_1 L_1}{D_1} \frac{V_1^2}{2g} - K_1 \frac{V_1^2}{2g} + h_p - \frac{f_2 L_2}{D_2} \frac{V_2^2}{2g} - (K_2 + K_3) \frac{V_2^2}{2g} - \frac{V_2^2}{2g} = 5$$

where  $V_1$  and  $V_2$  are the velocities in the 50-mm (=  $D_1$ ) and 100-mm (=  $D_2$ ) pipes, respectively;  $L_1$  and  $L_2$  are the corresponding pipe lengths;  $f_1$  and  $f_2$  are the corresponding friction factors;  $K_1$ ,  $K_2$ , and  $K_3$  are the loss coefficients for each of the three bends; and  $h_p$  is the head added by the pump. The cross-sectional areas of each of the pipes,  $A_1$  and  $A_2$ , are given by

$$A_1 = \frac{\pi}{4}D_1^2 = \frac{\pi}{4}(0.05)^2 = 0.001963 \text{ m}^2$$
  
 $A_2 = \frac{\pi}{4}D_2^2 = \frac{\pi}{4}(0.10)^2 = 0.007854 \text{ m}^2$ 

When the flowrate, Q, is 5 L/s, the velocities  $V_1$  and  $V_2$  are given by

$$V_1 = \frac{Q}{A_1} = \frac{0.005}{0.001963} = 2.54 \text{ m/s}$$
  
 $V_2 = \frac{Q}{A_2} = \frac{0.005}{0.007854} = 0.637 \text{ m/s}$ 

PVC pipe is considered smooth  $(k_s \approx 0)$  and therefore the friction factor, f, can be estimated using the Jain equation

$$f = \frac{0.25}{\left[\log_{10} \frac{5.74}{\text{Re}^{0.9}}\right]^2}$$

where Re is the Reynolds number. At 20°C, the kinematic viscosity,  $\nu$ , is equal to  $1.00 \times 10^{-6}$  m<sup>2</sup>/s and for the 50-mm pipe

$$Re_1 = \frac{V_1 D_1}{\nu} = \frac{(2.51)(0.05)}{1.00 \times 10^{-6}} = 1.27 \times 10^5$$

which leads to

$$f_1 = \frac{0.25}{\left[\log_{10} \frac{5.74}{(1.27 \times 10^5)^{0.9}}\right]^2} = 0.0170$$

and for the 100-mm pipe

$$Re_2 = \frac{V_2 D_2}{\nu} = \frac{(0.637)(0.10)}{1.00 \times 10^{-6}} = 6.37 \times 10^4$$

which leads to

$$f_2 = \frac{0.25}{\left[\log_{10} \frac{5.74}{(6.37 \times 10^4)^{0.9}}\right]^2} = 0.0197$$

Substituting the values of these parameters into the energy equation yields

$$0 - \left[1 + \frac{(0.0170)(8)}{0.05} + 0.25\right] \frac{2.54^{2}}{(2)(9.81)} + h_{p}$$
$$- \left[\frac{(0.0197)(22)}{0.10} + 0.25 + 0.25 + 1\right] \frac{0.637^{2}}{(2)(9.81)} = 5$$

which leads to

$$h_p = 6.43 \text{ m}$$

Therefore the head to be added by the pump is 6.43 m.

Minor losses are frequently neglected in the analysis of pipeline systems. As a general rule, neglecting minor losses is justified when, on average, there is a length of 1,000 diameters between each minor loss (Streeter et al., 1998).

Head Losses in Noncircular Conduits. Most pipelines are of circular cross-section, but flow of water in noncircular conduits is commonly encountered in cases such as rectangular culverts flowing full. The hydraulic radius, R, of a conduit of any shape is defined by the relation

$$R = \frac{A}{P} \tag{2.77}$$

where A is the cross-sectional area of the conduit and P is the wetted perimeter. For circular conduits of diameter D, the hydraulic radius is given by

$$R = \frac{\pi D^2 / 4}{\pi D} = \frac{D}{4} \tag{2.78}$$

or

$$D = 4R \tag{2.79}$$

Using the hydraulic radius, R, as the length scale of a closed conduit instead of D, the frictional head losses,  $h_f$ , in noncircular conduits can be estimated using the Darcy-Weisbach equation for circular conduits by simply replacing D by 4R, which yields

$$h_f = \frac{fL}{4R} \frac{V^2}{2g} \tag{2.80}$$

where the friction factor, f, is calculated using a Reynolds number, Re, defined by

$$Re = \frac{\rho V(4R)}{\mu} \tag{2.81}$$

and a relative roughness defined by  $k_s/4R$ .

Characterizing a noncircular conduit by the hydraulic radius, R, is necessarily approximate since conduits of arbitrary cross-section cannot be described with a single parameter. Secondary currents that are generated across a noncircular conduit cross-section to redistribute the shears are another reason why noncircular conduits cannot be completely characterized by the hydraulic radius (Liggett, 1994). However, according to Munson and colleagues (1994) and White (1994), using the hydraulic radius as a basis for calculating frictional head losses in noncircular conduits is usually accurate to within 15% for turbulent flow. This approximation is much less accurate for laminar flows, where the accuracy is on the order of  $\pm 40\%$  (White, 1994). Olson and Wright (1990) state that this approach can be used for rectangular conduits where the ratio of sides, called the aspect ratio, does not exceed about 8. Potter and Wiggert (2001) state that aspect ratios must be less than 4:1.

#### Example 2.7.

Water flows through a rectangular concrete culvert of width 2 m and depth 1 m. If the length of the culvert is 10 m and the flowrate is 6  $\mathrm{m}^3/\mathrm{s}$ , estimate the head loss through the culvert. Assume that the culvert flows full.

#### Solution.

The head loss can be calculated using Equation 2.80. The hydraulic radius, R, is given by

$$R = \frac{A}{P} = \frac{(2)(1)}{2(2+1)} = 0.333 \text{ m}$$

and the mean velocity, V, is given by

$$V = \frac{Q}{A} = \frac{6}{(2)(1)} = 3 \text{ m/s}$$

At  $20^{\circ}$ C,  $\nu = 1.00 \times 10^{-6}$  m<sup>2</sup>/s, and therefore the Reynolds number, Re, is given by

$$Re = \frac{V(4R)}{\nu} = \frac{(3)(4 \times 0.333)}{1.00 \times 10^{-6}} = 4.00 \times 10^{6}$$

A median equivalent sand roughness for concrete can be taken as  $k_s = 1.6$  mm (Table 2.1), and therefore the relative roughness,  $k_s/4R$ , is given by

$$\frac{k_s}{4R} = \frac{1.6 \times 10^{-3}}{4(0.333)} = 0.00120$$

Substituting Re and  $k_s/4R$  into the Jain equation (Equation 2.38) for the friction factor yields

$$\frac{1}{\sqrt{f}} = -2\log\left[\frac{k_s/4R}{3.7} + \frac{5.74}{\mathrm{Re}^{0.9}}\right] = -2\log\left[\frac{0.00120}{3.7} + \frac{5.74}{(4.00 \times 10^6)^{0.9}}\right] = 6.96$$

which yields

$$f = 0.0206$$

The frictional head loss in the culvert,  $h_f$ , is therefore given by the Darcy-Weisbach equation as

$$h_f = \frac{fL}{4R} \frac{V^2}{2g} = \frac{(0.0206)(10)}{(4 \times 0.333)} \frac{3^2}{2(9.81)} = 0.0709 \text{ m}$$

The head loss in the culvert can therefore be estimated as 7.1 cm.

Empirical Friction-Loss Formulae. Friction losses in pipelines should generally be calculated using the Darcy-Weisbach equation. However, a minor inconvenience in using the Darcy-Weisbach equation to relate the friction loss to the flow velocity results from the dependence of the friction factor on the flow velocity; therefore, the Darcy-Weisbach equation must be solved simultaneously with the Colebrook equation. In modern engineering practice, computer hardware and software make this a very minor inconvenience. In earlier years, however, this was considered a real problem, and various empirical head-loss formulae were developed to relate the head loss directly to the flow velocity. The most commonly used empirical formulae are the *Hazen-Williams formula* and the *Manning formula*.

The *Hazen-Williams formula* (Williams and Hazen, 1920) is applicable only to the flow of water in pipes and is given by

$$V = 0.849 C_H R^{0.63} S_f^{0.54}$$
(2.82)

where V is the flow velocity (in m/s),  $C_H$  is the Hazen-Williams roughness coefficient, R is the hydraulic radius (in m), and  $S_f$  is the slope of the energy grade line, defined by

$$S_f = \frac{h_f}{L} \tag{2.83}$$

where  $h_f$  is the head loss due to friction over a length L of pipe. Values of  $C_H$  for a variety of commonly used pipe materials are given in Table 2.2. Solving Equations 2.82 and 2.83 yields the

Table 2.2: Pipe Roughness Coefficients

	$C_{H}$	I	n	
Pipe material	Range	Typical	Range	Typical
Ductile and cast iron:				
New, unlined	120 – 140	130	_	0.013
Old, unlined	40 – 100	80	_	0.025
Cement lined and seal coated	100 – 140	120	0.011 – 0.015	0.013
Steel:				
Welded and seamless	80 – 150	120		0.012
Riveted	_	110	0.012 – 0.018	0.015
Mortar lining	120 - 145	130	_	
Asbestos cement		140		0.011
Concrete	100 – 140	120	0.011 – 0.015	0.012
Vitrified clay pipe (VCP)		110	0.012 – 0.014	
Polyvinyl chloride (PVC)	135 - 150	140	0.007 – 0.011	0.009
Corrugated metal pipe (CMP)	_		_	0.025

Source: Velon and Johnson (1993); Wurbs and James (2002).

following expression for the frictional head loss,

$$h_f = 6.82 \frac{L}{D^{1.17}} \left(\frac{V}{C_H}\right)^{1.85} \tag{2.84}$$

where D is the diameter of the pipe. The Hazen-Williams equation is applicable to the flow of water at 16°C in pipes with diameters between 50 mm and 1850 mm, and flow velocities less

than 3 m/s (Mott, 1994). Outside of these conditions, use of the Hazen-Williams equation is strongly discouraged. To further support these quantitative limitations, Street and colleagues (1996) and Liou (1998) have shown that the Hazen-Williams coefficient has a strong Reynolds number dependence, and is mostly applicable where the pipe is relatively smooth and in the early part of its transition to rough flow. Furthermore, Jain and colleagues (1978) have shown that an error of up to 39% can be expected in the evaluation of the velocity by the Hazen-Williams formula over a wide range of diameters and slopes. In spite of these cautionary notes, the Hazen-Williams formula is frequently used in the United States for the design of large water-supply pipes without regard to its limited range of applicability, a practice that can have very detrimental effects on pipe design and could potentially lead to litigation (Bombardelli and García, 2003).

A second empirical formula that is sometimes used to describe flow in pipes is the Manning formula, which is given by

$$V = \frac{1}{n}R^{\frac{2}{3}}S_f^{\frac{1}{2}}$$
 (2.85)

where V, R, and  $S_f$  have the same meaning and units as in the Hazen-Williams formula, and n is the Manning roughness coefficient. Values of n for a variety of commonly used pipe materials are given in Table 2.2 (Velon and Johnson, 1993). Solving Equations 2.85 and 2.83 yields the following expression for the frictional head loss

$$h_f = 6.35 \frac{n^2 L V^2}{D_3^{\frac{4}{3}}} \tag{2.86}$$

The Manning formula applies to fully turbulent flows, where the frictional head losses depend primarily on the relative roughness.

#### Example 2.8.

Water flows at a velocity of 1 m/s in a 150 mm new ductile iron pipe. Estimate the head loss over 500 m using: (a) the Hazen-Williams formula, (b) the Manning formula, and (c) the Darcy-Weisbach equation. Compare your results.

#### Solution.

(a) The Hazen-Williams roughness coefficient,  $C_H$ , can be taken as 130 (Table 2.2), L = 500 m, D = 0.150 m, V = 1 m/s, and therefore the head loss,  $h_f$ , is given by Equation 2.84 as

$$h_f = 6.82 \frac{L}{D^{1.17}} \left(\frac{V}{C_H}\right)^{1.85} = 6.82 \frac{500}{(0.15)^{1.17}} \left(\frac{1}{130}\right)^{1.85} = 3.85 \text{ m}$$

(b) The Manning roughness coefficient, n, can be taken as 0.013 (approximation from Table 2.2), and therefore the head loss,  $h_f$ , is given by Equation 2.86 as

$$h_f = 6.35 \frac{n^2 L V^2}{D^{\frac{4}{3}}} = 6.35 \frac{(0.013)^2 (500)(1)^2}{(0.15)^{\frac{4}{3}}} = 6.73 \text{ m}$$

(c) The equivalent sand roughness,  $k_s$ , can be taken as 0.26 mm (Table 2.1), and the Reynolds number, Re, is given by

$$Re = \frac{VD}{v} = \frac{(1)(0.15)}{1.00 \times 10^{-6}} = 1.5 \times 10^{5}$$

where  $\nu = 1.00 \times 10^{-6} \text{ m}^2/\text{s}$  at 20°C. Substituting  $k_s$ , D, and Re into the Colebrook equation yields the friction factor, f, where

$$\frac{1}{\sqrt{f}} = -2\log\left[\frac{k_s}{3.7D} + \frac{2.51}{\text{Re}\sqrt{f}}\right] = -2\log\left[\frac{0.26}{3.7(150)} + \frac{2.51}{1.5 \times 10^5 \sqrt{f}}\right]$$

Solving by trial and error leads to

$$f = 0.0238$$

The head loss,  $h_f$ , is therefore given by the Darcy-Weisbach equation as

$$h_f = f \frac{L}{D} \frac{V^2}{2q} = 0.0238 \frac{500}{0.15} \frac{1^2}{2(9.81)} = 4.04 \text{ m}$$

It is reasonable to assume that the Darcy-Weisbach equation yields the most accurate estimate of the head loss. In this case, the Hazen-Williams formula gives a head loss that is 5% too low and the Manning formula yields a head loss that is 67% too high.

# 2.3 Pipe Networks

Pipe networks are commonly encountered in the context of water-distribution systems. The performance criteria of these systems are typically specified in terms of minimum flow rates and pressure heads that must be maintained at the specified points in the network. Analyses of pipe networks are usually within the context of (1) designing a new network, (2) designing a modification to an existing network, and/or (3) evaluating the reliability of a network. The procedure for analyzing a pipe network usually aims at finding the flow distribution within the network, with the pressure distribution being derived from the flow distribution using the energy equation. A typical pipe network is illustrated in Figure 2.9, where the boundary conditions consist of inflows, outflows, and constant-head boundaries such as storage reservoirs. Inflows are typically from water-treatment fa-

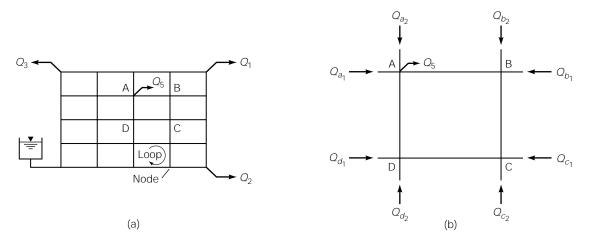


Figure 2.9: Typical Pipe Network

cilities, outflows from consumer withdrawals or fires. All outflows are assumed to occur at network junctions.

The basic equations to be satisfied in pipe networks are the continuity and energy equations. The continuity equation requires that, at each node in the network, the sum of the outflows is equal to the sum of the inflows. This requirement is expressed by the relation

$$\sum_{i=1}^{NP(j)} Q_{ij} - F_j = 0, \qquad j = 1, NJ$$
(2.87)

where  $Q_{ij}$  is the flowrate in pipe i at junction j (inflows positive); NP(j) is the number of pipes meeting at junction j;  $F_j$  is the external flow rate (outflows positive) at junction j; and NJ is the total number of junctions in the network. The energy equation requires that the heads at each of the nodes in the pipe network be consistent with the head losses in the pipelines connecting the nodes. There are two principal methods of calculating the flows in pipe networks: the nodal method and the loop method. In the nodal method, the energy equation is expressed in terms of the flows in closed loops within the pipe network.

## 2.3.1 Nodal Method

In the nodal method, the energy equation is written for each pipeline in the network as

$$h_2 = h_1 - \left(\frac{fL}{D} + \sum k_m\right) \frac{Q|Q|}{2gA^2} + \frac{Q}{|Q|} h_p$$
 (2.88)

where  $h_2$  and  $h_1$  are the heads at the upstream and downstream ends of a pipe; the terms in parentheses measure the friction loss and minor losses, respectively; and  $h_p$  is the head added by pumps in the pipeline. The energy equation stated in Equation 2.88 has been modified to account for the fact that the flow direction is in many cases unknown, in which case a positive flow direction in each pipeline must be assumed, and a consistent set of energy equations stated for the entire network. Equation 2.88 assumes that the positive flow direction is from node 1 to node 2. Application of the nodal method in practice is usually limited to relatively simple networks.

### Example 2.9.

The high-pressure ductile-iron pipeline shown in Figure 2.10 becomes divided at point B and rejoins at point C. The pipeline characteristics are given in the following tables.

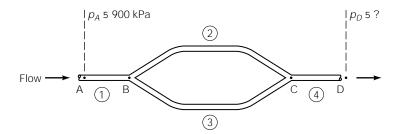


Figure 2.10: Pipe Network

	Diameter	Length
Pipe	(mm)	(m)
1	750	500
2	400	600
3	500	650
4	700	400

	Elevation
Location	(m)
A	5.0
В	4.5
$^{\mathrm{C}}$	4.0
D	3.5

If the flowrate in Pipe 1 is  $2 \text{ m}^3/\text{s}$  and the pressure at point A is 900 kPa, calculate the pressure at point D. Assume that the flows are fully turbulent in all pipes.

#### Solution.

The equivalent sand roughness,  $k_s$ , of ductile-iron pipe is 0.26 mm, and the pipe and flow characteristics are as follows:

	Area	Velocity		
Pipe	$(m^2)$	(m/s)	$k_s/D$	f
1	0.442	4.53	0.000347	0.0154
2	0.126		0.000650	0.0177
3	0.196		0.000520	0.0168
4	0.385	5.20	0.000371	0.0156

where it has been assumed that the flows are fully turbulent. Taking  $\gamma = 9.79 \text{ kN/m}^3$ , the head at location A,  $h_A$ , is given by

$$h_A = \frac{p_A}{\gamma} + \frac{V_1^2}{2g} + z_A = \frac{900}{9.79} + \frac{4.53^2}{(2)(9.81)} + 5 = 98.0 \text{ m}$$

and the energy equations for each pipe are as follows

Pipe 1: 
$$h_B = h_A - \frac{f_1 L_1}{D_1} \frac{V_1^2}{2g} = 98.0 - \frac{(0.0154)(500)}{0.75} \frac{4.53^2}{(2)(9.81)}$$
  
= 87.3 m (2.89)

$$= 87.3 \text{ m}$$

$$\text{Pipe 2:} \quad h_C = h_B - \frac{f_2 L_2}{D_2} \frac{Q_2^2}{2gA_2^2} = 87.3 - \frac{(0.0177)(600)}{0.40} \frac{Q_2^2}{(2)(9.81)(0.126)^2}$$

$$= 87.3 - 85.2Q_2^2$$

$$(2.89)$$

$$= 87.3 - 85.2Q_{2}^{2}$$
Pipe 3:  $h_{C} = h_{B} - \frac{f_{3}L_{3}}{D_{3}} \frac{Q_{3}^{2}}{2gA_{3}^{2}} = 87.3 - \frac{(0.0168)(650)}{0.50} \frac{Q_{3}^{2}}{(2)(9.81)(0.196)^{2}}$ 

$$= 87.3 - 29.0Q_{3}^{2}$$
(2.90)
$$= 87.3 - 29.0Q_{3}^{2}$$
(2.91)

Pipe 4: 
$$h_D = h_C - \frac{f_4 L_4}{D_4} \frac{Q_4^2}{2g A_4^2} = h_C - \frac{(0.0156)(400)}{0.70} \frac{Q_4^2}{(2)(9.81)(0.385)^2}$$
  
=  $h_C - 3.07 Q_4^2$  (2.92)

and the continuity equations at the two pipe junctions are

Junction B: 
$$Q_2 + Q_3 = 2 \text{ m}^3/\text{s}$$
 (2.93)

Junction C: 
$$Q_2 + Q_3 = Q_4$$
 (2.94)

Equations 2.90 to 2.94 are five equations in five unknowns:  $h_C$ ,  $h_D$ ,  $Q_2$ ,  $Q_3$ , and  $Q_4$ . Equations 2.93 and 2.94 indicate that

$$Q_4 = 2 \text{ m}^3/\text{s}$$

Combining Equations 2.90 and 2.91 leads to

$$87.3 - 85.2Q_2^2 = 87.3 - 29.0Q_3^2$$

and therefore

$$Q_2 = 0.583Q_3 \tag{2.95}$$

Substituting Equation 2.95 into Equation 2.93 yields

$$2 = (0.583 + 1)Q_3$$

or

$$Q_3 = 1.26 \text{ m}^3/\text{s}$$

and from Equation 2.95

$$Q_2 = 0.74 \text{ m}^3/\text{s}$$

According to Equation 2.91

$$h_C = 87.3 - 29.0Q_3^2 = 87.3 - 29.0(1.26)^2 = 41.3 \text{ m}$$

and Equation 2.92 gives

$$h_D = h_C - 3.07Q_4^2 = 41.3 - 3.07(2)^2 = 29.0 \text{ m}$$

Therefore, since the total head at D,  $h_D$ , is equal to 29.0 m, then

$$29.0 = \frac{p_D}{\gamma} + \frac{V_4^2}{2g} + z_D = \frac{p_D}{9.79} + \frac{5.20^2}{(2)(9.81)} + 3.5$$

which yields

$$p_D = 236 \text{ kPa}$$

Therefore, the pressure at location D is 236 kPa.

This problem has been solved by assuming that the flows in all pipes are fully turbulent. This is generally not known for sure a priori, and therefore a complete solution would require repeating the calculations until the assumed friction factors are consistent with the calculated flowrates.

# 2.3.2 Loop Method

In the loop method, the energy equation is written for each loop of the network, in which case the algebraic sum of the head losses within each loop is equal to zero. This requirement is expressed by the relation

$$\sum_{j=1}^{NP(i)} (h_{L,ij} - h_{p,ij}) = 0, \qquad i = 1, NL$$
(2.96)

where  $h_{L,ij}$  is the head loss in pipe j of loop i, and  $h_{p,ij}$  is the head added by any pumps that may exist in line ij. Combining Equations 2.87 and 2.96 with an expression for calculating the head losses in pipes, such as the Darcy-Weisbach equation, and the pump characteristic curves, which relate the head added by the pump to the flowrate through the pump, yields a complete mathematical description of the flow problem. Solution of this system of flow equations is complicated by the fact that the equations are nonlinear, and numerical methods must be used to solve for the flow distribution in the pipe network.

Hardy Cross Method. The Hardy Cross method (Cross, 1936) is a simple technique for handsolution of the loop system of equations governing flow in pipe networks. This iterative method was developed before the advent of computers, and much more efficient algorithms are used for numerical computations. In spite of this limitation, the Hardy Cross method is presented here to illustrate the iterative solution of the loop equations in pipe networks. The Hardy Cross method assumes that the head loss,  $h_L$ , in each pipe is proportional to the discharge, Q, raised to some power n, in which case

$$h_L = rQ^n (2.97)$$

The proportionality constant, r, depends on which head loss equation is used and the types of losses in the pipe. Clearly, if all head losses are due to friction and the Darcy-Weisbach equation is used to calculate the head losses, then r is given by

$$r = \frac{fL}{2gA^2D} \tag{2.98}$$

If the flow in each pipe is approximated as  $\hat{Q}$ , and  $\Delta Q$  is the error in this estimate, then the actual flowrate, Q, is related to  $\hat{Q}$  and  $\Delta Q$  by

$$Q = \hat{Q} + \Delta Q \tag{2.99}$$

and the head loss in each pipe is given by

$$h_{L} = rQ^{n}$$

$$= r(\hat{Q} + \Delta Q)^{n}$$

$$= r\left[\hat{Q}^{n} + n\hat{Q}^{n-1}\Delta Q + \frac{n(n-1)}{2}\hat{Q}^{n-2}(\Delta Q)^{2} + \dots + (\Delta Q)^{n}\right]$$
(2.100)

If the error in the flow estimate,  $\Delta Q$ , is small, then the higher order terms in  $\Delta Q$  can be neglected and the head loss in each pipe can be approximated by the relation

$$h_L \approx r\hat{Q}^n + rn\hat{Q}^{n-1}\Delta Q \tag{2.101}$$

This relation approximates the head loss in the flow direction. However, in working with pipe networks, it is required that the algebraic sum of the head losses in any loop of the network (see Figure 2.9) must be equal to zero. We must therefore define a positive flow direction (such as clockwise), and count head losses as positive in pipes when the flow is in the positive direction and negative when the flow is opposite to the selected positive direction. Under these circumstances, the sign of the head loss must be the same as the sign of the flow direction. Further, when the flow is in the positive direction, positive values of  $\Delta Q$  require a positive correction to the head loss; when the flow is in the negative direction, positive values in  $\Delta Q$  also require a positive correction to the calculated head loss. To preserve the algebraic relation among head loss, flow direction, and flow error  $(\Delta Q)$ , Equation 2.101 for each pipe can be written as

$$h_L = r\hat{Q}|\hat{Q}|^{n-1} + rn|\hat{Q}|^{n-1}\Delta Q$$
 (2.102)

where the approximation has been replaced by an equal sign. On the basis of Equation 2.102, the requirement that the algebraic sum of the head losses around each loop be equal to zero can be written as

$$\sum_{j=1}^{NP(i)} r_{ij} Q_j |Q_j|^{n-1} + \Delta Q_i \sum_{j=1}^{NP(i)} r_{ij} n |Q_j|^{n-1} = 0, \qquad i = 1, NL$$
(2.103)

where NP(i) is the number of pipes in loop i,  $r_{ij}$  is the head-loss coefficient in pipe j (in loop i),  $Q_j$  is the estimated flow in pipe j,  $\Delta Q_i$  is the flow correction for the pipes in loop i, and NL is the number of loops in the entire network. The approximation given by Equation 2.103 assumes that there are no pumps in the loop, and that the flow correction,  $\Delta Q_i$ , is the same for each pipe in each loop. Solving Equation 2.103 for  $\Delta Q_i$  leads to

$$\Delta Q_i = -\frac{\sum_{j=1}^{NP(i)} r_{ij} Q_j |Q_j|^{n-1}}{\sum_{j=1}^{NP(i)} n r_{ij} |Q_j|^{n-1}}$$
(2.104)

This equation forms the basis of the Hardy Cross method.

The steps to be followed in using the Hardy Cross method to calculate the flow distribution in pipe networks are:

- 1. Assume a reasonable distribution of flows in the pipe network. This assumed flow distribution must satisfy continuity.
- 2. For each loop, i, in the network, calculate the quantities  $r_{ij}Q_j|Q_j|^{n-1}$  and  $nr_{ij}|Q_j|^{n-1}$  for each pipe in the loop. Calculate the flow correction,  $\Delta Q_i$ , using Equation 2.104. Add the correction algebraically to the estimated flow in each pipe. [Note: Values of  $r_{ij}$  occur in both the numerator and denominator of Equation 2.104; therefore, values proportional to the actual  $r_{ij}$  may be used to calculate  $\Delta Q_i$ .]
- 3. Proceed to another circuit and repeat step 2.
- 4. Repeat steps 2 and 3 until the corrections  $(\Delta Q_i)$  are small.

The application of the Hardy Cross method is best demonstrated by an example.

### Example 2.10.

Compute the distribution of flows in the pipe network shown in Figure 2.11(a), where the head loss in each pipe is given by

$$h_L = rQ^2$$

and the values of r are shown in Figure 2.11(a). The flows are taken as dimensionless for the sake of illustration.

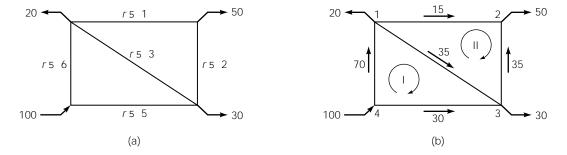


Figure 2.11: Flows in Pipe Network

#### Solution.

The first step is to assume a distribution of flows in the pipe network that satisfies continuity. The assumed distribution

of flows is shown in Figure 2.11(b), along with the positive-flow directions in each of the two loops. The flow correction for each loop is calculated using Equation 2.104. Since n=2 in this case, the flow correction formula becomes

$$\Delta Q_i = -\frac{\sum_{j=1}^{NP(i)} r_{ij} Q_j |Q_j|}{\sum_{j=1}^{NP(i)} 2r_{ij} |Q_j|}$$

The calculation of the numerator and denominator of this flow correction formula for loop I is tabulated as follows

Loop	Pipe	Q	rQ Q	2r Q
I	4-1	70	29,400	840
	1 - 3	35	3,675	210
	3-4	-30	-4,500	300
			28,575	1,350

The flow correction for loop I,  $\Delta Q_I$ , is therefore given by

$$\Delta Q_I = -\frac{28575}{1350} = -21.2$$

and the corrected flows are

Loop	Pipe	Q
I	4-1	48.8
	1 - 3	13.8
	3-4	-51.2

Moving to loop II, the calculation of the numerator and denominator of the flow correction formula for loop II is given by

Loop	Pipe	Q	rQ Q	2r Q
II	1-2	15	225	30
	2-3	-35	-2,450	140
	3-1	-13.8	-574	83
			-2,799	253

The flow correction for loop II,  $\Delta Q_{II}$ , is therefore given by

$$\Delta Q_{II} = -\frac{-2799}{253} = 11.1$$

and the corrected flows are

Loop	Pipe	Q
II	1-2	26.1
	2-3	-23.9
	3-1	-2.7

This procedure is repeated in the following table until the calculated flow corrections do not affect the calculated

flows.	to	the	level	of	significant	digits	retained	in	the calculations.

Iteration	Loop	Pipe	Q	rQ Q	2r Q	$\Delta Q$	Corrected $Q$
2	I	4-1	48.8	14,289	586		47.7
		1 - 3	2.7	22	16		1.6
		3-4	-51.2	$-13{,}107$	512		-52.3
				1,204	1,114	-1.1	
	II	1-2	26.1	681	52		29.1
		2-3	-23.9	-1,142	96		-20.9
		3-1	-1.6	-8	10		1.4
				-469	157	3.0	
3	I	4-1	47.7	13,663	573		47.7
		1-3	1.4	6	8		1.4
		3-4	-52.3	-13,666	523		-52.3
				3	1,104	0.0	
	II	1–2	29.1	847	58		29.2
		2–3	-20.9	-874	84		-20.8
		3–1	1.4	6	8	0.1	1.5
				-21	150	0.1	
4	I	1 1	477	12.660	579		47 7
4	1	$\begin{array}{c} 4-1 \\ 1-3 \end{array}$	47.7	13,662 $7$	573		47.7 $1.5$
		1–3 3–4	$ \begin{array}{r} 1.5 \\ -52.3 \end{array} $	-13,668	9 523		-52.3
		3-4	-52.5	$\frac{-15,008}{1}$		0.0	-52.5
				1	1,104	0.0	
	II	1-2	29.2	853	58		29.2
	11	$\frac{1-2}{2-3}$	-20.8	-865	83		-20.8
		2-3 3-1	-20.3 $1.5$	-303 7	9		-20.3 1.5
		0 1	1.0	-5	150	0.0	1.0
				0	100	0.0	

The final flow distribution, after four iterations, is given by

Pipe	Q
1-2	29.2
2-3	-20.8
3-4	-52.3
4-1	47.7
1–3	-1.5

It is clear that the final results are fairly close to the flow estimates after only one iteration.

As the above example illustrates, complex pipe networks can generally be treated as a combination of simple circuits or loops, with each balanced in turn until compatible flow conditions exist in all loops. Typically, after the flows have been computed for all pipes in a network, the elevation of the hydraulic grade line and the pressure are computed for each junction node. These pressures are then assessed relative to acceptable operating pressures.

In practice, analyses of complex pipe networks are usually done using commercial computer programs that solve the system of continuity and energy equations that govern the flows in pipe networks. These computer programs, such as EPANET (Rossman, 2000), generally use algorithms that are computationally more efficient than the Hardy Cross method, such as the linear theory method, the Newton-Raphson method, and the gradient algorithm (Lansey and Mays, 1999).

# 2.4 Pumps

Pumps are hydraulic machines that convert mechanical energy to fluid energy. They can be classified into two main categories: (1) positive displacement pumps, and (2) rotodynamic or kinetic pumps. Positive displacement pumps deliver a fixed quantity of fluid with each revolution of the pump rotor, such as with a piston or cylinder, while rotodynamic pumps add energy to the fluid by accelerating it through the action of a rotating impeller. Rotodynamic pumps are far more common in engineering practice and will be the focus of this section.

Three types of rotodynamic pumps commonly encountered are centrifugal pumps, axial-flow pumps, and mixed-flow pumps. In centrifugal pumps, the flow enters the pump chamber along the axis of the impeller and is discharged radially by centrifugal action, as illustrated in Figure 2.12(a). In axial-flow pumps, the flow enters and leaves the pump chamber along the axis of the

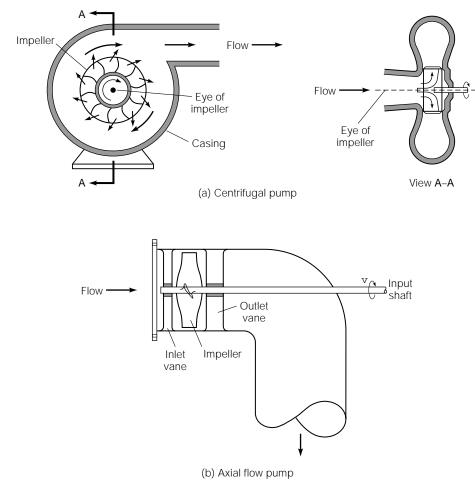


Figure 2.12: Types of Pumps

impeller, as shown in Figure 2.12(b). In mixed-flow pumps, outflows have both radial and axial components. Typical centrifugal and axial-flow pump installations are illustrated in Figure 2.13. Key components of the centrifugal pump are a foot valve installed in the suction pipe to prevent

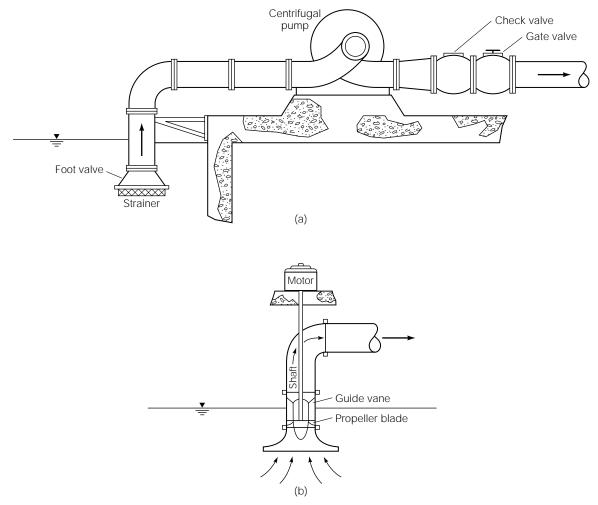


Figure 2.13: Centrifugal and Axial Flow Pump Installations Source: Finnemore and Franzini (2002).

water from leaving the pump when it is stopped and a check valve in the discharge pipe to prevent backflow if there is a power failure. If the suction line is empty prior to starting the pump, then the suction line must be *primed* prior to startup. Unless the water is known to be very clean, a strainer should be installed at the inlet to the suction piping. The pipe size of the suction line should never be smaller than the inlet connection on the pump; if a reducer is required, it should be of the eccentric type since concentric reducers place part of the supply pipe above the pump inlet where an air pocket could form. The discharge line from the pump should contain a valve close to the pump to allow service or pump replacement.

The pumps illustrated in Figure 2.13 are both *single-stage* pumps, which means that they have only one impeller. In *multistage* pumps, two or more impellers are arranged in series in such a way that the discharge from one impeller enters the eye of the next impeller. If a pump has three

impellers in series, it is called a three-stage pump. Multistage pumps are typically used when large pumping heads are required.

The performance of a pump is measured by the head added by the pump and the pump efficiency. The head added by the pump,  $h_p$ , is equal to the difference between the total head on the discharge side of the pump and the total head on the suction side of the pump, and is sometimes referred to as the total dynamic head. The efficiency of the pump,  $\eta$ , is defined by

$$\eta = \frac{\text{power delivered to the fluid}}{\text{power supplied to the shaft}}$$
(2.105)

Pumps are inefficient for a variety of reasons, such as frictional losses as the fluid moves over the solid surfaces, separation losses, leakage of fluid between the impeller and the casing, and mechanical losses in the bearings and sealing glands of the pump. The pump-performance parameters,  $h_p$  and  $\eta$ , can be expressed in terms of the fluid properties and the physical characteristics of the pump by the functional relation

$$gh_p \quad \text{or} \quad \eta = f_1(\rho, \mu, D, \omega, Q)$$
 (2.106)

where the energy added per unit mass of fluid,  $gh_p$ , is used instead of  $h_p$  (to remove the effect of gravity),  $f_1$  is an unknown function,  $\rho$  and  $\mu$  are the density and dynamic viscosity of the fluid respectively, Q is the flowrate through the pump, D is a characteristic dimension of the pump (usually the inlet or outlet diameter), and  $\omega$  is the speed of the pump impeller. Equation 2.106 is a functional relationship between six variables in three dimensions. According to the Buckingham pi theorem, this relationship can be expressed as a relation between three dimensionless groups as follows

$$\frac{gh_p}{\omega^2 D^2}$$
 or  $\eta = f_2\left(\frac{Q}{\omega D^3}, \frac{\rho\omega D^2}{\mu}\right)$  (2.107)

where  $gh_p/\omega^2D^2$  is called the *head coefficient*, and  $Q/\omega D^3$  is called the *flow coefficient* (Douglas et al., 1995). In most cases, the flow through the pump is fully turbulent and viscous forces are negligible relative to the inertial forces. Under these circumstances, the viscosity of the fluid is neglected and Equation 2.107 becomes

$$\frac{gh_p}{\omega^2 D^2}$$
 or  $\eta = f_3 \left(\frac{Q}{\omega D^3}\right)$  (2.108)

This relationship describes the performance of all pumps in which viscous effects are negligible, but the exact form of the function in Equation 2.108 depends on the geometry of the pump. A series of pumps having the same shape (but different sizes) are expected to have the same functional relationships between  $gh_p/(\omega^2D^2)$  and  $Q/(\omega D^3)$  as well as  $\eta$  and  $Q/(\omega D^3)$ . A class of pumps that have the same shape is called a homologous series, and the performance characteristics of a homologous series of pumps are described by curves such as those in Figure 2.14. Pumps are selected to meet specific design conditions and, since the efficiency of a pump varies with the operating condition, it is usually desirable to select a pump that operates at or near the point of maximum efficiency, indicated by the point P in Figure 2.14.

The point of maximum efficiency of a pump is commonly called the *best efficiency point* (bep), and is sometimes called the *nameplate* or *design point*. Maintaining operation near the bep will allow a pump to function for years with little maintenance, and as the operating point moves away from the bep, pump thrust and radial loads increase which increases the wear on the pump

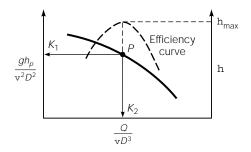


Figure 2.14: Performance Curves of a Homologous Series of Pumps

bearings and shaft. For these reasons, it is generally recommended that pump operation should be maintained between 70% and 130% of the bep flowrate (Lansey and El-Shorbagy, 2001). At the best efficiency point in Figure 2.14,

$$\frac{gh_p}{\omega^2 D^2} = K_1$$
, and  $\frac{Q}{\omega D^3} = K_2$  (2.109)

Eliminating D from these equations yields

$$\frac{\omega Q^{\frac{1}{2}}}{(gh_p)^{\frac{3}{4}}} = \sqrt{\frac{K_2}{K_1^{\frac{3}{2}}}} \tag{2.110}$$

The term on the righthand side of this equation is a constant for a homologous series of pumps and is denoted by the *specific speed*,  $n_s$ , defined by

$$n_s = \frac{\omega Q^{\frac{1}{2}}}{(gh_p)^{\frac{3}{4}}} \tag{2.111}$$

where any consistent set of units can be used. The specific speed,  $n_s$ , is also called the *shape* number (Hwang and Houghtalen, 1996; Wurbs and James, 2002) or the type number (Douglas et al., 2001). In SI units,  $\omega$  is in rad/s, Q in m³/s, g in m/s², and  $h_p$  in meters. The most efficient operating point for a homologous series of pumps is therefore specified by the specific speed. This nomenclature is somewhat unfortunate since the specific speed is dimensionless and hence does not have units of speed. It is common practice in the United States to define the specific speed by  $N_s$ , as

$$N_s = \frac{\omega Q^{\frac{1}{2}}}{h_p^{\frac{3}{4}}} \tag{2.112}$$

where  $N_s$  is not dimensionless,  $\omega$  is in revolutions per minute (rpm), Q is in gallons per minute (gpm), and  $h_p$  is in feet (ft). Although  $N_s$  has dimensions, the units are seldom stated in practice. The required pump operating point gives the flowrate, Q, and head,  $h_p$ , required from the pump; the rotational speed,  $\omega$ , is determined by the synchronous speeds of available motors; and the specific speed calculated from the required operating point is the basis for selecting the appropriate pump. Since the specific speed is independent of the size of a pump, and all homologous pumps (of varying sizes) have the same specific speed, then the calculated specific speed at the desired operating point indicates the type of pump that must be selected to ensure optimal efficiency.

		Typical	Typical
	Range of	flowrates	efficiencies
Type of pump	specific speeds, $n_s^*$	(L/s)	(%)
Centrifugal	0.15-1.5 (400-4,000)	< 60	70–94
Mixed flow	1.5 - 3.7  (4,000 - 10,000)	60 – 300	90-94
Axial flow	$3.7 – 5.5 \ (10,000 – 15,000)$	> 300	84-90

<sup>\*</sup>The specific speeds in parentheses correspond to  $N_s$  given by Equation 2.112, with  $\omega$  in rpm, Q in gpm, and  $h_p$  in ft.

The types of pump that give the maximum efficiency for given specific speeds,  $n_s$ , are listed in Table 2.3 along with typical flowrates delivered by the pumps. Table 2.3 indicates that centrifugal pumps have low specific speeds,  $n_s < 1.5$ ; mixed-flow pumps have medium specific speeds,  $1.5 < n_s < 3.7$ ; and axial-flow pumps have high specific speeds,  $n_s > 3.7$ . This indicates that centrifugal pumps are most efficient at delivering low flows at high heads, while axial flow pumps are most efficient at delivering high flows at low heads. The efficiencies of radial-flow (centrifugal) pumps increase with increasing specific speed, while the efficiencies of mixed-flow and axial-flow pumps decrease with increasing specific speed. Pumps with specific speed less than 0.3 tend to be inefficient (Finnemore and Franzini, 2002). Since axial-flow pumps are most efficient at delivering high flows at low heads, this type of pump is commonly used to move large volumes of water through major canals, and an example of this application is shown in Figure 2.15; where there are three axial-flow pumps operating in parallel, and these pumps are driven by motors housed in the pump station.



Figure 2.15: Axial Flow Pump Operating in a Canal

Most pumps are driven by standard electric motors. The standard speed of AC synchronous induction motors at 60 cycles and 220 to 440 volts is given by

Synchronous speed (rpm) = 
$$\frac{3600}{\text{no. of pairs of poles}}$$
 (2.113)

A common problem is that, for the motor speed chosen, the calculated specific speed does not exactly equal the specific speed of available pumps. In these cases, it is recommended to choose a

pump with a specific speed that is close to and greater than the required specific speed. In rare cases, a new pump may be designed to meet the design conditions exactly, however, this is usually very costly and only justified for very large pumps.

# 2.4.1 Affinity Laws

The performance curves for a homologous series of pumps is illustrated in Figure 2.14. Any two pumps in the homologous series are expected to operate at the same efficiency when

$$\left[ \left( \frac{Q}{\omega D^3} \right)_1 = \left( \frac{Q}{\omega D^3} \right)_2, \text{ and } \left( \frac{h_p}{\omega^2 D^2} \right)_1 = \left( \frac{h_p}{\omega^2 D^2} \right)_2 \right]$$
 (2.114)

These relationships are sometimes called the affinity laws for homologous pumps. An affinity law for the power delivered to the fluid, P, can be derived from the affinity relations given in Equation 2.114, since P is defined by

$$P = \gamma Q h_p \tag{2.115}$$

which leads to the following derived affinity relation

$$\left[ \left( \frac{P}{\omega^3 D^5} \right)_1 = \left( \frac{P}{\omega^3 D^5} \right)_2 \right] \tag{2.116}$$

In accordance with the dimensional analysis of pump performance, Equation 2.107, the affinity laws for scaling pump performance are valid as long as viscous effects are negligible. The effect of viscosity is measured by the Reynolds number, Re, defined by

$$Re = \frac{\rho \omega D^2}{\mu} \tag{2.117}$$

and scale effects are negligible when Re  $> 3 \times 10^5$  (Gerhart et al., 1992). In lieu of stating a Reynolds number criterion for scale effects to be negligible, it is sometimes stated that larger pumps are more efficient than smaller pumps and that the scale effect on efficiency is given by (Moody and Zowski, 1969; Stepanoff, 1957)

$$\frac{1 - \eta_2}{1 - \eta_1} = \left(\frac{D_1}{D_2}\right)^{\frac{1}{4}} \tag{2.118}$$

where  $\eta_1$  and  $\eta_2$  are the efficiencies of homologous pumps of diameters  $D_1$  and  $D_2$ , respectively. The effect of changes in flowrate on efficiency can be estimated using the relation

$$\frac{0.94 - \eta_2}{0.94 - \eta_1} = \left(\frac{Q_1}{Q_2}\right)^{0.32} \tag{2.119}$$

where  $Q_1$  and  $Q_2$  are corresponding homologous flowrates.

#### Example 2.11.

A pump with a 1,200 rpm motor has a performance curve of

$$h_p = 12 - 0.1Q^2$$

where  $h_p$  is in meters and Q is in cubic meters per minute. If the motor is changed to 2,400 rpm, estimate the new performance curve.

#### Solution.

The performance characteristics of a homologous series of pumps is given by

$$\frac{gh_p}{\omega^2 D^2} = f\left(\frac{Q}{\omega D^3}\right)$$

For a fixed pump size, D, for two different motor speeds,  $\omega_1$  and  $\omega_2$ , the general performance curve can be written as

$$\frac{h_1}{\omega_1^2} = f\left(\frac{Q_1}{\omega_1}\right)$$

and

$$\frac{h_2}{\omega_2^2} = f\left(\frac{Q_2}{\omega_2}\right)$$

where  $h_1$  and  $Q_1$  are the head added by the pump and the flowrate, respectively, when the speed is  $\omega_1$ ; and  $h_2$  and  $Q_2$  are the head and flowrate when the speed is  $\omega_2$ . Since the pumps are part of a homologous series, then, neglecting scale effects, the function f is fixed and therefore when

$$\frac{Q_1}{\omega_1} = \frac{Q_2}{\omega_2}$$

then

$$\frac{h_1}{\omega_1^2} = \frac{h_2}{\omega_2^2}$$

These relations are simply statements of the affinity laws. In the present case,  $\omega_1 = 1,200$  rpm and  $\omega_2 = 2,400$  rpm and the affinity laws give that

$$Q_1 = \frac{\omega_1}{\omega_2} Q_2 = \frac{1200}{2400} Q_2 = 0.5Q_2$$

$$h_1 = \frac{\omega_1^2}{\omega_2^2} h_2 = \frac{1200^2}{2400^2} h_2 = 0.25h_2$$

Since the performance curve of the pump at speed  $\omega_1$  is given by

$$h_1 = 12 - 0.1Q_1^2$$

then the performance curve at speed  $\omega_2$  is given by

$$0.25h_2 = 12 - 0.1(0.5Q_2)^2$$

which leads to

$$h_2 = 48 - 0.1Q_2^2$$

The performance curve of the pump with a 2,400 rpm motor is therefore given by

$$h_p = 48 - 0.1Q^2$$

# 2.4.2 Pump Selection

Selection of a pump generally requires specification of a manufacturer, model (homologous) series, impeller size, D, and rotational speed,  $\omega$ . For each model series and rotational speed, pump manufacturers provide a performance curve or characteristic curve that shows the relationship between the head,  $h_p$ , added by the pump and the flowrate, Q, through the pump. A typical example of a set of pump characteristic curves ( $h_p$  versus Q) provided by a manufacturer for a

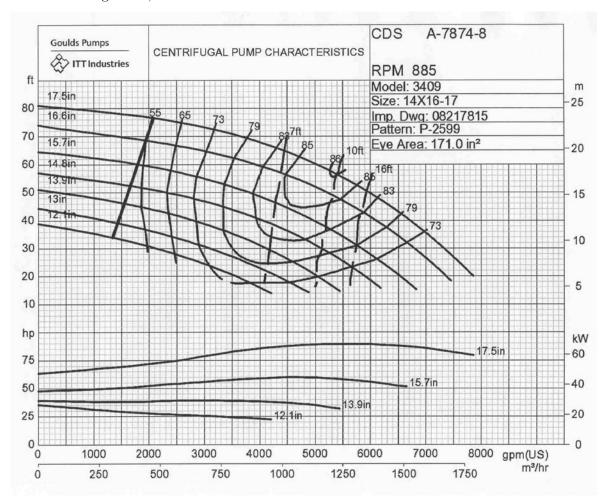


Figure 2.16: Pump Performance Curve Source: Goulds Pumps (www.gouldspumps.com).

homologous series of pumps is shown in Figure 2.16. In this case, the homologous series of pumps (Model 3409) have impeller diameters ranging from 12.1 in. (307 mm) to 17.5 in. (445 mm) with a rotational speed of 885 revolutions per minute. Superimposed on the characteristic curves are constant-efficiency lines for efficiencies ranging from 55% to 86%, and (dashed) isolines of net positive suction head which is the allowable difference between the pressure head on the suction side of the pump and the pressure head at which water vaporizes (i.e. saturation vapor pressure). In Figure 2.16, the allowable net positive suction head ranges from 16 ft (4.9 m) for higher flowrates down to approximately zero, which is indicated by a bold line that meets the 55% efficiency contour. Also shown in Figure 2.16, below the characteristic curves, is the power delivered to the pump (in kW) for various flowrates and impeller diameters. This power input to the pump shaft is called the brake horsepower.

The goal in pump selection is to select a pump that operates at a point of maximum efficiency and with a net positive suction head that exceeds the minimum allowable value. Pumps are placed in pipeline systems such as that illustrated in Figure 2.17, in which case the energy equation for

the pipeline system requires that the head,  $h_p$ , added by the pump is given by

$$h_p = \Delta z + Q^2 \left[ \sum \frac{fL}{2gA^2D} + \sum \frac{K_m}{2gA^2} \right]$$
 (2.120)

where  $\Delta z$  is the difference in elevation between the water surfaces of the inflow and outflow reservoirs, the first term in the square brackets is the sum of the head losses due to friction, and the second term is the sum of the minor head losses. Equation 2.120 gives a relationship between  $h_p$ 

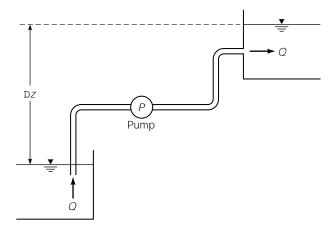


Figure 2.17: Pipeline System

and Q for the pipeline system, and this relationship is commonly called the *system curve*. Because the flowrate and head added by the pump must satisfy both the system curve and the pump characteristic curve, Q and  $h_p$  are determined by simultaneous solution of Equation 2.120 and the pump characteristic curve. The resulting values of Q and  $h_p$  identify the *operating point* of the pump. The location of the operating point on the performance curve is illustrated in Figure 2.18.

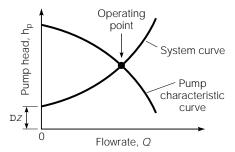


Figure 2.18: Operating Point in Pipeline System

### Example 2.12.

Water is being pumped from a lower to an upper reservoir through a pipeline system similar to the one shown in Figure 2.17. The reservoirs differ in elevation by 15.2 m, and the length of the steel pipe ( $k_s = 0.046$  mm) connecting the reservoirs is 21.3 m. The pipeline is 50-mm in diameter, and the performance curve of the 2400-rpm centrifugal pump being considered for selection is given by

$$h_p = 24.4 - 7.65Q^2 (2.121)$$

where  $h_p$  is in meters and Q is in liters per second. Using this pump, what flow do you expect in the pipeline? If the calculated operating point of the pump coincides with the point of maximum efficiency, which is the goal of pump selection, calculate the specific speed of the pump in U.S. Customary units and verify that a centrifugal-type pump should be used.

#### Solution.

Neglecting minor losses, the energy equation for the pipeline system is given by

$$h_p = 15.2 + \frac{fL}{2qA^2D}Q^2 \tag{2.122}$$

where  $h_p$  is the head added by the pump, f is the friction factor, L is the pipe length, A is the cross-sectional area of the pipe, and D is the diameter of the pipe. The area, A, is given by

$$A = \frac{\pi}{4}D^2 = \frac{\pi}{4}(0.05)^2 = 0.00196 \text{ m}^2$$

In general, f is a function of both the Reynolds number and the relative roughness. However, if the flow is fully turbulent, then the friction factor depends only on the relative roughness according to Equation 2.34

$$\frac{1}{\sqrt{f}} = -2\log\left(\frac{\epsilon}{3.7}\right) \tag{2.123}$$

where  $\epsilon$  is the relative roughness of the pipe given by

$$\epsilon = \frac{k_s}{D}$$

and  $k_s$  is the equivalent sand roughness. In this case,  $k_s = 0.046$  mm and D = 50 mm. Therefore

$$\epsilon = \frac{0.046}{50} = 0.000920$$

Substituting for  $\epsilon$  into Equation 2.123 yields

$$\frac{1}{\sqrt{f}} = -2\log\left(\frac{0.000920}{3.7}\right) = 7.21$$

Therefore

$$f = 0.0192$$

Substituting this value of f into the system equation (Equation 2.122) yields

$$h_p = 15.2 + \frac{fL}{2gA^2D}Q^2 = 15.2 + \frac{(0.0192)(21.3)}{(2)(9.81)(0.00196)^2(0.05)}Q^2 = 15.2 + 108500Q^2$$

This equation is for Q in  $m^3/s$ , and the corresponding equation for Q in L/s is

$$h_p = 15.2 + 0.109Q^2 \tag{2.124}$$

Combining the system curve, Equation 2.124, with the pump characteristic curve, Equation 2.121, leads to

$$\begin{array}{rcl} 15.2 + 0.109 Q^2 & = & 24.4 - 7.65 Q^2 \\ Q & = & 1.09 \; \mathrm{L/s} \end{array}$$

This flowrate was derived by assuming that the flow in the pipeline is fully turbulent. This assumption can now be verified by recalculating the friction factor with the Reynolds number corresponding to the calculated flowrate. The velocity in the pipeline, V, is given by

$$V = \frac{Q}{A} = \frac{1.09 \times 10^{-3}}{0.00196} = 0.556 \text{ m/s}$$

Since the kinematic viscosity,  $\nu$ , at 20°C is  $1.00 \times 10^{-6}$  m<sup>2</sup>/s, the Reynolds number, Re, is

$$Re = \frac{VD}{\nu} = \frac{(0.556)(0.05)}{1.00 \times 10^{-6}} = 2.78 \times 10^4$$

The friction factor can now be recalculated using the Jain equation (Equation 2.38), where

$$\frac{1}{\sqrt{f}} = -2\log\left[\frac{\epsilon}{3.7} + \frac{5.74}{\mathrm{Re}^{0.9}}\right] = -2\log\left[\frac{0.000920}{3.7} + \frac{5.74}{(2.78 \times 10^4)^{0.9}}\right] = 6.17$$

which leads to

$$f = 0.0263$$

Therefore, the original approximation of f = 0.0192 was in error and the estimation of the flow in the pipeline must be recalculated using f = 0.0263. After calculating the revised flow, the friction factor must again be calculated to see if it is equal to the assumed value. If not, the process is repeated until the assumed and calculated friction factors are equal. In this case, one more iteration shows that f = 0.0263 and

$$Q = 1.09 \; L/s$$

According to the pump characteristic curve, the head added by the pump,  $h_p$ , is

$$h_p = 24.4 - 7.65Q^2 = 24.4 - 7.65(1.09)^2 = 15.3 \text{ m}$$

In U.S. Customary units, Q = 1.09 L/s = 17.3 gpm;  $h_p = 15.3$  m = 50.2 ft;  $\omega = 2{,}400$  rpm; and the specific speed,  $N_s$ , is given by Equation 2.112 as

$$N_s = \frac{\omega Q^{\frac{1}{2}}}{h_n^{\frac{3}{4}}} = \frac{(2400)(17.3)^{\frac{1}{2}}}{(50.2)^{\frac{3}{4}}} = 529$$

According to Table 2.3, with a pump operating at a specific speed of  $N_s = 529$ , the best type of pump is a centrifugal pump.

# 2.4.3 Limits on Pump Location

If the absolute pressure on the suction side of a pump falls below the saturation vapor pressure of the fluid, the water will begin to vaporize. This process of vaporization is called *cavitation*. Cavitation is usually a transient phenomenon that occurs as water enters the low-pressure suction side of a pump and experiences the even lower pressures adjacent to the rotating pump impeller. As the water containing vapor cavities moves toward the high-pressure environment of the discharge side of the pump, the vapor cavities are compressed and ultimately implode, creating small localized high-velocity jets that can cause considerable damage to the pump machinery. Collapsing vapor cavities have been associated with jet velocities on the order of 110 m/s, and pressures of up to 800 MPa when the jets strike a solid wall (Finnemore and Franzini, 2002; Knapp et al., 1970). The damage caused by collapsing vapor cavities usually manifests itself as *pitting* of the metal casing and impeller, reduced pump efficiency, and excessive vibration of the pump. The noise generated by imploding vapor cavities resembles the sound of gravel going through a centrifugal pump. Since the saturation vapor pressure increases with temperature, a system that operates satisfactorily without cavitation during the winter may have problems with cavitation during the summer.

The potential for cavitation is measured by the net positive suction head, NPSH, defined as the difference between the head on the suction side of the pump and the head when cavitation begins, hence

$$NPSH = \left(\frac{p_s}{\gamma} + \frac{V_s^2}{2g} + z_s\right) - \left(\frac{p_v}{\gamma} + z_s\right) = \frac{p_s}{\gamma} + \frac{V_s^2}{2g} - \frac{p_v}{\gamma}$$
(2.125)

where  $p_s$ ,  $V_s$ , and  $z_s$  are the pressure, velocity, and elevation of the fluid at the suction side of the pump, and  $p_v$  is the saturation vapor pressure of water at the temperature of the fluid. In cases

where water is being pumped from a reservoir, the NPSH can be calculated by applying the energy equation between the reservoir and the suction side of the pump and, in this case the calculated NPSH is called the *available net positive suction head*, NPSH<sub>A</sub>, and is given by

$$NPSH_A = \frac{p_o}{\gamma} - \Delta z_s - h_L - \frac{p_v}{\gamma}$$
 (2.126)

where  $p_o$  is the pressure at the surface of the reservoir (usually atmospheric),  $\Delta z_s$  is the difference in elevation between the suction side of the pump and the fluid surface in the reservoir (called the suction lift or static suction head or static head),  $h_L$  is the head loss in the pipeline between the reservoir and suction side of the pump (including minor losses), and  $p_v$  is the saturation vapor pressure. In applying either Equation 2.125 or 2.126 to calculate NPSH, care must be taken to use a consistent measure of the pressures, using either gage pressures or absolute pressures. Absolute pressures are usually more convenient, since the vapor pressure is typically given as an absolute pressure. A pump requires a minimum NPSH to prevent the onset of cavitation within the pump, and this minimum NPSH is called the required net positive suction head, NPSH<sub>R</sub>, which is generally supplied by the pump manufacturer. A typical illustration of this is shown in Figure 2.16, where isolines of NPSR<sub>R</sub> are overlaid on the pump performance curves. In the case shown, the allowable net positive suction head ranges from 16 ft (4.9 m) for higher flowrates down to approximately zero, which is indicated by a bold line that meets the 55% efficiency contour.

### Example 2.13.

A pump with a performance curve of  $h_p = 12 - 0.01Q^2$  ( $h_p$  in m, Q in L/s) is located 3 m above a water reservoir and pumps water from the reservoir at a rate of 24.5 L/s through a 102-mm diameter ductile iron pipe ( $k_s = 0.26$  mm). The length of the pipeline between the reservoir and the suction side of the pump is 3.5 m, and the temperature of the water is 20°C. Calculate the available net positive suction head at the pump. If the pump manufacturer gives the required net positive suction head under the current operating conditions as 1.2 m, determine the maximum height above the surface of the reservoir that the pump can be located and still deliver the same flow.

#### Solution.

The available net positive suction head,  $NPSH_A$  is given by Equation 2.126 as

$$NPSH_A = \frac{p_o}{\gamma} - \Delta z_s - h_L - \frac{p_v}{\gamma}$$
 (2.127)

Atmospheric pressure,  $p_o$ , can be taken as 101 kPa; the specific weight of water,  $\gamma$ , is 9.79 kN/m³; the suction lift,  $\Delta z_s$ , is 3 m; and at 20°C, and the saturated vapor pressure of water,  $p_v$ , is 2.34 kPa. The head loss,  $h_L$ , must be estimated using the Darcy-Weisbach equation and minor loss coefficients. The flowrate, Q, is 24.5 L/s = 0.0245 m³/s, and the average velocity of flow in the pipe, V, is given by

$$V = \frac{Q}{A} = \frac{0.0245}{\frac{\pi}{4}(0.102)^2} = 3.0 \text{ m/s}$$

At  $20^{\circ}$ C the kinematic viscosity,  $\nu$ , is  $1.00 \times 10^{-6}$  m<sup>2</sup>/s and the Reynolds number of the flow, Re, is given by

$$Re = \frac{VD}{\nu} = \frac{(3)(0.102)}{1.00 \times 10^{-6}} = 3.06 \times 10^5$$

Using Re =  $3.06 \times 10^5$ ,  $k_s = 0.26$  mm and D = 0.102 m, the Colebrook equation gives f = 0.0257. Assuming an inlet head loss of  $V^2/2g$  (for a projecting inlet), then the head loss,  $h_L$ , in the pipeline between the reservoir and the suction side of the pump is given by

$$h_L = \left(1 + \frac{fL}{D}\right) \frac{V^2}{2g} = \left[1 + \frac{(0.0257)(3.5)}{(0.102)}\right] \frac{(3.0)^2}{2(9.81)} = 0.863 \text{ m}$$

Now that all the parameters necessary to calculate the available net positive suction head,  $NPSH_A$ , have been determined, Equation 2.127 gives

$$\mathrm{NPSH}_A = \frac{p_o}{\gamma} - z_s - h_L - \frac{p_v}{\gamma} = \frac{101}{9.79} - 3 - 0.863 - \frac{2.34}{9.79} = 6.21~\mathrm{m}$$

It is comforting to know that the available net positive suction head (NPSH<sub>A</sub> = 6.21 m) significantly exceeds the required net positive suction head (NPSH<sub>R</sub> = 1.2 m).

The maximum allowable static lift occurs when  $NPSH_A = NPSH_R = 1.2$  m, in which case Equation 2.127 gives

$$1.2 = \frac{p_o}{\gamma} - z_s - h_L - \frac{p_v}{\gamma} \tag{2.128}$$

where  $p_o = 101$  kPa, and  $p_v = 2.34$  kPa. The head loss,  $h_L$ , between the pump and the reservoir can be estimated by the relation

$$h_L = \left[1 + \frac{f(z_s + 0.5)}{D}\right] \frac{V^2}{2g}$$

where the length of the pipe from the reservoir to the pump is estimated as  $z_s + 0.5$  m, D = 0.102 m, f = 0.0257, and V = 3.0 m/s. Therefore,

$$h_L = \left[1 + \frac{(0.0257)(z_s + 0.5)}{0.102}\right] \frac{3^2}{2(9.81)} = 0.517 + 0.116z_s$$

Substituting this equation into Equation 2.128 gives

$$1.2 = \frac{p_o}{\gamma} - z_s - h_L - \frac{p_v}{\gamma}$$

$$= \frac{101}{9.79} - z_s - (0.517 + 0.116z_s) - \frac{2.34}{9.79}$$

$$= 9.56 - 1.116z_s$$

Solving for  $z_s$  yields

$$z_s = 7.49 \text{ m}$$

Therefore, the pump should be no more than 7.49 m above the reservoir.

It is interesting to note that, although the practical limit for the suction lift is typically on the order of 7 m, difficulties in keeping air out of the suction pipe frequently limit the suction lift to around 3 m (Kay, 1998).

# 2.4.4 Multiple-Pump Systems

In cases where a single pump is inadequate to achieve a desired operating condition, multiple pumps can be used. Combinations of pumps are referred to as pump systems, and the pumps within these systems are typically arranged either in series or parallel. The characteristic curve of a pump system is determined by the arrangement of pumps within the system. Consider the case of two identical pumps in series, illustrated in Figure 2.19(a). The flow through each pump is equal to Q, and the head added by each pump is  $h_p$ . For the two-pump system, the flow through the system is equal to Q and the head added by the system is  $2h_p$ . Consequently, the characteristic curve of the two-pump (in series) system is related to the characteristic curve of each pump in that for any flow Q the head added by the system is twice the head added by a single pump, and the relationship between the single-pump characteristic curve and the two-pump characteristic curve is illustrated in Figure 2.19(b). This analysis can be extended to cases where the pump system contains n identical pumps in series, in which case the n-pump characteristic curve is derived from the single-pump

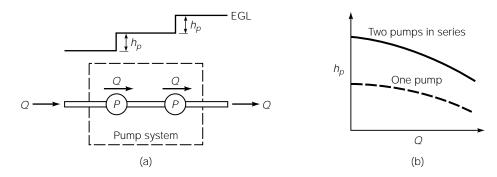


Figure 2.19: Pumps in Series

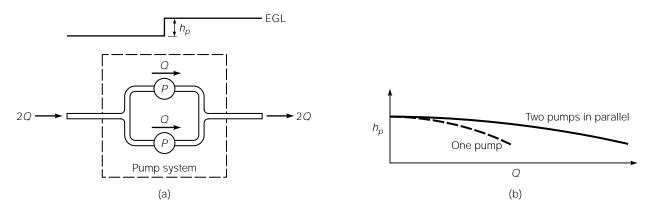


Figure 2.20: Pumps in Parallel

characteristic curve by multiplying the ordinate of the single-pump characteristic curve  $(h_p)$  by n. Pumps in series are used in applications involving unusually high heads.

The case of two identical pumps arranged in parallel is illustrated in Figure 2.20. In this case, the flow through each pump is Q and the head added is  $h_p$ ; therefore, the flow through the two-pump system is equal to 2Q, while the head added is  $h_p$ . Consequently, the characteristic curve of the two-pump system is derived from the characteristic curve of the individual pumps by multiplying the abscissa (Q) by two. This is illustrated in Figure 2.20(b). In a similar manner, the characteristic curves of systems containing n identical pumps in parallel can be derived from the single-pump characteristic curve by multiplying the abscissa (Q) by n. Pumps in parallel are used in cases where the desired flowrate is beyond the range of a single pump and also to provide flexibility in pump operations, since some pumps in the system can be shut down during low-demand conditions or for service. This arrangement is common in sewage pump stations and water-distribution systems, where flowrates vary significantly during the course of a day.

When pumps are placed either in series or parallel, it is usually desirable that these pumps be identical; otherwise, the pumps will be loaded unequally and the efficiency of the pump system will be less than optimal. In cases where nonidentical pumps are placed in series, the characteristic curve of the pump system is obtained by summing the heads added by the individual pumps for a given flowrate. In cases where nonidentical pumps are placed in parallel, the characteristic curve of the pump system is obtained by summing the flowrates through the individual pumps for a given head.

#### Example 2.14.

If a pump has a performance curve given by

$$h_n = 12 - 0.1Q^2$$

then what is the performance curve for: (a) a system having three of these pumps in series; and (b) a system having three of these pumps in parallel?

#### Solution.

(a) For a system with three pumps in series, the same flow, Q, goes through each pump, and each pump adds one-third of the head,  $H_p$ , added by the pump system. Therefore,

$$\frac{H_p}{3} = 12 - 0.1Q^2$$

and the characteristic curve of the pump system is

$$H_p = 36 - 0.3Q^2$$

(b) For a system consisting of three pumps in parallel, one-third of the total flow, Q, goes through each pump, and the head added by each pump is the same as the total head,  $H_p$  added by the pump system. Therefore

$$H_p = 12 - 0.1 \left(\frac{Q}{3}\right)^2$$

and the characteristic curve of the pump system is

$$H_p = 12 - 0.011Q^2$$

# 2.5 Design of Water Distribution Systems

Water distribution systems move water from treatment plants to homes, offices, industries, and other consumers. The major components of a water distribution system are pipelines, pumps, storage facilities, valves, and meters. The primary requirements of distribution system are to supply each customer with a sufficient volume of water at adequate pressure, to deliver safe water that satisfies the quality expectations of customers, and to have sufficient capacity and reserve storage for fire protection. (AWWA, 2003c).

### 2.5.1 Water Demand

Major considerations in designing water-supply systems are the water demands of the population being served, the fire flows needed to protect life and property, and the proximity of the service area to sources of water. There are usually several categories of water demand within any populated area, and these sources of demand can be broadly grouped into residential, commercial, industrial, and public. Residential water use is associated with houses and apartments where people live; commercial water use is associated with retail businesses, offices, hotels, and restaurants; industrial water use is associated with manufacturing and processing operations; and public water use includes governmental facilities that use water. Large industrial requirements are typically satisfied by sources other than the public water supply.

A typical distribution of water use for an average city in the United States is given in Table 2.4. These rates vary from city to city as a result of differences in local conditions that are unrelated

Table 2.4: Typical Distribution of Water Demand

	Average use	Percent of
Category	(liters/day)/person	total
Residential	380	56
Commercial	115	17
Industrial	85	12
Public	65	9
Loss	40	6
Total	685	100

Source: Solley, 1998

to the efficiency of water use. Water consumption is frequently stated in terms of the average amount of water delivered per day (to all categories of water use) divided by the population served, which is called the *average per capita demand*. The distribution of average per capita rates among 392 water-supply systems serving approximately 95 million people in the United States is shown in Table 2.5. The average per capita water usage in this sample was 660 L/d, with a standard

Table 2.5: Distribution of Per Capita Water Demand

Range	Number of	Percent of
(liters/day)/person	systems	systems
190-370	30	7.7
380 – 560	132	33.7
570 – 750	133	33.9
760 – 940	51	13.0
950 – 1130	19	4.8
> 1140	27	6.9

Source: Reprinted from 1984 Water Utility Operating Data, by permission. Copyright © 1986 American Water Works Association.

deviation of 270 L/d. Generally, high per capita rates are found in water-supply systems servicing large industrial or commercial sectors (Dziegielewski et al., 1996).

In the planning of municipal water-supply projects, the water demand at the end of the design life of the project is usually the basis for design. For existing water-supply systems, the American Water Works Association (AWWA, 1992) recommends that every 5 or 10 years, as a minimum, water-distribution systems be thoroughly reevaluated for requirements that would be placed on it by development and reconstruction over a 20-year period into the future. The estimation of the design flowrates for components of the water-supply system typically requires prediction of the population of the service area at the end of the design life, which is then multiplied by the per capita water demand to yield the design flowrate. Whereas the per capita water demand can usually be assumed to be fairly constant, the estimation of the future population typically involves a nonlinear extrapolation of past population trends.

A variety of methods are used in population forecasting. The simplest models treat the popula-

tion as a whole, forecast future populations based on past trends, and fit empirical growth functions to historical population data. The most complex models disaggregate the population into various groups and forecast the growth of each group separately. A popular approach that segregates the population by age and gender is *cohort analysis* (Sykes, 1995). High levels of disaggregation have the advantage of making forecast assumptions very explicit, but these models tend to be complex and require more data than the empirical models that treat the population as a whole. Over relatively short time horizons, on the order of 10 years, detailed disaggregation models may not be any more accurate than using empirical extrapolation models of the population as a whole. Several conventional extrapolation models are illustrated in the following paragraphs.

Populated areas tend to grow in at varying rates, as illustrated in Figure 2.21. In the early

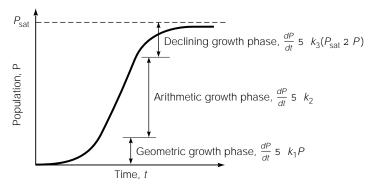


Figure 2.21: Growth Phases in Populated Areas

stages of growth, there are wide open spaces. Population, P, tends to grow geometrically according to the relation

$$\frac{dP}{dt} = k_1 P \tag{2.129}$$

where  $k_1$  is a growth constant. Integrating Equation 2.129 gives the following expression for the population as a function of time

$$P(t) = P_o e^{k_1 t} \tag{2.130}$$

where  $P_o$  is the population at some initial time designated as t = 0. Beyond the initial geometric growth phase, the rate of growth begins to level off and the following arithmetic growth relation may be more appropriate

$$\frac{dP}{dt} = k_2 \tag{2.131}$$

where  $k_2$  is an arithmetic growth constant. Integrating Equation 2.131 gives the following expression for the population as a function of time

$$P(t) = P_o + k_2 t \tag{2.132}$$

where  $P_o$  is the population at t=0. Ultimately, the growth of population centers becomes limited by the resources available to support the population, and further growth is influenced by the saturation population of the area,  $P_{\text{sat}}$ , and the population growth is described by a relation such as

$$\frac{dP}{dt} = k_3(P_{\text{sat}} - P) \tag{2.133}$$

where  $k_3$  is a constant. This phase of growth is called the *declining growth* phase. Almost all communities have zoning regulations that control the use of both developed and undeveloped areas within their jurisdiction (sometimes called a master plan), and a review of these regulations will yield an estimate of the saturation population of the undeveloped areas. Integrating Equation 2.133 gives the following expression for the population as a function of time

$$P(t) = P_{\text{sat}} - (P_{\text{sat}} - P_o)e^{-k_3 t}$$
(2.134)

where  $P_o$  is the population at t = 0.

The time scale associated with each growth phase is typically on the order of 10 years, although the actual duration of each phase can deviate significantly from this number. The duration of each phase is important in that population extrapolation using a single-phase equation can only be justified for the duration of that growth phase. Consequently, single-phase extrapolations are typically limited to 10 years or less, and these population predictions are termed short-term projections (Viessman and Welty, 1985). Extrapolation beyond 10 years, called long-term projections, involve fitting an S-shaped curve to the historical population trends and then extrapolating using the fitted equation. The most commonly fitted S-curve is the so-called logistic curve, which is described by the equation

$$P(t) = \frac{P_{\text{sat}}}{1 + ae^{bt}}$$
 (2.135)

where a and b are constants. The conventional methodology to fit the population equations to historical data is to plot the historical data, observe the trend in the data, and fit the curve that best matches the population trend. Regardless of which method is used to forecast the population, errors less than 10% can be expected for planning periods shorter than 10 years, and errors greater than 50% can be expected for planning periods longer than 20 years (Sykes, 1995).

### Example 2.15.

You are in the process of designing a water-supply system for a town, and the design life of your system is to end in the year 2020. The population in the town has been measured every 10 years since 1920 by the U.S. Census Bureau, and the reported populations are tabulated here. Estimate the population in the town using (a) graphical extension, (b) arithmetic growth projection, (c) geometric growth projection, (d) declining growth projection (assuming a saturation concentration of 600,000 people), and (e) logistic curve projection.

Year	Population
1920	125,000
1930	150,000
1940	150,000
1950	185,000
1960	185,000
1970	210,000
1980	280,000
1990	320,000

#### Solution.

The population trend is plotted in Figure 2.22, where a geometric growth rate approaching an arithmetic growth rate is indicated.

(a) A growth curve matching the trend in the measured populations is indicated in Figure 2.22. Graphical extension to the year 2020 leads to a population estimate of 530,000 people.

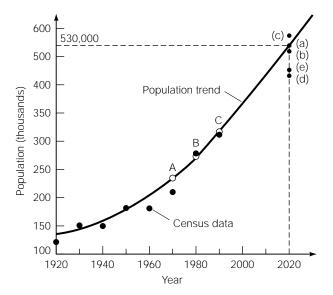


Figure 2.22: Population Trend

## (b) Arithmetic growth is described by Equation 2.132 as

$$P(t) = P_o + k_2 t (2.136)$$

where  $P_o$  and  $k_2$  are constants. Consider the arithmetic projection of a line passing through points B and C on the approximate growth curve shown in Figure 2.22. At point B, t = 0 (year 1980) and P = 270,000; at point C, t = 10 (year 1990) and P = 330,000. Applying these conditions to Equation 2.136 yields

$$P = 270000 + 6000t (2.137)$$

In the year 2020, t = 40 years and the population estimate given by Equation 2.137 is

$$P = 510,000 \text{ people}$$

# (c) Geometric growth is described by Equation 2.130 as

$$P = P_o e^{k_1 t} (2.138)$$

where  $k_1$  and  $P_o$  are constants. Using points A and C in Figure 2.22 as a basis for projection, then at t = 0 (year 1970), P = 225,000, and at t = 20 (year 1990), P = 330,000. Applying these conditions to Equation 2.138 yields

$$P = 225000e^{0.0195t} (2.139)$$

In the year 2020, t = 50 years and the population estimate given by Equation 2.139 is

$$P=597{,}000~\mathrm{people}$$

### (d) Declining growth is described by Equation 2.134 as

$$P(t) = P_{\text{sat}} - (P_{\text{sat}} - P_o)e^{-k_3 t}$$
(2.140)

where  $P_o$  and  $k_3$  are constants. Using points A and C in Figure 2.22, then at t=0 (year 1970),  $P=225{,}000$ , at t=20 (year 1990),  $P=330{,}000$ , and  $P_{\rm sat}=600{,}000$ . Applying these conditions to Equation 2.140 yields

$$P = 600000 - 375000e^{-0.0164t} (2.141)$$

In the year 2020, t = 50 years and the population given by Equation 2.141 is given by

$$P = 434,800 \text{ people}$$

(e) The logistic curve is described by Equation 2.135. Using points A and C in Figure 2.22 to evaluate the constants in Equation 2.135 (t = 0 in 1970) yields

$$P = \frac{600000}{1 + 1.67e^{-0.0357t}} \tag{2.142}$$

In 2020, t = 50 years and the population given by Equation 2.142 is

$$P = 469,000 \text{ people}$$

These results indicate that the population projection in 2020 is quite uncertain, with estimates ranging from 597,000 for geometric growth to 434,800 for declining growth. The projected results are compared graphically in Figure 2.22. Closer inspection of the predictions indicate that the declining and logistic growth models are limited by the specified saturation population of 600,000, while the geometric growth model is not limited by saturation conditions and produces the highest projected population.

The multiplication of the population projection by the per capita water demand is used to estimate the *average daily demand* for a municipal water-supply system. The (annual) average daily demand is equal to the average of the daily demands over one year and is typically given in  $m^3/s$ .

Variations in Demand. Water demand generally fluctuates between being below the average daily demand in the early morning hours and above the average daily demand during the midday hours. Typical daily cycles in water demand are shown in Figure 2.23. On a typical day in most

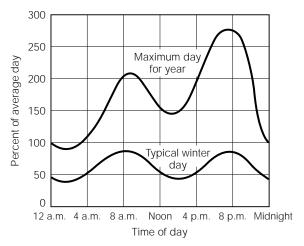


Figure 2.23: Typical Daily Cycles in Water Demand

Source: Linsley, Ray K. et al, Water-Resources Engineering. Copyright © 1992 by The McGraw-Hill Companies.

communities, water use is lowest at night (11 p.m. to 5 a.m.) when most people are asleep. Water use rises rapidly in the morning (5 a.m. to 11 a.m.) followed by moderate usage through midday (11 a.m. to 6 p.m.). Use then increases in the evening (6 p.m. to 10 p.m.) and drops rather quickly around 10 p.m. Overall, water-use patterns within a typical 24-hour period are characterized by demands that are 25% to 40% of the average daily demand during the hours between midnight and 6:00 a.m. and 150% to 175% of the average daily demand during the morning or evening peak periods (Velon and Johnson, 1993).

The range of demand conditions that are to be expected in water-distribution systems are specified by demand factors or peaking factors that express the ratio of the demand under certain

conditions to the average daily demand. Typical demand factors for various conditions are given in Table 2.6, where the *maximum daily demand* is defined as the demand on the day of the year that uses the most volume of water, and the *maximum hourly demand* is defined as the demand during the hour that uses the most volume of water. The demand factors in Table 2.6 should serve only

Table 2.6: Typical Demand Factors

rasio 2.0. Typicar Belliana ractors		
	Range of	Typical
Condition	demand factors	value
Daily average in maximum month	1.10-1.50	1.20
Daily average in maximum week	1.20 - 1.60	1.40
Maximum daily demand	1.50 – 3.00	1.80
Maximum hourly demand	2.00 – 4.00	3.25
Minimum hourly demand	0.20 – 0.60	0.30

Source: Velon and Johnson (1993). Reprinted by permission of The McGraw-Hill Companies.

as guidelines, with the actual demand factors in any one distribution system being best estimated from local measurements. In small water systems, demand factors may be significantly higher than those shown in Table 2.6.

Fire Demand. Besides the fluctuations in demand that occur under normal operating conditions, water-distribution systems are usually designed to accommodate the large (short-term) water demands associated with fighting fires. Although there is no legal requirement that a governing body must size its water-distribution system to provide fire protection, the governing bodies of most communities provide water for fire protection for reasons that include protection of the tax base from destruction by fire, preservation of jobs, preservation of human life, and reduction of human suffering. Flowrates required to fight fires can significantly exceed the maximum flowrates in the absence of fires, particularly in small water systems. In fact, for communities with populations less than 50,000, the need for fire protection is typically the determining factor in sizing water mains, storage facilities, and pumping facilities (AWWA, 2003c). In contrast to urban water systems, many rural water systems are designed to serve only domestic water needs, and fire flow requirements are not considered in the design of these systems (AWWA, 2003c).

Numerous methods have been proposed for estimating fire flows, the most popular of which was proposed by the Insurance Services Office, Inc. (ISO, 1980), which is an organization representing the fire insurance underwriters. The required fire flow for individual buildings can be estimated using the formula (ISO, 1980)

$$NFF_i = C_i O_i (X + P)_i$$
(2.143)

where NFF<sub>i</sub> is the needed fire flow at location i,  $C_i$  is the construction factor based on the size of the building and its construction,  $O_i$  is the occupancy factor reflecting the kinds of materials stored in the building (values range from 0.75 to 1.25), and  $(X+P)_i$  is the sum of the exposure factor  $(X_i)$  and communication factor  $(P_i)$  that reflect the proximity and exposure of other buildings (values range from 1.0 to 1.75). The construction factor,  $C_i$ , is the portion of the NFF attributed to the size of the building and its construction and is given by

$$C_i = 220F\sqrt{A_i} \tag{2.144}$$

where  $C_i$  is in L/min;  $A_i$  (m<sup>2</sup>) is the effective floor area, typically equal to the area of the largest floor in the building plus 50% of the area of all other floors; and F is a coefficient based on the class of construction, given in Table 2.7.

Table 2.7: Construction Coefficient, F

Class of	Constituction Coemeicne, 1	
construction	Description	F
1	frame	1.5
2	joisted masonry	1.0
3	${ m noncombustible}$	0.8
4	masonry, noncombustible	0.8
5	modified fire resistive	0.6
6	fire resistive	0.6

Source: AWWA (1992).

The maximum value of  $C_i$  calculated using Equation 2.144 is limited by the following: 30,000 L/min for construction classes 1 and 2; 23,000 L/min for construction classes 3, 4, 5, and 6; and 23,000 L/min for a one-story building of any class of construction. The minimum value of  $C_i$  is 2,000 L/min, and the calculated value of  $C_i$  should be rounded to the nearest 1,000 L/min. The occupancy factors,  $O_i$ , for various classes of buildings are given in Table 2.8. Detailed tables for

Table 2.8: Occupancy Factors,  $O_i$ 

_		
Combustibility class	Examples	$O_i$
C-1 Noncombustible	steel or concrete products storage	0.75
C-2 Limited combustible	apartments, churches, offices	0.85
C-3 Combustible	department stores, supermarkets	1.00
C-4 Free burning	auditoriums, warehouses	1.15
C-5 Rapid burning	paint shops, upholstering shops	1.25

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estimating the exposure and communication factors,  $(X+P)_i$ , can be found in AWWA (1992), and values of  $(X+P)_i$  are typically on the order of 1.4. The NFF calculated using Equation 2.143 should not exceed 45,000 L/min, nor be less than 2,000 L/min. According to AWWA (1992), 2,000 L/min is the minimum amount of water with which any fire can be controlled and suppressed safely and effectively. The NFF should be rounded to the nearest 1,000 L/min if less than 9,000 L/min, and to the nearest 2,000 L/min if greater than 9,000 L/min. For one- and two-family dwellings not exceeding two stories in height, the NFF listed in Table 2.9 should be used. For other habitable buildings not listed in Table 2.9, the NFF should not exceed 13,000 L/min maximum.

Usually the local water utility will have a policy on the upper limit of fire protection that it will provide to individual buildings. Those wanting higher fire flows need to either provide their own system or reduce fire-flow requirements by installing sprinkler systems, fire walls, or fire-retardant materials (Walski, 1996; AWWA, 1992). Estimates of the needed fire flow calculated using Equation 2.143 are used to determine the fire-flow requirements of the water-supply system, where the needed fire flow is calculated at several representative locations in the service area, and it is assumed that

Table 2.9: Needed Fire Flow for One- and Two-Family Dwellings

Distance between	Needed fire
buildings (m)	flow $(L/min)$
> 30	2,000
9.5 – 30	3,000
3.5 – 9.5	4,000
< 3.5	6,000

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only one building is on fire at any time (Sykes, 1995). The design duration of the fire should follow the guidelines in Table 2.10. If these durations cannot be maintained, insurance rates are typically

Table 2.10: Required Fire Flow Durations

Required fire flow	Duration
(L/min)	(h)
< 9000	2
$11,\!000 – 13,\!000$	3
$15,\!000 - \!17,\!000$	4
19,000-21,000	5
$23,\!000-\!26,\!000$	6
26,000 - 30,000	7
30,000 - 34,000	8
34,000-38,000	9
$38,\!000 – \!45,\!000$	10

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increased accordingly. A more detailed discussion of the requirements for fire protection has been published by the American Water Works Association (AWWA, 1992).

#### Example 2.16.

Estimate the flowrate and volume of water required to provide adequate fire protection to a 10-story noncombustible building with an effective floor area of  $8{,}000~{\rm m}^2$ .

## Solution.

The NFF can be estimated by Equation 2.143 as

$$NFF_i = C_i O_i (X + P)_i$$

where the construction factor,  $C_i$ , is given by

$$C_i = 220F\sqrt{A_i}$$

For the 10-story building, F = 0.8 (Table 2.7, noncombustible, Class 3 construction), and  $A_i = 8,000 \text{ m}^2$ , hence

$$C_i = 220(0.8)\sqrt{8000} = 16000 \text{ L/min}$$

where  $C_i$  has been rounded to the nearest 1,000 L/min. The occupancy factor,  $O_i$ , is given by Table 2.8 as 0.75 (C-1 Noncombustible);  $(X + P)_i$  can be estimated by the median value of 1.4; and hence the needed fire flow, NFF, is given by

$$NFF_i = (16000)(0.75)(1.4) = 17000 L/min$$

This flow must be maintained for a duration of four hours (Table 2.10). Hence the required volume, V, of water is given by

$$V = 17000 \times 4 \times 60 = 4.08 \times 10^6 \text{ L} = 4080 \text{ m}^3$$

Fire hydrants are placed throughout the service area to provide either direct hose connections for firefighting or connections to pumper trucks (also known as fire engines). A single-hose stream is generally taken as 950 L/min, and hydrants are typically located at street intersections or spaced 60–150 m apart (McGhee, 1991). In high-value districts, additional hydrants may be necessary in the middle of long blocks to supply the required fire flows. Fire hydrants may also be used to release air at high points in the water-distribution system and blow off sediments at low points in the system.

**Design Flows.** The design capacity of various components of the water-supply system are given in Table 2.11, where low-lift pumps refer to low-head, high-rate units that convey the raw-water supply to the treatment facility and high-lift pumps deliver finished water from the treatment facility into the distribution network at suitable pressures. The required capacities are based on per person use and population projections for full development of the service area. The required capacities shown in Table 2.11 consist of various combinations of the maximum daily demand, maximum hourly demand, and the fire demand. Typically, the delivery pipelines from the water source to the treatment plant, as well as the treatment plant itself, are designed with a capacity equal to the maximum daily demand. However, because of the high cost of providing treatment, some utilities have trended towards using peak flows averaged over a longer period than one day to design water treatment plants (such as 2 to 5 days), and relying on system storage to meet peak demands above treatment capacity. This approach has serious water quality implications and should be avoided if possible (AWWA, 2004). The flowrates and pressures in the distribution system are analyzed under both maximum daily plus fire demand and the maximum hourly demand, and the larger flowrate governs the design. Pumps are sized for a variety of conditions from maximum daily to maximum hourly demand, depending on their function in the distribution system. Additional reserve capacity is usually installed in water-supply systems to allow for redundancy and maintenance requirements.

#### Example 2.17.

A metropolitan area has a population of 130,000 people with an average daily demand of 600 L/d/person. If the needed fire flow is 20,000 L/min, estimate: (a) the design capacities for the wellfield and the water-treatment plant; (b) the duration that the fire flow must be sustained and the volume of water that must be kept in the service reservoir in case of a fire; and (c) the design capacity of the main supply pipeline to the distribution system.

#### Solution.

(a) The design capacity of the wellfield should be equal to the maximum daily demand (Table 2.11). With a demand factor of 1.8 (Table 2.6), the per capita demand on the maximum day is equal to  $1.8 \times 600 = 1,080$ 

Table 2.11: Design Periods and Capacities in Water-Supply Systems

	Design period	
Component	(years)	Design capacity
1. Source of supply:		
River	indefinite	maximum daily demand
Wellfield	10 – 25	maximum daily demand
Reservoir	25 – 50	average annual demand
2. Conveyance:		
Intake conduit	25 – 50	maximum daily demand
Conduit to treatment plant	25 – 50	maximum daily demand
3. Pumps:		
Low-lift	10	maximum daily demand, one reserve unit
High-lift	10	maximum hourly demand, one reserve unit
4. Treatment plant	10–15	maximum daily demand
5. Service reservoir	20 – 25	working storage plus fire demand
		plus emergency storage
6. Distribution system:		
Supply pipe or conduit	25–50	greater of (1) maximum daily demand plus fire demand, or (2) maximum hourly demand
Distribution grid	full development	same as for supply pipes
2150115001011 6110	Tan de velopinent	ballic ac for supply pipes

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L/day/person. Since the population served is 130,000 people, the design capacity of the wellfield,  $Q_{well}$ , is given by

$$Q_{\text{well}} = 1080 \times 130000 = 1.4 \times 10^8 \text{ L/d} = 1.62 \text{ m}^3/\text{s}$$

The design capacity of the water-treatment plant is also equal to the maximum daily demand, and therefore should also be taken as  $1.62~{\rm m}^3/{\rm s}$ .

(b) The needed fire flow,  $Q_{\rm fire}$ , is 20000 L/min = 0.33 m<sup>3</sup>/s. According to Table 2.10, the fire flow must be sustained for 5 hours. The volume,  $V_{\rm fire}$ , required for the fire flow will be stored in the service reservoir and is given by

$$V_{\rm fire} = 0.33 \times 5 \times 3600 = 5{,}940 \text{ m}^3$$

(c) The required flowrate in the main supply pipeline is equal to the maximum daily demand plus fire demand or the maximum hourly demand, whichever is greater.

Maximum daily demand + fire demand = 
$$1.62 + 0.33 = 1.95 \text{ m}^3/\text{s}$$
  
Maximum hourly demand =  $\frac{3.25}{1.80} \times 1.62 = 2.92 \text{ m}^3/\text{s}$ 

where a demand factor of 3.25 has been assumed for the maximum hourly demand. The main supply pipe to the distribution system should therefore be designed with a capacity of  $2.92~\text{m}^3/\text{s}$ . The water pressure within the distribution system must be above acceptable levels when the system demand is  $2.92~\text{m}^3/\text{s}$ .

# 2.5.2 Pipelines

Water-distribution systems typically consist of connected pipe loops throughout the service area. Pipelines in water-distribution systems include transmission lines, arterial mains, and distribution mains. Transmission lines carry flow from the water-treatment plant to the service area, typically have diameters greater than 600 mm, and are usually on the order of 3 km apart. Arterial mains are connected to transmission mains and are laid out in interlocking loops with the pipelines not more than 1 km apart and diameters in the range of 400–500 mm. Smaller form a grid over the entire service area, with diameters in the range of 150–300 mm, and supply water to every user. Pipelines in distribution systems are collectively called water mains, and a pipe that carries water from a main to a building or property is called a service line. Water mains are normally installed within the rights-of-way of streets. Dead ends in water-distribution systems should be avoided whenever possible, since the lack of flow in such lines may contribute to water-quality problems.

Pipelines in water-distribution systems are typically designed with constraints relating to the minimum pipe size, maximum allowable velocity, and commercially available materials that will perform adequately under operating conditions.

Minimum Size. The size of a water main determines its carrying capacity. Main sizes must be selected to provide the capacity to meet peak domestic, commercial, and industrial demands in the area to be served, and must also provide for fire flow at the necessary pressure. For fire protection, insurance underwriters typically require a minimum main size of 150 mm for residential areas and 200 mm for high-value districts (such as sports stadiums, shopping centers, and libraries) if cross-connecting mains are not more than 180 m apart. On principal streets, and for all long lines not connected at frequent intervals, 300-mm and larger mains are required.

Service Lines. Service lines are pipes, including accessories, that carry water from the main to the point of service, which is normally a meter setting or curb stop located at the property line. Service lines can be any size, depending on how much water is required to serve a particular customer. Single-family residences are most commonly served with 20-mm (3/4 in.) diameter service lines, while larger residences and buildings located far from the main connection should have a 25-mm (1 in.) or larger service line. To properly size service lines it is essential to know the peak demands than any service tap will be called on to serve. A common method to estimate service flows is to sum the fixture units associated with the number and type of fixtures served by the service line and then use a curve called the *Hunter* curve to relate the peak flowrate to total fixture units. This relationship is included in most local plumbing codes and is contained in the Uniform Plumbing Code (UPC). Recent research has indicated that the peak flows estimated from fixture units and the Hunter curve provide conservative estimates of peak flows (AWWA, 2004). Irrigation demands that occur simultaneously with peak domestic demands must be added to the estimated peak domestic demands. Service lines are sized to provide an adequate service pressure downstream of the water meter when the service line is delivering the peak flow. This requires that the pressure and elevation at the tap, length of service pipe, head loss at the meter, elevation at the water meter, valve losses, and desired pressure downstream of the meter be known. Using the energy equation, the minimum service line diameter is calculated using this information. It is usually better to overdesign a service line than to underdesign a service line because of the cost of replacing a service line if service pressures turn out to be inadequate. To prevent water hammer, velocities greater than 3 m/s should be avoided. Materials used for service-line pipe and tubing are typically either copper (tubing) or plastic, which includes polyvinyl chloride (PVC) and polyethylene (PE). Type K copper is the most commonly used material for copper service lines. Older service lines used lead and galvanized iron, which are no longer recommended. The valve used to connect a small-diameter service line to a water main is called a *corporation stop*, which is sometimes loosely referred to as the corporation cock, corporation tap, corp stop, corporation, or simply corp or stop (AWWA, 2003c). Tapping a water main and inserting a corporation stop directly into the pipe wall requires a tapping machine, and taps are typically installed at the 10 or 2 o'clock position on the pipe. Guidelines for designing water service lines and meters are given in AWWA Manual M22 (AWWA, 2004). Good construction practices must be used when installing service lines to avoid costly repairs in the future. This must include burying the pipe below frost lines, maintaining proper ditch conditions, proper backfill, trench compaction, and protection from underground structures that may cause damage to the ppe.

Allowable Velocities. Maximum allowable velocities in pipeline systems are imposed to control friction losses and hydraulic transients. Maximum allowable velocities of 0.9 to 1.8 m/s are common in water-distribution pipes, and the American Water Works Association recommends a limit of about 1.5 m/s under normal operating conditions, but velocities may exceed this guideline under fire-flow conditions (AWWA, 2003c). The importance of controlling the maximum velocities in water distribution systems is supported by the fact that a change in velocity of 0.3 m/s in water transmission and distribution systems can increase the pressure in a pipe by approximately 345 kPa, while the standard design for DIP includes only a 690 kPa allowance (AWWA, 2003d).

Material. Pipeline materials should generally be selected based on a consideration of service conditions, availability, properties of the pipe, and economics. In selecting pipe materials the following considerations should be taken into account:

- Most water distribution mains in older cities in the United States are made of (gray) cast iron pipe (CIP), with many cities having CIP over 100 years old and still providing satisfactory service (Mays, 2000; AWWA, 2003d). CIP is no longer manufactured in the United States.
- For new distribution mains, ductile iron pipe (DIP) is most widely used for pipe diameters up to 760 mm (30 in.), and it has largely replaced CIP in new construction. DIP has all the good qualities of CIP plus additional strength and ductility. DIP is manufactured in diameters from 76 to 1625 mm (3–64 in.). For diameters from 100 to 500 mm (4–20 in.), standard commercial sizes are available in 50-mm (2 in.) increments, while for diameters from 600 to 1200 mm (24–48 in.), the size increments are 150 mm (6 in.). The standard lengths of DIP are 5.5 m (18 ft) and 6.1 m (20 ft). DIP is usually coated (outside and inside) with an bituminous coating to minimize corrosion. An internal cement-mortar lining 1.5 3 mm thick is common, and external polyethylene wraps are used to reduce corrosion in corrosive soil environments. DIP used in water systems in the United States are provided with a cement-mortar lining unless otherwise specified by the purchaser. The design of DIP and fittings are covered in AWWA Manual M41

(AWWA, 2003d) and guidance for DIP lining is covered in AWWA Standard C105 (latest edition). Tests conducted by the Ductile Iron Pipe Research Association (DIPRA) suggest a Hazen-Williams C-value of 140 is appropriate for the design of cement-mortar lined DIP. A variety of joints are available for use with DIP, which includes push-on (the most common), mechanical, flanged, ball-and-socket, and numerous joint designs. A stack of DIP is shown in Figure 2.24, and the bell and spigot pipe ends that facilitate push-on connection are apparent. A rubber gasket, to ensure a tight fit, is contained in the bell side of the pipe.



Figure 2.24: Ductile Iron Pipe

- Steel pipe usually compares favorably with DIP for diameters larger than 400 mm (16 in.) As a consequence, steel pipe is primarily used for transmission lines in water distribution systems. Steel pipe available in diameters from 100 to 3600 mm (4–144 in.). The standard length of steel pipe is 12.2 m (40 ft). The interior of steel pipe is usually protected with either cement mortar or epoxy, and the exterior is protected by a variety of plastic coatings, bituminous materials, and polyethylene tapes depending on the degree of protection required. Guidance for the design of steel pipe are covered in AWWA Manual M11 (latest edition), and linings for steel pipe are covered under AWWA Standard C205 (latest edition) and AWWA Standard C210 (latest edition).
- Plastic materials used for fabricating water main pipe include polyvinyl chloride (PVC), polyethylene (PE), and polybutylene (PB). PVC pipe is by far the most widely used type of plastic pipe material for small-diameter water mains. The American Water Works Association standard (C900) for PVC pipe in sizes from 100 mm to 300 mm and laying lengths of 6.1 m (20 ft) is based on the same outside diameter as for DIP. In this way, standard DIP fittings can be used with PVC pipe. PVC pipe is commonly available in diameters from 100 to 914 mm. Extruded PE and PB pipe are primarily used for water service pipe in small sizes, however, the use of PB has decreased remarkably because of structural difficulties caused by premature pipe failures. Research has documented that pipe materials such as PVC, PE, and PB may be subject to permeation by lower molecular weight organic solvents or petroleum products (AWWA, 2002b). If a water

pipe must pass through an area subject to contamination, caution should be used is selecting PVC, PE, and PB pipes. In the hydraulic design of PVC pipes, a roughness height of 0.0015 mm or a Hazen-Williams C-value of 150 are appropriate for design (AWWA, 2002b). Details of large-diameter PE pipe are found in AWWA Standard C906 (latest edition) and information on PVC water main pipe is available in AWWA Manual M23 (2002b).

- Asbestos-cement (A-C) pipe has been widely installed in water distribution systems, especially in areas where metallic pipe is subject to corrosion, such as in coastal areas. It has also been installed in remote areas where its light weight makes it much easier to install than CIP. Common diameters are in the range of 100 to 890 mm. The U.S. Environmental Protection Agency banned most uses of asbestos in 1989 and, due to the manufacturing ban, new A-C pipe is no longer being installed in the United States.
- Fiberglass pipe is available for potable water used is sizes from 25 to 3600 mm. Advantages of fiberglass pipe include corrosion resistance, light weight, low installation cost, ease of repair, and hydraulic smoothness. Disadvantages include susceptibility to mechanical damage, low modulus of elasticity, and lack of standard joining system. Fiberglass pipe is covered in AWWA Standard C950 (latest edition).
- The use of concrete pressure pipe has grown rapidly since 1950. The pipe provides a combination of the high tensile strength of steel and the high compressive strength and corrosion resistance of concrete. The pipe is available in diameters ranging from 250 to 6400 mm and in standard lengths from 3.7 to 12.2 m. The design of concrete pressure pipe is covered in AWWA Manual M9 (latest edition). Concrete pipe is available with various types of liners and reinforcement, and the four types in common use in the United States and Canada are: prestressed concrete cylinder pipe, bar-wrapped concrete cylinder pipe, reinforced concrete cylinder pipe, and reinforced concrete noncylinder pipe. The manufacture of prestressed concrete cylinder pipe is covered under AWWA Standard C301 (latest edition) and AWWA Standard C304 (latest edition), bar-wrapped concrete cylinder pipe is covered under AWWA Standard C303 (latest edition), reinforced concrete cylinder pipe is covered under AWWA Standard C300 (latest edition), and reinforced concrete noncylinder pipe is covered under AWWA Standard C300 (latest edition).

Pipelines in water-distribution systems should be buried to a depth below the frost line in northern climates and at a depth sufficient to cushion the pipe against traffic loads in warmer climates (Clark, 1990). Generally, a cover of 1.2 m to 1.5 m is used for large mains and 0.75 m to 1.0 m for smaller mains. In areas where frost penetration is a significant factor, mains can have as much as 2.5 m of cover. Trenches for water mains should be as narrow as possible and still be wide enough to allow for proper joining and compaction around the pipe. The suggested trench width is the nominal pipe diameter plus 0.6 m; in deep trenches, sloping may be necessary to keep the bank from caving in. Trench bottoms should be undercut 15 to 25 cm, and sand, clean fill, or crushed stone installed to provide a cushion against the bottom of the excavation, which is usually rock (Clark, 1990). Standards for pipe construction, installation, and performance are published by the American Water Works Association in its C-series standards, which are continuously being updated.

## 2.5.3 Pumps

Service pressures are typically maintained by pumps, with head losses and increases in pipeline elevations acting to reduce pressures and decreases in pipeline elevations acting to increase pressures. When portions of the distribution system are separated by long distances or significant changes in elevation, booster pumps are sometimes used to maintain acceptable service pressures. In some cases, fire-service pumps are used to provide additional capacity for emergency fire protection. Pumps operate at the intersection of the pump performance curve and the system curve. Since the system curve is significantly affected by variations in water demand, there is a significant variation in pump operating conditions. In most cases, the range of operating conditions is too wide to be met by a single pump, and multiple-pump installations or variable speed pumps are required (Velon and Johnson, 1993).

## 2.5.4 Valves

Valves in water distribution systems are designed to perform several different functions, and the primary functions are to start and stop flow, isolate piping, regulate pressure and throttle flow, prevent backflow, and relieve pressure. Shutoff valves or gate valves are typically provided at 350-m intervals so that areas within the system can be isolated for repair or maintenance; air-relief valves or air-and-vacuum relief valves are required at high points to release trapped air; blowoff valves or drain valves may be required at low points; and backflow prevention devices are required by applicable regulations to prevent contamination from backflows of nonpotable water into the distribution system from system outlets. To maintain the performance of water-distribution systems it is recommended that each valve should be operated through a full cycle and then returned to its normal position on a regular schedule. The time interval between operations should be determined by the manufacturer's recommendations, size of the valve, severity of the operating conditions, and the importance of the installation (AWWA, 2003d).

## **2.5.5** Meters

The water meter s a changeable component of a customer's water system. Unlike the service line and water tap, whice when incorrectly sized will generally require expensive excavation and retapping, water meters can usually be changed less expensively. Selection of the type and size of a meter should be based primarily on the range of flow, and the pressure loss through the meter should also be a consideration. For many single-family residences, a 20-mm service line with a 15-mm meter is typical, while in areas where irrigation is prevalent, 20-mm or 25-mm meter may be more prevalent. Undersizing the meter can cause pressure-related problems, and oversizing the meter can result in reduced revenue and inaccurate meter recordings (since the flows do not register). Some customers such as hospitals, schools, and factories with processes requiring uninterrupted water service should have bypasses installed around the meter so that meter test and repair activities can be performed at scheduled intervals without inconvenience to either the customer or the utility. The bypass should be locked and valved appropriately.

## 2.5.6 Fire Hydrants

Fire hydrants are one of the few parts of a water distribution system that are visible to the public, so keeping them well maintained can help a water utility project a good public image. Fire hydrants

are direct connections to the water mains and, in addition to providing an outlet for fire protection, fire hydrants are used for flushing water mains, flushing sewers, filling tank trucks for street washing, tree spraying, and providing a temporary water source for construction jobs. A typical fire hydrant is shown in Figure 2.25, along with the pipe connection between the water main and the fire hydrant. The vertical pipe connecting the water main to the fire hydrant is commonly called the *riser*. The





Figure 2.25: Fire Hydrant and Connection to Water Main

water utility is usually responsible for keeping hydrants in working order, although fire departments sometime assume this responsibility. Standard practice is to install hydrants only on mains 150 mm or larger, however, larger mains are often necessary to ensure that the residual pressure during fire flow remains greater than 140 kPa. Guidelines for the placement of hydrants are as follows (AWWA, 2003c):

- Not too close to buildings since fire fighters will not position their fire (pumper) trucks where a building wall could fall on them.
- Preferably located near street intersections, where the hose can be strung to fight a fire in any of several directions.
- Far enough from a roadway to minimize the danger of them being struck by vehicles.
- Close enough to the pavement to ensure a secure connection with the pumper and hydrant without the risk of the truck getting stuck in mud or snow.
- In areas of heavy snow, hydrants must be located where they are least liable to be covered by plowed snow or struck by snow-removal equipment.
- Hydrants should be high enough off the ground that valve caps can be removed with a standard wrench, without the wrench hitting the ground.

Fire hydrants should be inspected and operated through a full cycle on a regular schedule, and the hydrant should be flushed to prevent sediment buildup in the hydrant or connecting piping.

## 2.5.7 Water Storage Reservoirs

Water usually enters the system at a fairly constant rate from the treatment plant. To accommodate fluctuations in demand, a storage reservoir is typically located at the head of the system to store the excess water during periods of low demand and provide water from storage during periods of

high demand. In addition to the operational storage required to accommodate diurnal (24-hour cycle) variations in water demand, storage facilities are also used to provide storage to fight fires, to provide storage for emergency conditions, and to equalize pressures in water-distribution systems.

Storage facilities are classified as either ground storage, elevated storage, or standpipes. The function and relative advantages of these types of systems are as follows:

Elevated-Storage Tanks. Elevated storage tanks are constructed above ground such that the height of the water in the elevated storage tank is sufficient to deliver water to the distribution system at the required pressure. The storage tank is generally supported by a steel or concrete tower, the tank is directly connected to the distribution system through a pipe called a riser, the water level in the storage tank is equal to the elevation of the hydraulic grade line in the distribution system (at the outlet of the storage tank), and the elevated storage tank is said to float on the system. Elevated storage is useful in the case of fires and emergency conditions since pumping of water from elevated tanks is not necessary, although the water must generally be pumped into elevated storage tanks. Occasionally, system pressure could become so high that the tank would overflow, and therefore altitude valves must be installed on the tank fill line to keep the tank from overflowing. Elevated tanks are usually made of steel.

Ground-Storage Reservoirs. Ground-storage reservoirs are constructed at or below ground level and usually discharge water to the distribution system through pumps. These systems, which are sometimes referred to simply as distribution-system reservoirs or ground-level tanks, are usually used where very large quantities of water must be stored or when an elevated tank is objectionable to the public. When a ground-level or buried reservoir is located at a low elevation on the distribution system, water is admitted through a remotely operated valve, and a pump station is provided to transfer water into the distribution system. Completely buried reservoirs are often used where an above-ground structure is objectionable, such as in a residential neighborhood. In some cases, the land over a buried reservoir can be used for recreational facilities such as a ball field or tennis court. Ground-storage reservoirs are typically constructed of steel or concrete.

**Standpipes.** A tank that rests on the ground with a height that is greater than its diameter is generally referred to as a *standpipe*. In most installations, only water in the upper portion of the tank will furnish usable system pressure, so most larger standpipes are equipped with an adjacent pumping system that can be used in an emergency to pump water to the system from the lower portion of the tank. Standpipes combine the advantages of elevated storage with the ability to store large quantities of water, and standpipes are usually constructed of steel. Standpipes taller than 15 m are usually uneconomical, since for taller standpipes it tends to be more economical to build an elevated tank than to accommodate the dead storage that must be pumped into the system.

Storage facilities in a distribution system are required to have sufficient volume to meet the following criteria (Velon and Johnson, 1993): (1) adequate volume to supply peak demands in excess of the maximum daily demand using no more than 50% of the available storage capacity; (2) adequate volume to supply the critical fire demand in addition to the volume required for meeting the maximum daily demand fluctuations; and (3) adequate volume to supply the average daily demand of the system for the estimated duration of a possible emergency. Conventional design practice

is to rely on pumping to meet the daily operational demands up to the maximum daily demand; where detailed demand data are not available, the storage available to supply the peak demands should equal 20% to 25% of the maximum daily demand volume. Sizing the storage volume for fire protection is based on the product of the critical fire flow and duration for the service area. In extremely large systems where fire demands be only a small fraction of the maximum daily demand fire storage may not be necessary (Walski, 2000). Emergency storage is generally necessary to provide water during power outages, breaks in water mains, problems at treatment plants, unexpected shutdowns of water-supply facilities, and other sporadic events. Emergency volumes for most municipal water-supply systems vary from one to two days of supply capacity at the average daily demand. The recommended standards for water works developed by the Great Lakes Upper Mississippi River Board of State Public Health and Environmental Managers suggest a minimum emergency storage capacity equal to the average daily system demand.

In cases where elevated storage tanks are used, the minimum acceptable height of water in an elevated storage tank is determined by computing the minimum acceptable piezometric head in the service area and then adding to that figure an estimate of the head losses between the critical service location and the location of the elevated service tank, under the condition of average daily demand. The maximum height of water in the elevated tank is then determined by adding the minimum acceptable piezometric head to the head loss between the tank location and the critical service location under the condition of maximum hourly demand. The difference between the calculated minimum and maximum heights of water in the elevated storage tank is then specified as the normal operating range within the tank. The normal operating range for water in elevated tanks is usually limited to 4.5 to 6 meters, so that fluctuations in pressure are limited to 35 to 70 kPa. In most cases, the operating range is located in the upper half of the storage tank, with storage in the lower half of the tank reserved for firefighting and emergency storage. Any water stored in elevated tanks less than 14 m (46 ft) above ground is referred to as ineffective storage (Walski et al., 1990) since the pressure in connected distribution pipes will be less than the usual minimum acceptable pressure during emergency conditions of 140 kPa (20 psi). Operational storage in elevated tanks is normally at elevations of more than 25 m (81 ft) above the ground, since under these conditions the pressure in connected distribution pipes will exceed the usual minimum acceptable pressure during normal operations of 240 kPa (35 psi). A typical elevated storage tank is illustrated in Figure 2.26. These types of storage facilities generally have only a single pipe connection to the distribution system, and this single pipe handles both inflows and outflows from the storage tank. This piping arrangement is in contrast to ground storage reservoirs, which have separate inflow and outflow piping. The inflow piping delivers the outflow from the water-treatment facility to the reservoir, while the outflow piping delivers the water from the reservoir to the pumps that input water into the distribution system. Elevated tanks are generally made of steel (Walski, 1996), and the largest elevated storage tank in the United States (as of 2000) has a volume of 15,520 m<sup>3</sup> (ASCE, 2000). Elevated storage tanks are best placed on the downstream side of the largest demand from the source, with the advantages that: (1) if a pipe breaks near the source, the break will not result in disconnecting all the storage from the customers; and (2) if flow reaches the center of demand from more than one direction, the flow carried by any individual pipe will be lower and pipe sizes will generally be smaller, with associated cost savings (Walski, 2000). If there are multiple storage tanks in the distribution system, the tanks should be placed roughly the same distance from the source or sources, and all tanks should have approximately the same overflow elevation (otherwise, it may be impossible to fill the highest tank without overflowing or shutting off the lower tanks.

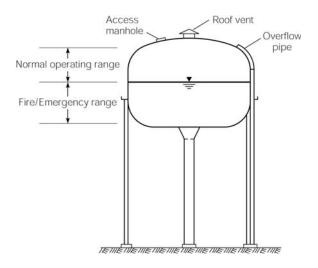




Figure 2.26: Elevated Storage Tank

#### Example 2.18.

A service reservoir is to be designed for a water-supply system serving 250,000 people with an average demand of 600 L/d/capita, and a needed fire flow of 37,000 L/min. Estimate the required volume of service storage.

#### Solution.

The required storage is the sum of three components: (1) volume to supply the demand in excess of the maximum daily demand, (2) fire storage, and (3) emergency storage.

The volume to supply the peak demand can be taken as 25% of the maximum daily demand volume. Taking the maximum daily demand factor as 1.8 (Table 2.6), then the maximum daily flowrate,  $Q_m$ , is given by

$$Q_m = (1.8)(600)(250000) = 2.7 \times 10^8 \text{ L/d} = 2.7 \times 10^5 \text{ m}^3/\text{d}$$

The storage volume to supply the peak demand,  $V_{\text{peak}}$ , is therefore given by

$$V_{\text{peak}} = (0.25)(2.7 \times 10^5) = 67500 \text{ m}^3$$

According to Table 2.10, the 37,000 L/min (= 0.62 m<sup>3</sup>/s) fire flow must be maintained for at least 9 hours. The volume to supply the fire demand,  $V_{\text{fire}}$ , is therefore given by

$$V_{\text{fire}} = 0.62 \times 9 \times 3600 = 20100 \text{ m}^3$$

The emergency storage,  $V_{\rm emer}$ , can be taken as the average daily demand, in which case

$$V_{\text{emer}} = 250000 \times 600 = 150 \times 10^6 \text{ L} = 150,000 \text{ m}^3$$

The required volume, V, of the service reservoir is therefore given by

$$V = V_{\text{peak}} + V_{\text{fire}} + V_{\text{emer}}$$

$$= 67500 + 20100 + 150000$$

$$= 237,600 \text{ m}^3$$

The service reservoir should be designed to store 238,000 m<sup>3</sup> of water. This large volume will require a ground storage tank (recall that the largest elevated-tank volume in the United States is 15,520 m<sup>3</sup>), and it is interesting to note that most of the storage in the service reservoir is reserved for emergencies.

#### Example 2.19.

A water-supply system is to be designed in an area where the minimum allowable pressure in the distribution system

is 300 kPa. A hydraulic analysis of the distribution network under average daily demand conditions indicates that the head loss between the low-pressure service location, which has a pipeline elevation of 5.40 m, and the location of the elevated storage tank is 10 m. Under maximum hourly demand conditions, the head loss between the low-pressure service location and the elevated storage tank is 12 m. Determine the normal operating range for the water stored in the elevated tank.

#### Solution.

Under average demand conditions, the elevation  $z_o$  of the hydraulic grade line (HGL) at the reservoir location is given by

$$z_o = \frac{p_{\min}}{\gamma} + z_{\min} + h_L$$

where  $p_{\min} = 300$  kPa,  $\gamma = 9.79$  kN/m<sup>3</sup>,  $z_{\min} = 5.4$  m, and  $h_L = 10$  m, which yields

$$z_o = \frac{300}{9.79} + 5.4 + 10 = 46.0 \text{ m}$$

Under maximum hourly demand conditions, the elevation  $z_1$  of the HGL at the service reservoir is given by

$$z_1 = \frac{300}{9.79} + 5.4 + 12 = 48.0 \text{ m}$$

Therefore, the operating range in the storage tank should be between elevations 46.0 m and 48.0 m.

It is important to keep in mind that the best hydraulic location and most economical design are not always the deciding factors in the location of an elevated tank. In some cases, the only acceptable location will be in an industrial area or public park. In cases where public feeling is very strong, a water utility may have to construct ground-level storage, which is more aesthetically acceptable.

## 2.5.8 Performance Criteria for Water-Distribution Systems

The primary functions of water-distribution systems (Zipparro and Hasen, 1993) are to (1) meet the water demands of users while maintaining acceptable pressures in the system; (2) supply water for fire protection at specific locations within the system, while maintaining acceptable pressures for normal service throughout the remainder of the system; and (3) provide a sufficient level of redundancy to support a minimum level of reliable service during emergency conditions, such as an extended loss of power or a major water-main failure. Real-time operation of water distribution systems are typically based on remote measurements of pressures and storage-tank water levels within the distribution system. The pressure and water-level data are typically transmitted to a central control facility via telemetry, and adjustments to the distribution system are made from the central facility by remote control of pumps and valves within the distribution system. These electronic control systems are generally called supervisory control and data acquisition (SCADA) systems (Chase, 2000). Operating criteria for service pressures and storage facilities are described below.

The requirement that adequate pressures be maintained in the distribution system while supplying the service demands requires that the system be analyzed on the basis of allowable pressures. Minimum acceptable pressures are necessary to prevent contamination of the water supply from cross-connections. Criteria for minimum acceptable service pressures recommended by the Great Lakes Upper Mississippi River Board of State Public Health and Environmental Managers (GLUMB, 1987) and endorsed by the American Water Works Association (AWWA, 2003c) are typical of most water-distribution systems, and they are listed in Table 2.12. During main breaks,

12. Millinum Acceptable I lessures in Distribution System		
	Minimum acceptable pressure	
Demand condition	(kPa)	
Average daily demand	240-410	
Maximum daily demand	240 – 410	
Maximum hourly demand	d 240–410	
Fire situation	> 140	
Emergency conditions	> 140	
C (I IIMD (1007)		

 ${\bf Table\ 2.1\underline{12:}\ Minimum\ Acceptable\ Pressures\ in\ Distribution\ Systems}$ 

Source: GLUMB (1987).

when the pressure in water-supply pipelines can drop below 140 kPa, it is not uncommon for a water utility to issue a "boil water" advisory because of the possibility of system contamination from cross connections (Chase, 2000). There are several considerations in assessing the adequacy of service pressures, including (1) the pressure required at street level for excellent flow to a 3-story building is about 290 kPa; (2) flow is adequate for residential areas if the pressure is not reduced below 240 kPa; (3) the pressure required for adequate flow to a 20-story building is about 830 kPa, which is not desirable because of the associated leakage and waste; (4) very tall buildings are usually served with their own pumping equipment; and (5) it is usually desirable to maintain normal pressures of 410–520 kPa since these pressures are adequate for the following purposes:

- To supply ordinary consumption for buildings up to 10 stories.
- To provide adequate sprinkler service in buildings of 4 to 5 stories.
- To provide direct hydrant service for quick response.
- To allow larger margin for fluctuations in pressure caused by clogged pipes and excessive length of service pipes.

Pressures higher than 650 kPa should be avoided if possible because of excessive leakage and water use, and the added burden of installing and maintaining pressure-reducing valves and other specialized equipment (Clark, 1990). Customers do not generally like high pressure because water comes out of a quickly-opened faucet with too much force (AWWA, 2003c). In addition, excessive pressures decrease the the life of water heaters and other plumbing fixtures.

### 2.5.9 Water Quality

The quality of water delivered to consumers can be significantly influenced by various components of a water distribution system. The principal factors affecting water quality in distribution systems are the quality of the treated water fed to the system; the material and condition of the pipes, valves, and storage facilities that make up the system; and the amount of time that the water is kept in the system (Grayman et al., 2000; AWWA, 2003c). Key processes that affect water quality within the distribution system usually include the loss of disinfection residual with resulting microbial regrowth, and the formation of disinfection byproducts such as trihalomethanes. Water-quality deterioration is often proportional to the time the water is resident in the distribution system. The longer the water is in contact with the pipe walls and is held in storage facilities, the greater the

opportunity for water-quality changes. Generally, a hydraulic detention time of less than 7 days in the distribution system is recommended (AWWA, 2003c).

The velocity of flow in most mains is normally very low because mains are designed to handle fire flow, which may be several times larger than domestic flow. As a result, corrosion products and other solids tend to settle on the pipe bottom, and this problem is especially bad in dead-end mains or in areas of low water consumption. These deposits can can be a source of color, odor, and taste in the water when the deposits are stirred up by an increase in flow velocity or a reversal of flow in the distribution system. To prevent these sediments from accumulating and causing water-quality problems, pipe flushing is a typical maintenance routine. Flushing involves opening a hydrant located near the problem area, and the hydrant should be kept open as long as needed to flush out the sediment, which typically requires the removal of up to three pipe volumes (AWWA, 2003c). Only through experience will an operator be able to how often or how long certain areas should be flushed. Some systems find that dead-end mains must be flushed as often as weekly to avoid customer complaints of rusty water. The flow required for effective flushing is in the range of 0.75 - 1.1 m/s, with velocities limited to less than 3.1 - 3.7 m/s to avoid excessive scouring (AWWA, 2003c). If flushing proves to be inadequate for cleaning mains, air purging or cleaning devices such as swabs or pigs may need to be used.

In recognition of the influence of the water distribution system on water quality, water quality regulations in the United States requires that water to be sampled at at the entry point to the distribution system, at various points within the distribution system, and at consumers' taps (Kirmeyer et al., 1999). The computer program EPANET (Rossman, 2000) is widely used to simulate the water quality in distribution networks.

## 2.5.10 Network Analysis

Methodologies for analyzing pipe networks were discussed in Section 2.3, and these methods can be applied to any given pipe network to calculate the pressure and flow distribution under a variety of demand conditions. In complex pipe networks, the application of computer programs to implement these methodologies is standard practice (Haestad Methods Inc., 1997a; 1997b; 2002)). Computer programs allow engineers to easily calculate the hydraulic performance of complex networks and such parameters as the age of water delivered to consumers and also to trace the origin of the delivered water. Water age is measured from the time the water enters the system and gives an indication of the overall quality of the delivered water. Steady-state analyses are usually adequate for assessing the performance of various components of the distribution system, including the pipelines, storage tanks, and pumping systems, while time-dependent simulations are useful in assessing the response of the system over short time periods (days or less), evaluating the operation of pumping stations and variable-level storage tanks, performing energy consumption and cost studies, and water quality modeling (Velon and Johnson, 1993; Haestad Methods, Inc., 2002). Modelers frequently refer to time-dependent simulations as extended-period simulations, and several examples can be found in Larock et al. (2000).

An important part of analyzing large water-distribution systems is the *skeletonizing* of the system, which consists of representing the full water-distribution system by a subset of the system that includes only the most important elements. For example, consider the case of a water supply to the subdivision shown in Figure 2.27(a), where the system shown includes the service connections to the houses. A slight degree of skeletonization could be achieved by omitting the household service

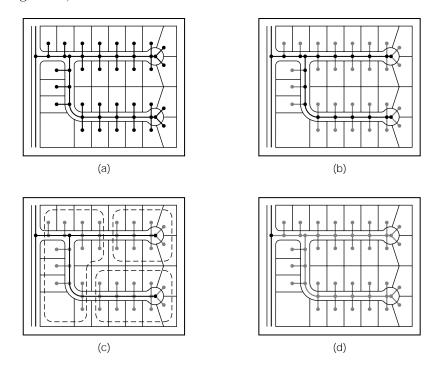


Figure 2.27: Skeletonizing a Water-Distribution System

Source: Haestad Methods, 1997 Practical Guide: Hydraulics and Hydrology p. 61–62. Copyright © 1997 by Haestad Methods, Inc. Reprinted by permission.

pipes (and their associated head losses) from consideration and accounting for the water demands at the tie-ins and as shown in Figure 2.27(b). This reduces the number of junctions from 48 to 19. Further skeletonization can be achieved by modeling just 4 junctions, consisting of the ends of the main piping and the major intersections shown in Figure 2.27(c). In this case, the water demands are associated with the nearest junctions to each of the service connections, and the dashed lines in Figure 2.27(c) indicate the service areas for each junction. A further level of skeletonization is shown in Figure 2.27(d), where the water supply to the entire subdivision is represented by a single node, at which the water demand of the subdivision is attributed.

Clearly, further levels of skeletonization could be possible in large water-distribution systems. As a general guideline, larger systems permit more degrees of skeletonization without introducing significant error in the flow conditions of main distribution pipes.

The results of a pipe-network analysis should generally include pressures and/or hydraulic grade line elevations at all nodes, flow, velocity, and head loss through all pipes as well as rates of flow into and out of all storage facilities. These results are used to assess the hydraulic performance and reliability of the network, and they are to be compared with the guidelines and specifications required for acceptable performance.

# 2.6 Computer Models

Several good computer models are available for simulating flow in closed conduits, with the majority of these models developed primarily for computing flows and pressure distributions in water-supply networks. In engineering practice, the use of computer models to apply the fundamental principles

covered in this chapter is usually essential. In choosing a model for a particular application, there are usually a variety of models to choose from, however, in doing work that is to be reviewed by regulatory bodies, models developed and maintained by agencies of the United States government have the greatest credibility and, perhaps more importantly, are almost universally acceptable in supporting permit applications and defending design protocols. A secondary guideline in choosing a model is that the simplest model that will accomplish the design objectives should be given the most serious consideration.

EPANET. EPANET is a water-distribution-system modeling package developed by the U.S. Environmental Protection Agency's Water Supply and Water Resources Division. It performs extended-period simulation of hydraulic and water-quality behavior within pressurized pipe networks. A more detailed description of EPANET can be found in Rossman (2000), and the program can be downloaded from the World Wide Web at www.epa.gov/ORD/NRMRL/wswrd/epanet.html.

## Summary

The hydraulics of flow in closed conduits is the basis for designing water-supply systems and other systems that involve the transport of water under pressure. The fundamental relationships governing flow in closed conduits are the conservation laws of mass, momentum, and energy; the forms of these equations that are most useful in engineering applications are derived from first principles. Of particular note is the momentum equation, the most useful form of which is the Darcy-Weisbach equation. Techniques for analyzing flows in both single and multiple pipelines, using the nodal and loop methods, are presented. Flows in closed conduits are usually driven by pumps, and the fundamentals of pump performance using dimensional analysis and similitude are presented. Considerations in selecting a pump include the specific speed under design conditions, the application of affinity laws in adjusting pump performance curves, the computation of operating points in pump-pipeline systems, practical limits on pump location based on the critical cavitation parameter, and the performance of pump systems containing multiple units.

Water-supply systems are designed to meet service-area demands during the design life of the system. Projection of water demand involves the estimation of per capita demands and population projections. Over short time scales, populations can be expected to follow either geometric, arithmetic, or declining growth models, while over longer time scales a logistic growth curve may be more appropriate. Components of water-supply systems must be designed to accommodate daily fluctuations in water demand plus potential fire flows. The design periods and capacities of various components of water-supply systems are listed in Table 2.11. Other key considerations in designing water distribution systems include required service pressures (Table 2.12), pipeline selection and installation, and provision of adequate storage capacity to meet fire demands and emergency conditions.

## **Problems**

**2.1.** Water at 20°C is flowing in a 100-mm diameter pipe at an average velocity of 2 m/s. If the diameter of the pipe is suddenly expanded to 150 mm, what is the new velocity in the pipe? What are the volumetric and mass flowrates in the pipe?

- **2.2.** A 200-mm diameter pipe divides into two smaller pipes each of diameter 100 mm. If the flow divides equally between the two smaller pipes and the velocity in the 200-mm pipe is 1 m/s, calculate the velocity and flowrate in each of the smaller pipes.
- **2.3.** The velocity distribution in a pipe is given by the equation

$$v(r) = V_o \left[ 1 - \left( \frac{r}{R} \right)^2 \right] \tag{2.145}$$

where v(r) is the velocity at a distance r from the centerline of the pipe,  $V_o$  is the centerline velocity, and R is the radius of the pipe. Calculate the average velocity and flowrate in the pipe in terms of  $V_o$ .

- **2.4.** Calculate the momentum correction coefficient,  $\beta$ , for the velocity distribution given in Equation 2.145.
- 2.5. Water is flowing in a horizontal 200-mm diameter pipe at a rate of 0.06 m<sup>3</sup>/s, and the pressures at sections 100 m apart are equal to 500 kPa at the upstream section and 400 kPa at the downstream section. Estimate the average shear stress on the pipe and the friction factor, f. [Hint: Use Equation 2.26 to calculate the shear stress and Equation 2.32 to calculate the friction factor.]
- 2.6. Water at 20°C flows at a velocity of 2 m/s in a 250-mm diameter horizontal ductile iron pipe. Estimate the friction factor in the pipe, and state whether the pipe is hydraulically smooth or rough. Compare the friction factors derived from the Moody diagram, the Colebrook equation, and the Jain equation. Estimate the change in pressure over 100 m of pipeline. How would the friction factor and pressure change be affected if the pipe is not horizontal but 1 m lower at the downstream section?
- **2.7.** Show that the Colebrook equation can be written in the (slightly) more convenient form:

$$f = \frac{0.25}{\{\log[(k_s/D)/3.7 + 2.51/(\text{Re}\sqrt{f})]\}^2}$$

Why is this equation termed "(slightly) more convenient"?

- **2.8.** If you had your choice of estimating the friction factor either from the Moody diagram or from the Colebrook equation, which one would you pick? Explain your reasons.
- 2.9. Water leaves a treatment plant in a 500-mm diameter ductile iron pipeline at a pressure of 600 kPa and at a flowrate of 0.50 m<sup>3</sup>/s. If the elevation of the pipeline at the treatment plant is 120 m, then estimate the pressure in the pipeline 1 km downstream where the elevation is 100 m. Assess whether the pressure in the pipeline would be sufficient to serve the top floor of a 10-story (approximately 30 m high) building.
- **2.10.** A 25-mm diameter galvanized iron service pipe is connected to a water main in which the pressure is 400 kPa. If the length of the service pipe to a faucet is 20 m and the faucet is 2.0 m above the main, estimate the flowrate when the faucet is fully open.

- 2.11. A galvanized iron service pipe from a water main is required to deliver 300 L/s during a fire. If the length of the service pipe is 40 m and the head loss in the pipe is not to exceed 45 m, calculate the minimum pipe diameter that can be used. Use the Colebrook equation in your calculations.
- **2.12.** Repeat Problem 2.11 using the Swamee-Jain equation.
- **2.13.** Use the velocity distribution given in Problem 2.3 to estimate the kinetic energy correction factor,  $\alpha$ , for turbulent pipe flow.
- **2.14.** The velocity profile, v(r), for turbulent flow in smooth pipes is sometimes estimated by the seventh-root law, originally proposed by Blasius (1911)

$$v(r) = V_o \left( 1 - \frac{r}{R} \right)^{\frac{1}{7}}$$

where  $V_o$  is the maximum (centerline) velocity and R is the radius of the pipe. Estimate the energy and momentum correction factors corresponding to the seventh-root law.

- **2.15.** Show that the kinetic energy correction factor,  $\alpha$ , corresponding to the power-law velocity profile is given by Equation 2.75. Use this result to confirm your answer to Problem 2.14.
- **2.16.** Water enters and leaves a pump in pipelines of the same diameter and approximately the same elevation. If the pressure on the inlet side of the pump is 30 kPa and a pressure of 500 kPa is desired for the water leaving the pump, what is the head that must be added by the pump, and what is the power delivered to the fluid?
- 2.17. Water leaves a reservoir at 0.06 m<sup>3</sup>/s through a 200-mm riveted steel pipeline that protrudes into the reservoir and then immediately turns a 90° bend with a minor loss coefficient equal to 0.3. Estimate the length of pipeline required for the friction losses to account for 90% of the total losses, which includes both friction losses and so-called "minor losses". Would it be fair to say that for pipe lengths shorter than the length calculated in this problem that the word "minor" should not be used?
- 2.18. The top floor of an office building is 40 m above street level and is to be supplied with water from a municipal pipeline buried 1.5 m below street level. The water pressure in the municipal pipeline is 450 kPa, the sum of the local loss coefficients in the building pipes is 10.0, and the flow is to be delivered to the top floor at 20 L/s through a 150 mm diameter PVC pipe. The length of the pipeline in the building is 60 m, the water temperature is 20°C, and the water pressure on the top floor must be at least 150 kPa. Will a booster pump be required for the building? If so, what power must be supplied by the pump?
- 2.19. Water is pumped from a supply reservoir to a ductile iron water transmission line, as shown in Figure 2.28. The high point of the transmission line is at point A, 1 km downstream of the supply reservoir, and the low point of the transmission line is at point B, 1 km downstream of A. If the flowrate through the pipeline is 1 m<sup>3</sup>/s, the diameter of the pipe is 750 mm, and the pressure at A is to be 350 kPa, then: (a) estimate the head that must be added by the pump; (b) estimate the power supplied by the pump; and (c) calculate the water pressure at B.

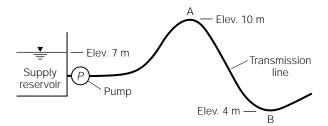


Figure 2.28: Problem 2.19

- 2.20. A pipeline is to be run from a water-treatment plant to a major suburban development 3 km away. The average daily demand for water at the development is 0.0175 m<sup>3</sup>/s, and the peak demand is 0.578 m<sup>3</sup>/s. Determine the required diameter of ductile iron pipe such that the flow velocity during peak demand is 2.5 m/s. Round the pipe diameter upward to the nearest 25 mm (i.e., 25 mm, 50 mm, 75 mm, ...). The water pressure at the development is to be at least 340 kPa during average demand conditions, and 140 kPa during peak demand. If the water at the treatment plant is stored in a ground-level reservoir where the level of the water is 10.00 m NGVD and the ground elevation at the suburban development is 8.80 m NGVD, determine the pump power (in kilowatts) that must be available to meet both the average daily and peak demands.
- **2.21.** Water flows at  $5 \text{ m}^3/\text{s}$  in a  $1 \text{ m} \times 2 \text{ m}$  rectangular concrete pipe. Calculate the head loss over a length of 100 m.
- **2.22.** Water flows at  $10 \text{ m}^3/\text{s}$  in a  $2 \text{ m} \times 2 \text{ m}$  square reinforced-concrete pipe. If the pipe is laid on a (downward) slope of 0.002, what is the change in pressure in the pipe over a distance of 500 m?
- **2.23.** Derive the Hazen-Williams head-loss relation, Equation 2.84, starting from Equation 2.82.
- **2.24.** Compare the Hazen-Williams formula for head loss (Equation 2.84) with the Darcy-Weisbach equation for head loss (Equation 2.33) to determine the expression for the friction factor that is assumed in the Hazen-Williams formula. Based on your result, identify the type of flow condition incorporated in the Hazen-Williams formula (rough, smooth, or transition).
- **2.25.** Derive the Manning head-loss relation, Equation 2.86.
- 2.26. Compare the Manning formula for head loss (Equation 2.86) with the Darcy-Weisbach equation for head loss (Equation 2.33) to determine the expression for the friction factor that is assumed in the Manning formula. Based on your result, identify the type of flow condition incorporated in the Manning formula (rough, smooth, or transition).
- **2.27.** Determine the relationship between the Hazen-Williams roughness coefficient and the Manning roughness coefficient.
- **2.28.** Given a choice between using the Darcy-Weisbach, Hazen-Williams, or Manning equations to estimate the friction losses in a pipeline, which equation would you choose? Why?

- 2.29. Water flows at a velocity of 2 m/s in a 300-mm new ductile iron pipe. Estimate the head loss over 500 m using: (a) the Hazen-Williams formula; (b) the Manning formula; and (c) the Darcy-Weisbach equation. Compare your results. Calculate the Hazen-Williams roughness coefficient and the Manning coefficient that should be used to obtain the same head loss as the Darcy-Weisbach equation.
- 2.30. Reservoirs A, B, and C are connected as shown in Figure 2.29. The water elevations in reservoirs A, B, and C are 100 m, 80 m, and 60 m, respectively. The three pipes connecting the reservoirs meet at the junction J, with pipe AJ being 900 m long, BJ 800 m long, CJ 700 m long, and the diameter of all pipes equal to 850 mm. If all pipes are made of ductile iron and the water temperature is 20°C, find the flow into or out of each reservoir.

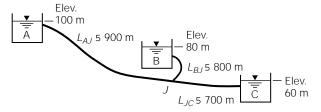


Figure 2.29: Problem 2.30

**2.31.** The water-supply network shown in Figure 2.30 has constant-head elevated storage tanks at A and B, with inflows and withdrawals at C and D. The network is on flat terrain, and the pipeline characteristics are as follows:

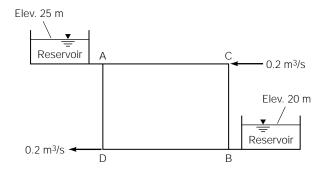


Figure 2.30: Problem 2.31

Pipe	L (km)	$D \pmod{mm}$
AD	1.0	400
$_{\mathrm{BC}}$	0.8	300
BD	1.2	350
AC	0.7	250

If all pipes are made of ductile iron, calculate the inflows/outflows from the storage tanks. Assume that the flows in all pipes are fully turbulent.

**2.32.** Consider the pipe network shown in Figure 2.31. The Hardy Cross method can be used to calculate the pressure distribution in the system, where the friction loss,  $h_f$ , is estimated

using the equation

$$h_f = rQ^n$$

and all pipes are made of ductile iron. What value of r and n would you use for each pipe in the system? The pipeline characteristics are as follows:

	L	D
Pipe	(m)	(mm)
AB	1,000	300
BC	750	325
CD	800	200
DE	700	250
$\operatorname{EF}$	900	300
FA	900	250
BE	950	350

You can assume that the flow in each pipe is hydraulically rough.

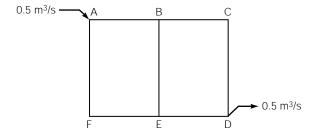


Figure 2.31: Problem 2.32

**2.33.** A portion of a municipal water distribution network is shown in Figure 2.32, where all pipes are made of ductile iron and have diameters of 300 mm. Use the Hardy Cross method to find the flowrate in each pipe. If the pressure at point P is 500 kPa and the distribution network is on flat terrain, determine the water pressures at each pipe intersection.

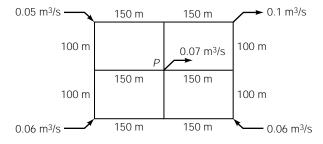


Figure 2.32: Problem 2.33

- **2.34.** What is the constant that can be used to convert the specific speed in SI units (Equation 2.111) to the specific speed in U.S. Customary units (Equation 2.112)?
- **2.35.** What is the highest synchronous speed for a motor driving a pump?

- **2.36.** Derive the affinity relationship for the power delivered to a fluid by two homologous pumps. [*Note*: This affinity relation is given by Equation 2.116.]
- 2.37. A pump is required to deliver 150 L/s ( $\pm$  10%) through a 300-mm diameter PVC pipe from a well to a reservoir. The water level in the well is 1.5 m below the ground and the water surface in the reservoir is 2 m above the ground. The delivery pipe is 300 m long, and minor losses can be neglected. A pump manufacturer suggests using a pump with a performance curve given by

$$h_p = 6 - 6.67 \times 10^{-5} Q^2$$

where  $h_p$  is in meters and Q in L/s. Is this pump adequate?

- **2.38.** A pump is to be selected to deliver water from a well to a treatment plant through a 300-m long pipeline. The temperature of the water is  $20^{\circ}$ C, the average elevation of the water surface in the well is 5 m below ground surface, the pump is 50 cm above ground surface, and the water surface in the receiving reservoir at the water-treatment plant is 4 m above ground surface. The delivery pipe is made of ductile iron ( $k_s = 0.26$  mm) with a diameter of 800 mm. If the selected pump has a performance curve of  $h_p = 12 0.1Q^2$ , where Q is in m<sup>3</sup>/s and  $h_p$  is in m, then what is the flowrate through the system? Calculate the specific speed of the required pump (in U.S. Customary units), and state what type of pump will be required when the speed of the pump motor is 1,200 rpm. Neglect minor losses.
- **2.39.** A pump lifts water through a 100-mm diameter ductile iron pipe from a lower to an upper reservoir (Figure 2.33). If the difference in elevation between the reservoir surfaces is 10 m, and the performance curve of the 2400-rpm pump is given by

$$h_p = 15 - 0.1Q^2$$

where  $h_p$  is in meters and Q in L/s, then estimate the flowrate through the system. If the pump manufacturer gives the required net positive suction head under these operating conditions as 1.5 m, what is the maximum height above the lower reservoir that the pump can be placed and maintain the same operating conditions?

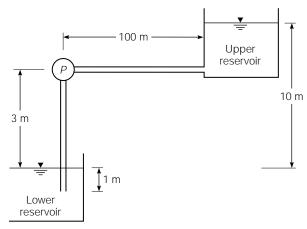


Figure 2.33: Problem 2.39

**2.40.** Water is being pumped from reservoir A to reservoir F through a 30-m long PVC pipe of diameter 150 mm (see Figure 2.34). There is an open gate valve located at C; 90° bends (threaded) located at B, D, and E; and the pump performance curve is given by

$$h_p = 20 - 4713Q^2$$

where  $h_p$  is the head added by the pump in meters and Q is the flowrate in  $m^3/s$ . The specific speed of the pump (in U.S. Customary units) is 3,000. Assuming that the flow is turbulent (in the smooth, rough, or transition range) and the temperature of the water is  $20^{\circ}$ C, then (a) write the energy equation between the upper and lower reservoirs, accounting for entrance, exit, and minor losses between A and F; (b) calculate the flowrate and velocity in the pipe; (c) if the required net positive suction head at the pump operating point is 3.0 m, assess the potential for cavitation in the pump (for this analysis you may assume that the head loss in the pipe is negligible between the intake and the pump); and (d) use the affinity laws to estimate the pump performance curve when the motor on the pump is changed from 800 rpm to 1,600 rpm.

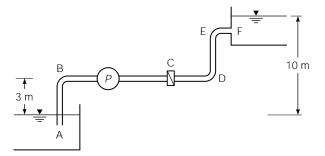


Figure 2.34: Problem 2.40

**2.41.** If the performance curve of a certain pump model is given by

$$h_p = 30 - 0.05Q^2$$

where  $h_p$  is in meters and Q is in L/s, what is the performance curve of a pump system containing n of these pumps in series? What is the performance curve of a pump system containing n of these pumps in parallel?

**2.42.** A pump is placed in a pipe system in which the energy equation (system curve) is given by

$$h_p = 15 + 0.03Q^2$$

where  $h_p$  is the head added by the pump in meters and Q is the flowrate through the system in L/s. The performance curve of the pump is

$$h_p = 20 - 0.08Q^2$$

What is the flowrate through the system? If the pump is replaced by two identical pumps in parallel, what would be the flowrate in the system? If the pump is replaced by two identical pumps in series, what would be the flowrate in the system?

- **2.43.** Derive an expression for the population, P, versus time, t, where the growth rate is: (a) geometric, (b) arithmetic, and (c) declining.
- 2.44. The design life of a planned water-distribution system is to end in the year 2030, and the population in the town has been measured every 10 years since 1920 by the U.S. Census Bureau. The reported populations are tabulated below. Estimate the population in the town using: (a) graphical extension, (b) arithmetic growth projection, (c) geometric growth projection, (d) declining growth projection (assuming a saturation concentration of 100,000 people), and (e) logistic curve projection.

Year	Population
1920	25,521
1930	30,208
1940	30,721
1950	37,253
1960	38,302
1970	41,983
1980	56,451
1990	64,109

- **2.45.** A city founded in 1950 had a population of 13,000 in 1960; 125,000 in 1975; and 300,000 in 1990. Assuming that the population growth follows a logistic curve, estimate the saturation population of the city.
- **2.46.** The average demand of a population served by a water-distribution system is 580 L/d/capita, and the population at the end of the design life is estimated to be 100,000 people. Estimate the maximum daily demand and maximum hourly demand.
- **2.47.** Estimate the flowrate and volume of water required to provide adequate fire protection to a five-story office building constructed of joisted masonry. The effective floor area of the building is  $5,000 \text{ m}^2$ .
- **2.48.** What is the maximum fire flow and corresponding duration that can be estimated for any building?
- 2.49. A water-supply system is being designed to serve a population of 200,000 people, with an average per capita demand of 600 L/d/person and a needed fire flow of 28,000 L/min. If the water supply is to be drawn from a river, then what should be the design capacity of the supply pumps and water-treatment plant? For what duration must the fire flow be sustained, and what volume of water must be kept in the service reservoir to accommodate a fire? What should the design capacity of the distribution pipes be?
- **2.50.** What is the minimum acceptable water pressure in a distribution system under average daily demand conditions?
- **2.51.** Calculate the volume of storage required for the elevated storage reservoir in the water-supply system described in Problem 2.49.

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